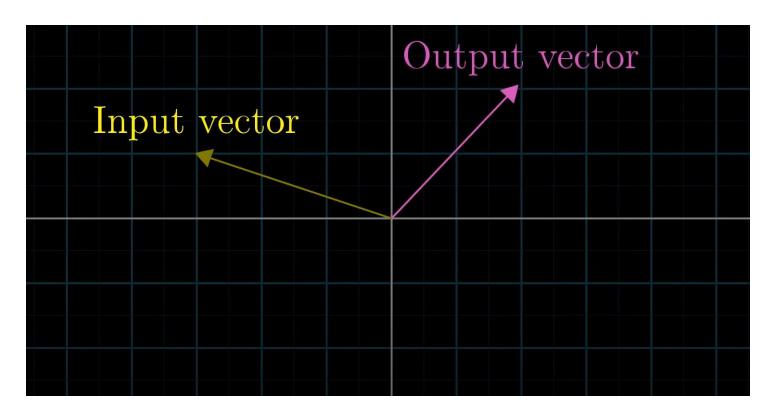
Singular Value Decomposition (SVD)

Introduction to NLP, Spring '22
Tutorial - 3 [Part I]

 Matrix Multiplications are nothing but <u>Linear Transformations</u> (stretching or rotating)

"2x2 Matrix"
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x \begin{bmatrix} a \\ c \end{bmatrix} + y \begin{bmatrix} b \\ d \end{bmatrix} = \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$$
Where all the intuition is

• Transforming a vector (r, Θ) to another vector (r', Θ') requires changing its length and its angle.

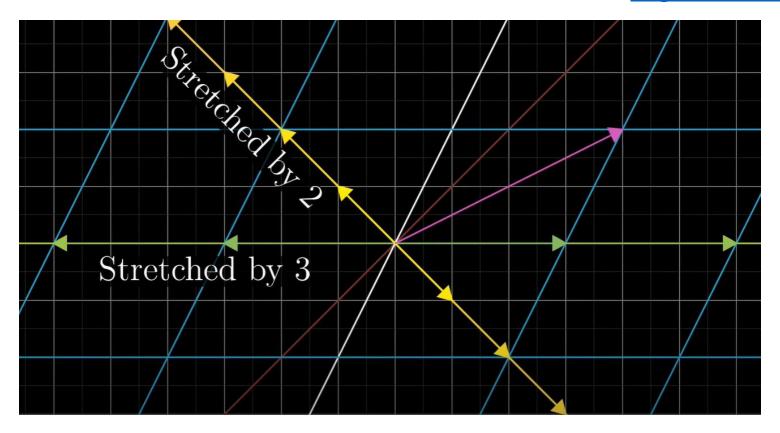


- Consider a matrix X which spans the vector space V
- Let's say we transform the basis vector X with matrix A
- Due to the transformation, all the vectors within the space must also be transformed (change in angle and length).

- Except a few, which just incur a change in length.
- The vectors which only change by a constant on transformation are called eigen vectors.
- And the constant it changes by is called eigen value.

$$Ax = \lambda x$$

• Red represents non-eigen vector before transformation. Pink represents non-eigen vector after rotation. Yellow and Green are <u>eigenvectors</u>.

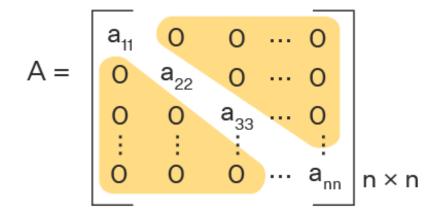


Orthogonal and Semi-Orthogonal Matrix

- Orthogonal matrices are square matrix for which $A^T = A^{-1}$. This entails that $A^T A = A^{-1}A = I$
- <u>Semi-Orthogonal Matrix</u> are non-square matrix which act like orthogonal matrix, and follow the property: $A^TA = I$

Diagonalisation

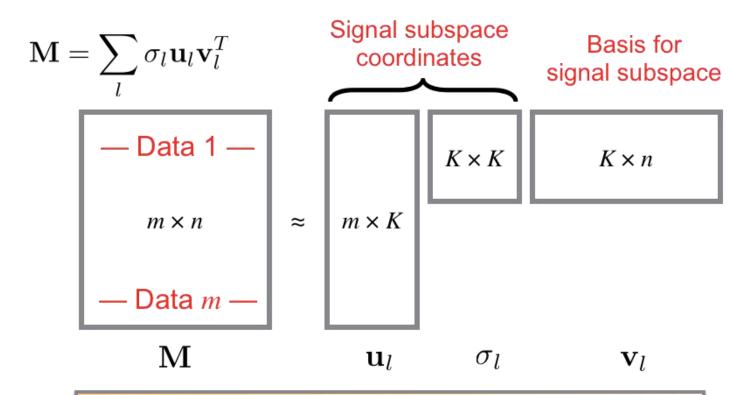
- Diagonal Matrix are square matrix with every element except diagonal ones equal to 0
- Diagonalisation is a transformation of a square matrix to a diagonal matrix



Eigen Decomposition

- $M = P D P^{-1}$
- M is original matrix you want to diagonalise.
- P is an orthogonal matrix composed of eigenvectors of M
- D is a diagonal matrix made up of eigenvalues of M
- There are some cases where M is not diagonalisable (M is not square, or not full rank)

Singular Value Decomposition



Project data to signal subspace : $\{\mathbf{v}_1,\dots,\mathbf{v}_K\}$

Coordinates in the signal subspace : $[\sigma_1 \mathbf{u}_1 \ \cdots \ \sigma_K \mathbf{u}_K]$

Singular Value Decomposition

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M = U \( \text{V}^T \) \( \text{Orthogonal} \)

M^TM = V \( \text{E}^T \( \text{E} \) \( \text{V}^T \) \( \text{Jagonalisation of makin} \)

= V \( \( \text{E}^T \text{E} \) \( \text{V}^T \) \( \text{Jagonalisation of m^Tm} \)

do the same for U by

computing M. M^T
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Doubts