

# Probability and Statistics: Lecture-41

Monsoon-2020

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on November 18, 2020



## Asymptotic Properties of MLEs

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$$\frac{\hat{\Theta}_{ML} - \theta}{\sqrt{\text{Var}(\hat{\Theta}_{ML})}}$$

converges in distribution to  $N(0, 1)$ .





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$$\hat{\theta}_2 = \hat{\theta}_1 + W$$

is also an unbiased estimator for  $\theta$

$$\begin{aligned} E[\hat{\theta}_2] &= E[\hat{\theta}_1] + E[W] \\ &= E[\hat{\theta}_1] \end{aligned}$$

### Example

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2. Let  $\hat{\Theta}_1$  be an estimator for  $\theta$  such that  $E[\hat{\Theta}_1] = a\theta + b$ , where  $a \neq 0$ .

## » Solved Example 1 ...

$$\underline{E[\hat{\theta}_2]}: \quad \frac{E[\hat{\theta}_1] - b}{a} = \frac{a\theta + \cancel{b} - \cancel{b}}{a} = \underline{\underline{\theta}}$$

### Example

Show the following:

1. Let  $\hat{\theta}_1$  be an **unbiased estimator** for  $\theta$ , and  $W$  is a zero mean random variable. Show that

$$\hat{\theta}_2 = \hat{\theta}_1 + W$$

is also an **unbiased estimator** for  $\theta$

2. Let  $\hat{\theta}_1$  be an estimator for  $\theta$  such that  $E[\hat{\theta}_1] = a\theta + b$ , where  $a \neq 0$ . Show that

$$\hat{\theta}_2 = \frac{\hat{\theta}_1 - b}{a}$$

is an **unbiased estimator** for  $\theta$

» Answer to previous problem...



Example

Let  $X_1, X_2, \dots, X_n$  be a random variable from a  $\text{Uniform}(0, \theta)$  distribution, where  $\theta$  is unknown.



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1. Find the bias of  $\hat{\Theta}_n$ ,  $B(\hat{\Theta}_n)$
2. Find the MSE of  $\hat{\Theta}_n$ ,  $\text{MSE}(\hat{\Theta}_n)$

$$B[\hat{\theta}_n] = \underline{E[\hat{\theta}_n]} - \theta.$$

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$$\hat{\theta}_n = \max\{X_1, X_2, \dots, X_n\}$$

1. Find the bias of  $\hat{\theta}_n$ ,  $B(\hat{\theta}_n)$
2. Find the MSE of  $\hat{\theta}_n$ ,  $MSE(\hat{\theta}_n)$
3. Is  $\hat{\theta}_n$  a consistent estimator of  $\theta$ ?

» Answer to previous problem...

$x \sim \text{Uniform}(0, \theta)$ , then PDF  
and CDF

$$f_x(x) = \begin{cases} 1/\theta & 0 \leq x \leq \theta \\ 0 & \text{otherwise} \end{cases}$$

$$F_x(x) = \begin{cases} 0 & x < 0 \\ x/\theta & 0 \leq x \leq \theta \\ 1 & x > \theta \end{cases}$$

Since  $\hat{\theta}_n = X_{(n)}$ , PDF of  $\hat{\theta}_n$

is

$$f_{\hat{\theta}_n}(y) = \frac{n}{\theta^n} f_x(y) [F_x(y)]^{n-1}$$

[Recall order stat.]

$$= \begin{cases} n \cdot \frac{1}{\theta} \cdot \left(\frac{y}{\theta}\right)^{n-1} & 0 \leq y \leq \theta \\ 0 & \text{otherwise} \end{cases}$$

$$= \begin{cases} \frac{n}{\theta^n} y^{n-1} & 0 \leq y \leq \theta \\ 0 & \text{otherwise} \end{cases}$$

To find the Bias of  $\hat{\theta}_n$

$$E[\hat{\theta}_n] = \int_0^\theta y \cdot \frac{n}{\theta^n} y^{n-1} dy$$
$$= \frac{n}{\theta^n} \int_0^\theta y^n dy = \frac{n}{\theta^n} \left[ \frac{y^{n+1}}{n+1} \right]_0^\theta$$
$$= \frac{n}{n+1} \theta$$

» Answer to previous problem...

Thus Bias

$$\begin{aligned} B(\hat{\theta}_n) &= E[\hat{\theta}_n] - \theta \\ &= \frac{n}{n+1}\theta - \theta = -\frac{\theta}{n+1} \end{aligned}$$

$$\textcircled{b} \text{ MSE}[\hat{\theta}_n] = \text{Var}(\hat{\theta}_n) + B(\hat{\theta}_n)^2$$

$$= \text{Var}(\hat{\theta}_n) + \frac{\theta^2}{(n+1)^2}$$

$\uparrow$  need this

$$E(\hat{\theta}_n^2) = \int_0^\theta y^2 \frac{ny^{n+1}}{\theta^n} dy = \frac{n}{n+2}\theta^2$$

$$\begin{aligned} \text{Var}(\hat{\theta}_n) &= E[\hat{\theta}_n^2] - (E[\hat{\theta}_n])^2 \\ &= \frac{n}{(n+2)(n+1)^2}\theta^2 \quad (\text{check}) \end{aligned}$$

$$\begin{aligned} \Rightarrow \text{MSE}[\hat{\theta}_n] &= \frac{n}{(n+2)(n+1)^2}\theta^2 + \frac{\theta^2}{(n+1)^2} \\ &= \frac{2\theta^2}{(n+2)(n+1)} \end{aligned}$$

$$\begin{aligned} \textcircled{c} \quad & \lim_{n \rightarrow \infty} \text{MSE}(\hat{\theta}_n) \\ &= \lim_{n \rightarrow \infty} \frac{2\theta^2}{(n+2)(n+1)} = 0 \end{aligned}$$

$\Rightarrow \hat{\theta}_n$  is a consistent estimator of  $\theta$ .





Example

Let  $X_1, X_2, X_3, \dots, X_n$  be a random sample from a Geometric( $\theta$ ) distribution, where  $\theta$  is unknown.

$$L(x_1, x_2, \dots, x_n; \theta) = \frac{P(x_1, x_2, \dots, x_n; \theta)}{P(x_1)P(x_2) \dots P(x_n)}$$

### Example

Let  $X_1, X_2, X_3, \dots, X_n$  be a random sample from a Geometric( $\theta$ ) distribution, where  $\theta$  is unknown. Find the maximum likelihood estimator (MLE) of  $\theta$  based on this random sample.

Solution:  $X_i \sim \text{Geometric}(\theta)$ , then

$$P_{X_i}(x_i; \theta) = \frac{(1-\theta)^{x_i-1} \theta}{1}$$

Likelihood  $f_n$

$$L(x_1, x_2, \dots, x_n; \theta) = P_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n; \theta)$$

$$= P_{X_1}(x_1; \theta) \cdot P_{X_2}(x_2; \theta) \cdot \dots \cdot P_{X_n}(x_n; \theta)$$

$$= (1-\theta)^{\sum_{i=1}^n x_i - n} \theta^n \quad \leftarrow$$

Better to use log likelihood to maximize

$$\ln L(x_1, x_2, \dots, x_n; \theta)$$

$$= (\sum x_i - n) \ln(1-\theta) + n \ln \theta$$

Maximize:

$$\frac{d}{d\theta} \ln L(x_1, \dots, x_n; \theta)$$

$$= \left( \sum x_i - n \right) \frac{-1}{1-\theta} + \frac{n}{\theta} = 0$$

Solve for  $\theta$

$$\Rightarrow \hat{\theta}_{ML} = \frac{n}{\sum_{i=1}^n x_i}$$



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5. The confidence level is the probability that the interval that we construct includes the real value of  $\theta$
6. The smaller the interval, the higher the precision with which we can estimate  $\theta$ , and higher the confidence level



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- \* Here  $\hat{\theta}_l$  and  $\hat{\theta}_h$  are random variables because they are functions of  $X_1, \dots, X_n$



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$$\underbrace{P(X \leq x_l)} = \frac{\alpha}{2} \quad \text{and} \quad P(X \geq x_h) = \frac{\alpha}{2}$$

$\underbrace{1 - P(X \leq x_h)} = 1 - \frac{\alpha}{2}$

4. That is, we have from above

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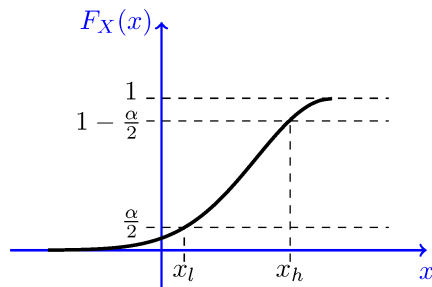
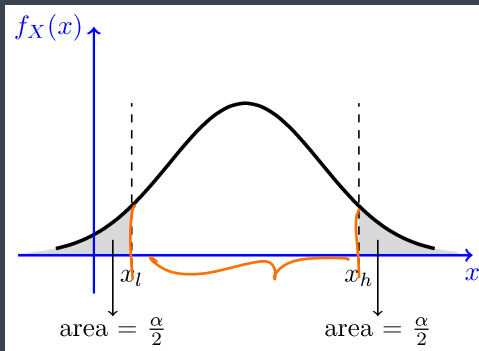
$$F_X(x_l) = \frac{\alpha}{2} \quad \text{and} \quad F_X(x_h) = 1 - \frac{\alpha}{2}$$

5. Rewriting these equations by using inverse, we have

$$x_l = F_X^{-1}\left(\frac{\alpha}{2}\right) \quad \text{and} \quad x_h = F_X^{-1}\left(1 - \frac{\alpha}{2}\right)$$



## » Plot of confidence Interval...



\*  $[x_l, x_h]$  is a  $(1 - \alpha)$  interval for  $X$ , that is,  $P(x_l \leq X \leq x_h) = 1 - \alpha$





## » Example of Interval Estimation...

### Example

Let  $Z \sim N(0, 1)$ , find  $x_l$  and  $x_h$  such that

$$P(x_l \leq Z \leq x_h) = 0.95 = 1 - \alpha$$

$$\Rightarrow \alpha = 0.05$$

$$\text{CDF of } Z = \Phi$$

$$\textcircled{x_l} = \Phi^{-1}\left(\frac{\alpha}{2}\right) = \Phi^{-1}(0.025) = \underline{\underline{-1.96}}$$

$$\textcircled{x_h} = \Phi^{-1}\left(1 - \frac{\alpha}{2}\right) = \Phi^{-1}(1 - 0.025) = \underline{\underline{0.95}}$$

» Answer to previous problem...

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#### Frequentist Approach

In that approach, the unknown quantity  $\theta$  is assumed to be a fixed (non-random) quantity that is to be estimated by the observed data.

#### Bayesian Approach

In the Bayesian framework, we treat the unknown quantity,  $\Theta$ , as a random variable. More specifically, we assume that we have some initial guess about the distribution of  $\Theta$ . This distribution is called the prior distribution. After observing some data, we update the distribution of  $\Theta$  (based on the observed data).



## » Motivating Example...

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Suppose that you would like to estimate the portion of voters in your town that plan to vote for Party A in an upcoming election. To do so, you take a random sample of size  $n$  from the likely voters in the town. Since you have a limited amount of time and resources, your sample is relatively small. Specifically, suppose that  $n = 20$ . After doing your sampling, you find out that 6 people in your sample say they will vote for Party A.

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- \* More specifically, here your data is a random sample of size  $n=20$  voters, 6 of whom are voting for Party A.
- \* you can then proceed to find an updated distribution for  $\Theta$ , called the posterior distribution, using Bayes' rule:

$$f_{\Theta|D}(\theta|D) = \frac{P(D|\theta) f_{\Theta}(\theta)}{P(D)} \quad (1)$$

*Handwritten notes: An arrow points from the word "prior" to  $f_{\Theta}(\theta)$ . The term  $f_{\Theta|D}(\theta|D)$  is circled in orange.*

- \* We can now use the posterior density,  $f_{\Theta|D}(\theta|D)$  to further draw inferences about  $\Theta$

» Answer to previous problem...



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5. Note that in the above setting,  $X$  or  $Y$  (or possibly both) could be random vectors



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4. Here  $f_{X|Y}(x|y)$  is called posterior distribution



Example

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» Solved Example...

$$(1) \text{ Bayes's rule } f_{X|Y}(x|2) = \frac{P_{Y|X}(2|x) f_X(x)}{P_Y(2)}$$

Since  $Y|x \sim \text{Geometric}(x)$

$$P_{Y|X}(y|x) = x(1-x)^{y-1} \quad \text{for } y=1, 2, \dots \Rightarrow P_{Y|X}(2|x) = x(1-x)$$

Example

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Find the posterior density of  $X$  given  $Y = 2$ ,  $f_{X|Y}(x|2)$

$$f_Y(2) = \int_{-\infty}^{\infty} P_{Y|X}(2|x) \underline{f_X(x)} dx = \int_0^1 x(1-x) \cdot 1 dx = \frac{1}{6}$$

$$\Rightarrow f_{X|Y}(x|2) = \frac{x(1-x) \cdot 1}{1/6} = 6x(1-x) \quad \underline{0 \leq x \leq 1}$$



» Answer to previous problem...

## » Maximum Apriori Estimation (MAP)...

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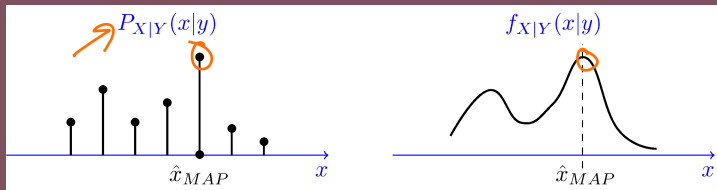
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Here  $\hat{x}_{MAP}$  is the value of  $X$  for which the posterior  $f_{X|Y}(x|y)$  is maximized





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$$\underline{f_{Y|X}(y|x)f_X(x)}.$$

(forget  $f_Y(y)$  in denominator)

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## » Example of MAP Estimate...

$$P_{Y|X}(y|x) = x(1-x)^{y-1} \quad y = 1, 2, \dots$$

$\Rightarrow P_{Y|X}(3|x) = \underline{x(1-x)^2}$ . Need to find value  $x \in [0, 1]$  that maximizes  $\underline{P_{Y|X}(y|x)} \underline{f_X(x)}$

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$$Y|X = x \sim \text{Geometric}(x).$$

Find the MAP estimate of  $X$  given  $Y = 3$ .

$$= x(1-x)^2 \cdot 2x = 2x^2(1-x)^2$$

Maximizing:  $\frac{d}{dx} (x^2(1-x)^2) = 2x(1-x)^2 - 2(1-x)x^2 = 0$  (check)

$$\Rightarrow \hat{x}_{\text{MAP}} = \frac{1}{2}$$

» Answer to previous problem...



## » Comparison of MAP to ML Estimator...

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4. If  $X$  is uniformly distributed over a finite interval, then ML and MAP estimate is same

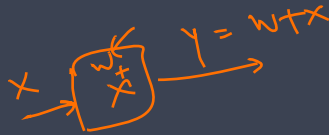


### Example

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## » Solved Example...



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» Solved Example...

Sol<sup>n</sup> :  $f_X(x) = \frac{1}{\sqrt{2\pi} \sigma_x} e^{-\frac{x^2}{2\sigma_x^2}}$

$Y|X=x \sim N(x, \sigma_w^2)$  (check)  $\Rightarrow f_{Y|X}(y|x) = \frac{1}{\sqrt{2\pi} \sigma_w} e^{-\frac{(y-x)^2}{2\sigma_w^2}}$

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Maximize :  $\min (y-x)^2 \Rightarrow \hat{x}_{ML} = y$

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Maximize  $\Rightarrow$  minimize  $-\frac{(y-x)^2}{2\sigma_w^2} + \frac{x^2}{2\sigma_x^2}$

$\Rightarrow \hat{x}_{MAP} = \frac{\sigma_x^2 y}{\sigma_x^2 + \sigma_w^2}$

## » Minimum Mean Squared Error (MMSE) Estimation...

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## » Example of MMSE Computation...

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*Exercise*

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» Answer to previous problem...

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