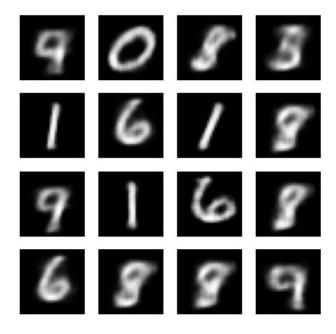
```
from IPython import display
import alob
import imageio
import matplotlib.pyplot as plt
import numpy as np
import PIL
import tensorflow as tf
import tensorflow probability as tfp
import time
(train_images, _), (test_images, _) =
tf.keras.datasets.mnist.load data()
Downloading data from https://storage.googleapis.com/tensorflow/tf-
keras-datasets/mnist.npz
                               ----- Os Ous/step
11490434/11490434 -
def preprocess images(images):
  images = images.reshape((images.shape[0], 28, 28, 1)) / 255.
  return np.where(images > .5, 1.0, 0.0).astype('float32')
train images = preprocess images(train images)
test images = preprocess images(test images)
train size = 60000
batch size = 32
test size = 10000
train_dataset = (tf.data.Dataset.from_tensor_slices(train_images)
                 .shuffle(train size).batch(batch size))
test dataset = (tf.data.Dataset.from tensor slices(test images)
                .shuffle(test size).batch(batch size))
```

##A. 1. Basic Vanilla VAE model implementation

```
tf.keras.layers.Conv2D(
                filters=64, kernel size=3, strides=(2, 2),
activation='relu'),
            tf.keras.layers.Flatten(),
            # No activation
            tf.keras.layers.Dense(latent_dim + latent_dim),
        ]
    )
    self.decoder = tf.keras.Sequential(
            tf.keras.layers.InputLayer(input shape=(latent dim,)),
            tf.keras.layers.Dense(units=7*7*32,
activation=tf.nn.relu),
            tf.keras.layers.Reshape(target shape=(7, 7, 32)),
            tf.keras.layers.Conv2DTranspose(
                filters=64, kernel size=3, strides=2, padding='same',
                activation='relu'),
            tf.keras.layers.Conv2DTranspose(
                filters=32, kernel size=3, strides=2, padding='same',
                activation='relu'),
            # No activation
            tf.keras.layers.Conv2DTranspose(
                filters=1, kernel_size=3, strides=1, padding='same'),
        ]
    )
 @tf.function
  def sample(self, eps=None):
    if eps is None:
      eps = tf.random.normal(shape=(100, self.latent dim))
    return self.decode(eps, apply_sigmoid=True)
  def encode(self, x):
    mean, logvar = tf.split(self.encoder(x), num or size splits=2,
axis=1)
    return mean, logvar
  def reparameterize(self, mean, logvar):
    eps = tf.random.normal(shape=mean.shape)
    return eps * tf.exp(logvar * .5) + mean
  def decode(self, z, apply_sigmoid=False):
    logits = self.decoder(z)
    if apply sigmoid:
      probs = tf.sigmoid(logits)
      return probs
    return logits
```

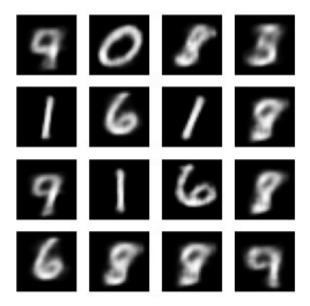
```
optimizer = tf.keras.optimizers.Adam(1e-4)
def log_normal_pdf(sample, mean, logvar, raxis=1):
  log2pi = tf.math.log(2. * np.pi)
  return tf.reduce sum(
      -.5 * ((sample - mean) ** 2. * tf.exp(-logvar) + logvar +
log2pi),
      axis=raxis)
def compute loss(model, x):
 mean, logvar = model.encode(x)
  z = model.reparameterize(mean, logvar)
  x logit = model.decode(z)
  cross ent = tf.nn.sigmoid cross entropy with logits(logits=x logit,
labels=x)
  logpx_z = -tf.reduce_sum(cross_ent, axis=[1, 2, 3])
  logpz = log normal pdf(z, 0., 0.)
  logqz x = log normal pdf(z, mean, logvar)
  return -tf.reduce mean(logpx z + logpz - logqz x)
@tf.function
def train step(model, x, optimizer):
  """Executes one training step and returns the loss.
 This function computes the loss and gradients, and uses the latter
to
  update the model's parameters.
 with tf.GradientTape() as tape:
    loss = compute loss(model, x)
  gradients = tape.gradient(loss, model.trainable variables)
  optimizer.apply gradients(zip(gradients, model.trainable variables))
epochs = 10
# set the dimensionality of the latent space to a plane for
visualization later
latent dim = 2
num examples_to_generate = 16
# keeping the random vector constant for generation (prediction) so
# it will be easier to see the improvement.
random vector for generation = tf.random.normal(
    shape=[num_examples_to_generate, latent_dim])
model = CVAE(latent dim)
/usr/local/lib/python3.10/dist-packages/keras/src/layers/core/
input layer.py:26: UserWarning: Argument `input shape` is deprecated.
```

```
Use `shape` instead.
 warnings.warn(
def generate and save images(model, epoch, test sample):
 mean, logvar = model.encode(test sample)
  z = model.reparameterize(mean, logvar)
  predictions = model.sample(z)
  fig = plt.figure(figsize=(4, 4))
  for i in range(predictions.shape[0]):
    plt.subplot(4, 4, i + 1)
    plt.imshow(predictions[i, :, :, 0], cmap='gray')
    plt.axis('off')
 # tight layout minimizes the overlap between 2 sub-plots
  plt.savefig('image at epoch {:04d}.png'.format(epoch))
  plt.show()
# Pick a sample of the test set for generating output images
assert batch size >= num examples to generate
for test batch in test dataset.take(1):
  test sample = test batch[0:num examples to generate, :, :, :]
generate and save images(model, 0, test sample)
for epoch in range(1, epochs + 1):
  start time = time.time()
  for train x in train dataset:
    train step(model, train x, optimizer)
  end time = time.time()
  loss = tf.keras.metrics.Mean()
  for test x in test dataset:
    loss(compute loss(model, test_x))
  elbo = -loss.result()
  display.clear output(wait=False)
  print('Epoch: {}, Test set ELBO: {}, time elapse for current epoch:
        .format(epoch, elbo, end time - start time))
  generate and save images(model, epoch, test sample)
Epoch: 10, Test set ELBO: -157.56301879882812, time elapse for current
epoch: 8.055445194244385
```



```
def display_image(epoch_no):
    return PIL.Image.open('image_at_epoch_{:04d}.png'.format(epoch_no))
plt.imshow(display_image(epoch))
plt.axis('off') # Display images

(-0.5, 399.5, 399.5, -0.5)
```



```
anim file = 'cvae1.gif'
with imageio.get writer(anim file, mode='I') as writer:
  filenames = glob.glob('image*.png')
  filenames = sorted(filenames)
  for filename in filenames:
    image = imageio.imread(filename)
    writer.append data(image)
  image = imageio.imread(filename)
 writer.append data(image)
<ipython-input-14-2c902c6cafcb>:7: DeprecationWarning: Starting with
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
`imageio.v2.imread` directly.
  image = imageio.imread(filename)
<ipython-input-14-2c902c6cafcb>:9: DeprecationWarning: Starting with
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
`imageio.v2.imread` directly.
  image = imageio.imread(filename)
!pip install git+https://github.com/tensorflow/docs
Collecting git+https://github.com/tensorflow/docs
  Cloning https://github.com/tensorflow/docs to /tmp/pip-req-build-
v0bm55hn
  Running command git clone --filter=blob:none --guiet
https://github.com/tensorflow/docs/tmp/pip-reg-build-v0bm55hn
  Resolved https://github.com/tensorflow/docs to commit
460419a6369bd00bfc3ce7a7c92b0ca2a832c91b
  Preparing metadata (setup.py) ... tensorflow-docs==2024.7.15.51478)
  Downloading astor-0.8.1-py2.py3-none-any.whl.metadata (4.2 kB)
Requirement already satisfied: absl-py in
/usr/local/lib/python3.10/dist-packages (from tensorflow-
docs==2024.7.15.51478) (1.4.0)
Requirement already satisfied: jinja2 in
/usr/local/lib/python3.10/dist-packages (from tensorflow-
docs=2024.7.15.51478) (3.1.4)
Requirement already satisfied: nbformat in
/usr/local/lib/python3.10/dist-packages (from tensorflow-
docs==2024.7.15.51478) (5.10.4)
Requirement already satisfied: protobuf>=3.12 in
/usr/local/lib/python3.10/dist-packages (from tensorflow-
docs==2024.7.15.51478) (3.20.3)
Requirement already satisfied: pyyaml in
/usr/local/lib/python3.10/dist-packages (from tensorflow-
docs=2024.7.15.51478) (6.0.1)
```

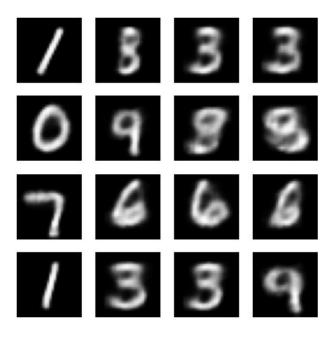
```
Requirement already satisfied: MarkupSafe>=2.0 in
/usr/local/lib/python3.10/dist-packages (from jinja2->tensorflow-
docs==2024.7.15.51478) (2.1.5)
Requirement already satisfied: fastjsonschema>=2.15 in
/usr/local/lib/python3.10/dist-packages (from nbformat->tensorflow-
docs==2024.7.15.51478) (2.20.0)
Requirement already satisfied: jsonschema>=2.6 in
/usr/local/lib/python3.10/dist-packages (from nbformat->tensorflow-
docs==2024.7.15.51478) (4.23.0)
Requirement already satisfied: jupyter-core!=5.0.*,>=4.12 in
/usr/local/lib/python3.10/dist-packages (from nbformat->tensorflow-
docs==2024.7.15.51478) (5.7.2)
Requirement already satisfied: traitlets>=5.1 in
/usr/local/lib/python3.10/dist-packages (from nbformat->tensorflow-
docs==2024.7.15.51478) (5.7.1)
Requirement already satisfied: attrs>=22.2.0 in
/usr/local/lib/python3.10/dist-packages (from jsonschema>=2.6-
>nbformat->tensorflow-docs==2024.7.15.51478) (24.1.0)
Requirement already satisfied: jsonschema-specifications>=2023.03.6 in
/usr/local/lib/python3.10/dist-packages (from jsonschema>=2.6-
>nbformat->tensorflow-docs==2024.7.15.51478) (2023.12.1)
Requirement already satisfied: referencing>=0.28.4 in
/usr/local/lib/python3.10/dist-packages (from jsonschema>=2.6-
>nbformat->tensorflow-docs==2024.7.15.51478) (0.35.1)
Requirement already satisfied: rpds-py>=0.7.1 in
/usr/local/lib/python3.10/dist-packages (from jsonschema>=2.6-
>nbformat->tensorflow-docs==2024.7.15.51478) (0.19.1)
Requirement already satisfied: platformdirs>=2.5 in
/usr/local/lib/python3.10/dist-packages (from jupyter-core!
=5.0.*,>=4.12->nbformat->tensorflow-docs==2024.7.15.51478) (4.2.2)
Downloading astor-0.8.1-py2.py3-none-any.whl (27 kB)
Building wheels for collected packages: tensorflow-docs
  Building wheel for tensorflow-docs (setup.py) ... e=tensorflow docs-
2024.7.15.51478-py3-none-any.whl size=182586
sha256=1e0bde080d37425fe41930fc303a226a9ad76383f56298bb485f52a7a371db7
d
  Stored in directory:
/tmp/pip-ephem-wheel-cache-axjk72k0/wheels/86/0f/1e/3b62293c8ffd0fd5a4
9508e6871cdb7554abe9c62afd35ec53
Successfully built tensorflow-docs
Installing collected packages: astor, tensorflow-docs
Successfully installed astor-0.8.1 tensorflow-docs-2024.7.15.51478
import tensorflow docs.vis.embed as embed
embed.embed file(anim file)
<IPython.core.display.HTML object>
```

```
class CVAE 2(tf.keras.Model):
    """VAE with Encoder-Decoder architecture as Encoder."""
    def init (self, latent dim):
        super(CVAE 2, self). init_()
        self.latent dim = latent dim
        # Encoder-Decoder architecture for the encoder part
        self.encoder decoder = tf.keras.Sequential(
                tf.keras.layers.InputLayer(input shape=(28, 28, 1)),
                # Downsampling
                tf.keras.layers.Conv2D(32, 3, strides=(2, 2),
activation='relu', padding='same'),
                tf.keras.layers.Conv2D(64, 3, strides=(2, 2),
activation='relu', padding='same'),
                tf.keras.layers.Conv2D(128, 3, strides=(2, 2),
activation='relu', padding='same'),
                tf.keras.layers.Flatten(),
                tf.keras.layers.Dense(128, activation='relu'),
                # Bottleneck (latent space representation)
                tf.keras.layers.Dense(7 * 7 * 128, activation='relu'),
                tf.keras.layers.Reshape((7, 7, 128)),
                # Upsampling
                tf.keras.layers.Conv2DTranspose(128, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(64, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(32, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(1, 3, strides=1,
padding='same'),
                tf.keras.layers.Flatten(),
                # No activation for latent space
                tf.keras.layers.Dense(latent dim + latent dim)
            ]
        )
        # Decoder remains the same
        self.decoder = tf.keras.Sequential(
            Γ
                tf.keras.layers.InputLayer(input_shape=(latent_dim,)),
                tf.keras.layers.Dense(units=7*7*32,
activation=tf.nn.relu),
                tf.keras.layers.Reshape(target shape=(7, 7, 32)),
                tf.keras.layers.Conv2DTranspose(
                    filters=64, kernel size=3, strides=2,
padding='same',
                    activation='relu'),
                tf.keras.layers.Conv2DTranspose(
```

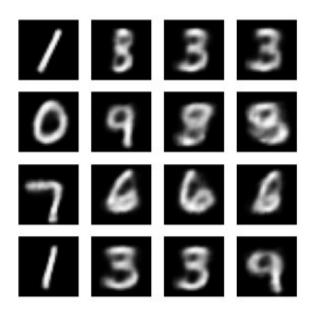
```
filters=32, kernel size=3, strides=2,
padding='same',
                    activation='relu'),
                # No activation
                tf.keras.layers.Conv2DTranspose(
                    filters=1, kernel size=3, strides=1,
padding='same'),
    def call(self, inputs):
        # Encode input to latent space
        encoded = self.encoder decoder(inputs)
        # Split latent space into mean and log-variance
        mean, logvar = tf.split(encoded, num or size splits=2, axis=1)
        return mean, logvar
    @tf.function
    def sample(self, eps=None):
        if eps is None:
            eps = tf.random.normal(shape=(100, self.latent dim))
        return self.decode(eps, apply sigmoid=True)
    def encode(self, x):
        mean, logvar = self.call(x)
        return mean, logvar
    def reparameterize(self, mean, logvar):
        eps = tf.random.normal(shape=tf.shape(mean))
        return eps * tf.exp(logvar * .5) + mean
    def decode(self, z, apply sigmoid=False):
        logits = self.decoder(z)
        if apply sigmoid:
            probs = tf.sigmoid(logits)
            return probs
        return logits
# Instantiate the model
latent dim = 2
model = CVAE 2(latent dim)
optimizer = tf.keras.optimizers.Adam(1e-4)
def log_normal_pdf(sample, mean, logvar, raxis=1):
  log2pi = tf.math.log(2. * np.pi)
  return tf.reduce sum(
      -.5 * ((sample - mean) ** 2. * tf.exp(-logvar) + logvar +
log2pi),
```

```
axis=raxis)
def compute loss(model, x):
 mean, logvar = model.encode(x)
  z = model.reparameterize(mean, logvar)
  x logit = model.decode(z)
  cross ent = tf.nn.sigmoid cross entropy with logits(logits=x logit,
labels=x)
  logpx z = -tf.reduce sum(cross ent, axis=[1, 2, 3])
  logpz = log normal pdf(z, 0., 0.)
  logqz x = log normal pdf(z, mean, logvar)
  return -tf.reduce_mean(logpx_z + logpz - logqz_x)
@tf.function
def train step(model, x, optimizer):
  """Executes one training step and returns the loss.
  This function computes the loss and gradients, and uses the latter
to
  update the model's parameters.
 with tf.GradientTape() as tape:
    loss = compute loss(model, x)
  gradients = tape.gradient(loss, model.trainable variables)
  optimizer.apply gradients(zip(gradients, model.trainable variables))
epochs = 10
# set the dimensionality of the latent space to a plane for
visualization later
latent dim = 2
num examples to generate = 16
# keeping the random vector constant for generation (prediction) so
# it will be easier to see the improvement.
random vector for generation = tf.random.normal(
    shape=[num examples to generate, latent dim])
model = CVAE 2(latent dim)
def generate and save images 2(model, epoch, test sample):
 mean, logvar = model.encode(test sample)
  z = model.reparameterize(mean, logvar)
  predictions = model.sample(z)
  fig = plt.figure(figsize=(4, 4))
  for i in range(predictions.shape[0]):
    plt.subplot(4, 4, i + 1)
    plt.imshow(predictions[i, :, :, 0], cmap='gray')
    plt.axis('off')
```

```
# tight layout minimizes the overlap between 2 sub-plots
  plt.savefig('image 2 at epoch {:04d}.png'.format(epoch))
  plt.show()
# Pick a sample of the test set for generating output images
assert batch size >= num examples to generate
for test batch in test dataset.take(1):
  test sample = test batch[0:num examples to generate, :, :, :]
generate and save images 2(model, 0, test sample)
for epoch in range(1, epochs + 1):
  start time = time.time()
  for train x in train dataset:
    train step(model, train x, optimizer)
  end time = time.time()
  loss = tf.keras.metrics.Mean()
  for test x in test dataset:
    loss(compute loss(model, test x))
  elbo = -loss.result()
  display.clear output(wait=False)
  print('Epoch: {}, Test set ELBO: {}, time elapse for current epoch:
{}'
        .format(epoch, elbo, end time - start time))
  generate and save images 2(model, epoch, test sample)
Epoch: 10, Test set ELBO: -145.325927734375, time elapse for current
epoch: 17.4734308719635
```



```
def display_image_2(epoch_no):
    return
PIL.Image.open('image_2_at_epoch_{:04d}.png'.format(epoch_no))
plt.imshow(display_image_2(epoch))
plt.axis('off') # Display images
(-0.5, 399.5, 399.5, -0.5)
```



```
anim file = 'cvae2.gif'
with imageio.get writer(anim file, mode='I') as writer:
  filenames = glob.glob('image 2*.png')
  filenames = sorted(filenames)
  for filename in filenames:
    image = imageio.imread(filename)
    writer.append data(image)
  image = imageio.imread(filename)
 writer.append data(image)
<ipython-input-25-f2399fed895a>:7: DeprecationWarning: Starting with
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
`imageio.v2.imread` directly.
  image = imageio.imread(filename)
<ipython-input-25-f2399fed895a>:9: DeprecationWarning: Starting with
```

```
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
`imageio.v2.imread` directly.
image = imageio.imread(filename)
```

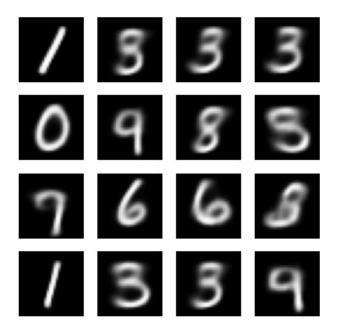
##3. Changing the Decoder to an Encoder-Decoder Architecture

```
class CVAE 3(tf.keras.Model):
    """VAE with vanilla encoder and Encoder-Decoder architecture as
Decoder,"""
    def __init__(self, latent_dim):
        super(CVAE 3, self). init ()
        self.latent dim = latent dim
        # Vanilla encoder
        self.encoder = tf.keras.Sequential(
                tf.keras.layers.InputLayer(input shape=(28, 28, 1)),
                tf.keras.layers.Conv2D(32, 3, strides=(2, 2),
activation='relu'),
                tf.keras.layers.Conv2D(64, 3, strides=(2, 2),
activation='relu'),
                tf.keras.layers.Flatten(),
                tf.keras.layers.Dense(128, activation='relu'),
                # No activation for latent space
                tf.keras.layers.Dense(latent dim + latent dim)
            ]
        )
        # Encoder-Decoder architecture for the decoder part
        self.decoder encoder = tf.keras.Sequential(
            tf.keras.layers.InputLayer(input shape=(latent dim,)),
                tf.keras.layers.Dense(units=7 * 7 * 32,
activation='relu'),
                tf.keras.layers.Reshape(target shape=(7, 7, 32)),
                # Downsampling
                tf.keras.layers.Conv2D(64, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2D(128, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Flatten(),
                tf.keras.layers.Dense(128, activation='relu'),
                # Bottleneck (latent space representation)
                tf.keras.layers.Dense(7 * 7 * 128, activation='relu'),
                tf.keras.layers.Reshape((7, 7, 128)),
                # Upsampling
```

```
tf.keras.layers.Conv2DTranspose(128, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(64, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(32, 3, strides=1,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(1, 3, strides=1,
padding='same')
    def call(self, inputs):
        # Encode input to latent space
        encoded = self.encoder(inputs)
        # Split latent space into mean and log-variance
        mean, logvar = tf.split(encoded, num or size splits=2, axis=1)
        return mean, logvar
    @tf.function
    def sample(self, eps=None):
        if eps is None:
            eps = tf.random.normal(shape=(100, self.latent dim))
        return self.decode(eps, apply sigmoid=True)
    def encode(self, x):
        mean, logvar = self.call(x)
        return mean, logvar
    def reparameterize(self, mean, logvar):
        eps = tf.random.normal(shape=tf.shape(mean))
        return eps * tf.exp(logvar * .5) + mean
    def decode(self, z, apply sigmoid=False):
        logits = self.decoder encoder(z)
        if apply sigmoid:
            probs = tf.sigmoid(logits)
            return probs
        return logits
# Instantiate the model
latent dim = 2
model = CVAE 3(latent dim)
optimizer = tf.keras.optimizers.Adam(1e-4)
def log_normal_pdf(sample, mean, logvar, raxis=1):
  log2pi = tf.math.log(2. * np.pi)
  return tf.reduce sum(
      -.5 * ((sample - mean) ** 2. * tf.exp(-logvar) + logvar +
```

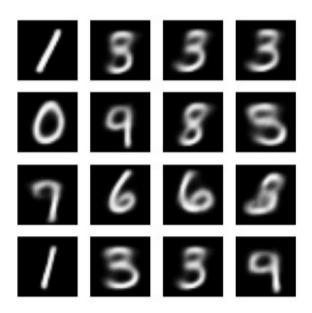
```
log2pi),
      axis=raxis)
def compute loss(model, x):
 mean, logvar = model.encode(x)
  z = model.reparameterize(mean, logvar)
  x logit = model.decode(z)
  cross ent = tf.nn.sigmoid cross entropy with logits(logits=x logit,
labels=x)
  logpx z = -tf.reduce sum(cross ent, axis=[1, 2, 3])
  logpz = log normal pdf(z, 0., 0.)
  logqz x = log normal pdf(z, mean, logvar)
  return -tf.reduce mean(logpx z + logpz - logqz x)
@tf.function
def train_step(model, x, optimizer):
  """Executes one training step and returns the loss.
  This function computes the loss and gradients, and uses the latter
  update the model's parameters.
 with tf.GradientTape() as tape:
    loss = compute loss(model, x)
  gradients = tape.gradient(loss, model.trainable variables)
  optimizer.apply_gradients(zip(gradients, model.trainable_variables))
epochs = 10
# set the dimensionality of the latent space to a plane for
visualization later
latent dim = 2
num examples to generate = 16
# keeping the random vector constant for generation (prediction) so
# it will be easier to see the improvement.
random vector for generation = tf.random.normal(
    shape=[num_examples_to_generate, latent_dim])
model = CVAE 3(latent dim)
def generate and save images 3(model, epoch, test sample):
 mean, logvar = model.encode(test sample)
  z = model.reparameterize(mean, logvar)
  predictions = model.sample(z)
  fig = plt.figure(figsize=(4, 4))
  for i in range(predictions.shape[0]):
    plt.subplot(4, 4, i + 1)
    plt.imshow(predictions[i, :, :, 0], cmap='gray')
```

```
plt.axis('off')
 # tight layout minimizes the overlap between 2 sub-plots
  plt.savefig('image 3 at epoch {:04d}.png'.format(epoch))
  plt.show()
generate and save images 3(model, 0, test sample)
for epoch in range(1, epochs + 1):
  start time = time.time()
  for train x in train dataset:
    train_step(model, train_x, optimizer)
  end time = time.time()
 loss = tf.keras.metrics.Mean()
 for test x in test dataset:
    loss(compute loss(model, test x))
  elbo = -loss.result()
  display.clear output(wait=False)
  print('Epoch: {}, Test set ELBO: {}, time elapse for current epoch:
        .format(epoch, elbo, end_time - start_time))
  generate and save images 3(model, epoch, test sample)
Epoch: 10, Test set ELBO: -142.83706665039062, time elapse for current
epoch: 13.64205527305603
```



```
def display_image_3(epoch_no):
    return
PIL.Image.open('image_3_at_epoch_{:04d}.png'.format(epoch_no))
```

```
plt.imshow(display_image_3(epoch))
plt.axis('off') # Display images
(-0.5, 399.5, 399.5, -0.5)
```



```
anim_file = 'cvae3.gif'
with imageio.get writer(anim file, mode='I') as writer:
  filenames = glob.glob('image 3*.png')
  filenames = sorted(filenames)
  for filename in filenames:
    image = imageio.imread(filename)
    writer.append_data(image)
  image = imageio.imread(filename)
 writer.append data(image)
<ipython-input-43-c53a5a2e94f7>:7: DeprecationWarning: Starting with
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
`imageio.v2.imread` directly.
  image = imageio.imread(filename)
<ipython-input-43-c53a5a2e94f7>:9: DeprecationWarning: Starting with
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
```

```
`imageio.v2.imread` directly.
  image = imageio.imread(filename)
```

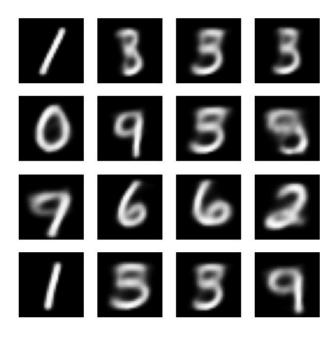
##4. Changing both the Encoder and Decoder to an Encoder-Decoder Architecture

```
class CVAE 4(tf.keras.Model):
    """VAE with Encoder-Decoder architectures for both Encoder and
Decoder."""
    def init (self, latent dim):
        super(CVAE 4, self). init ()
        self.latent dim = latent dim
        # Encoder-Decoder architecture for the encoder part
        self.encoder decoder = tf.keras.Sequential(
                tf.keras.layers.InputLayer(input shape=(28, 28, 1)),
                # Downsampling
                tf.keras.layers.Conv2D(32, 3, strides=(2, 2),
activation='relu', padding='same'),
                tf.keras.layers.Conv2D(64, 3, strides=(2, 2),
activation='relu', padding='same'),
                tf.keras.layers.Conv2D(128, 3, strides=(2, 2),
activation='relu', padding='same'),
                tf.keras.layers.Flatten(),
                tf.keras.layers.Dense(128, activation='relu'),
                # Bottleneck (latent space representation)
                tf.keras.layers.Dense(7 * 7 * 128, activation='relu'),
                tf.keras.layers.Reshape((7, 7, 128)),
                # Upsampling
                tf.keras.layers.Conv2DTranspose(128, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(64, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(32, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(1, 3, strides=1,
padding='same'),
                tf.keras.layers.Flatten(),
                # No activation for latent space
                tf.keras.layers.Dense(latent dim + latent dim)
            ]
        )
        # Encoder-Decoder architecture for the decoder part
        self.decoder encoder = tf.keras.Sequential(
                tf.keras.layers.InputLayer(input shape=(latent dim,)),
                tf.keras.layers.Dense(units=7 * 7 * 32,
```

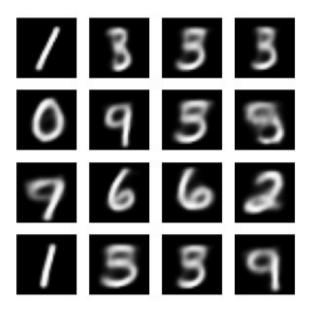
```
activation='relu'),
                tf.keras.layers.Reshape(target shape=(7, 7, 32)),
                # Downsampling
                tf.keras.layers.Conv2D(64, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2D(128, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Flatten(),
                tf.keras.layers.Dense(128, activation='relu'),
                # Bottleneck (latent space representation)
                tf.keras.layers.Dense(7 * 7 * 128, activation='relu'),
                tf.keras.layers.Reshape((7, 7, 128)),
                # Upsampling
                tf.keras.layers.Conv2DTranspose(128, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(64, 3, strides=2,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(32, 3, strides=1,
activation='relu', padding='same'),
                tf.keras.layers.Conv2DTranspose(1, 3, strides=1,
padding='same')
        )
    def call(self, inputs):
        # Encode input to latent space
        encoded = self.encoder decoder(inputs)
        # Split latent space into mean and log-variance
        mean, logvar = tf.split(encoded, num or size splits=2, axis=1)
        return mean, logvar
    @tf.function
    def sample(self, eps=None):
        if eps is None:
            eps = tf.random.normal(shape=(100, self.latent dim))
        return self.decode(eps, apply sigmoid=True)
    def encode(self, x):
        mean, logvar = self.call(x)
        return mean, logvar
    def reparameterize(self, mean, logvar):
        eps = tf.random.normal(shape=tf.shape(mean))
        return eps * tf.exp(logvar * .5) + mean
    def decode(self, z, apply sigmoid=False):
        logits = self.decoder encoder(z)
        if apply sigmoid:
            probs = tf.sigmoid(logits)
            return probs
```

```
return logits
# Instantiate the model
latent dim = 2
model = CVAE 4(latent_dim)
epochs = 10
# set the dimensionality of the latent space to a plane for
visualization later
latent dim = 2
num examples to generate = 16
# keeping the random vector constant for generation (prediction) so
# it will be easier to see the improvement.
random vector for generation = tf.random.normal(
    shape=[num examples to generate, latent dim])
model = CVAE 4(latent dim)
def generate_and_save_images_4(model, epoch, test_sample):
 mean, logvar = model.encode(test sample)
  z = model.reparameterize(mean, logvar)
  predictions = model.sample(z)
  fig = plt.figure(figsize=(4, 4))
  for i in range(predictions.shape[0]):
    plt.subplot(4, 4, i + 1)
    plt.imshow(predictions[i, :, :, 0], cmap='gray')
    plt.axis('off')
 # tight layout minimizes the overlap between 2 sub-plots
  plt.savefig('image 4 at epoch {:04d}.png'.format(epoch))
  plt.show()
optimizer = tf.keras.optimizers.Adam(1e-4)
def log normal pdf(sample, mean, logvar, raxis=1):
  log2pi = tf.math.log(2. * np.pi)
  return tf.reduce sum(
      -.5 * ((sample - mean) ** 2. * tf.exp(-logvar) + logvar +
log2pi),
      axis=raxis)
def compute loss(model, x):
 mean, logvar = model.encode(x)
  z = model.reparameterize(mean, logvar)
  x logit = model.decode(z)
  cross ent = tf.nn.sigmoid cross entropy with logits(logits=x logit,
labels=x)
  logpx z = -tf.reduce sum(cross ent, axis=[1, 2, 3])
```

```
logpz = log normal pdf(z, 0., 0.)
  logqz x = log normal pdf(z, mean, logvar)
  return -tf.reduce mean(logpx z + logpz - loggz x)
@tf.function
def train_step(model, x, optimizer):
  """Executes one training step and returns the loss.
  This function computes the loss and gradients, and uses the latter
  update the model's parameters.
 with tf.GradientTape() as tape:
    loss = compute loss(model, x)
  gradients = tape.gradient(loss, model.trainable variables)
  optimizer.apply gradients(zip(gradients, model.trainable variables))
generate and save images 4(model, 0, test sample)
for epoch in range(1, epochs + 1):
  start time = time.time()
  for train x in train dataset:
    train step(model, train x, optimizer)
  end time = time.time()
  loss = tf.keras.metrics.Mean()
  for test x in test dataset:
    loss(compute loss(model, test x))
  elbo = -loss.result()
  display.clear_output(wait=False)
  print('Epoch: {}, Test set ELBO: {}, time elapse for current epoch:
{}'
        .format(epoch, elbo, end time - start time))
  generate_and_save_images_4(model, epoch, test_sample)
Epoch: 10, Test set ELBO: -140.47776794433594, time elapse for current
epoch: 24.610986471176147
```



```
def display_image_4(epoch_no):
    return
PIL.Image.open('image_4_at_epoch_{:04d}.png'.format(epoch_no))
plt.imshow(display_image_4(epoch))
plt.axis('off') # Display images
(-0.5, 399.5, 399.5, -0.5)
```

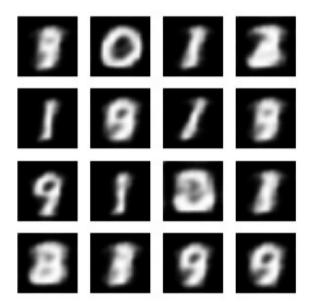


```
anim file = 'cvae4.gif'
with imageio.get writer(anim file, mode='I') as writer:
  filenames = glob.glob('image 4*.png')
  filenames = sorted(filenames)
  for filename in filenames:
    image = imageio.imread(filename)
    writer.append data(image)
  image = imageio.imread(filename)
  writer.append data(image)
<ipython-input-62-b070b0b1f2ee>:7: DeprecationWarning: Starting with
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
`imageio.v2.imread` directly.
  image = imageio.imread(filename)
<ipython-input-62-b070b0b1f2ee>:9: DeprecationWarning: Starting with
ImageIO v3 the behavior of this function will switch to that of
iio.v3.imread. To keep the current behavior (and make this warning
disappear) use `import imageio.v2 as imageio` or call
`imageio.v2.imread` directly.
  image = imageio.imread(filename)
```

##Comparing Results

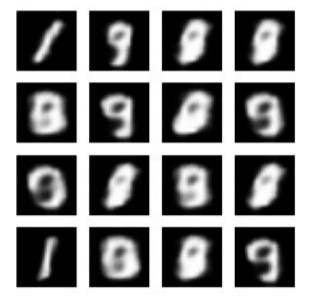
At Epoch 1 -

```
plt.imshow(display_image(1))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```

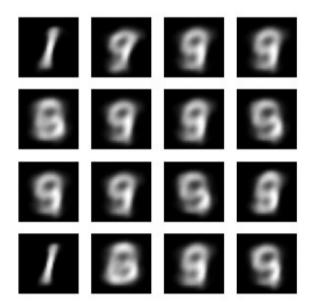


plt.imshow(display_image_2(1))
plt.axis('off')

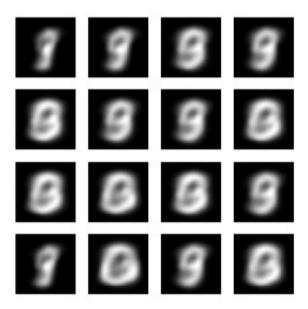
(-0.5, 399.5, 399.5, -0.5)



```
plt.imshow(display_image_3(1))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```

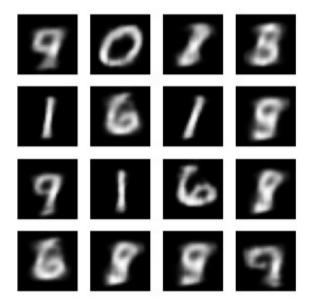


```
plt.imshow(display_image_4(1))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```



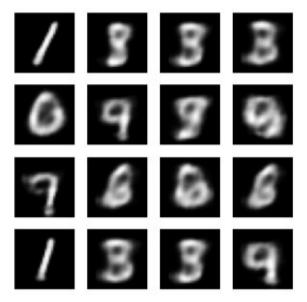
At epoch 5 -

```
plt.imshow(display_image(5))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```

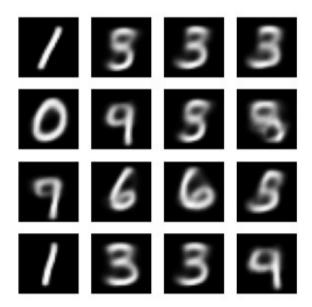


plt.imshow(display_image_2(5))
plt.axis('off')

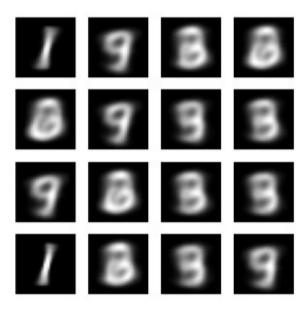
(-0.5, 399.5, 399.5, -0.5)



```
plt.imshow(display_image_3(5))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```

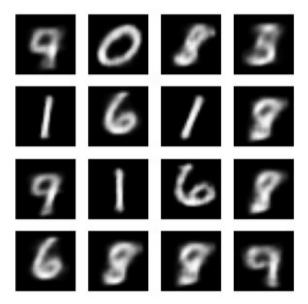


```
plt.imshow(display_image_4(5))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```

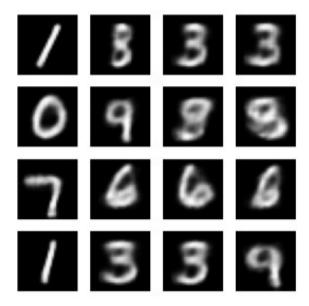


At epoch 10 -

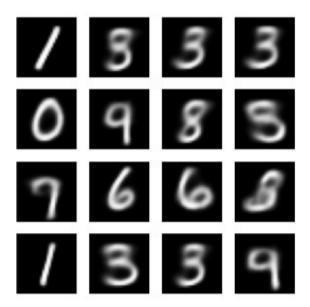
```
plt.imshow(display_image(10))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```



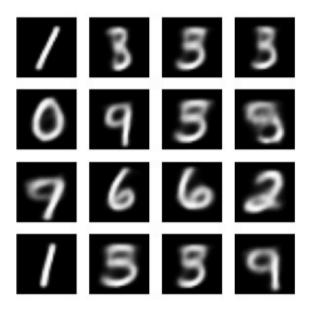
plt.imshow(display_image_2(10))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)



```
plt.imshow(display_image_3(10))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```



```
plt.imshow(display_image_4(10))
plt.axis('off')
(-0.5, 399.5, 399.5, -0.5)
```



Comparing the Gifs -

```
import tensorflow_docs.vis.embed as embed
embed.embed_file('cvael.gif')

<IPython.core.display.HTML object>
embed.embed_file('cvae2.gif')

<IPython.core.display.HTML object>
embed.embed_file('cvae3.gif')

<IPython.core.display.HTML object>
embed.embed_file('cvae4.gif')

<IPython.core.display.HTML object>
```

The best architecture was the fourth one (VAE with Encoder-Decoder on both sides). It turned out to be the best in terms of both accuracy and output image quality. The complex structures on both the encoder and decoder sides enabled better feature extraction and image reconstruction.

The second and third architectures performed better than the original VAE but had trade-offs depending on whether the complexity was in the encoder or decoder.

The original VAE served as a good starting point but was outperformed by the more complex variants.