

CSCI2100C Data Structures

Tutorial 10: *AVL Tree and Traversal*

LI Muzhi

mzli@cse.cuhk.edu.hk

Slides made by Mr. LI Yanwei, TA of CSCI2100B (2020-21 Spring)

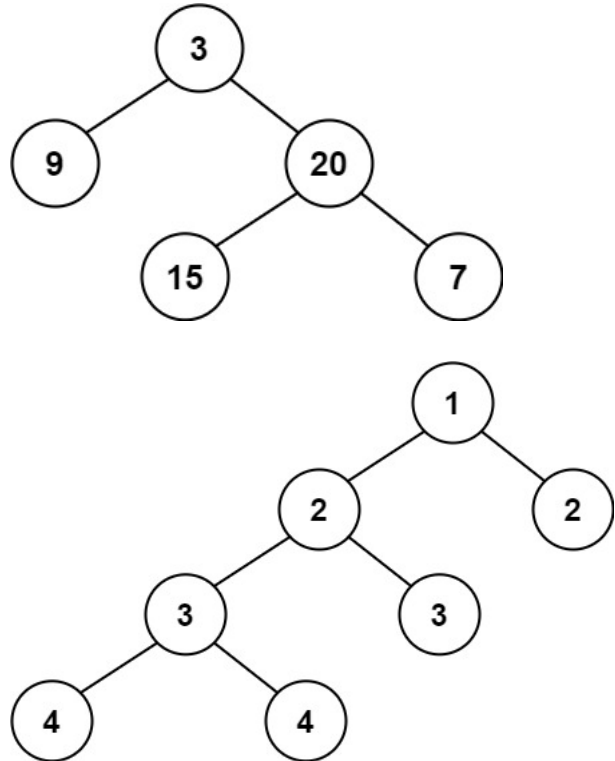


Exercise 1

Balanced Binary Tree

Question: Given a binary tree t , determine if it is height-balanced. For this problem, a height-balanced binary tree is defined as:

a binary tree in which the left and right subtrees of every node differ in height by no more than 1.



Example 1:

Input: $t = [3, 9, 20, \text{null}, \text{null}, 15, 7]$

Output: true

An example to illustrate values in the tree, **NOT** the structure of the tree.

Example 2:

Input: $t = [1, 2, 2, 3, 3, \text{null}, \text{null}, 4, 4]$

Output: false



```
typedef struct BinaryTreeCDT
*BinaryTreeADT;
```

```
typedef struct TreeNodeCDT
*TreeNodeADT;
```

```
BinaryTreeADT NonemptyBinaryTree(TreeNodeADT,
                                   BinaryTreeADT, BinaryTreeADT);
```

```
BinaryTreeADT EmptyBinaryTree(void);
```

```
BinaryTreeADT LeftSubtree(BinaryTreeADT);
```

```
BinaryTreeADT RightSubtree(BinaryTreeADT);
```

```
int TreeIsEmpty(BinaryTreeADT);
```

```
TreeNodeADT Root(BinaryTreeADT);
```

```
char *GetNodeKey(TreeNodeADT);
```

```
bool isBalanced(BinaryTreeADT t) {
```

```
    // Please type your code here
```

```
}
```

Exercise 1

Balanced Binary Tree



Definition: a binary tree in which the left and right subtrees of every node differ in height by **no more than 1**.

Base case:

If tree root is NULL, it is viewed as a binary tree.

Condition: `t = [null]`

Result: `true`

Common case:

*According to the definition, if the difference between the depth of left-subtree and right-subtree should **no more than 1**.*

Condition: `|maxDepth(t->lst) - maxDepth(t->rst)| <= 1`

Result: `true`

```
typedef struct BinaryTreeCDT
*BinaryTreeADT;
```

```
typedef struct TreeNodeCDT
*TreeNodeADT;
```

```
BinaryTreeADT NonemptyBinaryTree(TreeNodeADT,
                                   BinaryTreeADT, BinaryTreeADT);
BinaryTreeADT EmptyBinaryTree(void);
BinaryTreeADT LeftSubtree(BinaryTreeADT);
BinaryTreeADT RightSubtree(BinaryTreeADT);
int TreeIsEmpty(BinaryTreeADT);
TreeNodeADT Root(BinaryTreeADT);
char *GetNodeKey(TreeNodeADT);
```

```
int maxDepth(BinaryTreeADT t) {
    if (TreeIsEmpty(t)) return 0;
    else
    {
        int lDepth = maxDepth(LeftSubtree(t));
        int rDepth = maxDepth(RightSubtree(t));
        if (lDepth > rDepth) return lDepth+1;
        else return rDepth+1;
    }
}
```

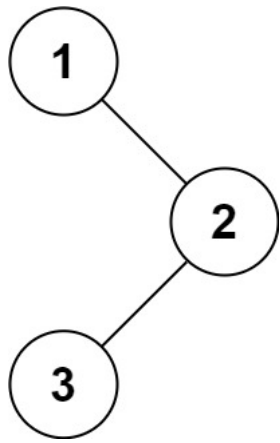
```
bool isBalanced(BinaryTreeADT t) {
    // Please type your code here
    if (TreeIsEmpty(t)) return true;
    int lDepth = maxDepth(LeftSubtree(t));
    int rDepth = maxDepth(RightSubtree(t));
    if ((lDepth - rDepth > 1) || (lDepth - rDepth < -1))
    {return false;}
    return (isBalanced(LeftSubtree(t)) &&
            isBalanced(RightSubtree(t)));
}
```

Exercise 2

Binary Tree Inorder Traversal



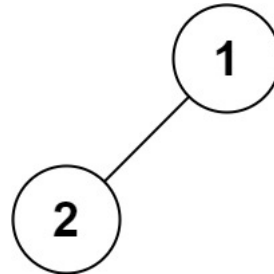
Question: Given the a binary tree t , return *the inorder traversal of its nodes' values*.



Example 1:

Input: $t = [1, \text{null}, 2, 3]$

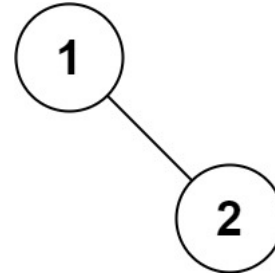
Output: $[1, 3, 2]$



Example 2:

Input: $t = [1, 2]$

Output: $[2, 1]$



Example 3:

Input: $t = [1, \text{null}, 2]$

Output: $[1, 2]$

```
typedef struct BinaryTreeCDT
*BinaryTreeADT;
```

```
typedef struct TreeNodeCDT
*TreeNodeADT;
```

```
BinaryTreeADT NonemptyBinaryTree(TreeNodeADT,
                                   BinaryTreeADT, BinaryTreeADT);
BinaryTreeADT EmptyBinaryTree(void);
BinaryTreeADT LeftSubtree(BinaryTreeADT);
BinaryTreeADT RightSubtree(BinaryTreeADT);
int TreeIsEmpty(BinaryTreeADT);
TreeNodeADT Root(BinaryTreeADT);
char *GetNodeKey(TreeNodeADT);
```

```
int* inorderTraversal(BinaryTreeADT t,
int* returnSize) {
    // The returned array must be malloced
    // Please type your code here
}
```

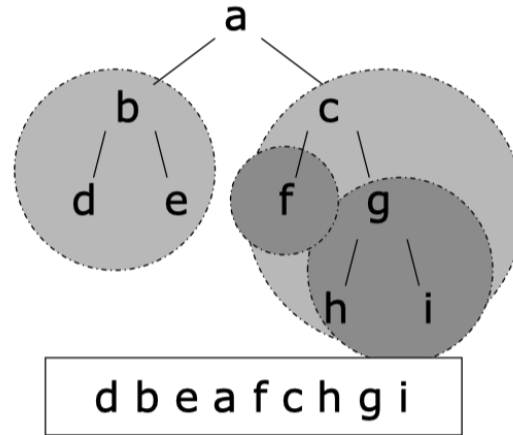
Exercise 2

Binary Tree Inorder Traversal



Definition: In an in-order traversal of a tree, we 'visit' the tree nodes in this order as:

- **First:** Visiting nodes in the **left** subtrees using inorder traversal;
- **Then:** Visiting the **root**;
- **Finally:** Visiting nodes in the **right** subtrees using inorder traversal.



```
void create(BinaryTreeADT t, int* res,
int* index){
    if (TreeIsEmpty(t)) return NULL;
    create(LeftSubtree(t), res, index);
    res[(*index)++] = GetNodeData(Root(t));
    create(RightSubtree(t), res, index);
}
```

```
int* inorderTraversal(BinaryTreeADT t,
int* returnSize) {
    // The returned array must be malloced
    // Please type your code here
    *returnSize = 0;
    int* res = malloc(sizeof(int) * 100);
    create(t, res, returnSize);
    return res;
}
```

```
typedef struct BinaryTreeCDT *BinaryTreeADT;
typedef struct TreeNodeCDT *TreeNodeADT;

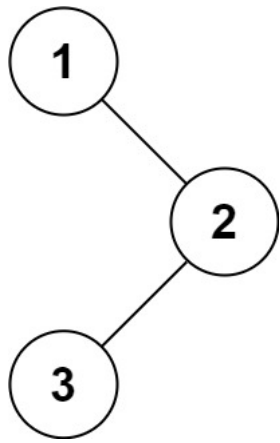
BinaryTreeADT NonemptyBinaryTree(TreeNodeADT,
                                   BinaryTreeADT, BinaryTreeADT);
BinaryTreeADT EmptyBinaryTree(void);
BinaryTreeADT LeftSubtree(BinaryTreeADT);
BinaryTreeADT RightSubtree(BinaryTreeADT);
int TreeIsEmpty(BinaryTreeADT);
TreeNodeADT Root(BinaryTreeADT);
char *GetNodeKey(TreeNodeADT);
```

Exercise 3

Binary Tree Preorder Traversal



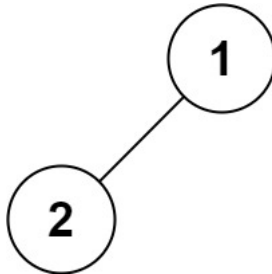
Question: Given the a binary tree t , return *the preorder traversal of its nodes' values*.



Example 1:

Input: $t = [1, \text{null}, 2, 3]$

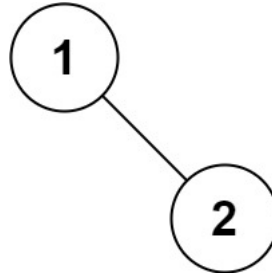
Output: $[1, 2, 3]$



Example 2:

Input: $t = [1, 2]$

Output: $[1, 2]$



Example 3:

Input: $t = [1, \text{null}, 2]$

Output: $[1, 2]$

```
typedef struct BinaryTreeCDT
*BinaryTreeADT;
```

```
typedef struct TreeNodeCDT
*TreeNodeADT;
```

```
BinaryTreeADT NonemptyBinaryTree(TreeNodeADT,
                                   BinaryTreeADT, BinaryTreeADT);
BinaryTreeADT EmptyBinaryTree(void);
BinaryTreeADT LeftSubtree(BinaryTreeADT);
BinaryTreeADT RightSubtree(BinaryTreeADT);
int TreeIsEmpty(BinaryTreeADT);
TreeNodeADT Root(BinaryTreeADT);
char *GetNodeKey(TreeNodeADT);
```

```
int* preorderTraversal(BinaryTreeADT t,
int* returnSize) {
    // The returned array must be malloced
    // Please type your code here
}
```

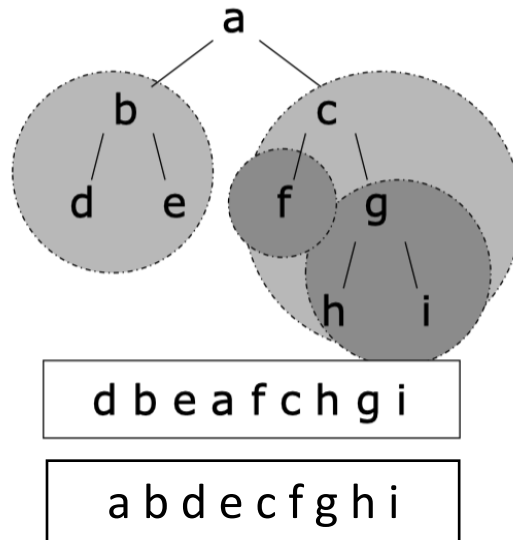
Exercise 3

Binary Tree Preorder Traversal



Definition: In an pre-order traversal of a tree, we 'visit' the tree nodes in this order as:

- **First:** Visiting the **root**;
- **Then:** Visiting nodes in the **left** subtrees using preorder traversal;
- **Finally:** Visiting nodes in the **right** subtrees using preorder traversal.



```
typedef struct BinaryTreeCDT
*BinaryTreeADT;
```

```
typedef struct TreeNodeCDT
*TreeNodeADT;
```

```
typedef struct BinaryTreeCDT {
    TreeNodeADT rt;
    BinaryTreeADT lft;
    BinaryTreeADT rst;};

struct TreeNodeCDT{int val;};
```

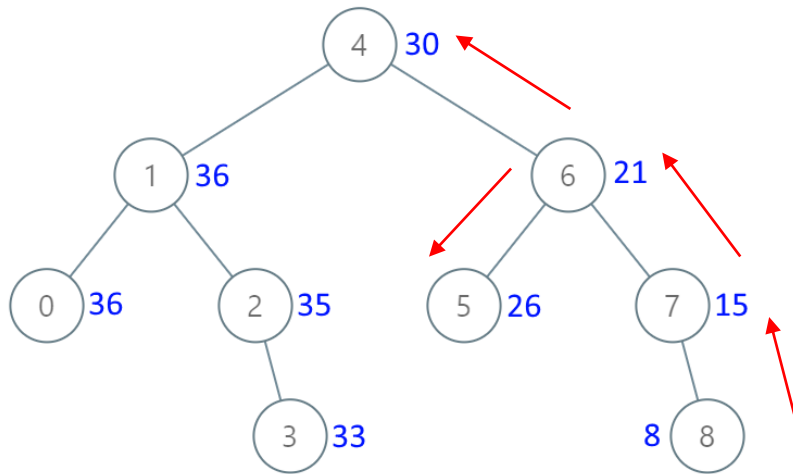
```
void create(BinaryTreeADT t, int* res,
int* index){
    if (TreeIsEmpty(t)) return NULL;
    res[(*index)++] = GetNodeData(Root(t));
    create(LeftSubtree(t), res, index);
    create(RightSubtree(t), res, index);
}
```

```
int* preorderTraversal(BinaryTreeADT t,
int* returnSize) {
    // The returned array must be malloced
    // Please type your code here
    *returnSize = 0;
    int* res = malloc(sizeof(int) * 100);
    create(t, res, returnSize);
    return res;
}
```

Exercise 4

Convert BST to Greater Tree

Question: Given the root t of a Binary Search Tree (BST), convert it to a *Greater Tree* such that every key of the original BST is changed to the *original key plus sum of all keys **greater than** the original key in BST.*



An example to illustrate values in the tree, **NOT** the structure of the tree.

Example:

Input: $t = [4, 1, 6, 0, 2, 5, 7, \text{null}, \text{null}, \text{null}, 3, \text{null}, \text{null}, \text{null}, 8]$

Output: $[30, 36, 21, 36, 35, 26, 15, \text{null}, \text{null}, \text{null}, 33, \text{null}, \text{null}, \text{null}, 8]$



```
typedef struct BinaryTreeCDT
*BinaryTreeADT;
```

```
typedef struct TreeNodeCDT
*TreeNodeADT;
```

```
BinaryTreeADT NonemptyBinaryTree(TreeNodeADT,
                                   BinaryTreeADT, BinaryTreeADT);
BinaryTreeADT EmptyBinaryTree(void);
BinaryTreeADT LeftSubtree(BinaryTreeADT);
BinaryTreeADT RightSubtree(BinaryTreeADT);
int TreeIsEmpty(BinaryTreeADT);
TreeNodeADT Root(BinaryTreeADT);
char *GetNodeKey(TreeNodeADT);
```

```
TreeADT convertBST(TreeADT t){
    // Please type your code here
}
```




Exercise 4

Convert BST to Greater Tree

Remind: A balanced binary search tree satisfies:

- The **left subtree** of a node contains only nodes with keys **less than** the node's key.
- The **right subtree** of a node contains only nodes with keys **greater than** the node's key.
- Both left and right subtrees must be binary search trees.

Base case:

If tree root is NULL, we just return the NULL.

Condition: `t = [null]`

Result: `null`

Common case:

We first visit all the nodes in the right subtree and get the accumulated value, then visit nodes in the left subtree.

Step: visit `t->rst`; accumulate value; visit `t->lst`;

Result: the converted tree

```
typedef struct TreeCDT
*TreeADT;
```

```
typedef struct TreeNodeCDT
*TreeNodeADT;
```

Adapted from LeetCode Question #538: [Covert BST to Greater Tree](#)

```
typedef struct TreeCDT {
    TreeNodeADT rt;
    TreeADT lst;
    TreeADT rst;};
```

```
struct TreeNodeCDT{int val;};
```

```
TreeADT visitBST(TreeADT t, int *acc_val){
    if (TreeIsEmpty(t)) return t;
    TreeADT rst = visitBST(RightSubtree(t), acc_val);
    int root_val = GetNodeData(Root(t)) + *acc_val;
    TreeNodeADT root = NewTreeNode(root_val);
    t = NonemptyBinaryTree(root, LeftSubtree(t), rst);
    *acc_val = GetNodeData(Root(t));
    TreeADT lst = visitBST(LeftSubtree(t), acc_val);
    t = NonemptyBinaryTree(root, lst, RightSubtree(t));
    return t;
}
```

```
TreeADT convertBST(TreeADT t){
    // Please type your code here
    int acc_val = 0;
    t = visitBST(t, &acc_val);
    return t;
}
```

Thanks!

Contact me for more questions.

Muzhi Li

mzli@cse.cuhk.edu.hk

