CSCI 3150: Introduction to Operating System

Lab 6. pthread Library

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Lab Six

- In this lab, you will learn how to use pthread library to implement multithreading programs. In particular, we will use the following functions:
 - pthread_create
 - pthread_exit
 - pthread_join
 - pthread_mutex_init
 - pthread_mutex_lock
 - pthread_mutex_trylock()
 - pthread_mutex_timedlock()
 - pthread_mutex_unlock()

Thread Creation

- thread: Used to interact with this thread.
- attr: Used to specify any attributes this thread might have.
 - Stack size, Scheduling priority, etc...
- start routine: the pointer to the function this thread execute.
- arg: the argument to be passed to the function (start_routine)
 - a void pointer allows us to pass in any type of argument.
- It will return 0 if thread is created successfully. Otherwise returns the error code.

Thread Creation

```
void pthread_exit(void* retval);
```

• retval: A pointer to the return value

```
int pthread_join(pthread_t thread, void** value_ptr);
```

- thread: Specify which thread *to wait for*
- value_ptr: A pointer to the <u>return value</u>
 - Because pthread_join() routine changes the value, you need to pass in a pointer to that value.

Passing data from child thread to calling threads

■ Be careful with <u>how value is returned</u> from a child thread.

```
void* thr_func(void* arg) {
    thread_data_t* data = (thread_data_t*)arg;
    printf("%d + %d\n", data->a, data->b);
    int* retptr = malloc(sizeof(int));
    *retptr = data->a + data->b;
    return retptr;
}
```

■ A wrong implementation.

```
void* thr_func(void* arg) {
    thread_data_t* data = (thread_data_t*)arg;
    printf("%d + %d\n", data->a, data->b);
    int retval = data->a + data->b;
    return (void*)&retval;
}
```

Locks

- All locks must be properly initialized.
 - One way: using PTHREAD_MUTEX_INITIALIZER

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
```

The dynamic way: using pthread_mutex_init()

```
int rc = pthread_mutex_init(&lock, NULL);
assert(rc == 0); // always check success!
```

Locks

- Provide mutual exclusion to a critical section
 - Interface

```
int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread_mutex_unlock(pthread_mutex_t *mutex);
```

Usage (lock initialization and error check)

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_mutex_lock(&lock);
x = x + 1; // or whatever your critical section is
pthread_mutex_unlock(&lock);
```

Locks

- □ Check errors code when calling lock and unlock
 - An example wrapper

```
// Use this to keep your code clean but check for failures
void pthread_mutex_lock(pthread_mutex_t *mutex) {
   int rc = pthread_mutex_lock(mutex);
   assert(rc == 0);
}
```

Non-blocking locks

- Provide a non-blocking way to lock mutex.
 - Interface

• Usage

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
int rc = pthread_mutex_trylock(&lock);
if (rc == EBUSY) {
    // failed to get the lock due to the resource busy
}
else {
    x = x + 1; // or whatever your critical section is
    pthread_mutex_unlock(&lock);
}
```

Non-blocking locks

- Provide a non-blocking way to lock mutex.
 - Interface

• Usage

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
int rc = pthread_mutex_timedlock(&lock);
if (rc == ETIMEDOUT) {
    // failed to get the lock due to the resource busy
}
else {
    x = x + 1; // or whatever your critical section is
    pthread_mutex_unlock(&lock);
}
```

Exercise

