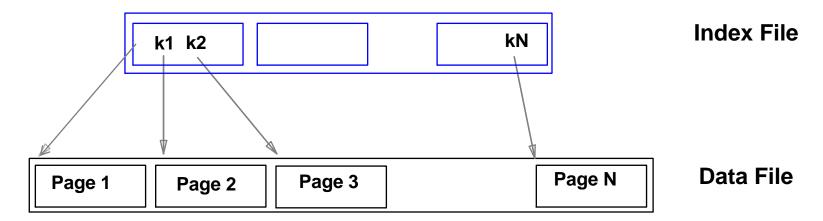
Tree-Structured Indexing

Range Searches

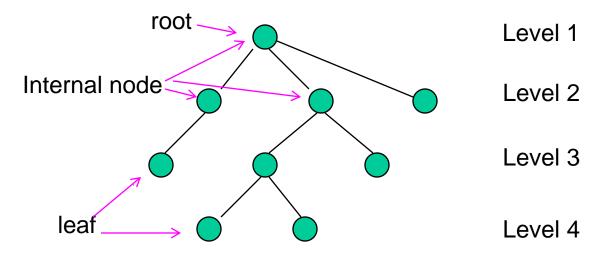
- ``Find all students with 3.0 < gpa < 3.5''
 - If records are sorted on gpa, do binary search to find first such student, then scan to find others.
 - Cost of binary search can be quite high.
- Simple idea: Create an 'index' file.



→ Can do binary search on (smaller) index file!

B+ Tree: Most Widely Used Index

• General concept of a tree:

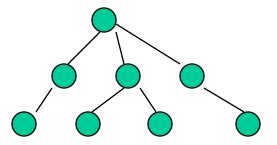


- I. Height of a node: its distance to the root
- II. If a higher level node is connected to a lower level node, then the higher level node is called a parent (grandparent, ancestor, etc.) of the lower level node

B+ Tree (cont.)

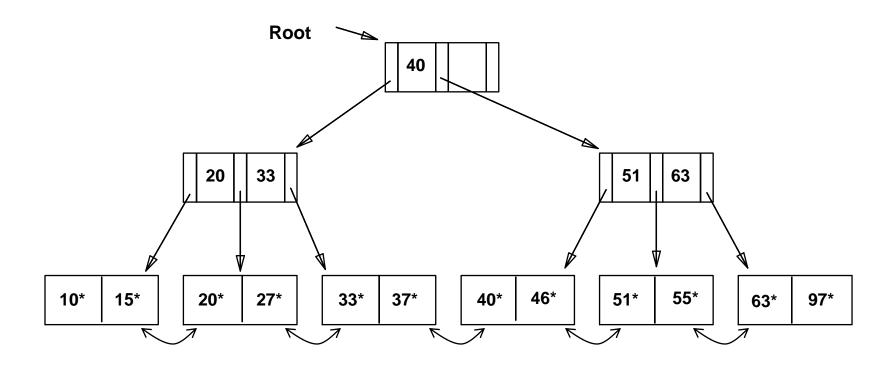
• Balanced tree: all leafs at the same level

– Example:

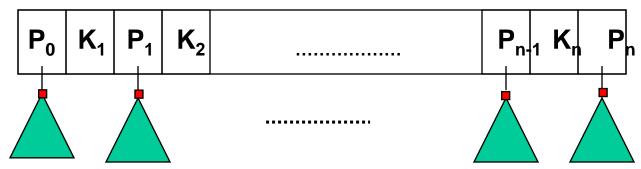


- Structure of a B+ tree:
 - It is **balanced**: all leaf nodes at the same level
 - It's node has a special structure

An example of a B+ tree



B+ tree: Internal node structure

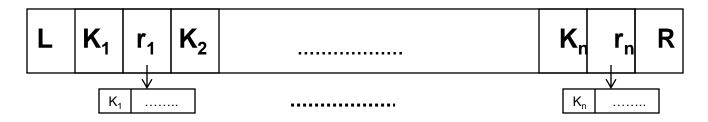


Each P_i is a pointer to a child node, each K_i is a search key value Pointers outnumber search key values by *exactly one*.

Requirements:

- **■** K₁ < K₂ < ... < K_n
- If the node is not the root, we require d ≤ n ≤ 2d where d is a pre-determined value for this B+ tree, called its order
- If the node is the root, we require $1 \le n \le 2d$
- For any search key value K in the subtree pointed by P_i,
 - •If $P_i = P_0$, we require $K < K_1$
 - •If $P_i = P_1, ..., P_{n-1}$, we require $K_i \le K < K_{i+1}$
 - •If $P_i = P_n$, we require $K_n \le K$

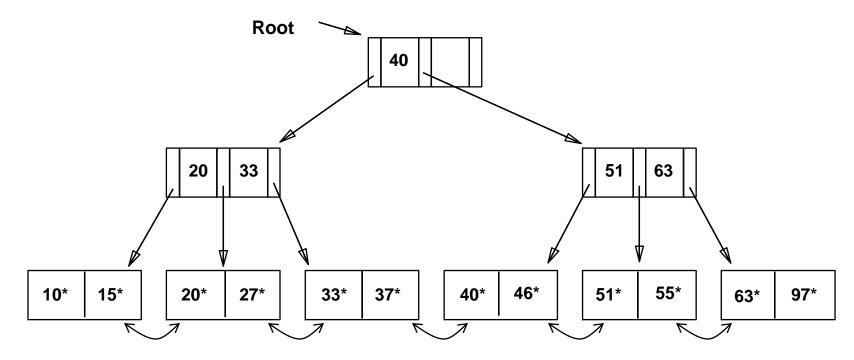
B+ tree: leaf node structure



- Each r_i is a pointer to a record that contains search key value K_i
- L points to the left neighbor, and R points to the right neighbor
- $K_1 < K_2 < ... < K_n$
- We require d ≤ n ≤ 2d where d is the order of this B+ tree
- We will use K_i* for the pair K_i, r_i and omit L and R for simplicity

Example: A B+ tree with order of 1

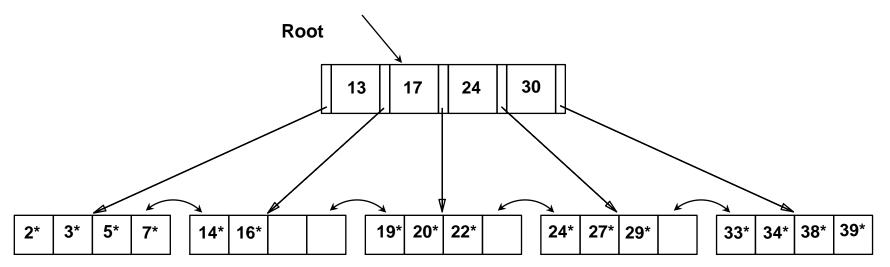
• Each node must hold at least 1 entry, and at most 2 entries



- Given search key values 27, 51, 64, how to find the rids?
 - Search begins at the root, and key comparisons direct it to a leaf

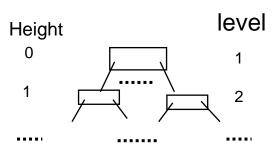
Example: a B+ tree with order 2

- Search for 5^* , 15^* , all data entries $\ge 24^*$...
- The last one is a range search, we need to do the sequential scan, starting from the first leaf containing a value >= 24.



Cost for searching a value in B+ tree

- In general nodes are pages
- Let H be the height of the B+ tree: need to read
 H+1 pages to reach a leaf node
- Let F be the (average) number of pointers in a node (for internal node, called *fanout*)
 - Level 1 = 1 page = F^0 page
 - Level 2 = F pages $= F^1$ pages
 - Level $3 = Fx F pages = F^2 pages$
 - Level $H+1 = \dots = F^H$ pages (i.e., leaf nodes)
 - Suppose there are D data entries. So there are D/(F-1) leaf nodes
 - D/(F-1) = F^H. That is, H = $\log_F(\frac{D}{F-1})$



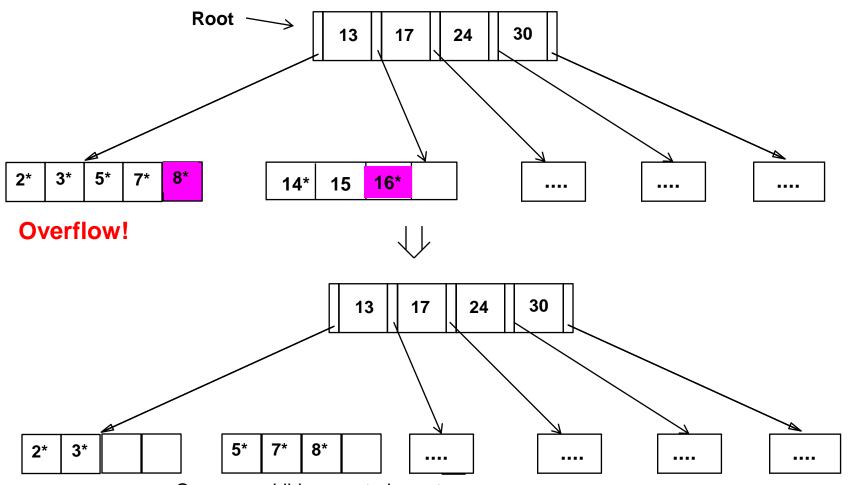
B+ Trees in Practice

- Typically, a node is a page
- Typical order: 100. Typical fill-factor: 67%.
 - average fanout = 133 (i.e, # of pointers in internal node)
- Can often hold top levels in buffer pool:
 - Level 1 = 1 page = 8 Kbytes
 - Level 2 = 133 pages = 1 Mbyte
 - Level 3 = 17,689 pages = 133 MBytes
- Suppose there are 1,000,000,000 data entries.
 - $-H = log_{133}(10000000000132) < 4$
 - The cost is 5 pages read

Inserting a Data Entry into a B+ Tree

- Find correct leaf L.
- Put data entry onto *L*.
 - If L has enough space, done!
 - Else, must split L (into L and a new node L2)
 - Redistribute entries evenly, put middle key in L2
 - **copy up** middle key.
 - Insert index entry pointing to L2 into parent of L.
- This can happen recursively
 - To split an internal node, redistribute entries evenly, but
 push up middle key. (Contrast with leaf splits.)
- Splits "grow" tree; root split increases height.
 - Tree growth: gets *wider* or *one level taller at top*.

Inserting 16*, 8* into Example B+ tree

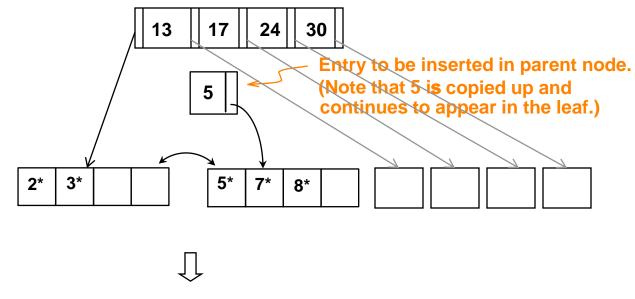


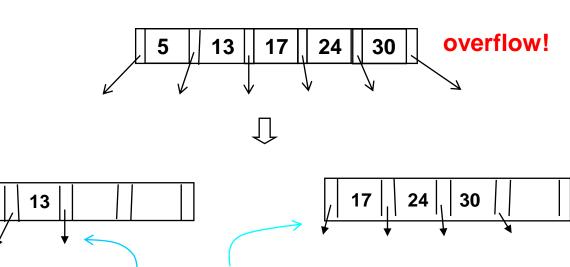
One more child generated, must add one more pointer to its parent, thus one more key value as well.

Inserting 8* into Example B+ Tree (order 2)

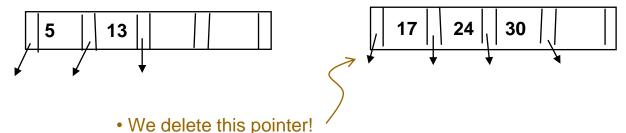
- Copy the middle value up. Why not push up?
- Observe how
 minimum occupancy
 is guaranteed in both
 leaf and index pg
 splits.

5

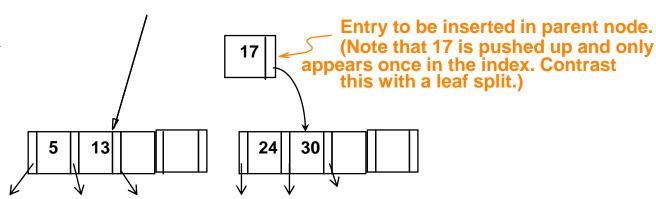




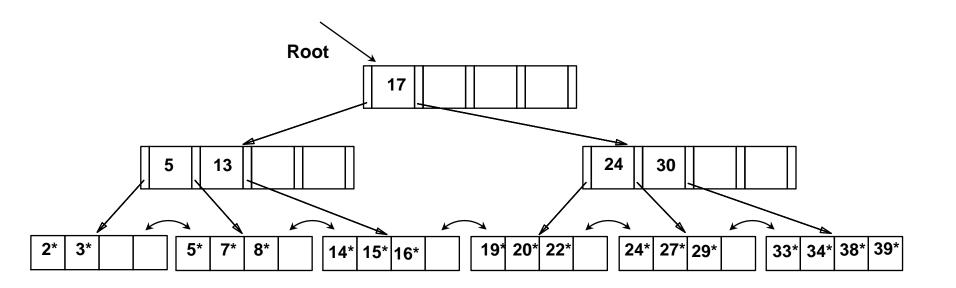
Insertion into B+ tree (cont.)



- But then we should also delete 17
- On the other hand, a value must be inserted into its parent.
- Therefore, we insert 17 to its parent
- This explains why
 we must push up
 the middle entry,
 instead of copying it
 up, when we split
 an internal node.



Example B+ Tree After Inserting 8*

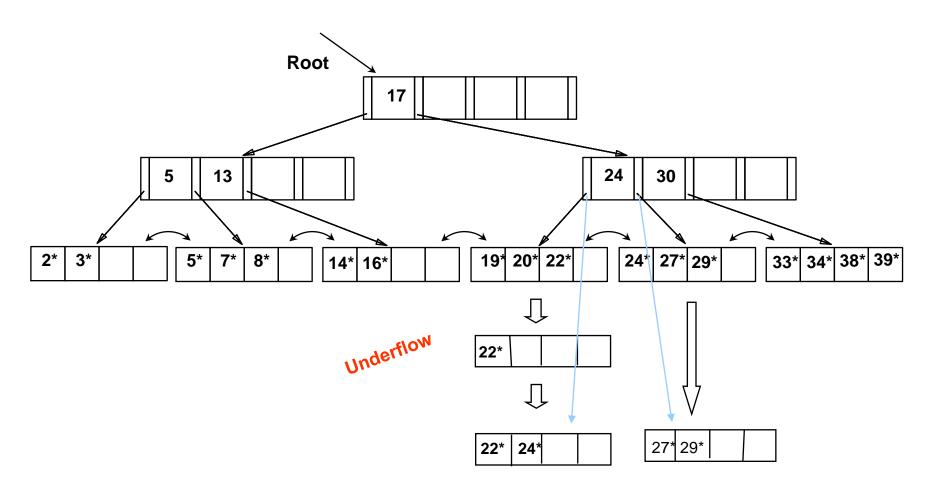


- Notice that root was split, leading to increase in height.
- In this example, we can avoid splitting by re-distributing entries; however, this is usually not done in practice.

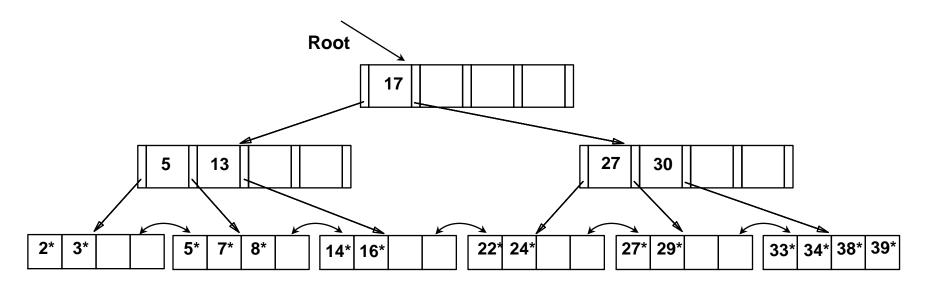
Deleting a Data Entry from a B+ Tree

- Start at root, find leaf L where entry belongs.
- Remove the entry.
 - If L is at least half-full, done!
 - If L has only **d-1** entries,
 - Try to re-distribute, borrowing from <u>sibling</u> (adjacent node with same parent as L).
 - If re-distribution fails, <u>merge</u> L and sibling.
- If merge occurred, must delete entry (pointing to *L* or sibling) from parent of *L*.
- Merge could propagate to root, decreasing height.

Delete 19* and 20*

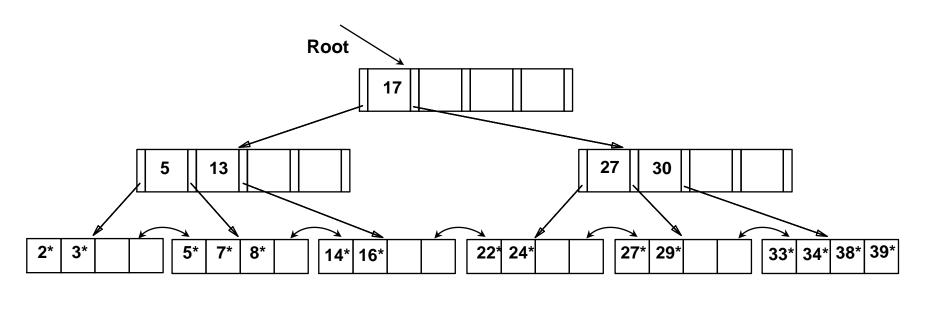


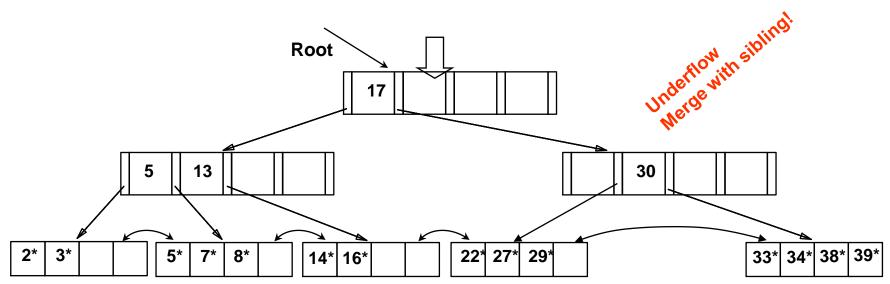
Deleting 19* and 20* (cont.)

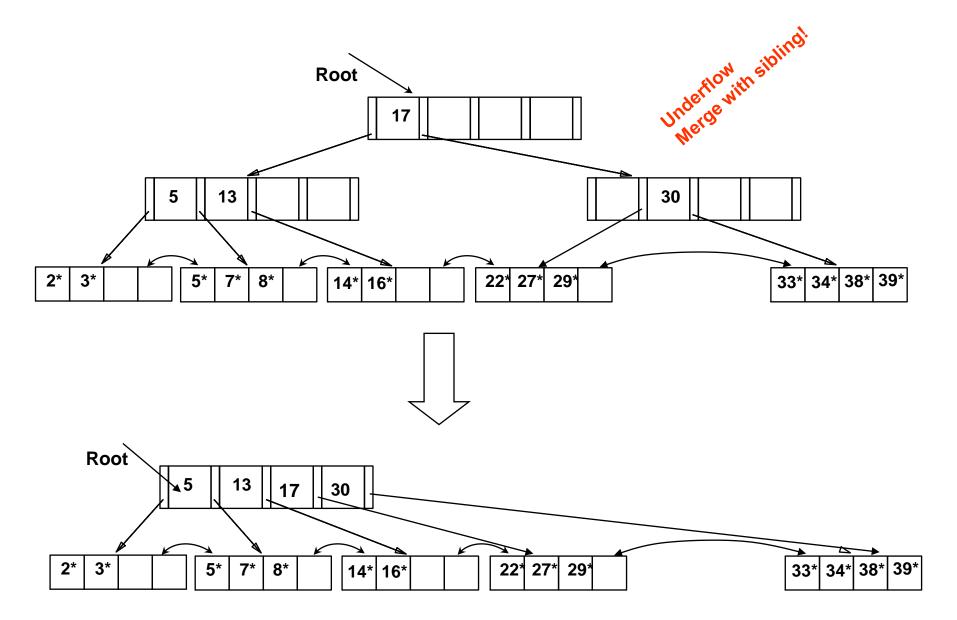


- Notice how 27 is *copied up*.
- But can we move it up?
- Now we want to delete 24
- Underflow again! But can we redistribute this time?

19







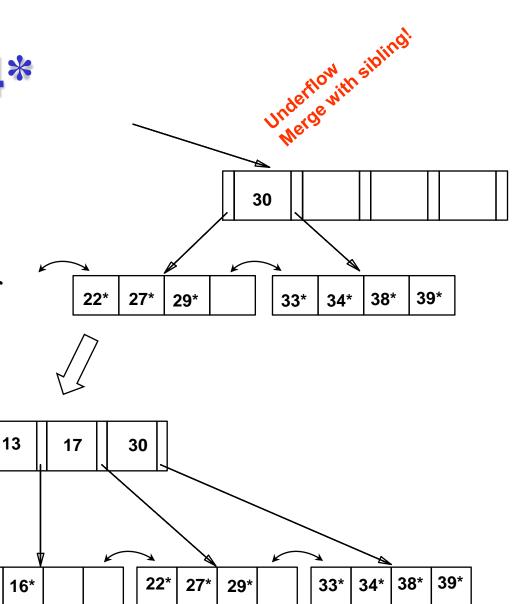
Deleting 24*

8*

14*

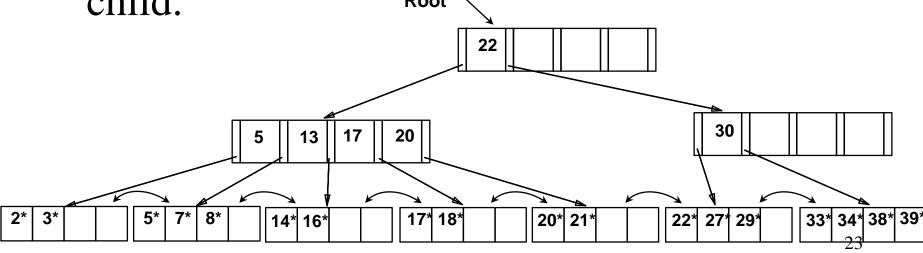
- Observe the two leaf nodes are merged, and 27 is discarded from their parent.
- Observe *pull down* of index entry (below).

2*



Example of Non-leaf Re-distribution

- Tree is shown below *during deletion* of 24*. (What could be a possible initial tree?)
- In contrast to previous example, can redistribute entry from left child of root to right child.



After Re-distribution

• Intuitively, entries are re-distributed by `pushing through' the splitting entry in the parent node.

