## Chapter 6. Case study: Polio

#### **Objectives**

- Demonstrate the use of covariates in pomp to add demographic data (birth rates and total population) and seasonality to an epidemiological model.
- Show how partially observed Markov process (POMP) models and methods can be used to understand transmission dynamics of polio.
- Practice maximizing the likelihood for such models. How to set up a global search for a maximum likelihood estimate. How to assess whether a search has been successful.

## Reviewing covariates in time series analysis

- Suppose our time series of primary interest is  $y_{1:N}$ .
- A **covariate** time series is an additional time series  $z_{1:N}$  which is used to help explain  $y_{1:N}$ .
- When we talk about covariates, it is often implicit that we think of  $z_{1:N}$  as a measure of an **external forcing** to the system producing  $y_{1:N}$ . This means that the process generating the data  $z_{1:N}$  affects the process generating  $y_{1:N}$ , but not vice versa.
- For example, the weather might affect human health, but human health has negligible effect on weather: weather is an external forcing to human health processes.
- When the process leading to  $z_{1:N}$  is not external to the system generating it, we must be alert to the possibility of **reverse** causation and confounding variables.

### Including covariates in the general POMP framework

- The general POMP modeling framework allows essentially arbitrary modeling of covariates.
- ullet Recall that a POMP model is specified by defining, for n=1:N,

$$f_{X_0}(x_0;\theta),$$
  
 $f_{X_n|X_{n-1}}(x_n | x_{n-1};\theta),$   
 $f_{Y_n|X_n}(y_n | x_n;\theta).$ 

ullet The possibility of a general dependence on n includes the possibility that there is some covariate time series  $z_{0:N}$  such that

$$\begin{array}{lll} f_{X_0}(x_0\,;\theta) & = & f_{X_0}(x_0\,;\theta,z_0) \\ f_{X_n|X_{n-1}}(x_n\,|\,x_{n-1}\,;\theta) & = & f_{X_n|X_{n-1}}(x_n\,|\,x_{n-1}\,;\theta,z_n), \\ f_{Y_n|X_n}(y_n\,|\,x_n\,;\theta) & = & f_{Y_n|X_n}(y_n\,|\,x_n\,;\theta,z_n). \end{array}$$

# Seasonality in a POMP model

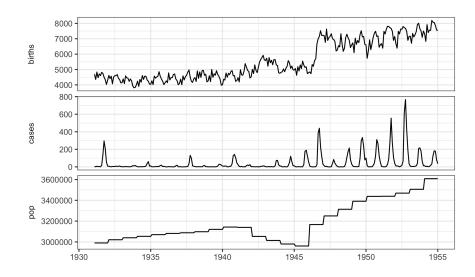
- One specific choice of covariates is to construct  $z_{0:N}$  so that it fluctuates periodically, once per year. This allows **seasonality** enter the POMP model in whatever way is appropriate for the system under investigation.
- All that remains is to hypothesize what is a reasonable way to include covariates for your system, and to fit the resulting model.
- Now we can evaluate and maximize the log likelihood, we can construct AIC or likelihood ratio tests to see if the covariate helps describe the data.
- This also lets us compare alternative ways the covariates might enter the process model and/or the measurement model.

# Covariates in the pomp package

- pomp provides facilities for including covariates in a pomp object.
- Named covariate time series entered via the covar argument to pomp are automatically defined within Csnippets used for the rprocess, dprocess, rmeasure, dmeasure and rinit arguments.
- We see this in practice in the following epidemiological model, which has population census, birth data and seasonality as covariates.

#### Polio in Wisconsin

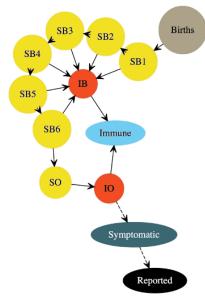
- The massive global polio eradication initiative (GPEI) has brought polio from a major global disease to the brink of extinction.
- Finishing this task is proving hard, and improved understanding polio ecology might assist.
- Martinez-Bakker et al. (2015) investigated this using extensive state level pre-vaccination era data in USA.
- We will follow the approach of Martinez-Bakker et al. (2015) for one state (Wisconsin). In the context of their model, we can quantify seasonality of transmission, the role of the birth rate in explaining the transmission dynamics, and the persistence mechanism of polio.
- Martinez-Bakker et al. (2015) carrried out this analysis for all 48
   contigous states and District of Columbia, and their data and code
   are publicly available. The data we study, in polio\_wisconsin.csv,
   consist of cases, the monthly reported polio cases; births, the
   monthly recorded births; pop, the annual census; time, date in years.



- We use the compartment model of Martinez-Bakker et al. (2015).
- Compartments representing susceptible babies in each of six one-month birth cohorts  $(S_1^B,...,S_6^B)$ , susceptible older individuals  $(S^O)$ , infected babies  $(I^B)$ , infected older individuals  $(I^O)$ , and recovered with lifelong immunity (R).
- The state vector of the disease transmission model consists of numbers of individuals in each compartment at each time,

$$X(t) = (S_1^B(t), ..., S_6^B(t), I^B(t), I^O(t), R(t)).$$

- Babies under six months are modeled as fully protected from symptomatic poliomyelitis.
- ullet Older infections lead to reported cases (usually paralysis) at a rate ho.
- The flows through the compartments are graphically represented on the following slide (Figure 1A of Martinez-Bakker et al. (2015)):



SBk, susceptible babies k months IB, infected babies SO, susceptible older people IO, infected older people

# Setting up the model

- Duration of infection is comparable to the one-month reporting aggregation, so a discrete time model may be appropriate.
- Martinez-Bakker et al. (2015) fitted monthly reported cases, May 1932 through January 1953, so we set  $t_n=1932+(4+n)/12$  and

$$X_n = X(t_n) = (S_{1,n}^B, ..., S_{6,n}^B, I_n^B, I_n^O, R_n).$$

• The mean force of infection, in units of  $yr^{-1}$ , is modeled as

$$\bar{\lambda}_n = \left(\beta_n \frac{I_n^O + I_n^B}{P_n} + \psi\right)$$

where  $P_n$  is census population interpolated to time  $t_n$  and seasonality of transmission is modeled as

$$\beta_n = \exp\left\{\sum_{k=1}^K b_k \xi_k(t_n)\right\},$$

with  $\{\xi_k(t), k=1,\ldots,K\}$  being a periodic B-spline basis with K=6.

•  $P_n$  and  $\xi_k(t_n)$  are covariate time series.

• The force of infection has a stochastic perturbation,

$$\lambda_n = \bar{\lambda}_n \epsilon_n,$$

where  $\epsilon_n$  is a Gamma random variable with mean 1 and variance  $\sigma_{\rm env}^2 + \sigma_{\rm dem}^2/\bar{\lambda}_n$ . These two terms capture variation on the environmental and demographic scales, respectively. All compartments suffer a mortality rate, set at  $\delta=1/60{\rm yr}^{-1}$ .

 Within each month, all susceptible individuals are modeled as having exposure to constant competing hazards of mortality and polio infection. The chance of remaining in the susceptible population when exposed to these hazards for one month is therefore

$$p_n = \exp\left\{-\left(\delta + \lambda_n\right)/12\right\},\,$$

with the chance of polio infection being

$$q_n = (1 - p_n)\lambda_n/(\lambda_n + \delta).$$

• We employ a continuous population model, with no demographic stochasticity. Writing  $B_n$  for births in month n, we obtain the dynamic model of Martinez-Bakker et al. (2015):

$$\begin{array}{rcl} S^{B}_{1,n+1} & = & B_{n+1} \\ S^{B}_{k,n+1} & = & p_{n}S^{B}_{k-1,n} \text{ for } k = 2, \dots, 6 \\ S^{O}_{n+1} & = & p_{n}(S^{O}_{n} + S^{B}_{6,n}) \\ I^{B}_{n+1} & = & q_{n}\sum_{k=1}^{6}S^{B}_{k,n} \\ I^{O}_{n+1} & = & q_{n}S^{O}_{n} \end{array}$$

#### The measurement model

 The model for the reported observations, conditional on the state, is a discretized normal distribution truncated at zero, with both environmental and Poisson-scale contributions to the variance:

$$Y_n = \max\{\text{round}(Z_n), 0\}, \quad Z_n \sim \text{normal}\left(\rho I_n^O, \left(\tau I_n^O\right)^2 + \rho I_n^O\right).$$

#### Initial conditions

- Additional parameters are used to specify initial state values at time  $t_0 = 1932 + 4/12$ .
- We will suppose there are parameters  $(\tilde{S}_{1,0}^B,...,\tilde{S}_{6,0}^B,\tilde{I}_0^B,\tilde{I}_0^O,\tilde{S}_0^O)$  that specify the population in each compartment at time  $t_0$  via  $S_{1,0}^B = \tilde{S}_{1,0}^B,...,S_{6,0}^B = \tilde{S}_{6,0}^B, \quad I_0^B = P_0\tilde{I}_0^B, \quad S_0^O = P_0\tilde{S}_0^O, \quad I_0^O = P_0\tilde{I}_0^O.$
- Following Martinez-Bakker et al. (2015), we make an approximation for the initial conditions of ignoring infant infections at time  $t_0$ . Thus, we set  $\tilde{I}_0^B=0$  and use monthly births in the preceding months (ignoring infant mortality) to fix  $\tilde{S}_{k,0}^B=B_{1-k}$  for  $k=1,\ldots,6$ . The estimated initial conditions are then defined by the two parameters  $\tilde{I}_0^O$  and  $\tilde{S}_0^O$ , since the initial recovered population,  $R_0$ , is specified by subtraction of all the other compartments from the total initial population,  $P_0$ .
- It is convenient to parameterize the estimated initial states as fractions of the population, whereas the initial states fixed at births are parameterized directly as a count.

## Building a pomp object for the polio model

ullet We code the state and observation variables, and the choice of  $t_0$ , as

```
polio_statenames <- c("SB1","SB2","SB3","SB4","SB5","SB6",
    "IB","S0","I0")
polio_obsnames <- "cases"
polio_t0 <- 1932+4/12</pre>
```

ullet We do not explictly code R, since it is defined implicitly as the total population minus the sum of the other compartments. Due to lifelong immunity, individuals in R play no role in the dynamics. Even occasional negative values of R (due to a discrepancy between the census and the mortality model) would not be a fatal flaw.

## Setting up the covariate table

- time gives the time at which the covariates are defined.
- P is a smoothed interpolation of the annual census.
- B is monthly births.
- xi1,...,xi6 is a periodic B-spline basis

```
polio_K <- 6
polio_covar <- covariate_table(
    t=polio_data$time,
    B=polio_data$births,
    P=predict(smooth.spline(x=1931:1954,
        y=polio_data$pop[seq(12,24*12,by=12)]))$y,
    periodic.bspline.basis(t,nbasis=polio_K,
        degree=3,period=1,names="xi%d"),
    times="t"
)</pre>
```

## Regular parameters and initial value parameters

• The parameters  $b_1, \ldots, b_K, \psi, \rho, \tau, \sigma_{\text{dem}}, \sigma_{\text{env}}$  in the model above are regular parameters (RPs), coded as

```
polio_rp_names <- c("b1","b2","b3","b4","b5","b6",
    "psi","rho","tau","sigma_dem","sigma_env")
```

 $\bullet$  The initial value parameters (IVPs),  $\tilde{I}_0^O$  and  $\tilde{S}_0^O$  , are coded for each state named by adding \_0 to the state name:

```
polio_ivp_names <- c("SO_0","IO_0")
polio_paramnames <- c(polio_rp_names,polio_ivp_names)</pre>
```

# Fixed parameters (FPs)

- Two quantities in the dynamic model specification,  $\delta=1/60 {\rm yr}^{-1}$  and K=6, are not estimated.
- Six other initial value quantities,  $\{\tilde{S}_{1,0}^B,\dots,\tilde{S}_{6,0}^B\}$ , are treated as fixed.
- Fixed quantities could be coded as constants using the globals argument of pomp, but here we pass them as fixed parameters (FPs).

```
polio_fp_names <- c("delta","K",
    "SB1_0","SB2_0","SB3_0","SB4_0","SB5_0","SB6_0")
polio_paramnames <- c(polio_rp_names,
    polio_ivp_names,polio_fp_names)
covar_index_t0 <- which(abs(polio_covar@times-polio_t0)<0.01)
polio_initial_births <- polio_covar@table["B",covar_index_t0-0:5]
names(polio_initial_births) <- c("SB1_0","SB2_0",
    "SB3_0","SB4_0","SB5_0","SB6_0")
polio_fixed_params <- c(delta=1/60,K=polio_K,
    polio_initial_births)</pre>
```

### A starting value for the parameters

- We have to start somewhere for our search in parameter space.
- The following parameter vector is based on informal model exploration and prior research:

```
polio_params_guess <- c(b1=3,b2=0,b3=1.5,b4=6,b5=5,b6=3,
    psi=0.002,rho=0.01,tau=0.001,sigma_dem=0.04,sigma_env=0.5,
    S0_0=0.12,I0_0=0.001,polio_fixed_params)</pre>
```

```
polio_rprocess <- Csnippet("</pre>
  double beta = exp(dot_product((int) K, &xi1, &b1));
  double lambda = (beta * (IO+IB) / P + psi);
  double var_epsilon = pow(sigma_dem,2)/ lambda +
    pow(sigma_env,2);
  lambda *= (var_epsilon < 1.0e-6) ? 1 :
    rgamma(1/var_epsilon, var_epsilon);
  double p = \exp(-(delta + lambda)/12);
  double q = (1-p)*lambda/(delta+lambda);
  SB1 = B;
  SB2 = SB1*p;
  SB3=SB2*p;
  SB4=SB3*p;
  SB5=SB4*p;
  SB6=SB5*p;
  SO= (SB6+SO)*p;
  IB=(SB1+SB2+SB3+SB4+SB5+SB6)*q;
  I0=S0*q;
```

```
polio_dmeasure <- Csnippet("</pre>
  double tol = 1.0e-25;
  double mean_cases = rho*IO;
  double sd_cases = sqrt(pow(tau*I0,2) + mean_cases);
  if(cases > 0.0){
    lik = pnorm(cases+0.5,mean_cases,sd_cases,1,0)
      - pnorm(cases-0.5, mean_cases, sd_cases, 1,0) + tol;
  } else{
    lik = pnorm(cases+0.5,mean_cases,sd_cases,1,0) + tol;
  if (give_log) lik = log(lik);
")
polio_rmeasure <- Csnippet("</pre>
  cases = rnorm(rho*IO, sqrt( pow(tau*IO,2) + rho*IO ) );
  if (cases > 0.0) {
    cases = nearbyint(cases);
   else {
    cases = 0.0;
```

The map from the initial value parameters to the initial value of the states at time  $t_0$  is coded by the rinit function:

```
polio_rinit <- Csnippet("
    SB1 = SB1_0;
    SB2 = SB2_0;
    SB3 = SB3_0;
    SB4 = SB4_0;
    SB5 = SB5_0;
    SB6 = SB6_0;
    IB = 0;
    I0 = I0_0 * P;
    S0 = S0_0 * P;
")</pre>
```

#### Parameter transformations

 For parameter estimation, it is helpful to have transformations that map each parameter into the whole real line and which put uncertainty close to a unit scale

```
polio_partrans <- parameter_trans(
  log=c("psi","rho","tau","sigma_dem","sigma_env"),
  logit=c("SO_0","IO_0")
)</pre>
```

• Since the seasonal splines are exponentiated, the beta parameters are already defined on the real line with unit scale uncertainty.

We now put these pieces together into a pomp object.

```
polio <- pomp(</pre>
  data=subset(polio_data,
    (time > polio_t0 + 0.01) & (time < 1953+1/12+0.01),
    select=c("cases","time")),
  times="time",
  t0=polio_t0,
  params=polio_params_guess,
  rprocess = euler(step.fun = polio_rprocess, delta.t=1/12),
  rmeasure= polio_rmeasure,
  dmeasure = polio_dmeasure,
  covar=polio_covar,
  obsnames = polio_obsnames,
  statenames = polio_statenames,
  paramnames = polio_paramnames,
  rinit=polio_rinit,
  partrans=polio_partrans
```

## Setting run levels to control computation time

- run\_level=1 will set all the algorithmic parameters to the first column of values in the following code, for debugging.
- Here, Np is the number of particles, and Nmif is the number of iterations of the optimization procedure carried.
- run\_level=2 uses Np=1000 and Nmif=100. enough effort in this
  case to gives reasonably stable results for a moderate amount of
  computational time.
- Larger values give more refined computations, implemented here by run\_level=3 which was run on a computing node.

```
run_level=3
polio_Np <- switch(run_level,100, 1e3, 5e3)
polio_Nmif <- switch(run_level, 10, 100, 200)
polio_Nreps_eval <- switch(run_level, 2, 10, 20)
polio_Nreps_local <- switch(run_level, 10, 20, 40)
polio_Nreps_global <-switch(run_level, 10, 20, 100)
polio_Nsim <- switch(run_level, 50, 100, 500)</pre>
```

## Comments on setting algorithmic parameters

- run\_level is a facility that is convenient for when you are editing the source code. It plays no fundamental role in the final results. If you are not editing the source code, or using the code as a template for developing your own analysis, it has no function.
- When you edit a document with different run\_level options, you
  can debug your code by editing run\_level=1. Then, you can get
  preliminary assessment of whether your results are sensible with
  run\_level=2 and get finalized results, with reduced Monte Carlo
  error, by editing run\_level=3.
- In practice, you probably want run\_level=1 to run in minutes, run\_level=2 to run in tens of minutes, and run\_level=3 to run in hours.
- You can increase or decrease the numbers of particles, or the number of mif2 iterations, or the number of global searches carried out, to make sure this procedure is practical on your machine.
- Appropriate values of the algorithmic parameters for each run-level are context dependent.

#### Exercise 6.1. Choosing algorithmic parameters.

Suppose you have selected a number of particles, Np, and number of iterated filtering iterations, Nmif, and number of Monte Carlo replications, Reps, that give a 10 minute maximization search using mif2(). Propose how you would adjust these to plan a more intensive search lasting about 2 hours.

# Likelihood evaluation at the starting parameter estimate

```
require(doParallel)
registerDoParallel()
```

```
stew(file=sprintf("pf1-%d.rda",run_level),{
  t1 <- system.time(
    pf1 <- foreach(i=1:20,.packages='pomp') %dopar% pfilter(
        polio,Np=polio_Np)
  )
},seed=493536993,kind="L'Ecuyer")
L1 <- logmeanexp(sapply(pf1,logLik),se=TRUE)</pre>
```

• In 2.5 seconds, we obtain a log likelihood estimate of -816.82 with a Monte standard error of 0.18.

## Simulation to investigate local persistence

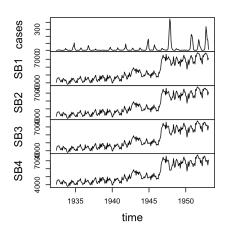
- The scientific purpose of fitting a model typically involves analyzing properties of the fitted model, often investigated using simulation.
- Following Martinez-Bakker et al. (2015), we are interested in how often months with no reported cases  $(Y_n=0)$  correspond to months without any local asymptomatic cases, defined for our continuous state model as  $I_n^B+I_n^O<1/2$ .
- For Wisconsin, using our model at the estimated MLE, we simulate in parallel as follows:

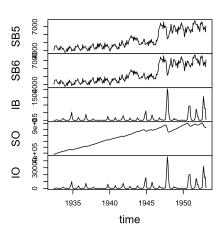
```
stew(sprintf("persistence-%d.rda",run_level),{
  t_sim <- system.time(
    sim <- foreach(i=1:polio_Nsim,
        .packages='pomp') %dopar% simulate(polio)
  )
},seed=493536993,kind="L'Ecuyer")</pre>
```

For the data, there were 26 months with no reported cases, similar to the mean of 51.3 for simulations from the fitted model. Months with no asyptomatic infections for the simulations were rare, on average 0.8 months per simulation. Months with fewer than 100 infections averaged 63.8 per simulation, which in the context of a reporting rate of 0.01 can explain the absences of case reports. The mean monthly infections due to importations, modeled by  $\psi$ , is 117.5. This does not give much opportunity for local elimination of poliovirus. A profile over  $\psi$  would show how sensitive this conclusion is to values of  $\psi$  consistent with the data.

• It is also good practice to look at simulations from the fitted model:

```
mle_simulation <- simulate(polio, seed=127)
plot(mle_simulation)</pre>
```





- We see from this simulation that the fitted model can generate report histories that look qualitatively similar to the data. However, there are things to notice in the reconstructed latent states. Specifically, the pool of older susceptibles,  $S^O(t)$ , is mostly increasing. The reduced case burden in the data in the time interval 1932–1945 is explained by a large initial recovered (R) population, which implies much higher levels of polio before 1932. There were large epidemics of polio in the USA early in the 20th century, so this is not implausible.
- A liklihood profile over the parameter  $\tilde{S}_0^O$  could help to clarify to what extent this is a critical feature of how the model explains the data.

#### Local likelihood maximization

Let's see if we can improve on the previous MLE. We use the IF2
algorithm. We set a constant random walk standard deviation for
each of the regular parameters and a larger constant for each of the
initial value parameters:

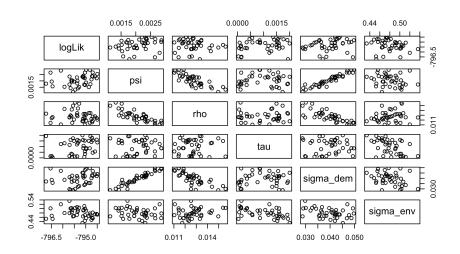
```
polio_rw.sd_rp <- 0.02
polio_rw.sd_ivp <- 0.2
polio_cooling.fraction.50 <- 0.5
polio_rw.sd <- rw.sd(
  b1=polio_rw.sd_rp,b2=polio_rw.sd_rp,b3=polio_rw.sd_rp,
  b4=polio_rw.sd_rp,b5=polio_rw.sd_rp,b6=polio_rw.sd_rp,
  psi=polio_rw.sd_rp, rho=polio_rw.sd_rp,
  tau=polio_rw.sd_rp, sigma_dem=polio_rw.sd_rp,
  sigma_env=polio_rw.sd_rp,
  I0_0=ivp(polio_rw.sd_ivp), S0_0=ivp(polio_rw.sd_ivp)
)</pre>
```

```
stew(sprintf("mif-%d.rda",run_level),{
  t2 <- system.time({
   m2 <- foreach(i=1:polio_Nreps_local,</pre>
      .packages='pomp', .combine=c) %dopar% mif2(polio,
           Np=polio_Np,
           Nmif=polio_Nmif,
           cooling.fraction.50=polio_cooling.fraction.50,
           rw.sd=polio_rw.sd)
    lik_m2 <- foreach(i=1:polio_Nreps_local,</pre>
      .packages='pomp', .combine=rbind) %dopar% logmeanexp(
        replicate(polio_Nreps_eval,logLik(
          pfilter(polio,params=coef(m2[[i]]),Np=polio_Np))),
        se=TRUE)
}, seed=318817883, kind="L'Ecuyer")
```

```
r2 <- data.frame(logLik=lik_m2[,1],logLik_se=lik_m2[,2],
    t(sapply(m2,coef)))
polio_results <- read.table("polio_params_in.csv",
    row.names=NULL,header=T)
write.table(rbind(polio_results,r2),
    file="polio_params_out.csv",row.names=FALSE)
summary(r2$logLik,digits=5)
## Min. 1st Qu. Median Mean 3rd Qu. Max.
## -796.7 -795.6 -795.2 -795.3 -795.0 -794.5</pre>
```

- This investigation took 23.6 minutes.
- These repeated stochastic maximizations can also show us the geometry of the likelihood surface in a neighborhood of this point estimate:

# pairs(~logLik+psi+rho+tau+sigma\_dem+sigma\_env, data=subset(r2,logLik>max(logLik)-20))



• We see strong tradeoffs between  $\psi$ ,  $\rho$  and  $\sigma_{\rm dem}$ . By itself, in the absence of other assumptions, the pathogen immigration rate  $\psi$  is fairly weakly identified. However, the reporting rate  $\rho$  is essentially the fraction of poliovirus infections leading to acute flaccid paralysis, which is known to be around 1%. This plot suggests that fixing an assumed value of  $\rho$  might lead to much more precise inference on  $\psi$ ; the rate of pathogen immigration presumably being important for understanding disease persistence. These hypotheses could be investigated more formally by construction of profile likelihood plots and likelihood ratio tests.

#### Global likelihood maximization

- Practical parameter estimation involves trying many starting values for the parameters. One can specify a large box in parameter space that contains all sensible parameter vectors.
- If the estimation gives stable conclusions with starting values drawn randomly from this box, we have some confidence that our global search is reliable.
- For our polio model, a reasonable box might be:

```
polio_box <- rbind(
  b1=c(-2,8), b2=c(-2,8),
  b3=c(-2,8), b4=c(-2,8),
  b5=c(-2,8), b6=c(-2,8),
  psi=c(0,0.1), rho=c(0,0.1), tau=c(0,0.1),
  sigma_dem=c(0,0.5), sigma_env=c(0,1),
  S0_0=c(0,1), I0_0=c(0,0.01)
)</pre>
```

We then carry out a search identical to the local one except for the starting parameter values. This can be succinctly coded by calling mif2 on the previously constructed object, m2[[1]], with a reset starting value:

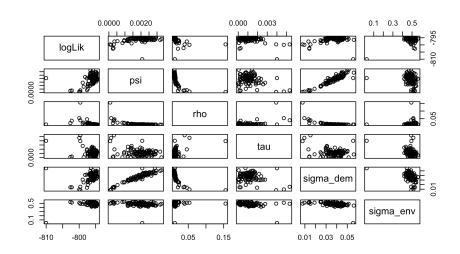
```
stew(file=sprintf("box_eval-%d.rda",run_level),{
  t3 <- system.time({
    m3 <- foreach(i=1:polio_Nreps_global,.packages='pomp',</pre>
      .combine=c) %dopar% mif2(
        m2[[1]],
        params=c(apply(polio_box,1,function(x)runif(1,x[1],x[2])),
          polio_fixed_params)
    lik_m3 <- foreach(i=1:polio_Nreps_global,.packages='pomp',</pre>
      .combine=rbind) %dopar% logmeanexp(
        replicate(polio_Nreps_eval,
        logLik(pfilter(polio,
          params=coef(m3[[i]]),Np=polio_Np))),
        se=TRUE)
}, seed=290860873, kind="L'Ecuyer")
```

```
r3 <- data.frame(logLik=lik_m3[,1],logLik_se=lik_m3[,2],t(sapply(m3)
if(run_level>1) write.table(
   r3,file="polio_params_out.csv",append=TRUE,col.names=FALSE,row.namessummary(r3$logLik,digits=5)

## Min. 1st Qu. Median Mean 3rd Qu. Max.
## -856.4 -796.7 -795.7 -797.6 -795.1 -794.5
```

- Evaluation of the best result of this search gives a likelihood of -794.5
  with a standard error of 0.1. We see that optimization attempts from
  diverse remote starting points can approach our MLE, but do not
  exceed it. This gives us some reasonable confidence in our MLE.
- Plotting these diverse parameter estimates can help to give a feel for the global geometry of the likelihood surface

# pairs(~logLik+psi+rho+tau+sigma\_dem+sigma\_env, data=subset(r3,logLik>max(logLik)-20))



### Benchmark likelihoods for non-mechanistic models

- To understand these global searches, many of which may correspond to parameter values having no meaningful scientific interpretation, it is helpful to put the log likelihoods in the context of some non-mechanistic benchmarks.
- The most basic statistical model for data is independent, identically distributed (IID). Picking a negative binomial model,

```
nb_lik <- function(theta) -sum(dnbinom(as.vector(obs(polio)),
    size=exp(theta[1]),prob=exp(theta[2]),log=TRUE))
nb_mle <- optim(c(0,-5),nb_lik)
-nb_mle$value
## [1] -1036.227</pre>
```

We see that a model with likelihood below -1036.2 is unreasonable.
 This explains a cutoff around this value in the global searches: in these cases, the model is finding essentially IID explanations for the data.

#### ARMA models as benchmarks

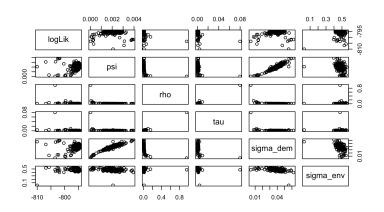
- Linear, Gaussian auto-regressive moving-average (ARMA) models provide non-mechansitic fits to the data including flexible dependence relationships.
- We fit to  $\log(y_n^*+1)$  and correct the likelihood back to the scale appropriate for the untransformed data:

```
log_y <- log(as.vector(obs(polio))+1)
arma_fit <- arima(log_y,order=c(2,0,2),
    seasonal=list(order=c(1,0,1),period=12))
arma_fit$loglik-sum(log_y)
## [1] -822.0827</pre>
```

- This 7-parameter model, which knows nothing of susceptible depletion, attains a likelihood of -822.1.
- Although the goal of mechanistic modeling here is not to beat non-mechanistic models, it is comforting that we're competitive with them.

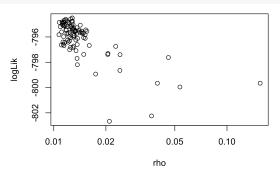
## Mining previous investigations of the likelihood

```
polio_params <- read.table("polio_params_out.csv",row.names=NULL,
   header=TRUE)
pairs("logLik+psi+rho+tau+sigma_dem+sigma_env,
   data=subset(polio_params,logLik>max(logLik)-20))
```



 Here, we see that the most successful searches have always led to models with reporting rate around 1-2%. This impression can be reinforced by looking at results from the global searches:

plot(logLik~rho,data=subset(r3,logLik>max(r3\$logLik)-10),log="x")



 Reporting rates close to 1% provide a small but clear advantage (several units of log likelihood) in explaining the data. For these reporting rates, depletion of susceptibles can help to explain the dynamics.

#### Profile likelihood

- First, we must decide the ranges of parameter starting values for the searches.
- We build a search box using the range of finishing values from previous searches.

```
library(tidyverse)
    polio_params %>%
    filter(logLik>max(logLik)-20) %>%
    select(-logLik,-logLik_se,-rho) %>%
    gather(variable,value) %>%
    group_by(variable) %>%
    dplyr::summarize(min=min(value),max=max(value)) %>%
    ungroup() %>%
    column_to_rownames(var="variable") %>%
    t() -> box
```

• We build a dataframe with a row setting up each profile search

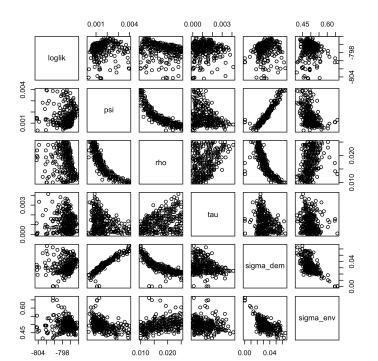
```
profileDesign(
  rho=seq(0.01,0.025,length=30),
  lower=box["min",],upper=box["max",],
  nprof=10
) -> starts
```

• Note that  $\rho$  is not perturbed in the IF iterations for the purposes of the profile calculation.

```
profile_rw.sd <- polio_rw.sd <- rw.sd(
    rho=0,
    b1=polio_rw.sd_rp,b2=polio_rw.sd_rp,b3=polio_rw.sd_rp,
    b4=polio_rw.sd_rp,b5=polio_rw.sd_rp,b6=polio_rw.sd_rp,
    psi=polio_rw.sd_rp,
    tau=polio_rw.sd_rp, sigma_dem=polio_rw.sd_rp,
    sigma_env=polio_rw.sd_rp,
    IO_0=ivp(polio_rw.sd_ivp), SO_0=ivp(polio_rw.sd_ivp)
)</pre>
```

 Otherwise, the following code to compute the profile is identical to a global saerch . . .

```
bake(file="profile_rho.rds",{
  foreach(start=iter(starts, "row"),.combine=rbind) %dopar% {
    library(pomp)
    polio %>% mif2(params=unlist(start),
        Np = 2000,
        Nmif=300,
        cooling.fraction.50=0.5,
        rw.sd=profile_rw.sd
      ) %>% mif2(
        Np = 5000,
        Nmif=100.
        cooling.fraction.50=0.1
      ) -> mf
    replicate(10,
      mf %>% pfilter(Np=5000) %>% logLik()
    ) %>% logmeanexp(se=TRUE) -> 11
    data.frame(as.list(coef(mf)),logLik=ll[1],logLik.se=ll[2])
```



**Exercise 6.2**. **Initial values**. When carrying out parameter estimation for dynamic systems, we need to specify beginning values for both the dynamic system (in the state space) and the parameters (in the parameter space). By convention, we use **initial values** for the initialization of the dynamic system and **starting values** for initialization of the parameter search. Discuss issues in specifying and inferring initial conditions, with particular reference to this polio example.

Suggest a possible improvement in the treatment of initial conditions here, code it up and make some preliminary assessment of its effectiveness. How will you decide if it is a substantial improvement?

**Exercise 6.3.** Parameter estimation using randomized starting values. Think about possible improvements on the assignment of randomized starting values for the parameter estimation searches. Propose and try out a modification of the procedure. Does it make a difference?

**Exercise 6.4**. **Demography and discrete time**. It can be surprisingly hard to include birth, death, immigration, emmigration and aging into a disease model in satisfactory ways. Consider the strengths and weaknesses of the analysis presented, and list changes to the model that might be improvements.

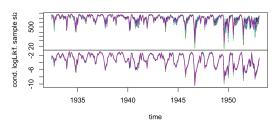
In an imperfect world, it is nice to check the extent to which the conclusions are insensitive to alternative modeling decisions. These are testable hypotheses, which can be addressed within a plug-and-play inference framework. Identify what would have to be done to investigate the changes you have proposed. Optionally, you could have a go at coding something up to see if it makes a difference.

#### Exercise 6.5. Diagnosing filtering and maximization convergence.

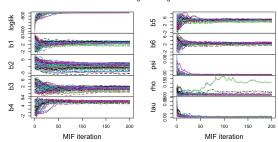
Are there outliers in the data (i.e., observations that do not fit well with our model)? Are we using unnecessarily large amounts of computer time to get our results? Are there indications that we would should run our computations for longer? Or maybe with different choices of algorithmic settings? In particular, cooling.fraction.50 gives the fraction by which the random walk standard deviation is decreased ("cooled") in 50 iterations. If cooling.fraction.50 is too small, the search will "freeze" too soon, evidenced by flat parallel lines in the convergence diagnostics. If cooling.fraction.50 is too large, the researcher may run of of time, patience or computing budget (or all three) before the parameter trajectories approach an MLE.

#### plot(m3[r3\$logLik>max(r3\$logLik)-10])

Filter diagnostics (last iteration)

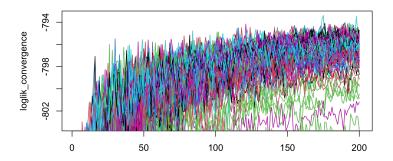


MIF2 convergence diagnostics



- The likelihood is particularly important to keep in mind. If parameter estimates are numerically unstable, that could be a consequence of a weakly identified parameter subspace.
- The presence of some weakly identified combinations of parameters is not fundamentally a scientific flaw; rather, our scientific inquiry looks to investigate which questions can and cannot be answered in the context of a set of data and modeling assumptions.
- As long as the search is demonstrably approaching the maximum likelihood region we should not necessarily be worried about the stability of parameter values (at least, from the point of diagnosing successful maximization).
- So, we zoom in on the likelihood convergence:

```
loglik_convergence <- do.call(cbind,
   traces(m3[r3$logLik>max(r3$logLik)-10],"loglik"))
matplot(loglik_convergence,type="l",lty=1,
   ylim=max(loglik_convergence,na.rm=T)+c(-10,0))
```



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- Previous versions were presented at SISMID by ELI and AAK in 2015–2019. Carles Breto assisted in 2018.
- Produced with R version 4.0.1 and pomp version 3.0.1.1.
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#### References I

Martinez-Bakker, M., King, A. A. and Rohani, P. (2015). Unraveling the transmission ecology of polio, *PLoS Biology* **13**(6): e1002172.