Below are the questions corresponding to the Final Exam. Please read the following instructions before starting:

- The exam must be submitted on Gradescope tomorrow, Thursday 7/2 by 11:59AM Boston Time. You may upload a scan or a picture of you documents. Late submissions won't be accepted. Please indicate which pages correspond to which question when uploading.
- During the completion of this exam, you may **NOT** check the official textbook, notes, or any material posted on the course website.
- The use of any on-line/physical resources will be considered cheating.
- Each step on each answer must be justified. Indicate the methods you use to solve the equations (separable, guess and check, ...) to integrate function (*u*-substitution, by parts, partial fractions).
- By submitting the answers you agree to abide by the BU honor code. As instructors, we reserve our right, after the completion of the exam, to **ask privately** about your solutions to any of the problems.

Table 6.1 Frequently Encountered Laplace Transforms.

$y(t) = \mathcal{L}^{-1}[Y]$	$Y(s) = \mathcal{L}[y]$	$y(t) = \mathcal{L}^{-1}[Y]$	$Y(s) = \mathcal{L}[y]$
$y(t) = e^{at}$	$Y(s) = \frac{1}{s - a} (s > a)$	$y(t) = t^n$	$Y(s) = \frac{n!}{s^{n+1}} (s > 0)$
$y(t) = \sin \omega t$	$Y(s) = \frac{\omega}{s^2 + \omega^2}$	$y(t) = \cos \omega t$	$Y(s) = \frac{s}{s^2 + \omega^2}$
$y(t) = e^{at} \sin \omega t$	$Y(s) = \frac{\omega}{(s-a)^2 + \omega^2}$	$y(t) = e^{at} \cos \omega t$	$Y(s) = \frac{s - a}{(s - a)^2 + \omega^2}$
$y(t) = t \sin \omega t$	$Y(s) = \frac{2\omega s}{(s^2 + \omega^2)^2}$	$y(t) = t\cos\omega t$	$Y(s) = \frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}$
$y(t) = u_a(t)$	$Y(s) = \frac{e^{-as}}{s} (s > 0)$	$y(t) = \delta_a(t)$	$Y(s) = e^{-as}$

Table 6.2
Rules for Laplace Transforms:

Given functions y(t) and w(t) with $\mathcal{L}[y] = Y(s)$ and $\mathcal{L}[w] = W(s)$ and constants α and a.

Rule for Laplace Transform	Rule for Inverse Laplace Transform	
$\mathcal{L}\left[\frac{dy}{dt}\right] = s\mathcal{L}[y] - y(0) = sY(s) - y(0)$		
$\mathcal{L}[y+w] = \mathcal{L}[y] + \mathcal{L}[w] = Y(s) + W(s)$	$\mathcal{L}^{-1}[Y+W] = \mathcal{L}^{-1}[Y] + \mathcal{L}^{-1}[W] = y(t) + w(t)$	
$\mathcal{L}[\alpha y] = \alpha \mathcal{L}[y] = \alpha Y(s)$	$\mathcal{L}^{-1}[\alpha Y] = \alpha \mathcal{L}^{-1}[Y] = \alpha y(t)$	
$\mathcal{L}[u_a(t)y(t-a)] = e^{-as}\mathcal{L}[y] = e^{-as}Y(s)$	$\mathcal{L}^{-1}[e^{-as}Y] = u_a(t)y(t-a)$	
$\mathcal{L}[e^{at}y(t)] = Y(s-a)$	$\mathcal{L}^{-1}[Y(s-a)] = e^{at}\mathcal{L}^{-1}[Y] = e^{at}y(t)$	

1. (40 points) Consider the following non-linear system **restricted to the first quadrant** (i.e. $x \ge 0$ and $y \ge 0$).

$$\frac{dx}{dt} = -5x^2 - xy + 114x$$
$$\frac{dy}{dt} = -x^2y - y^3 + 900y$$

- (a) (5 points) Find all of the equilibrium points in the first quadrant.
- (b) (5 points) Find the Jacobian matrix of the system.
- (c) (15 points) Find the linearized system near each equilibrium point and classify each equilibrium point.
- (d) (10 points) Sketch the nullclines and indicate the direction of the vector field along the nullclines.
- (e) (5 points) Finally, write a brief paragraph describing the possible behavior of a particular solution. You may choose the initial position, but it must be in the first quadrant, and it cannot be an equilibrium point.
- 2. (20 points) Answer the following questions about forced oscillators.
 - (a) (10 points) Without solving explicitly, sketch an approximate graph of the solution with the given initial conditions.
 - $y'' + 4y = \delta_3(t), y(0) = 0, y'(0) = 0.$
 - $y'' + y' + 4y = \delta_1(t), y(0) = 3, y'(0) = 0.$
 - $y'' + 10y' + y = u_7(t)\sin(t), y(0) = 3, y'(0) = 0.$
 - (b) (10 points) In lecture we saw that, for a damped oscillator with sinusoidal forcing, the amplitude of the steady state was given by the following explicit formula:

$$A(p,q,\omega) = \frac{1}{\sqrt{(q-\omega^2)^2 + p^2\omega^2}}.$$

- Suppose $\omega = 2$ and p = 1 are fixed. For what value of q is the amplitude of the forced response largest?
- For the above values, determine if slightly increasing ω has produces an increase or a decrease in $A(p, q, \omega)$. Justify your answer.
- 3. (20 points) In an RC circuit with certain parameters, the voltage across the capacitor $v_c(t)$ satisfies the differential equation

$$\frac{dv_c}{dt} + \frac{v_c}{2} = V(t),$$

where V(t) is the voltage across the source. The source comes with a switch. When off, the voltage is V=0, and when on, V=1.

- (a) (10 points) Suppose that the system is switched off at t = 0. At t = 1, you decide to turn it on, and then at t = 3, you turn it off again. Write a closed form expression for V(t). (HINT: you may write first a piece wise definition, then use one or more Heaviside functions $u_a(t)$).
- (b) (10 points) Using the Laplace Transform method, find the solution with initial conditions $v_c(0) = 0$ and $v'_c(0) = 0$.
- 4. (30 points) True or False. Please justify your answers with sufficient details. A correct answer with no/not enough justification will receive no/partial credit(s).
 - (a) (10 points) The phase plane of the system

$$\frac{dx}{dt} = 2x - x^2 - xy, \quad x \ge 0$$

$$\frac{dy}{dt} = y^2 - yx, \quad y \ge 0$$

contains four separatrices.

- (b) (10 points) $\mathcal{L}[t^2]$ is undefined if s > 0.
- (c) (10 points) Consider the following system depending on the parameter a,

$$\frac{dx}{dt} = y - x^2,$$
$$\frac{dy}{dt} = y - ax.$$

When a > 5, all the equilibrium points of the system are saddles.

- 5. (10 points) Evaluate the following expressions:
 - (a) (5 points) $\mathcal{L}[e^{2t}t\sin(t)]$.
 - (b) (5 points) $\mathcal{L}^{-1}\left[\frac{e^{3t}}{s^2-4}\right]$.