```
--- Day 19: Beacon Scanner ---
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As your probe drifted down through this area, it released an assortment of beacons and scanners into the water. It's difficult to navigate in the pitch black open waters of the ocean trench, but if you can build a map of the trench using data from the scanners, you should be able to safely reach the bottom.

The beacons and scanners float motionless in the water; they're designed to maintain the same position for long periods of time. Each scanner is capable of detecting all beacons in a large cube centered on the scanner; beacons that are at most 1000 units away from the scanner in each of the three axes (x, y), and (x) have their precise position determined relative to the scanner. However, scanners cannot detect other scanners. The submarine has automatically summarized the relative positions of beacons detected by each scanner (your puzzle input).

For example, if a scanner is at x,y,z coordinates 500,0,-500 and there are beacons at -500,1000,-1500 and 1501,0,-500, the scanner could report that the first beacon is at -1000,1000,-1000 (relative to the scanner) but would not detect the second beacon at all.

Unfortunately, while each scanner can report the positions of all detected beacons relative to itself, the scanners do not know their own position. You'll need to determine the positions of the beacons and scanners yourself.

The scanners and beacons map a single contiguous 3d region. This region can be reconstructed by finding pairs of scanners that have overlapping detection regions such that there are at least 12 beacons that both scanners detect within the overlap. By establishing 12 common beacons, you can precisely determine where the scanners are relative to each other, allowing you to reconstruct the beacon map one scanner at a time.

For a moment, consider only two dimensions. Suppose you have the following scanner reports:

```
--- scanner 0 ---
0,2
4,1
3,3
--- scanner 1 ---
-1,-1
-5,0
-2.1
```

Drawing \bar{x} increasing rightward, \bar{y} increasing upward, scanners as \bar{S} , and beacons as \bar{B} , scanner $\bar{0}$ detects this:

```
...B.
B....
....B
S....
```

Scanner 1 detects this:

```
...B..
B....S
....B.
```

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For this example, assume scanners only need 3 overlapping beacons. Then, the beacons visible to both scanners overlap to produce the following complete map:

B....B. B....B. S....

Unfortunately, there's a second problem: the scanners also don't know their rotation or facing direction. Due to magnetic alignment, each scanner is rotated some integer number of 90-degree turns around all of the x, y, and z axes. That is, one scanner might call a direction positive x, while another scanner might call that direction negative y. Or, two scanners might agree on which direction is positive x, but one scanner might be upside-down from the perspective of the other scanner. In total, each scanner could be in any of 24 different orientations: facing positive or negative x, y, or z, and considering any of four directions "up" from that facing.

For example, here is an arrangement of beacons as seen from a scanner in the same position but in different orientations:

-5,4,-6 7,0,8

```
By finding pairs of scanners that both see at least 12 of the same beacons,
you can assemble the entire map. For example, consider the following
report:
--- scanner 0 ---
-838,591,734
-618,-824,-621
553,345,-567
-584,868,-557
-689,845,-530
423,-701,434
630,319,-379
443,580,662
686,422,578
-336,658,858
-476,619,847
-340,-569,-846
-460,603,-452
729,430,532
-500,-761,534
-429,-592,574
-355,545,-477
-328,-685,520
649,640,665
682,-795,504
-588, -843, 648
```

```
-30,6,44
-555,-800,653
-675,-892,-343
493,664,-388
-138,-166,112
646,-828,498
-589,542,597
-500,565,-823
-488,449,543
-938,-730,414
543,643,-506
-778,-728,485
-868,-804,481
-714,465,-776
466,436,-512
-393,719,612
```

```
808,-476,-593

-575,615,604

-485,667,467

-680,325,-822

-627,-443,-432

872,-547,-609

833,512,582

807,604,487

839,-516,451

891,-625,532

-652,-548,-490

30,-46,-14
```

Because all coordinates are relative, in this example, all "absolute" positions will be expressed relative to scanner 0 (using the orientation of scanner 0 and as if scanner 0 is at coordinates 0,0,0).

Scanners ① and ① have overlapping detection cubes; the 12 beacons they both detect (relative to scanner ②) are at the following coordinates:

```
-618,-824,-621
-537,-823,-458
-447,-329,318
404,-588,-901
544,-627,-890
528,-643,409
-661,-816,-575
390,-675,-793
423,-701,434
-345,-311,381
459,-707,401
-485,-357,347
```

These same 12 beacons (in the same order) but from the perspective of scanner $\overline{1}$ are:

```
686,422,578

605,423,415

515,917,-361

-336,658,858

-476,619,847

-460,603,-452

729,430,532

-322,571,750

-355,545,-477

413,935,-424

-391,539,-444

553,889,-390
```

Because of this, scanner 1 must be at 68,-1246,-43 (relative to scanner 0).

Scanner 4 overlaps with scanner 1; the 12 beacons they both detection (relative to scanner 0) are:

```
432,-2009,850
528,-643,409
423,-701,434
534,-1912,768
-447,-329,318
So, scanner \boxed{4} is at \boxed{-20,-1133,1061} (relative to scanner \boxed{0}).
Following this process, scanner 2 must be at 1105,-1205,1229 (relative to
-838,591,734
-689,845,-530
-687,-1600,576
-654,-3158,-753
-635,-1737,486
-624,-1620,1868
-612,-1695,1788
-601,-1648,-643
-537,-823,-458
-532,-1715,1894
-518,-1681,-600
-499,-1607,-770
-430,-3130,366
-413,-627,1469
-36,-1284,1171
396,-1931,-563
404,-588,-901
408,-1815,803
```

```
459,-707,401
465,-695,1988
474,580,667
496,-1584,1900
497,-1838,-617
528,-643,409
534,-1912,768
564,392,-477
605,-1665,1952
612,-1593,1893
630,319,-379
776,-3184,-501
846,-3110,-434
1135,-1161,1235
1735,-437,1738
1749,-1800,1813
1772,-405,1572
1779,-442,1789
1780,-1548,337
1847,-1591,415
1994,-1805,1792
In total, there are 79 beacons.
Assemble the full map of beacons. How many beacons are there?
Your puzzle answer was 438.
--- Part Two ---
Sometimes, it's a good idea to appreciate just how big the ocean is. Using
the Manhattan distance, how far apart do the scanners get?
In the above example, scanners 2 (1105,-1205,1229) and 3 (-92,-2380,-20)
are the largest Manhattan distance apart. In total, they are
1197 + 1175 + 1249 = 3621 units apart.
What is the largest Manhattan distance between any two scanners?
Your puzzle answer was 11985.
Both parts of this puzzle are complete! They provide two gold stars: **
At this point, you should return to your Advent calendar and try another puzzle.
You can also [Share] this puzzle.
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