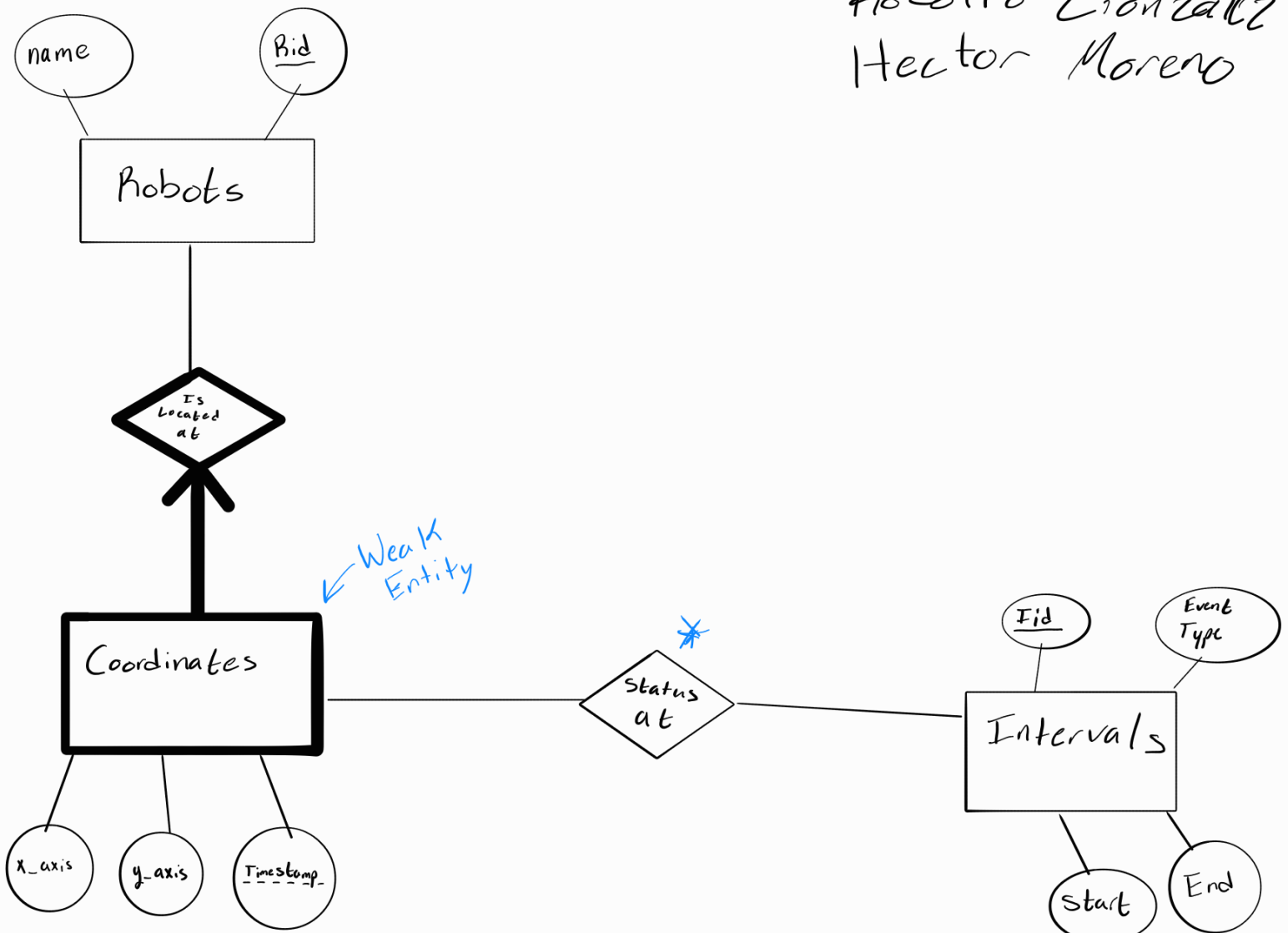


Rodolfo Cronzatz
Hector Moreno



Robots (Rid: int, name: str)

Coordinates (Rid: int, Timestamp: int, x_axis: int, y_axis: int)

Intervals (Iid: int, start: int, end: int, event_type: str)

* status_at (Rid: int, timestamp: int, Iid: int)

Intervals is many to many because interval times may overlap.

* We did not implement the status_at table since it was not necessary for our queries.