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Homework 4  
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The code used to generate the following results can be found at the end of this document.

### Problem 3.15

If  $\mathcal{F}[x(n)] = e^{-j\alpha\omega}$  for  $\omega_c < |\omega| \leq \pi$ , then

$$\begin{aligned} x(n) &= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-j\alpha\omega} e^{j\omega n} d\omega \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} (e^{-j\alpha} e^{jn})^{\omega} d\omega \\ &= \frac{1}{2\pi} \left. \frac{(e^{-j\alpha} e^{jn})^{\omega}}{\ln(e^{jn-j\alpha})} \right|_{-\pi}^{\pi} \\ &= \frac{(e^{-j\alpha} e^{jn})^{\pi} - (e^{-j\alpha} e^{jn})^{-\pi}}{2\pi(jn - j\alpha)} \\ &= \frac{e^{\pi(jn-j\alpha)} - e^{-\pi(jn-j\alpha)}}{2\pi j(n - \alpha)} \\ &= \frac{e^{j\pi(n-\alpha)} - e^{-j\pi(n-\alpha)}}{2j} \frac{1}{\pi(n - \alpha)} \\ &= \frac{\sin(\pi(n - \alpha))}{\pi(n - \alpha)} \end{aligned}$$

### Problem 3.17

For the following problems, it is important to understand that if  $h$  is the impulse response,  $x$  is the excitation, and  $y$  is the result, then  $Y = HX$ , where  $Y$ ,  $H$ , and  $X$  are the DTFTs of  $y$ ,  $h$ , and  $x$ , respectively.

## Part 1

$$y(n) = \frac{1}{5} \sum_{m=0}^4 x(n-m) = \frac{1}{5} [x(n) + x(n-1) + x(n-2) + x(n-3) + x(n-4)]$$

$$Y(e^{j\omega}) = \frac{1}{5} [X(e^{j\omega}) + X(e^{j\omega})e^{-j\omega} + X(e^{j\omega})e^{-2j\omega} + X(e^{j\omega})e^{-3j\omega} + X(e^{j\omega})e^{-4j\omega}]$$

$$Y(e^{j\omega}) = \frac{X(e^{j\omega})}{5} \sum_{m=0}^4 e^{-j\omega m}$$

$$\frac{Y(e^{j\omega})}{X(e^{j\omega})} = H(e^{j\omega}) = \frac{1}{5} \sum_{m=0}^4 e^{-j\omega m}$$

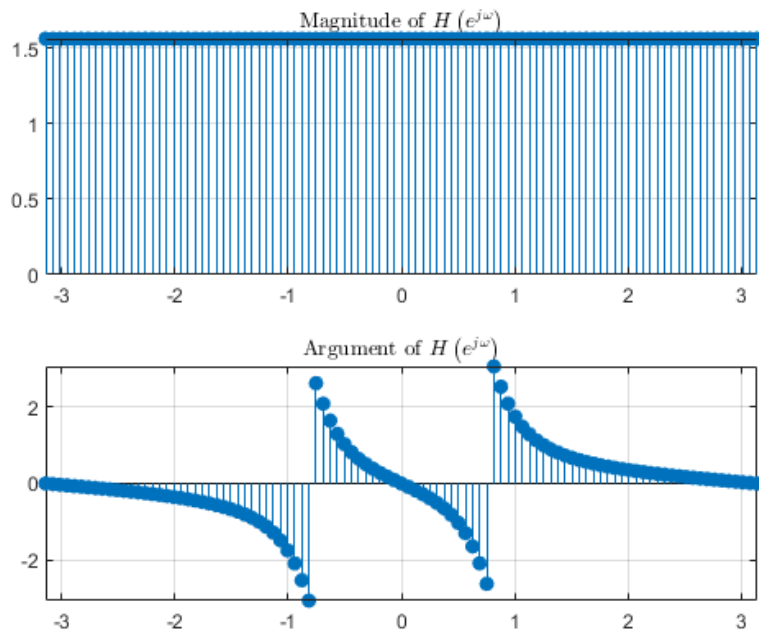


Figure 1: Magnitude and argument plot.

## Part 4

$$\begin{aligned}
 y(n) &= x(n) - 1.7678x(n-1) + 1.5625x(n-2) \\
 &\quad + 1.1314y(n-1) - 0.64y(n-2) \\
 Y(e^{j\omega}) &= X(e^{j\omega}) - 1.7678X(e^{j\omega})e^{-j\omega} + 1.5625X(e^{j\omega})e^{-2j\omega} \\
 &\quad + 1.1314Y(e^{j\omega})e^{-j\omega} - 0.64Y(e^{j\omega})e^{-2j\omega} \\
 Y(e^{j\omega}) - 1.1314Y(e^{j\omega})e^{-j\omega} + 0.64Y(e^{j\omega})e^{-2j\omega} \\
 &= X(e^{j\omega}) - 1.7678X(e^{j\omega})e^{-j\omega} + 1.5625X(e^{j\omega})e^{-2j\omega} \\
 Y(e^{j\omega})(1 - 1.1314e^{-j\omega} + 0.64e^{-2j\omega}) \\
 &= X(e^{j\omega})(1 - 1.7678e^{-j\omega} + 1.5625e^{-2j\omega}) \\
 \frac{Y(e^{j\omega})}{X(e^{j\omega})} &= H(e^{j\omega}) = \frac{1 - 1.7678e^{-j\omega} + 1.5625e^{-2j\omega}}{1 - 1.1314e^{-j\omega} + 0.64e^{-2j\omega}}
 \end{aligned}$$

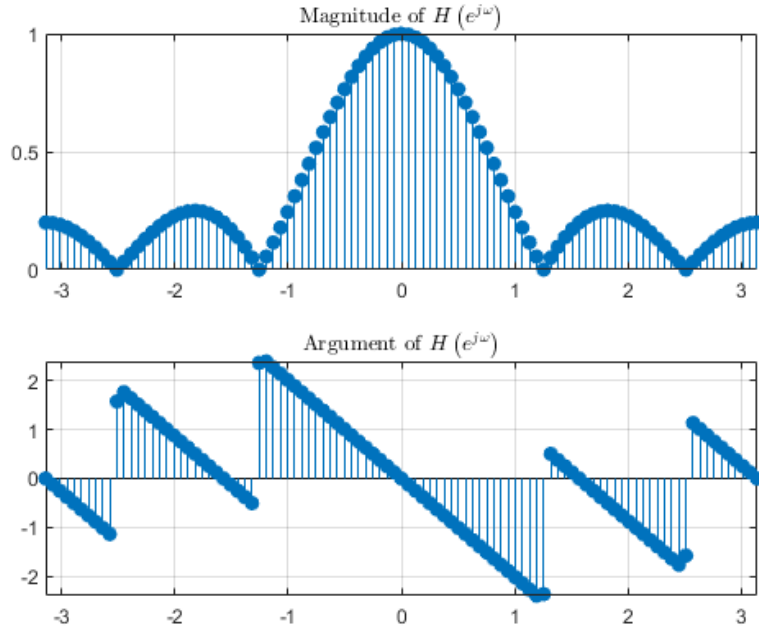


Figure 2: Magnitude and argument plot.

### Problem 3.18

The frequency response can be found using the difference equation given.

$$\begin{aligned}
 y(n) &= x(n) + x(n-2) + x(n-4) + x(n-6) \\
 &\quad - 0.81y(n-2) - 0.81^2y(n-4) - 0.81^3y(n-6) \\
 y(n) + 0.81y(n-2) + 0.81^2y(n-4) + 0.81^3y(n-6) \\
 &= x(n) + x(n-2) + x(n-4) + x(n-6) \\
 Y(e^{j\omega}) (1 + 0.81e^{-2j\omega} + 0.81^2e^{-4j\omega} + 0.81^3e^{-6j\omega}) \\
 &= X(e^{j\omega}) (1 + e^{-2j\omega} + e^{-4j\omega} + e^{-6j\omega}) \\
 \frac{Y(e^{j\omega})}{X(e^{j\omega})} &= H(e^{j\omega}) = \frac{1 + e^{-2j\omega} + e^{-4j\omega} + e^{-6j\omega}}{1 + 0.81e^{-2j\omega} + 0.81^2e^{-4j\omega} + 0.81^3e^{-6j\omega}}
 \end{aligned}$$

#### Part 1

Through Fourier analysis (numerical DTFT), it can be seen that the signal  $x(n) = 5 + 10(-1)^n$  is identical (in the discrete case) to the signal  $x(n) = 5 \cos(0n) + 10 \cos(\pi n)$ .

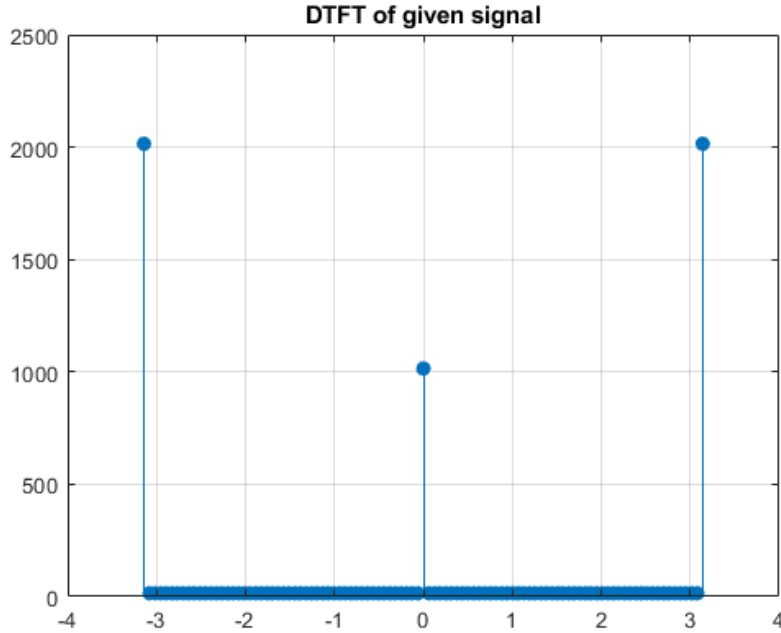


Figure 3: DTFT of signal.

Using the frequency response in MATLAB and the definition of the steady-state response, one can determine numerically the steady-state response of the system when  $x(n) = 5 + 10(-1)^n$  is applied. The resulting plot can be found below.

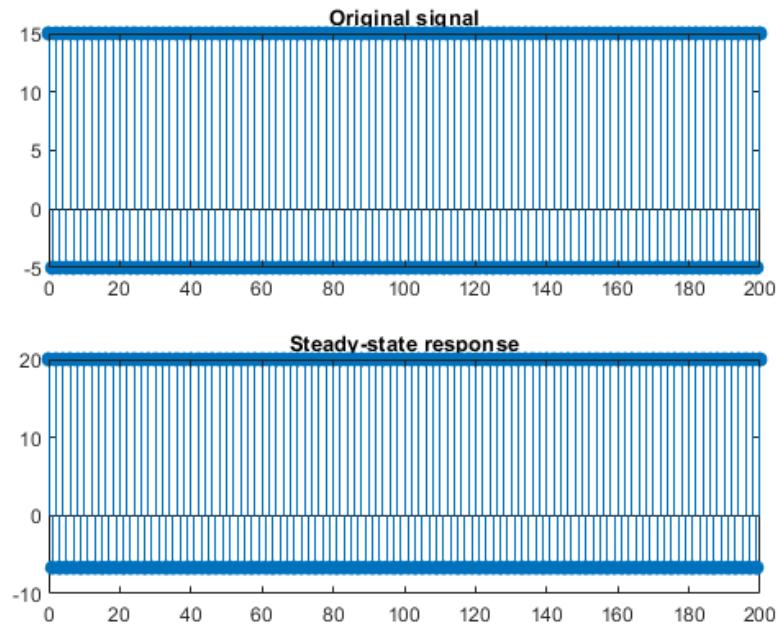


Figure 4: Magnitude and argument plot of steady-state response.

## Part 2

The steady-state response for the same system when a signal of  $x(n) = 1 + \cos(0.5\pi n + \pi/2)$  can be found below.

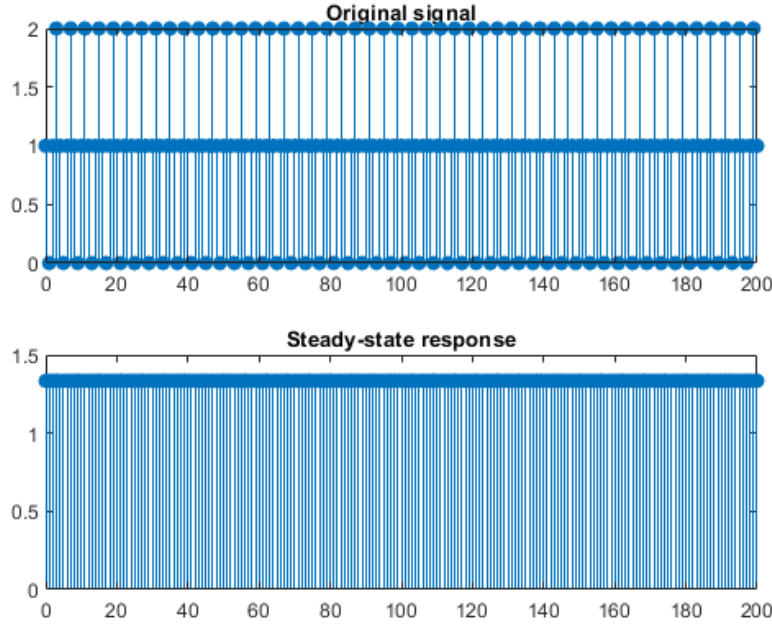


Figure 5: Magnitude and argument plot of steady-state response.

## Problem 3.20

### Part 1

Let  $x_a(t) = 10 \cos(10000\pi t)$ . The angular frequency is  $\omega_x = 10\,000\pi \text{ s}^{-1}$  (radian per second). If we divide by the ADC sample rate of 8000 Hz (samples per second), we arrive at the discrete angular frequency of  $1.25\pi$  (unitless, or radian per sample). This translates to a discrete signal  $x(n) = 10 \cos(1.25\pi n)$ .

### Part 2

If the impulse response  $h(n) = (-0.9)^n u(n)$ , then the frequency response is  $H(e^{j\omega}) = \frac{1}{1+0.9e^{-j\omega}}$ . This comes from the DTFT pair

$$\mathcal{F}[\alpha^n u(n)] = \frac{1}{1 - \alpha e^{-j\omega}}$$

for  $-\pi \leq \omega \leq \pi$ . The magnitude and argument of  $H(e^{j\omega})$  are calculated below.

$$\begin{aligned}
H(e^{j\omega}) &= \frac{1}{1 + 0.9e^{-j\omega}} \\
&= \frac{1}{(1 + 0.9\cos(\omega)) - j0.9\sin(\omega)} \cdot \frac{(1 + 0.9\cos(\omega)) + j0.9\sin(\omega)}{(1 + 0.9\cos(\omega)) + j0.9\sin(\omega)} \\
&= \frac{(1 + 0.9\cos(\omega)) + j0.9\sin(\omega)}{(1 + 0.9\cos(\omega))^2 - j^2(0.9\sin(\omega))^2} \\
&= \frac{(1 + 0.9\cos(\omega)) + j0.9\sin(\omega)}{1 + 1.8\cos(\omega) + 0.81\cos^2(\omega) + 0.81\sin^2(\omega)} \\
&= \frac{(1 + 0.9\cos(\omega)) + j0.9\sin(\omega)}{1.81 + 1.8\cos(\omega)} \\
&= \frac{1 + 0.9\cos(\omega)}{1.81 + 1.8\cos(\omega)} + j \frac{0.9\sin(\omega)}{1.81 + 1.8\cos(\omega)} \\
\\
\arg(H(e^{j\omega})) &= \arctan\left(\frac{\text{Im}(H(e^{j\omega}))}{\text{Re}(H(e^{j\omega}))}\right) \\
&= \arctan\left(\frac{0.9\sin(\omega)}{1.81 + 1.8\cos(\omega)} \div \frac{1 + 0.9\cos(\omega)}{1.81 + 1.8\cos(\omega)}\right) = \arctan\left(\frac{0.9\sin(\omega)}{1 + 0.9\cos(\omega)}\right) \\
\\
|H(e^{j\omega})| &= \sqrt{\left(\frac{1 + 0.9\cos(\omega)}{1.81 + 1.8\cos(\omega)}\right)^2 + \left(\frac{0.9\sin(\omega)}{1.81 + 1.8\cos(\omega)}\right)^2} \\
&= \sqrt{\frac{1 + 1.8\cos(\omega) + 0.81\cos^2(\omega) + 0.81\sin^2(\omega)}{(1.81 + 1.8\cos(\omega))^2}} \\
&= \sqrt{\frac{1.81 + 1.8\cos(\omega)}{(1.81 + 1.8\cos(\omega))^2}} = \sqrt{\frac{1}{1.81 + 1.8\cos(\omega)}}
\end{aligned}$$

Thus,  $H(e^{j\omega})$  can also be written as

$$H(e^{j\omega}) = \frac{1}{1 + 0.9e^{-j\omega}} = \sqrt{\frac{1}{1.81 + 1.8\cos(\omega)}} \exp\left(j \arctan\left(\frac{0.9\sin(\omega)}{1 + 0.9\cos(\omega)}\right)\right)$$

Below are four plots visually confirming the validity of this result. The left two plots graph the magnitude and argument of  $1/(1 + 0.9e^{-j\omega})$ , while the right two plots graph  $\arg(H(e^{j\omega}))$  and  $|H(e^{j\omega})|$ , respectively, as derived above.

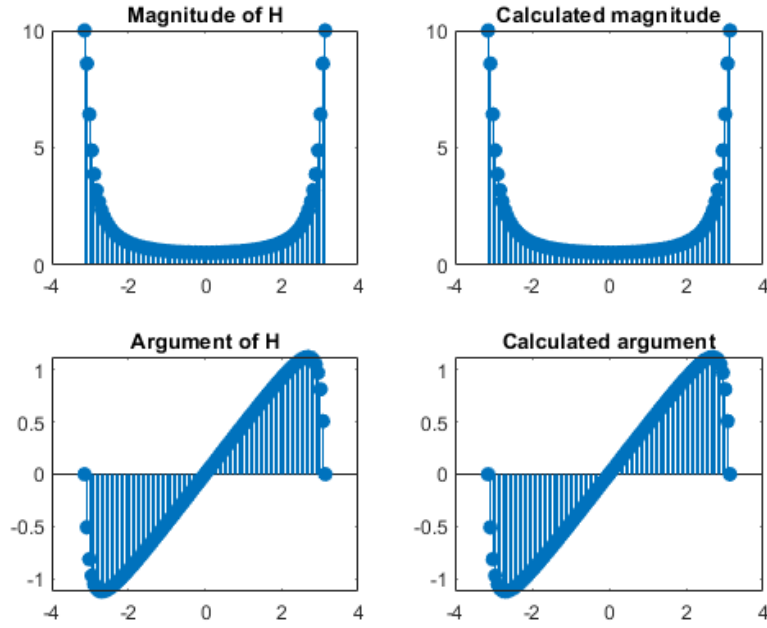


Figure 6: Magnitude and argument plots.

The steady-state response of  $x(n) = 10 \cos(1.25\pi n)$  is

$$y(n) = 10 \sqrt{\frac{1}{1.81 - 1.8/\sqrt{2}}} \cos \left( 1.25\pi n + \arctan \left( \frac{-0.9/\sqrt{2}}{1 - 0.9/\sqrt{2}} \right) \right) \\ \approx 13.644 \cos(1.25\pi n - 1.052)$$

### Part 3

If the continuous signal is  $x(t) = 5 \sin(8000\pi t)$ , then at a 8000 Hz ADC sample rate, the discrete signal will be  $x(n) = 5 \sin(\pi n)$ . The steady-state response to this signal is

$$y(n) = 5 \sqrt{\frac{1}{1.81 - 1.8}} \sin \left( \pi n + \arctan \left( \frac{-0.9}{1 - 0.9} \right) \right) \\ \approx 50 \sin(\pi n - 1.460)$$

### Part 4

Both the magnitude and the argument of  $H(e^{j\omega})$  are functions of  $\omega$ , and both functions are periodic with respect to  $2\pi$ ; this is because  $\omega$  is contained solely



within sine and cosine functions. Therefore, the discrete frequencies  $3.25\pi$  and  $5.25\pi$ . In other words, the signals  $x(n) = 10 \cos(3.25\pi n)$  and  $x(n) = 10 \cos(5.25\pi n)$  will produce the same steady-state response as the signal  $x(n) = 10 \cos(1.25\pi n)$ .

Assuming the same ADC sample rate of 8000 Hz, this is achieved by analog radian frequencies of  $26\pi \times 10^3 \text{ s}^{-1}$  and  $42\pi \times 10^3 \text{ s}^{-1}$ , respectively (the associated signals are  $x(t) = 10 \cos(26000\pi t)$  and  $x(t) = 10 \cos(42000\pi t)$ , respectively).

## Part 5

To prevent aliasing, a low-pass filter should be used. This is to remove any signals with frequencies greater than half of the desired Nyquist rate. Since the ADC is sampling at a rate of 8000 Hz, the filter would need to remove any signals with frequencies above 4000 Hz.

## Problem 4.1

For the following parts, remember that the  $z$ -transform is defined as follows:

$$\mathcal{Z}[x(n)] \equiv X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

## Part 2

$$\begin{aligned} x(n) &= 0.8^n u(n-2) \\ X(z) &= \sum_{n=2}^{\infty} 0.8^n z^{-n} = \sum_{n=0}^{\infty} \left(\frac{0.8}{z}\right)^n - 0.8^0 z^0 - 0.8^1 z^{-1} \\ &= \frac{1}{1 - 0.8z^{-1}} - 1 - 0.8z^{-1}, \text{ROC: } |z| > 0.8 \\ &= \frac{1 - (1 - 0.8z^{-1}) - 0.8z^{-1}(1 - 0.8z^{-1})}{1 - 0.8z^{-1}}, \text{ROC: } |z| > 0.8 \\ &= \frac{1 - 1 + 0.8z^{-1} - 0.8z^{-1} + 0.64z^{-2}}{1 - 0.8z^{-1}}, \text{ROC: } |z| > 0.8 \\ &= \frac{0.64z^{-2}}{1 - 0.8z^{-1}}, \text{ROC: } |z| > 0.8 \end{aligned}$$

Below is a plot of the original signal  $x(n)$  and the  $z$ -transform filter when excited by a unit impulse at index  $n = 2$ . If the  $z$ -transform is truly correct, the two plots would be the same. In the plot, the two signals are identical save for a shift of two indexes. I could not figure out why this was the case.

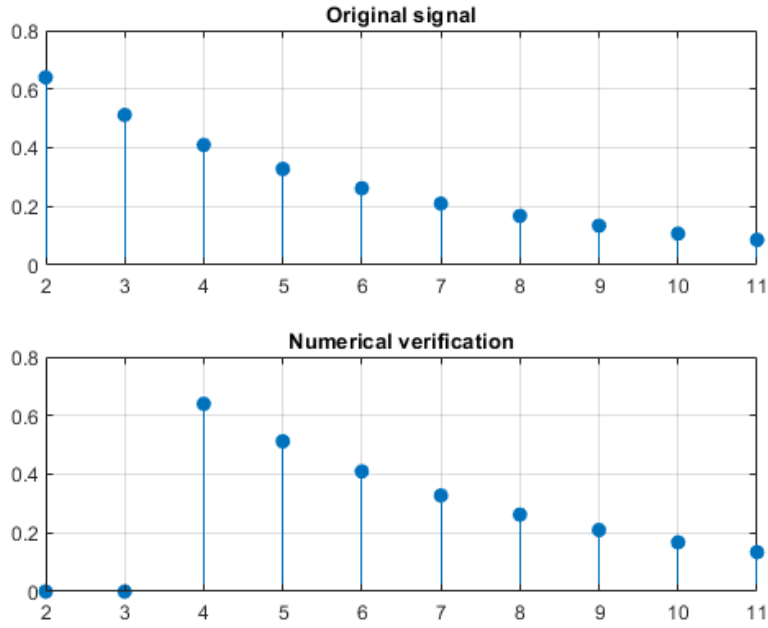


Figure 7: Verification of filter.

### Part 3

$$\begin{aligned}
 x(n) &= [0.5^n + (-0.8)^n] u(n) \\
 X(z) &= \sum_{n=0}^{\infty} (0.5^n + (-0.8)^n) z^{-n} = \sum_{n=0}^{\infty} 0.5^n z^{-n} + \sum_{n=0}^{\infty} (-0.8)^n z^{-n} \\
 &= \sum_{n=0}^{\infty} (0.5z^{-1})^n + \sum_{n=0}^{\infty} (-0.8z^{-1})^n \\
 &= \frac{1}{1 - 0.5z^{-1}}, \text{ROC: } |z| > 0.5 + \frac{1}{1 + 0.8z^{-1}}, \text{ROC: } |z| > 0.8 \\
 &= \frac{1}{1 - 0.5z^{-1}} + \frac{1}{1 + 0.8z^{-1}}, \text{ROC: } |z| > 0.8
 \end{aligned}$$

The verification plots can be found below.

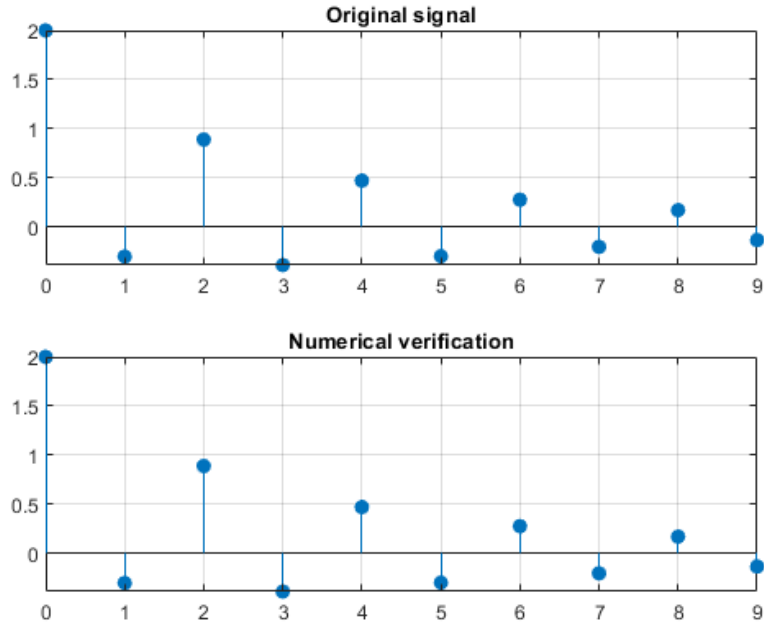


Figure 8: Verification of filter.

## Problem 4.3

### Part 1

$$\begin{aligned}
 x(n) &= 2\delta(n-2) + 3u(n-3) \\
 X(z) &= 2z^{-2} + \frac{3z^{-3}}{1-z^{-1}}, \text{ROC: } |z| > 1 \\
 &= \frac{2z^{-2}(1-z^{-1}) + 3z^{-3}}{1-z^{-1}}, \text{ROC: } |z| > 1 \\
 &= \frac{2z^{-2} - 2z^{-3} + 3z^{-3}}{1-z^{-1}}, \text{ROC: } |z| > 1 \\
 &= \frac{2z^{-2} + z^{-3}}{1-z^{-1}}, \text{ROC: } |z| > 1
 \end{aligned}$$

The verification plots can be found below.

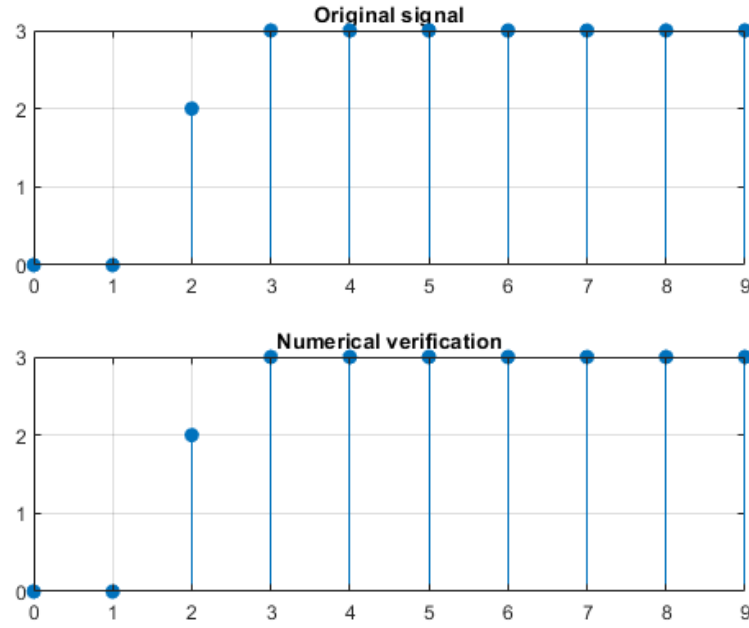


Figure 9: Verification of filter.

## Part 2

$$\begin{aligned}
 x(n) &= 3(0.75)^n \cos(0.3\pi n)u(n) + 4(0.75)^n \sin(0.3\pi n)u(n) \\
 X(z) &= \frac{3 - 2.25 \cos(0.3\pi)z^{-1}}{1 - 1.5 \cos(0.3\pi)z^{-1} + 0.5625z^{-2}}, \text{ROC: } |z| > 0.75 \\
 &\quad + \frac{3 \sin(0.3\pi)z^{-1}}{1 - 1.5 \cos(0.3\pi)z^{-1} + 0.5625z^{-2}}, \text{ROC: } |z| > 0.75 \\
 &= \frac{3 + (3 \sin(0.3\pi) - 2.25 \cos(0.3\pi))z^{-1}}{1 - 1.5 \cos(0.3\pi)z^{-1} + 0.5625z^{-2}}, \text{ROC: } |z| > 0.75
 \end{aligned}$$

The verification plots can be found below.

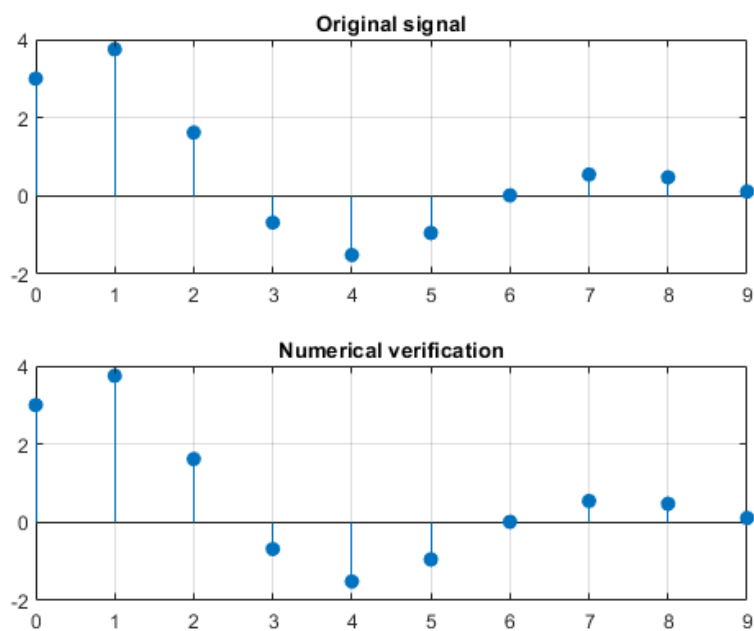


Figure 10: Verification of filter.

## Problem 4.5

For the following problems, let  $\mathcal{Z}[x(n)] = X(z) = \frac{1}{1+0.5z^{-1}}$ , ROC:  $|z| > 0.5$ .

### Part 1

$$\begin{aligned}
 x_1(n) &= x(-n+3) + x(n-3) \\
 X_1(z) &= X(1/z)z^3, \text{ROC: } 0 < |z| < 2 + X(z)z^{-3}, \text{ROC: } |z| > 0.5 \\
 &= \frac{z^3}{1+0.5z} + \frac{z^{-3}}{1+0.5z^{-1}}, \text{ROC: } 0.5 < |z| < 2
 \end{aligned}$$

## Part 2

$$\begin{aligned}
 x_2(n) &= (1 + n + n^2)x(n) = x(n) + nx(n) + n^2x(n) \\
 X_2(z) &= X(z), \text{ROC: } |z| > 0.5 + \frac{-2z}{(2z+1)^2}, \text{ROC: } |z| > 0.5 \\
 &\quad + \frac{-2z(2z-1)}{(2z+1)^3} \\
 X_2(z) &= \frac{1}{1+0.5z^{-1}} - \frac{2z}{(2z+1)^2} - \frac{2z(2z-1)}{(2z+1)^3}, \text{ROC: } |z| > 0.5
 \end{aligned}$$

## Part 3

$$\begin{aligned}
 x_3(n) &= (0.5)^n x(n-2) \\
 X_3(z) &= X(2z)z^{-2}, \text{ROC: } |z| > 0.25 \\
 &= \frac{z^{-2}}{1+0.5(2z)^{-1}}, \text{ROC: } |z| > 0.25 \\
 &= \frac{z^{-2}}{1+0.25z^{-1}}, \text{ROC: } |z| > 0.25
 \end{aligned}$$

## Part 4

$$\begin{aligned}
 x_4(n) &= x(n+2) * x(n-2) \\
 X_4(z) &= X(z)z^2X(z)z^{-2}, \text{ROC: } |z| > 0.5 \\
 &= \left( \frac{1}{1+0.5z^{-1}} \right)^2, \text{ROC: } |z| > 0.5 \\
 &= \frac{1}{1+z^{-1}+0.25z^{-2}}, \text{ROC: } |z| > 0.5
 \end{aligned}$$

## Part 5

$$\begin{aligned}
 x_5(n) &= \cos(\pi n/2)x^*(n) \\
 X_5(n) &= \frac{1}{2\pi j} \oint_C \mathcal{Z}[\cos(\pi n/2)]X^*(z^*/v)v^{-1} dv, \\
 &\quad \text{ROC: } |z| > 0.5
 \end{aligned}$$