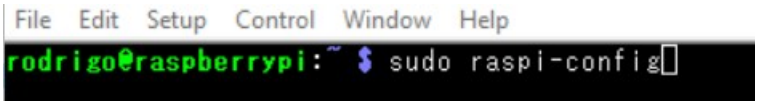
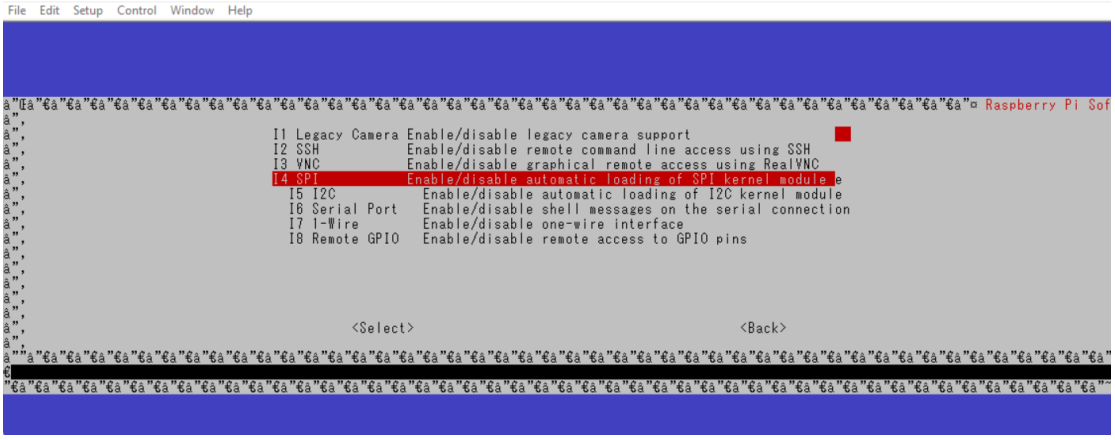
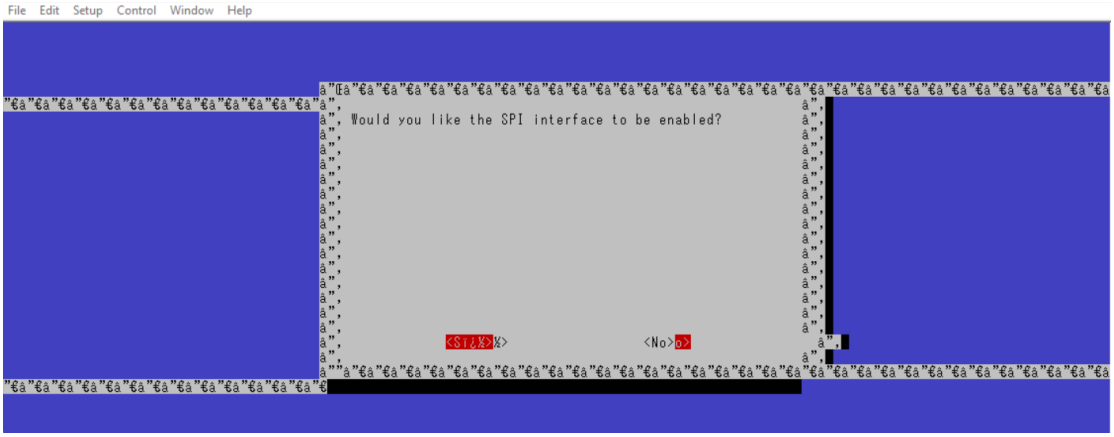

Configuración de Raspberry Pi
Sistema
Display
Interfaces
Rendimiento
Localización
SSH:
VNC:
SPI:
I2C:
Serial Port:
Serial Console:
1-Wire:
Remote GPIO:
Cancelar
Aceptar


File Edit Setup Control Window Help
rodrigo@raspberrypi:~ $ sudo raspi-config


File Edit Setup Control Window Help
Raspberry Pi 3 Model B Rev 1.2
1 System Options Configure system settings
2 Display Options Configure display settings
3 Interface Options Configure connections to peripherals
4 Performance Options Configure performance settings
5 Localisation Options Configure language and regional settings
6 Advanced Options Configure advanced settings
8 Update Update this tool to the latest version
9 About raspi-config Information about this configuration tool
<Select>
<Finish>


File Edit Setup Control Window Help
I1 Legacy Camera Enable/disable legacy camera support
I2 SSH Enable/disable remote command line access using SSH
I3 VNC Enable/disable graphical remote access using RealVNC
I4 SPI Enable/disable automatic loading of SPI kernel module
I5 I2C Enable/disable automatic loading of I2C kernel module
I6 Serial Port Enable/disable shell messages on the serial connection
I7 1-Wire Enable/disable one-wire interface
I8 Remote GPIO Enable/disable remote access to GPIO pins
<Select>
<Back>




```
File  Edit  Setup  Control  Window  Help
rodrigo@raspberrypi:~ $ sudo apt install git libpci-dev libusb-1.0 libusb-dev
```

```
File  Edit  Setup  Control  Window  Help
rodrigo@raspberrypi:~ $ sudo apt install git libpci-dev libusb-1.0 libusb-dev
Leyendo lista de paquetes... Hecho
Creando Ãirbol de dependencias... Hecho
Leyendo la informaciÃ³n de estado... Hecho
E: No se ha podido localizar el paquete libusb-1.0
E: No se pudo encontrar ningÃºn paquete usando Â«*Â» con Â«libusb-1.0Â»
```

```
rodrigo@raspberrypi:~ $ sudo apt-get install flashrom
Leyendo lista de paquetes... Hecho
Creando Ãirbol de dependencias... Hecho
Leyendo la informaciÃ³n de estado... Hecho
flashrom ya estÃi en su versiÃ³n mÃis reciente (1.2-5).
fijado flashrom como instalado manualmente.
0 actualizados, 0 nuevos se instalarÃin, 0 para eliminar y 0 no actualizados.
rodrigo@raspberrypi:~ $
```

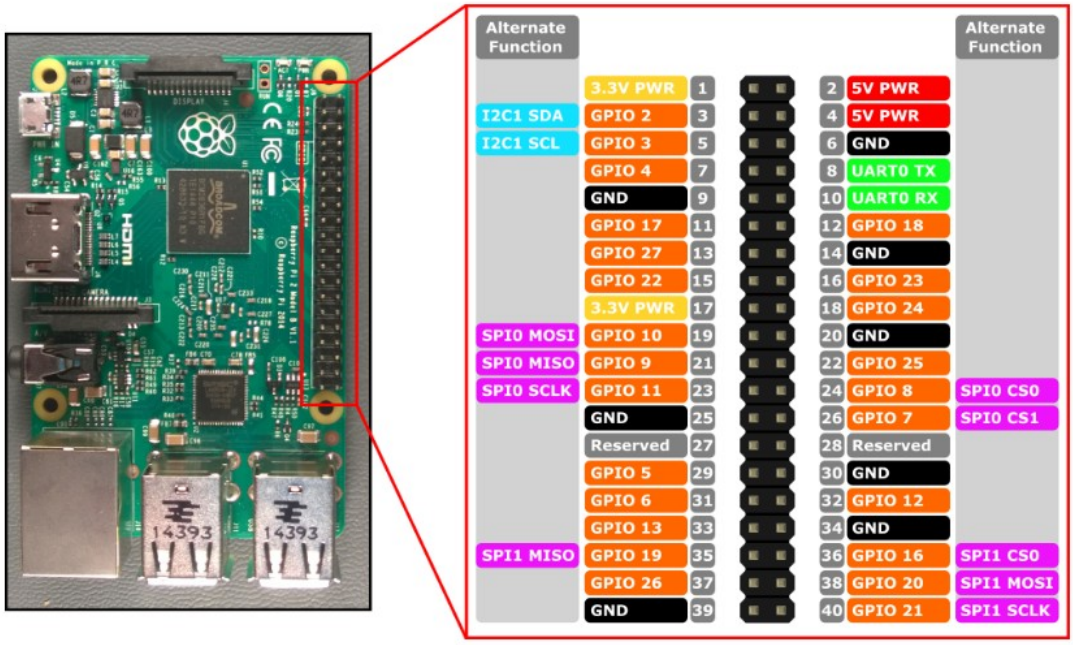
```
rodrigo@raspberrypi:~ $ flashrom --help
flashrom v1.2 on Linux 6.1.21-v8+ (aarch64)
flashrom is free software, get the source code at https://flashrom.org

Usage: flashrom [-h|-R|-L|
       -p <programmername>[:<parameters>] [-c <chipname>]
               (--flash-name|--flash-size|
                [-E|(-r|-w|-v) <file>]
                [(-l <layoutfile>|--ifd| --fmap|--fmap-file <file>) [-i <imagename>]...]
                [-n] [-N] [-f])]
       [-V[V[V]]] [-o <logfile>]
```

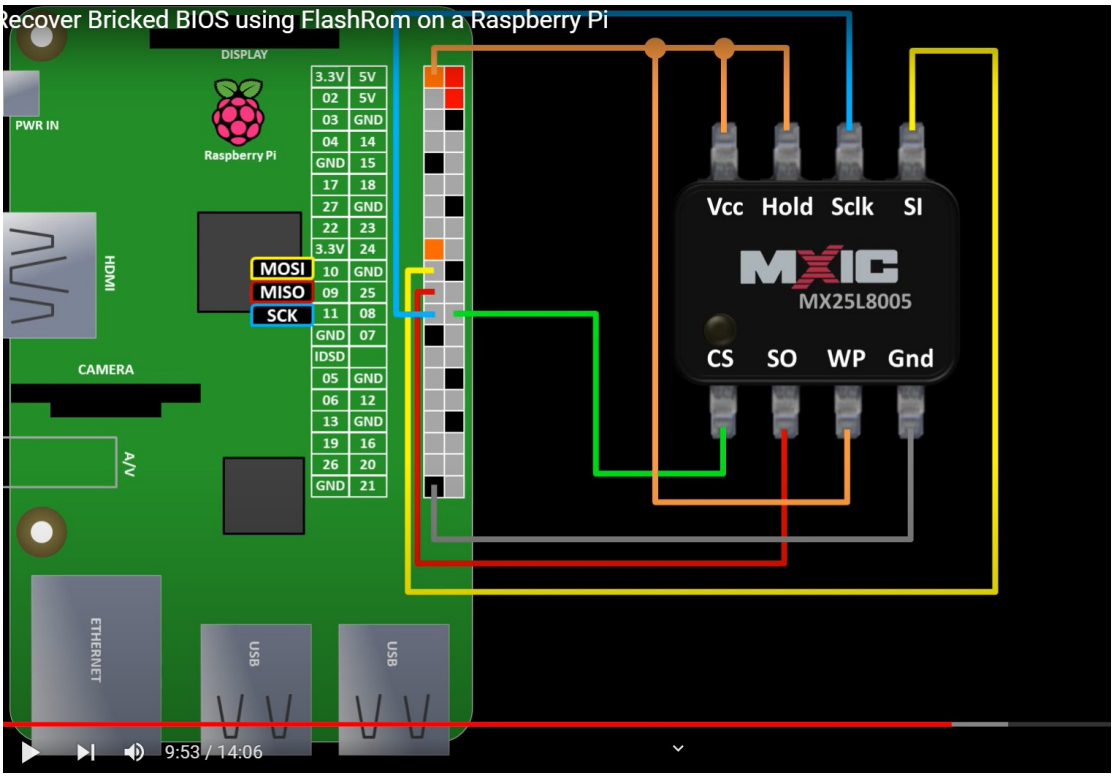
flashrom -p linux_spi:dev=/dev/spidev0.0,spidev=2000 -V

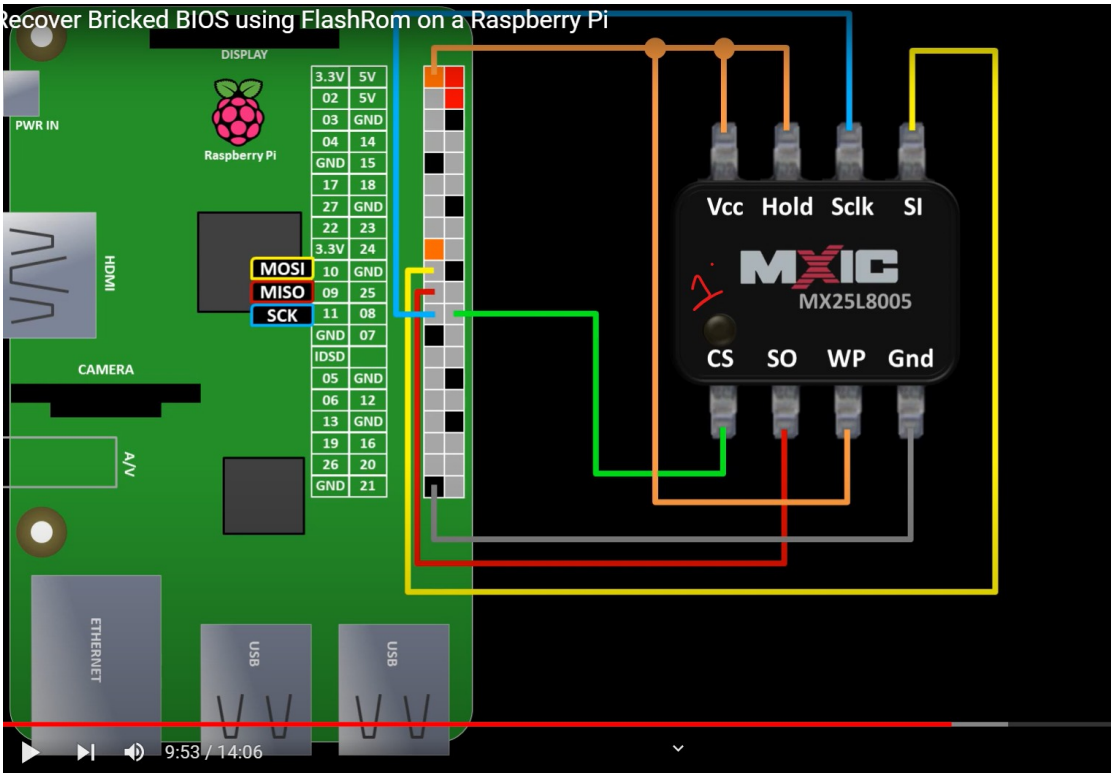
flashrom -p linux_spi:dev=/dev/spidev0.0,spidev=2000 -r <SaveFileName>

flashrom -p linux_spi:dev=/dev/spidev0.0,spidev=2000 -w <FileNameToLoad>

RPi pin	SPI flash
25	GND
24	CS
23	SCK
21	DO
19	DI
17	VCC 3.3V and /HOLD and /WP




Recover Bricked BIOS using FlashRom on a Raspberry Pi
DISPLAY
PWR IN
Raspberry Pi
HDMI
CAMERA
A/V
ETHERNET
USB
USB
MOSI
MISO
SCK
Vcc Hold Sclk SI
MXIC
MX25L8005
CS SO WP Gnd
9:53 / 14:06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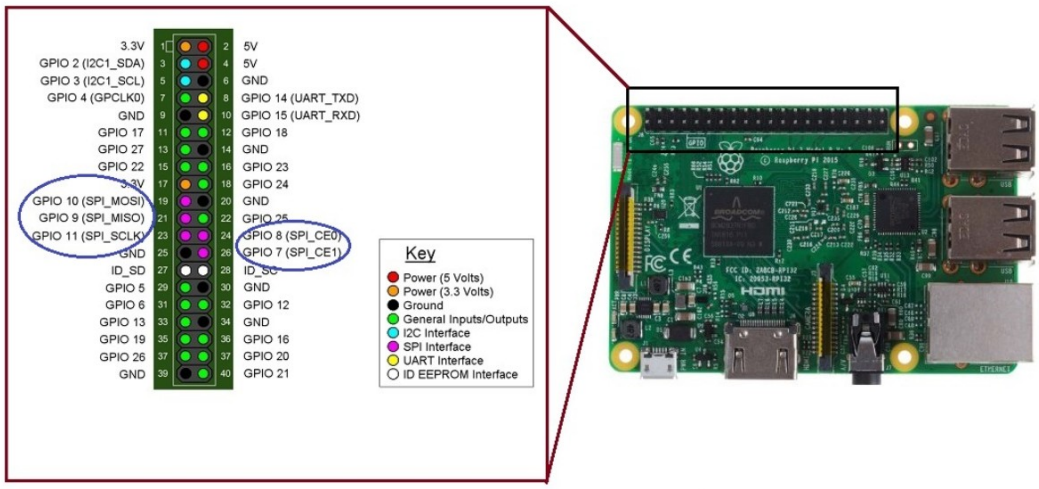
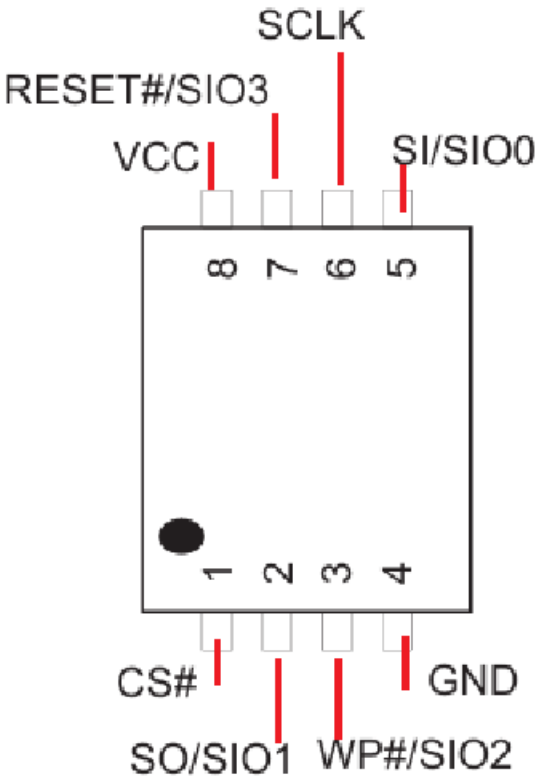
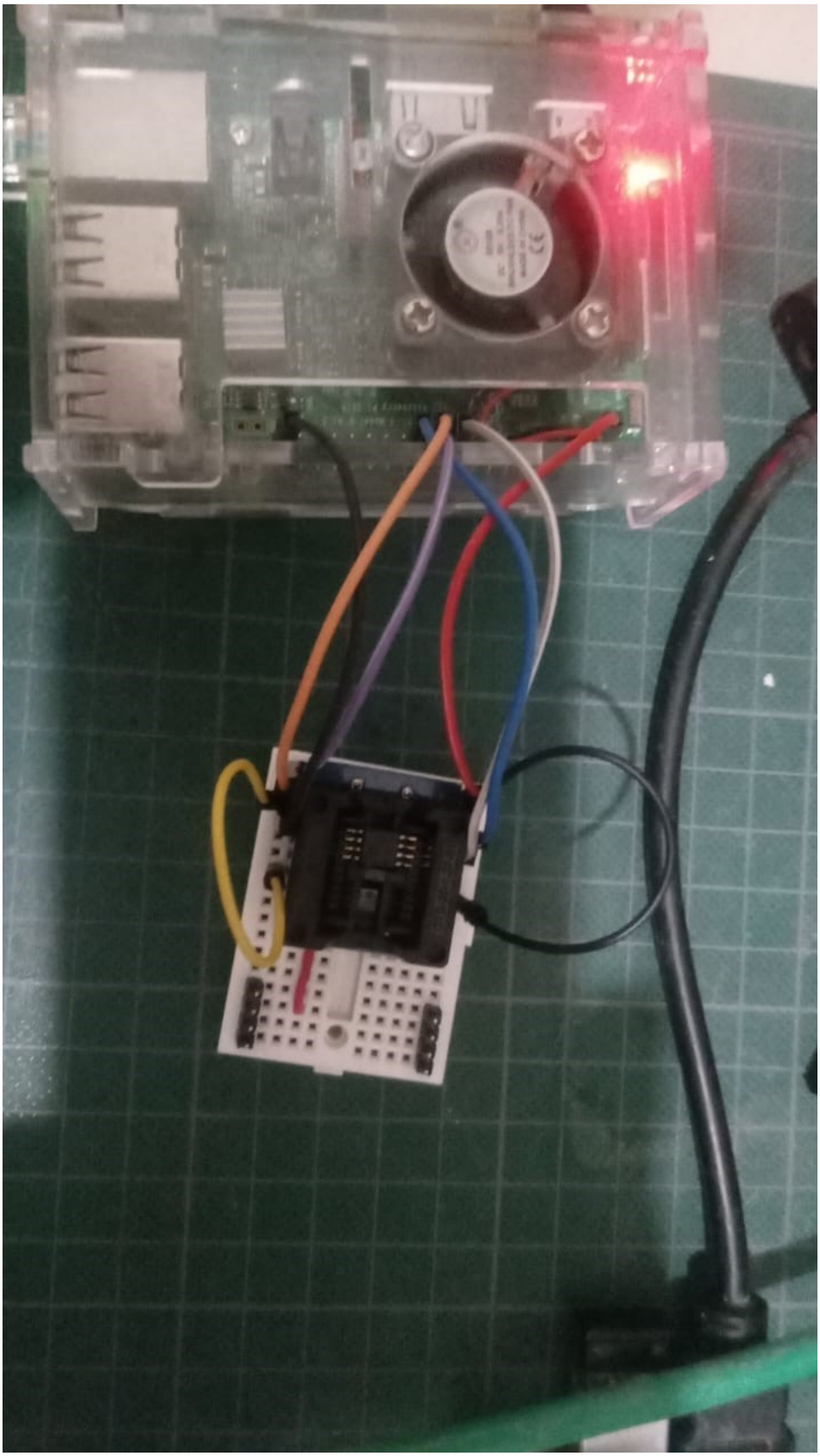


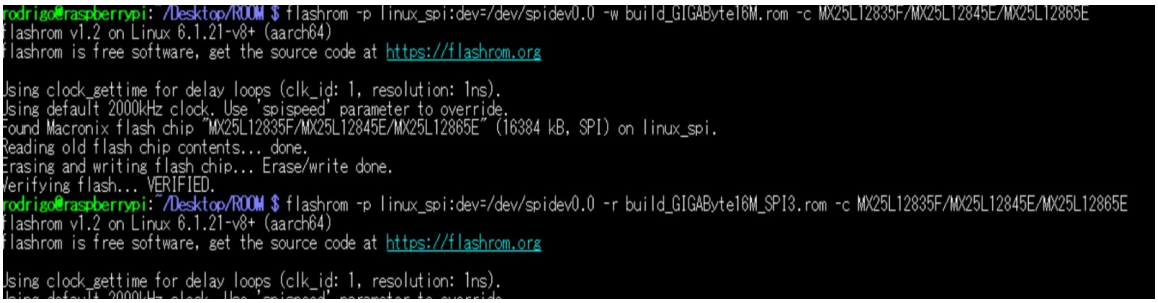
ProjectIoT123.com

check for the pin #1 in the ice marked by circle

s


SCLK
RESET#/SIO3
VCC
SI/SIO0
8
7
6
5
1
2
3
4
CS#
GND
SO/SIO1
WP#/SIO2





construya el archivo BIOS con 16 megas en mente 0x100 000 es igual a 16 megabytes 0x800 000 es 8 megabytes 0x40 000 es 4 megabytes

usaremso una combinacion de 16 megabytes para el tamaño de la ROM y 0x80 000 para el tamaño del CBFS (la mitad de la ROM)

nota: **si recibe un mensaje de error al grabar el IC no force la escritura en la memoria SPI, esto puede dañar al componente, corrija el archivo en la compilación antes de continuar**

use la opcion de lectura sin especificar el tipo de integrado para detectar el IC

flashrom -p linux_spi:dev=/dev/spidev0.0 -r build_GIGAByte16M_SPI.rom -c MX25L12835F/MX25L12845E/MX25L12865E

aplique la opcion de borrado antes de grabar el nuevo contenido

flashrom -p linux_spi:dev=/dev/spidev0.0 -E -c MX25L12835F/MX25L12845E/MX25L12865E

flashrom -p linux_spi:dev=/dev/spidev0.0 -w build_GIGAByte16M.rom -c MX25L12835F/MX25L12845E/MX25L12865E

Macronix MX25L12835F/ PREW 16384 SPI

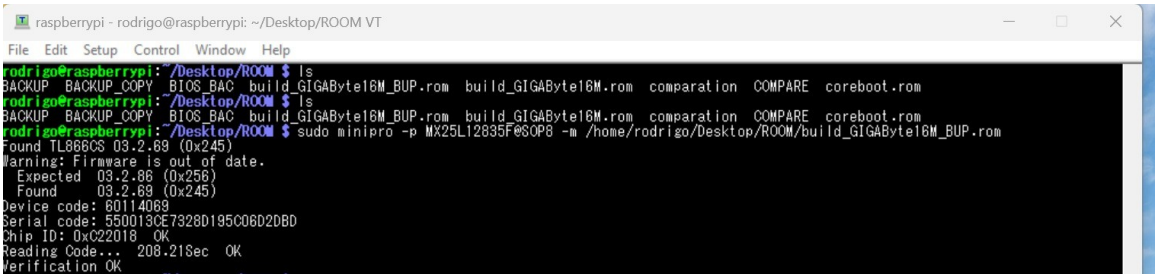
MX25L12845E/

MX25L12865E

nota: **si recibe un mensaje de error al grabar el IC no force la escritura en la memoria SPI, esto puede dañar al componente, corrija el archivo en la compilación antes de continuar**

minipro -p MX25L12835F@SOP8 -w /home/rodrigo/Desktop/ROOM/build_GIGABYTE.rom

minipro -p MX25L12835F@SOP8 -r /home/rodrigo/Desktop/ROOM/build_GIGABYTE_BUP.rom



diff Desktop/ROOM/coreboot.rom Desktop/ROOM/comparation -s

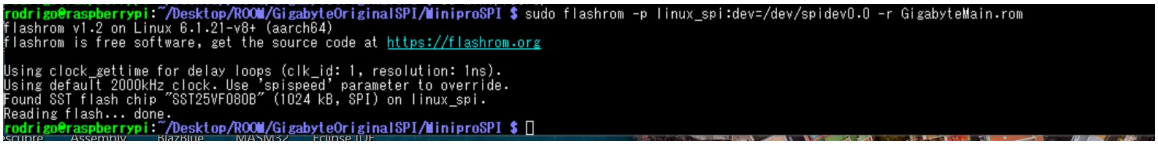
cmp Desktop/ROOM/BACKUP Desktop/ROOM/BACKUP -l

hexdump Desktop/ROOM/coreboot.rom

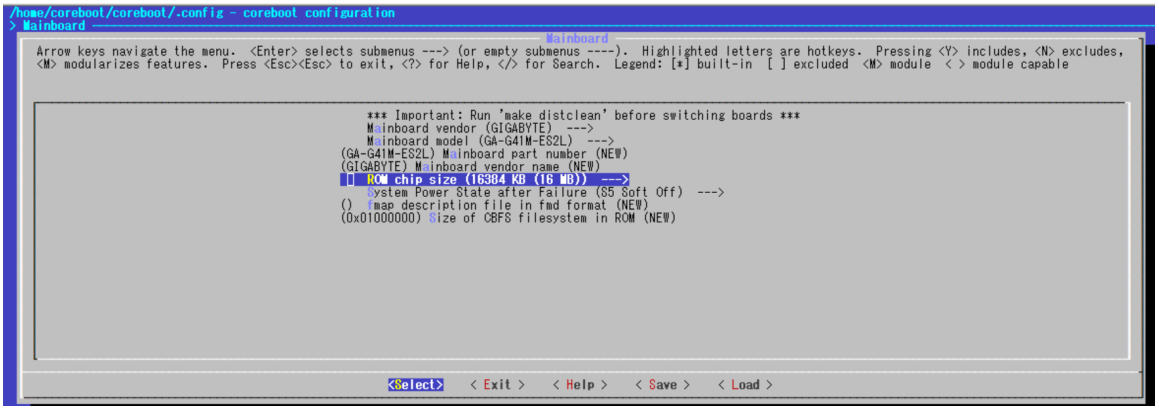
md5sum Desktop/ROOM/BACKUP

sudo minipro -p SST25VF080B -r GigabyteBackupMP.rom

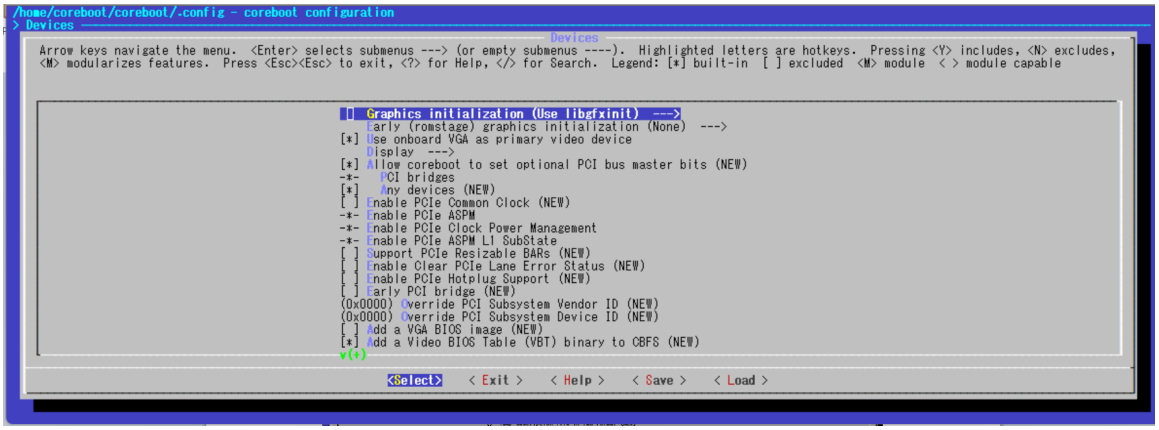
sudo flashrom -p linux_spi:dev=/dev/spidev0.0 -r GigabyteMain.rom



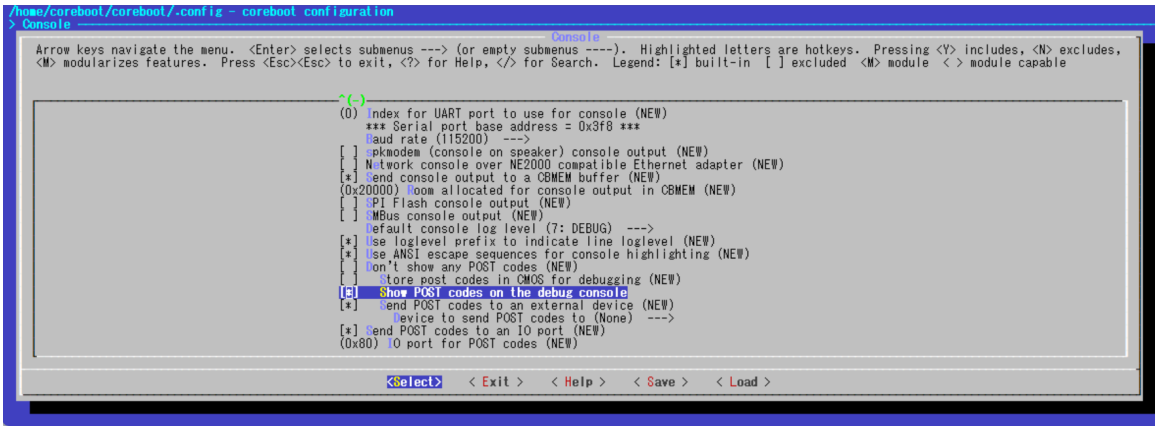
MainBoard: Elegimos el nombre del fabricante, el modelo de la tarjeta y el tamaño del IC de SPI la opción de CBFS que sea 1 000 000, guardamos los cambios (importante)



Devices: Habilitamos la segunda opción "VGA as primary device" con sus opciones por defecto (frame buffer text), guardamos los cambios

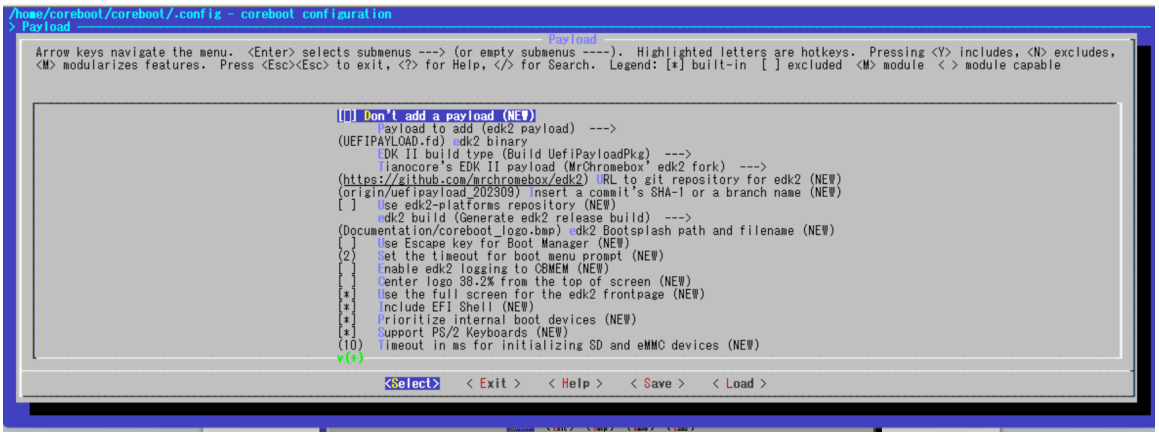


Console: habilitamos la opcion "SHOW post codes on debug console " y guardamos cambios



Payload: Elegimos UEFI payload e indicamos la dirección del archivo de Payload UEFIPAYLOAD.fd (version

32-64 revisar EDK2 compilacion)



UEFIPAYLOAD32.fd no usaremos esta