My Project

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# **Class Index**

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Here are the classes, structs, unions and interfaces with brief descriptions:					
Point	Ę				

2 Class Index

# File Index

### 2.1 File List

Here is a list of all files with brief descriptions:

geometry.cpp																					7	7
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File Index

## **Class Documentation**

#### 3.1 Point Struct Reference

```
#include <geometry.h>
```

#### **Public Attributes**

- float x
- float y

#### 3.1.1 Detailed Description

Struct to facilitate manipulation of x and y coordinates.

#### 3.1.2 Member Data Documentation

```
3.1.2.1 x float Point::x
```

### 3.1.2.2 y

float Point::y

The documentation for this struct was generated from the following file:

• geometry.h

6 Class Documentation

## **File Documentation**

### 4.1 geometry.cpp File Reference

```
#include "geometry.h"
```

#### **Functions**

- float orientationTriangleArea (Point a, Point b, Point c)
- int intersection (void)
- void savePair (Point p1, Point p2)

#### 4.1.1 Function Documentation

#### 4.1.1.1 intersection()

```
void intersection (
     void )
```

Computes if there is an intersection between all pairs of segments.

If the intersection exists, its coordinates are calculated. It uses the orientation method to determine whether the points are on different sides

#### 4.1.1.2 orientationTriangleArea()

```
float orientationTriangleArea (  \begin{array}{ccc} {\tt Point} \ a, \\ {\tt Point} \ b, \\ {\tt Point} \ c \ ) \end{array}
```

Computes twice the signed area of the orientation triangle. If it is oriented counterclockwise, the area is positive. Otherwise, it is negative.

#### **Parameters**

а	a Point struct
b	a Point struct
С	a Point struct

#### Returns

Two times the area of the orientation triangle

#### 4.1.1.3 savePair()

```
void savePair (  \begin{array}{c} {\tt Point} \ p{\tt 1}, \\ {\tt Point} \ p{\tt 2} \end{array} )
```

Saves a pair of points (starting point and end point) of a segment.

It saves the pair of points in a vector.

#### **Parameters**

p1	a Point struct
p2	a Point struct

### 4.2 geometry.h File Reference

```
#include <vector>
#include <iostream>
#include <GL/glut.h>
```

#### Classes

• struct Point

#### **Functions**

- float orientationTriangleArea (Point a, Point b, Point c)
- int intersection (void)
- void savePair (Point p1, Point p2)

#### **Variables**

- Point p1
- Point p2
- vector< pair< Point, Point >> points
- vector< Point > intersectionPoints
- · int click\_counter

#### 4.2.1 Function Documentation

#### 4.2.1.1 intersection()

```
int intersection (
    void )
```

Computes if there is an intersection between all pairs of segments.

If the intersection exists, its coordinates are calculated. It uses the orientation method to determine whether the points are on different sides

#### 4.2.1.2 orientationTriangleArea()

```
float orientationTriangleArea (  \begin{array}{ccc} {\tt Point} \ a, \\ {\tt Point} \ b, \\ {\tt Point} \ c \ ) \end{array}
```

Computes twice the signed area of the orientation triangle. If it is oriented counterclockwise, the area is positive. Otherwise, it is negative.

#### **Parameters**

а	a Point struct
b	a Point struct
С	a Point struct

#### Returns

Two times the area of the orientation triangle

#### 4.2.1.3 savePair()

```
void savePair (  \begin{array}{c} \text{Point } p1, \\ \text{Point } p2 \end{array} )
```

Saves a pair of points (starting point and end point) of a segment.

It saves the pair of points in a vector.

#### **Parameters**

p1	a Point struct
p2	a Point struct

#### 4.2.2 Variable Documentation

#### 4.2.2.1 click\_counter

int click\_counter

#### 4.2.2.2 intersectionPoints

vector<Point> intersectionPoints

#### 4.2.2.3 p1

Point p1

#### 4.2.2.4 p2

Point p2

#### 4.2.2.5 points

vector<pair<Point,Point> > points

### 4.3 main.cpp File Reference

#include "geometry.h"

#### **Functions**

- void changeSize (int w, int h)
- void myMouse (int button, int state, int x, int y)
- void renderScene (void)
- int main (int argc, char \*\*argv)

#### **Variables**

- float width = 640
- float height = 480
- int click\_counter = 0
- Point p1
- Point p2
- vector< pair< Point, Point >> points
- vector< Point > intersectionPoints

#### 4.3.1 Detailed Description

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#### 4.3.2 Function Documentation

#### 4.3.2.1 changeSize()

```
void changeSize ( \inf \ w, \inf \ h \ )
```

Resizes the viewport when the window size changes.

#### **Parameters**

W	an integer variable
h	an integer variable

#### 4.3.2.2 main()

```
int main (
```

```
int argc,
char ** argv )
```

#### 4.3.2.3 myMouse()

Callback function that gets mouse coordinates and button state.

#### **Parameters**

button	an integer variable
state	an integer variable
X	an integer variable
У	an integer variable

#### 4.3.2.4 renderScene()

```
void renderScene (
    void )
```

Callback function to render OpenGL scene and draw the segments and intersections.

#### 4.3.3 Variable Documentation

#### 4.3.3.1 click\_counter

```
int click_counter = 0
```

#### 4.3.3.2 height

```
float height = 480
```

#### 4.3.3.3 intersectionPoints

vector<Point> intersectionPoints

4.3.3.4 p1

Point p1

4.3.3.5 p2

Point p2

#### 4.3.3.6 points

vector<pair<Point,Point> > points

#### 4.3.3.7 width

float width = 640

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