



EECE 4353 Image Processing

Lecture Notes: Color Correction

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Fall Semester 2016





Color Correction

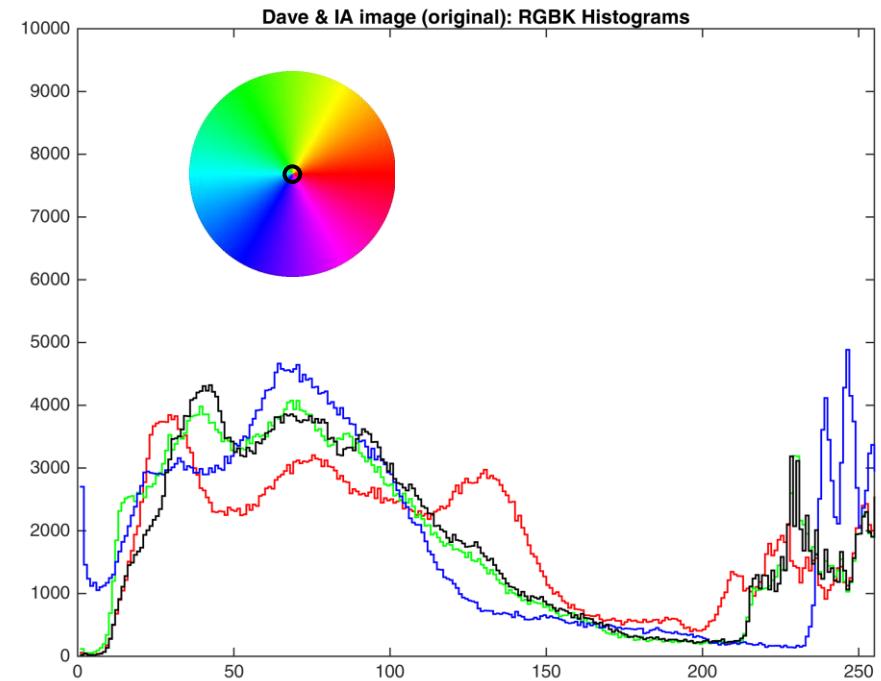
is a global change in the coloration of an image to alter its tint, its hues, or the saturation of its colors with minimal changes to its luminant features.





Gamma Adjustment of Color Bands

original

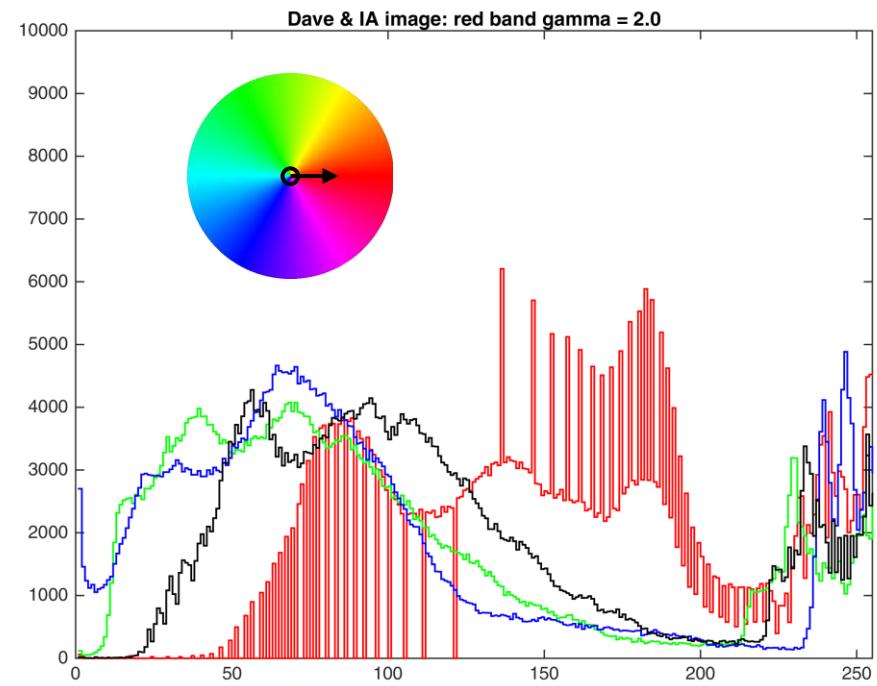


David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



Gamma Adjustment of Color Bands

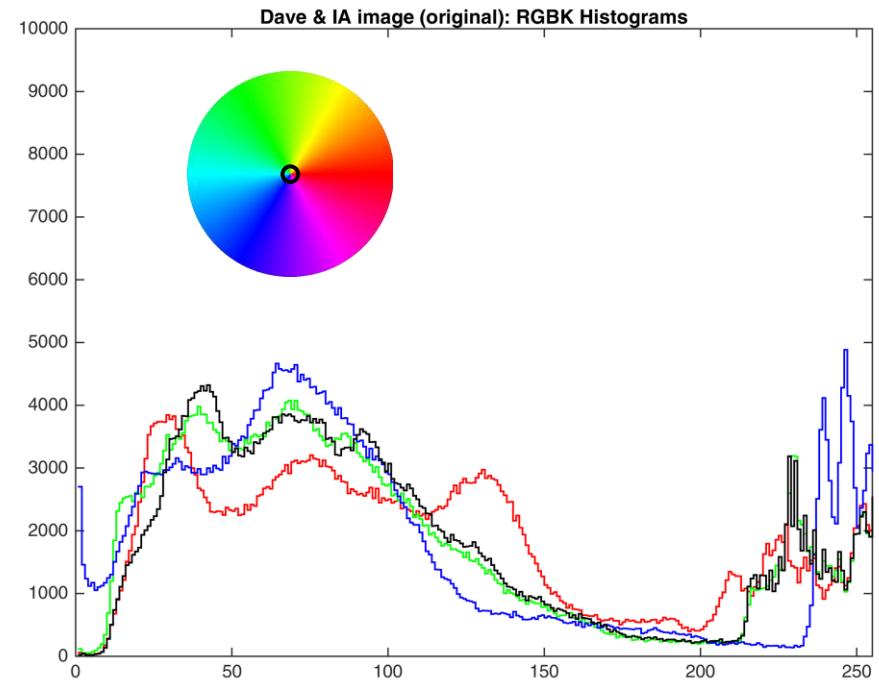
red $\gamma=2$





Gamma Adjustment of Color Bands

original

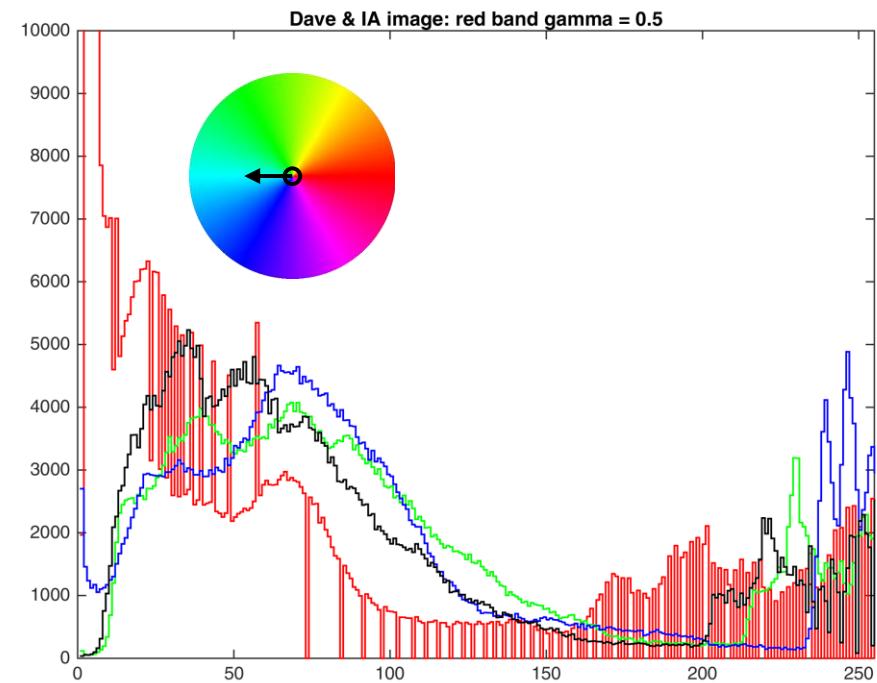


David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



Gamma Adjustment of Color Bands

red $\gamma=0.5$

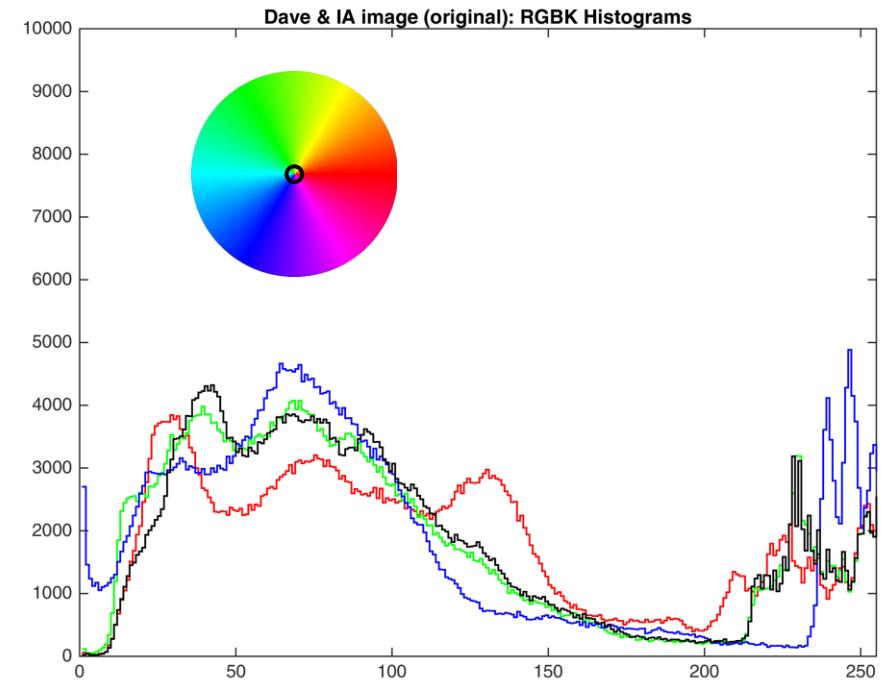


reduced red = increased cyan



Gamma Adjustment of Color Bands

original

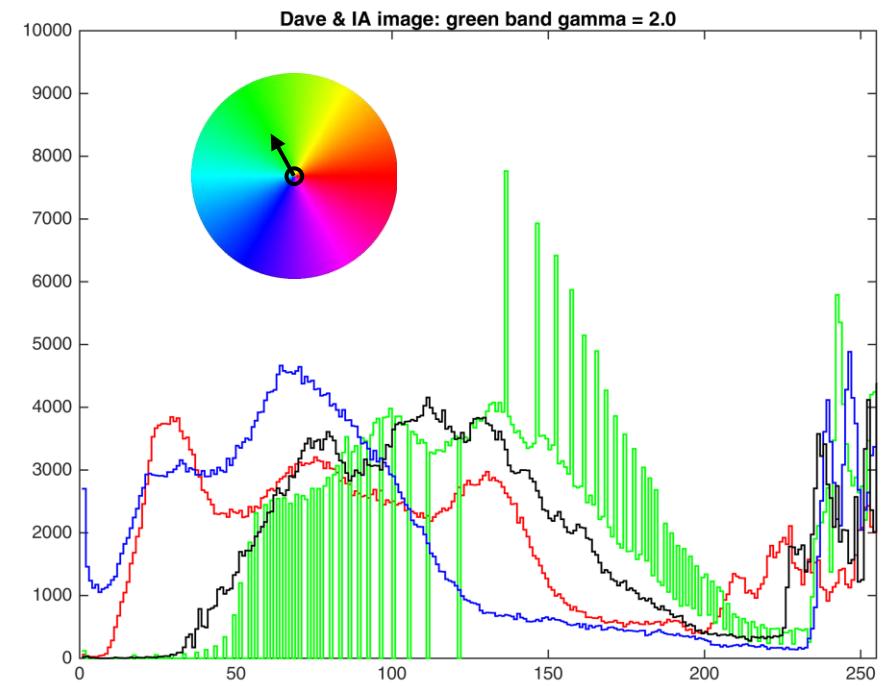


David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



Gamma Adjustment of Color Bands

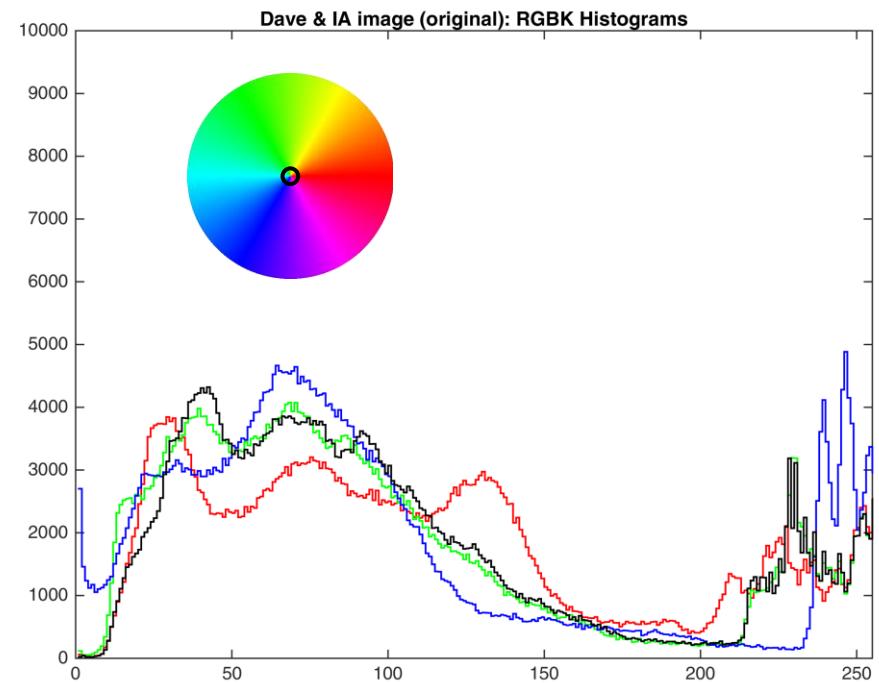
green $\gamma=2$





Gamma Adjustment of Color Bands

original

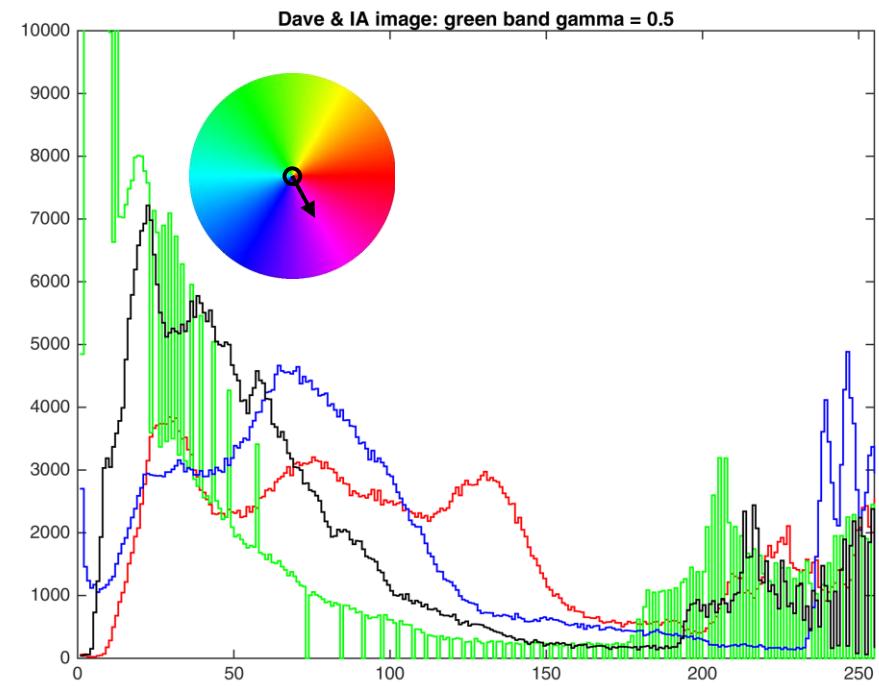


David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



Gamma Adjustment of Color Bands

green $\gamma=0.5$

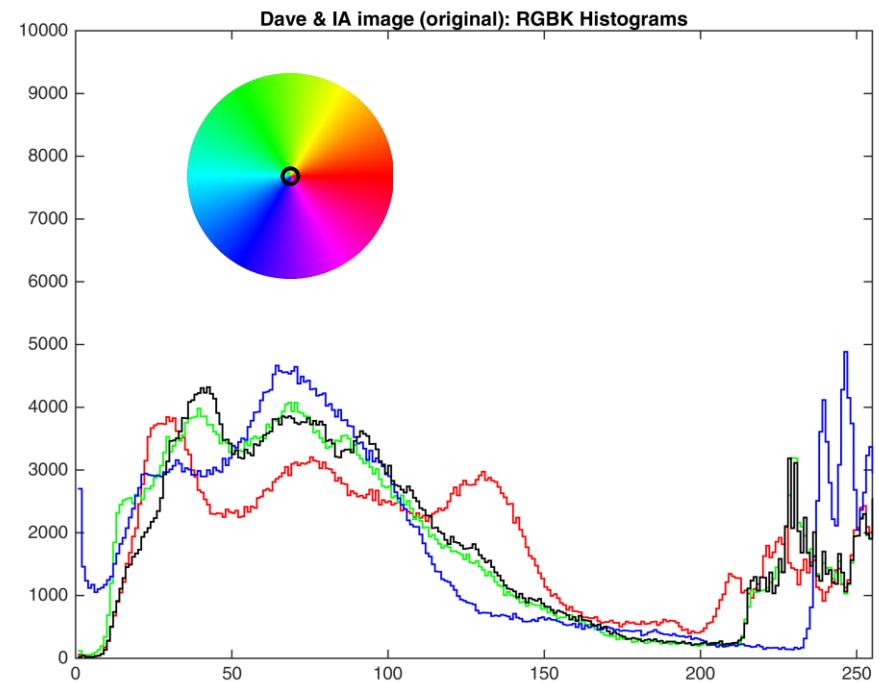


reduced green = incr. magenta



Gamma Adjustment of Color Bands

original

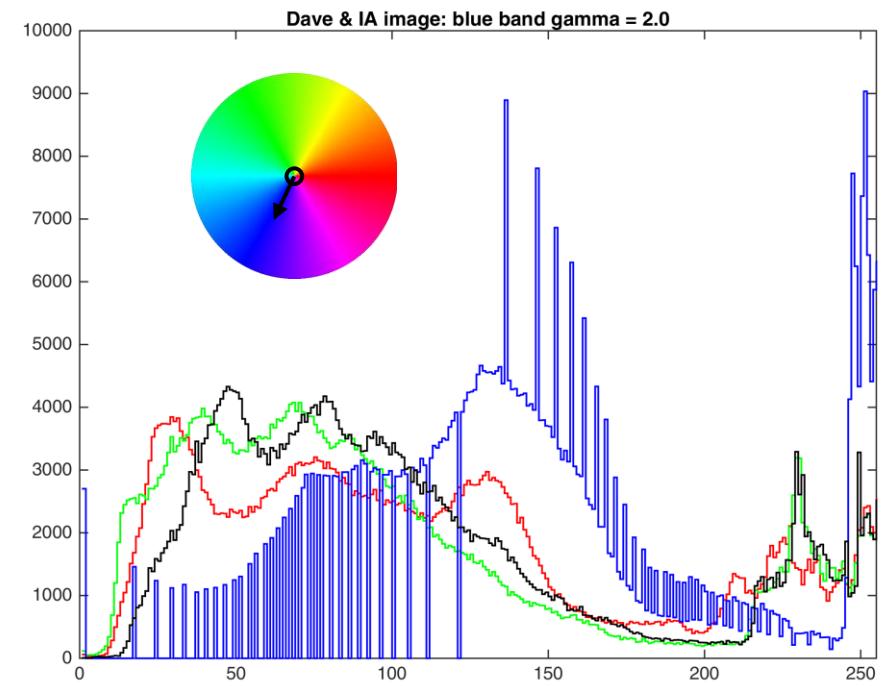


David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



Gamma Adjustment of Color Bands

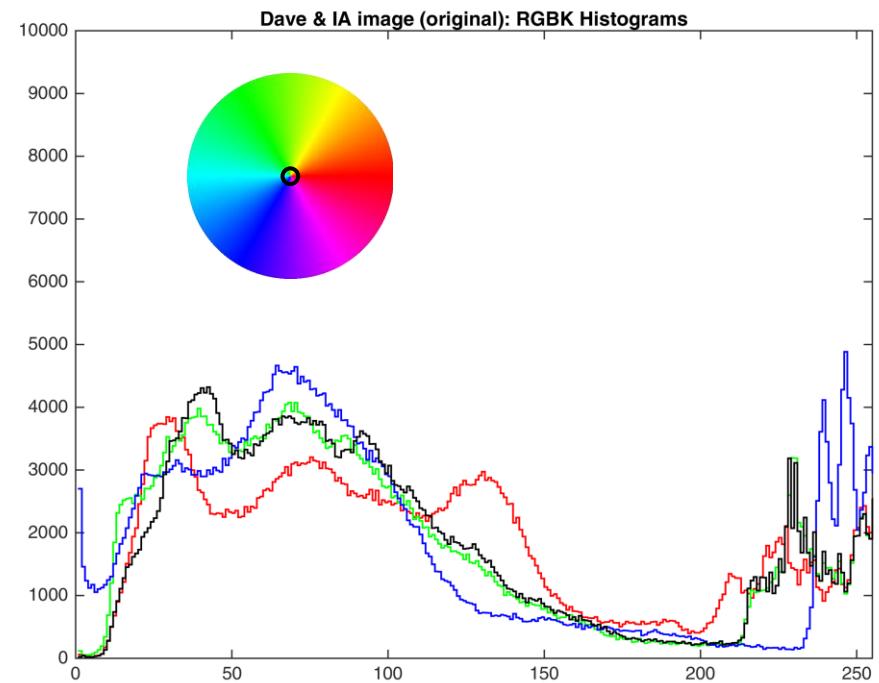
blue $\gamma=2$





Gamma Adjustment of Color Bands

original

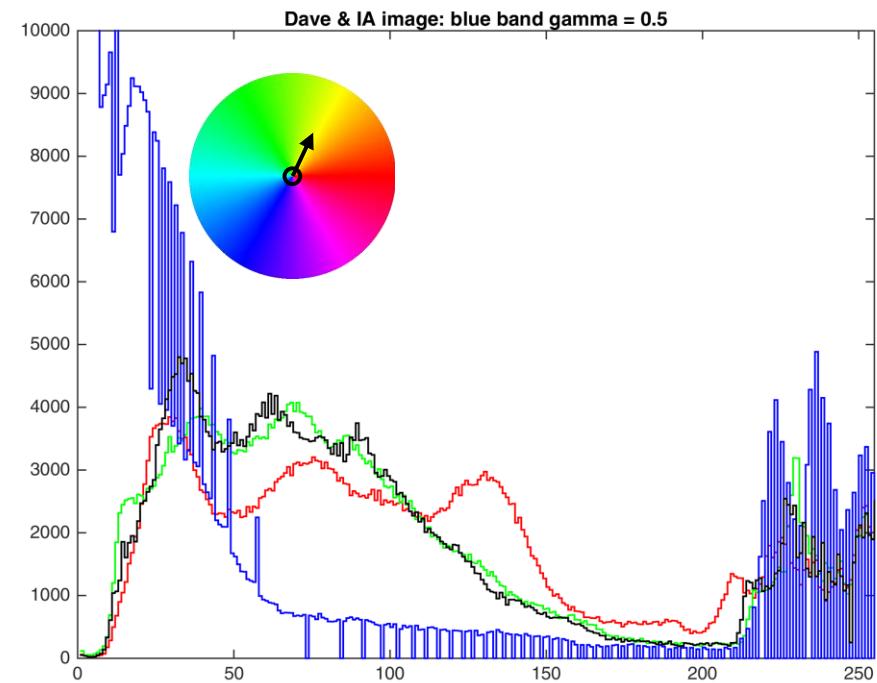


David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



Gamma Adjustment of Color Bands

blue $\gamma=0.5$

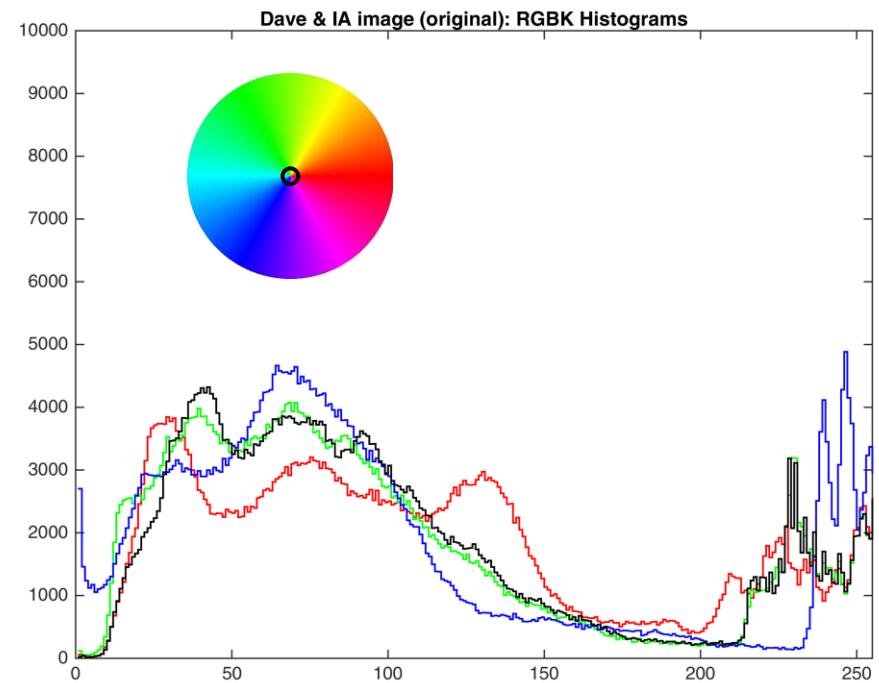


reduced blue = incr. yellow



Gamma Adjustment of Color Bands

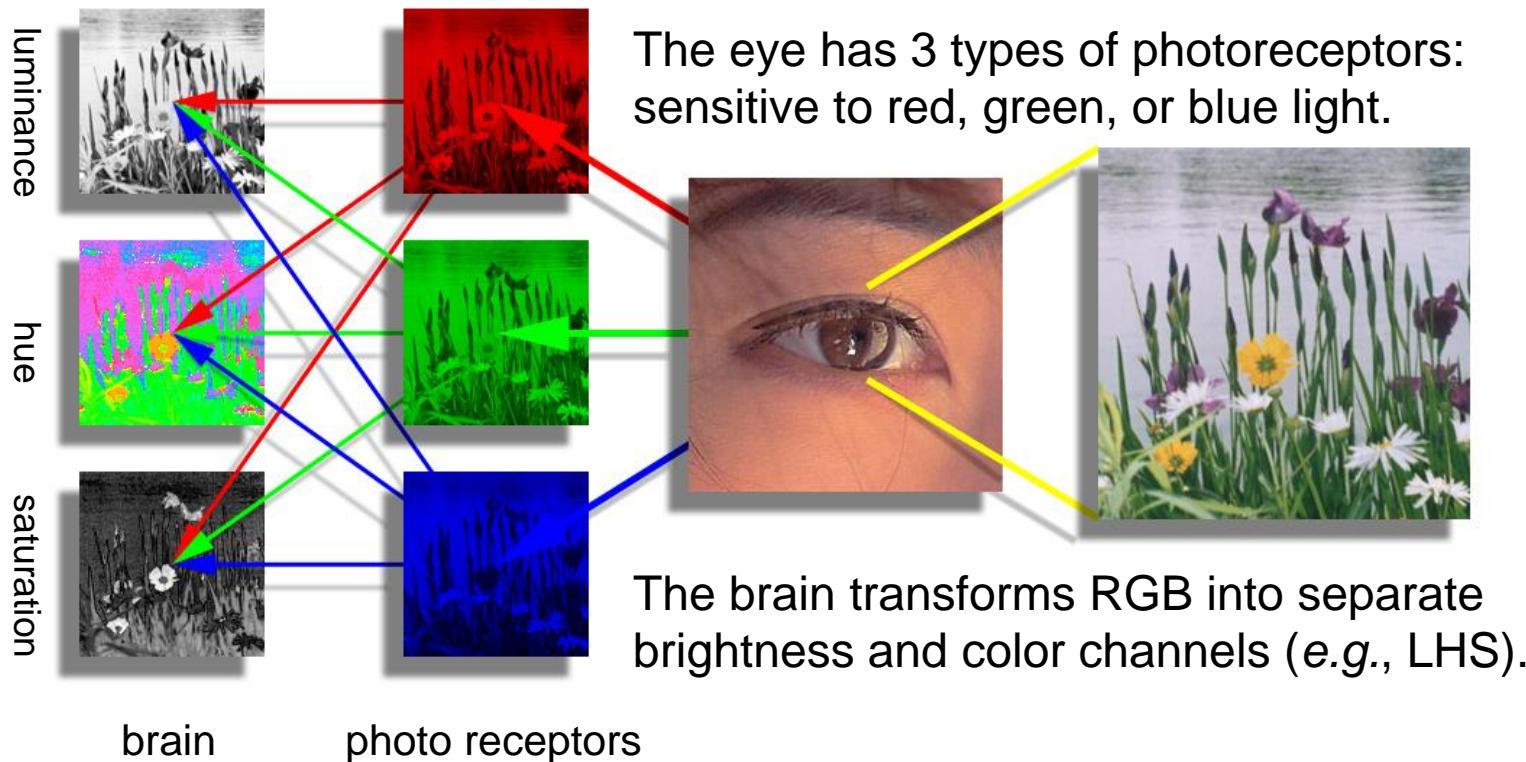
original



David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).

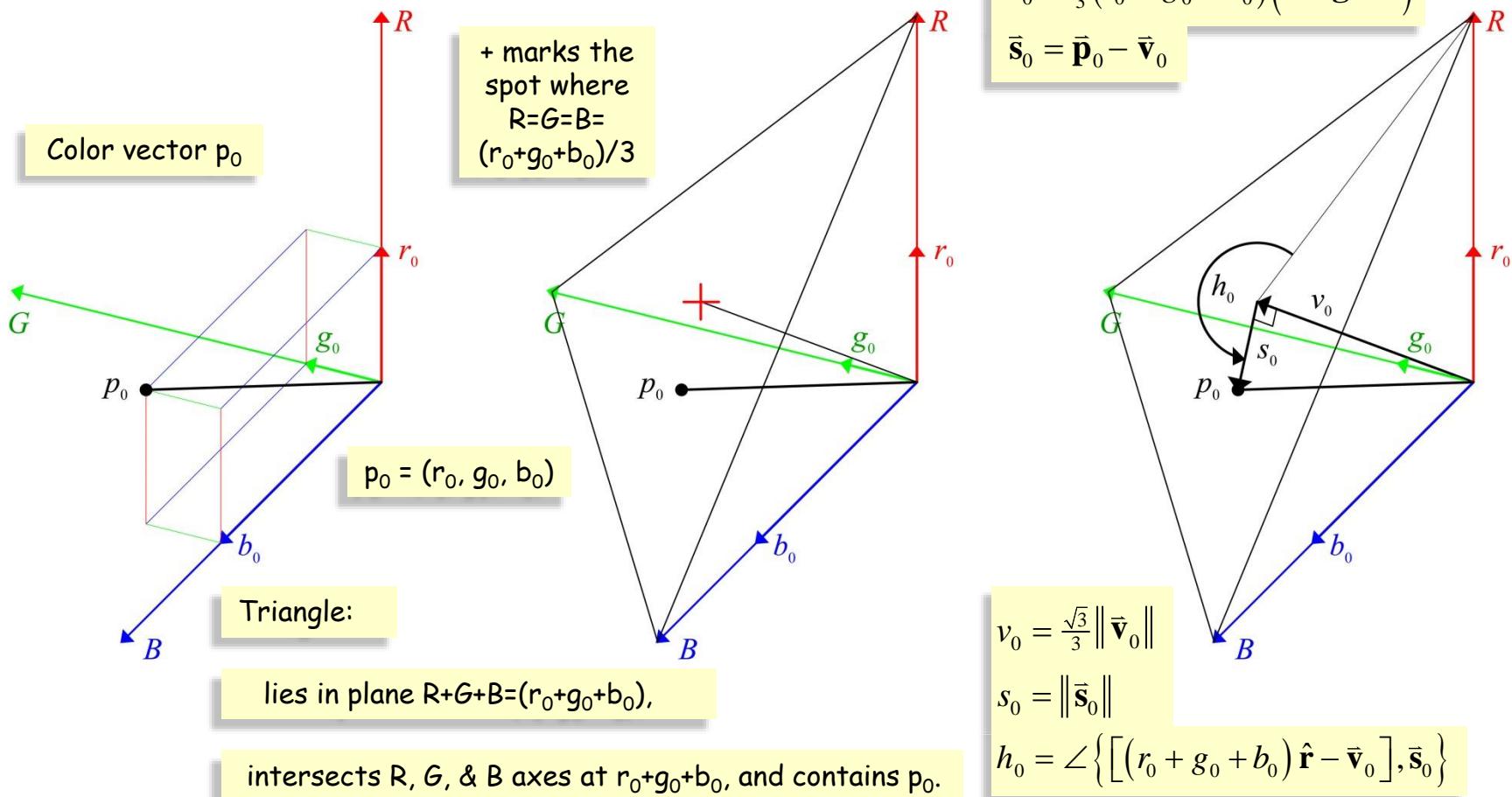


RGB to LHS: A Perceptual Transformation





HSV Color Representation





$\|\cdot\|$ is the norm operator - the square root of the pixel-wise sum of the squares of the image intensity components.

RGB to HSV Algorithm

A vector-geometric algorithm

1. Compute scalar value image, \mathbf{v} , from RGB image, $\mathbf{I} = [\mathbf{r} \ \mathbf{g} \ \mathbf{b}]^T$.
2. Compute vector value image, $\mathbf{v} = [\mathbf{v} \ \mathbf{v} \ \mathbf{v}]^T$.
3. Compute vector saturation image, $\mathbf{s} = \mathbf{I} - \mathbf{v}$.
4. Compute scalar saturation image, $s = \|\mathbf{s}\|$.
5. Compute red axis vector image, $\mathbf{x} = [2\mathbf{v} \ -\mathbf{v} \ -\mathbf{v}]^T$.
6. Compute red axis scalar image, $\mathbf{x} = \|\mathbf{x}\|$.
7. Create an indicator image, $\mathbf{z}(r,c) = \mathbf{s}(r,c) == 0$.
8. Compute hue cosine image, $\mathbf{c} = (\mathbf{s} \cdot \mathbf{x}) / ((\mathbf{s} + \mathbf{z}) \cdot \mathbf{x})$.
9. Compute hue angle image, $\mathbf{h} = \cos^{-1}(\mathbf{c})$.
10. Create an indicator image, $\mathbf{m}(r,c) = \mathbf{b}(r,c) > \mathbf{g}(r,c)$.
11. Adjust $\mathbf{h} = \sim \mathbf{m} \cdot \mathbf{h} + \mathbf{m} \cdot (2\pi - \mathbf{h})$.
12. Scale $\mathbf{s} = \mathbf{s} / 208.2066$.
13. Return $[\mathbf{h} \ \mathbf{s} \ \mathbf{v}]^T$.

$\mathbf{s} \cdot \mathbf{x}$ is the pixel-wise dot product of images \mathbf{s} & \mathbf{x} .

\mathbf{z} and \mathbf{m} are binary images
 $\mathbf{z}(r,c) == 1$ iff $\mathbf{s}(r,c) == 0$;
 $\mathbf{m}(r,c) == 1$ iff $\mathbf{b}(r,c) > \mathbf{g}(r,c)$.



HSV to RGB Conversion

Therefore, the rotation matrix is

$$A = \frac{\sqrt{6}}{6} \begin{bmatrix} 2 & 0 & \sqrt{2} \\ -1 & \sqrt{3} & \sqrt{2} \\ -1 & -\sqrt{3} & \sqrt{2} \end{bmatrix}.$$

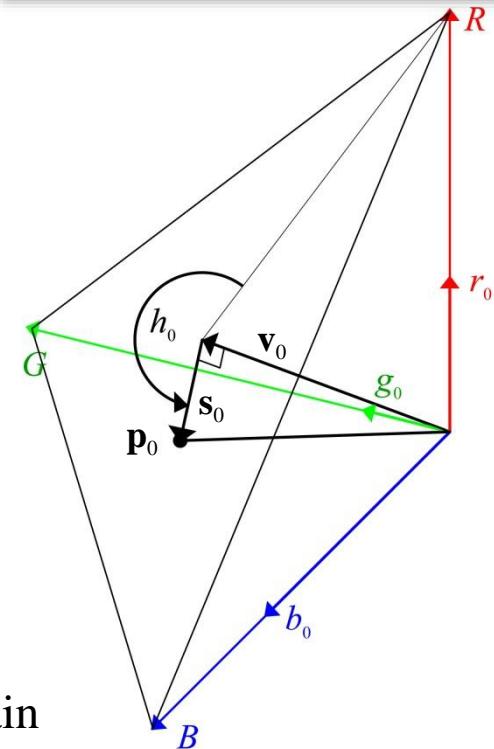
Substitute that into the 2nd equation on slide [94](#) to get:

$$\begin{aligned} [\mathbf{s}]_{\text{rgb}} &= s \frac{\sqrt{6}}{6} \cos(h) \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix} + s \frac{\sqrt{2}}{2} \sin(h) \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + 0 \frac{\sqrt{3}}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \\ &= s \frac{\sqrt{6}}{6} \cos(h) \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix} + s \frac{\sqrt{2}}{2} \sin(h) \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}. \end{aligned}$$

Finally, $[\mathbf{s}]_{\text{rgb}}$ must be translated to the value vector to obtain the rgb color of \mathbf{p}_0 :

$$\mathbf{p}_0 = [\mathbf{p}]_{\text{rgb}} = [\mathbf{s}]_{\text{rgb}} + [\mathbf{v}]_{\text{rgb}}, \text{ where } \mathbf{s}_0 = [\mathbf{s}]_{\text{rgb}} \text{ and } [\mathbf{v}]_{\text{rgb}} = \mathbf{v}_0 \text{ as def'd. on slide } \underline{81}.$$

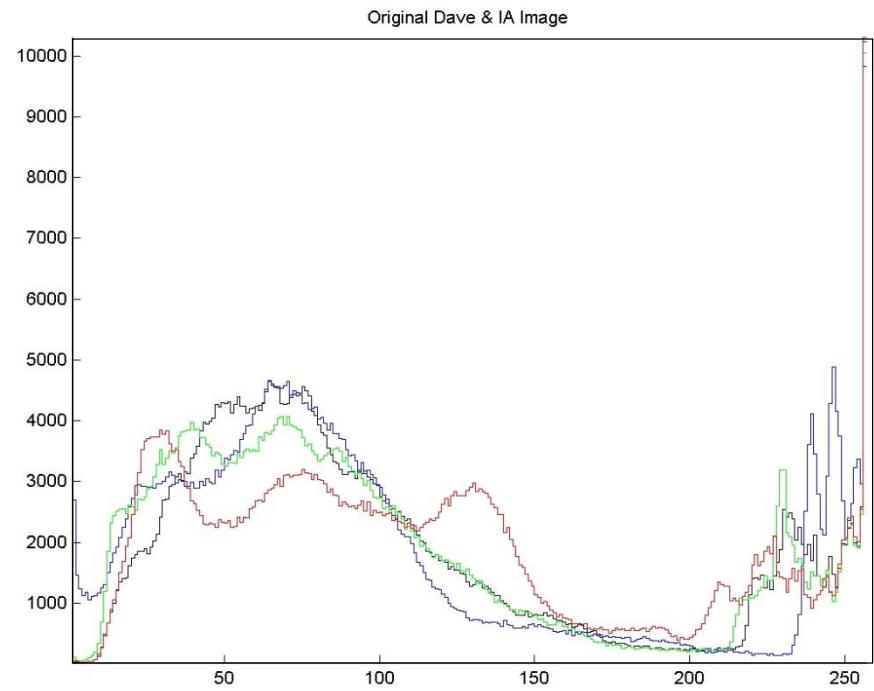
The x, y, & z unit vectors in r, g, & b coordinates are the columns of the rotation matrix:





Saturation Adjustment

original

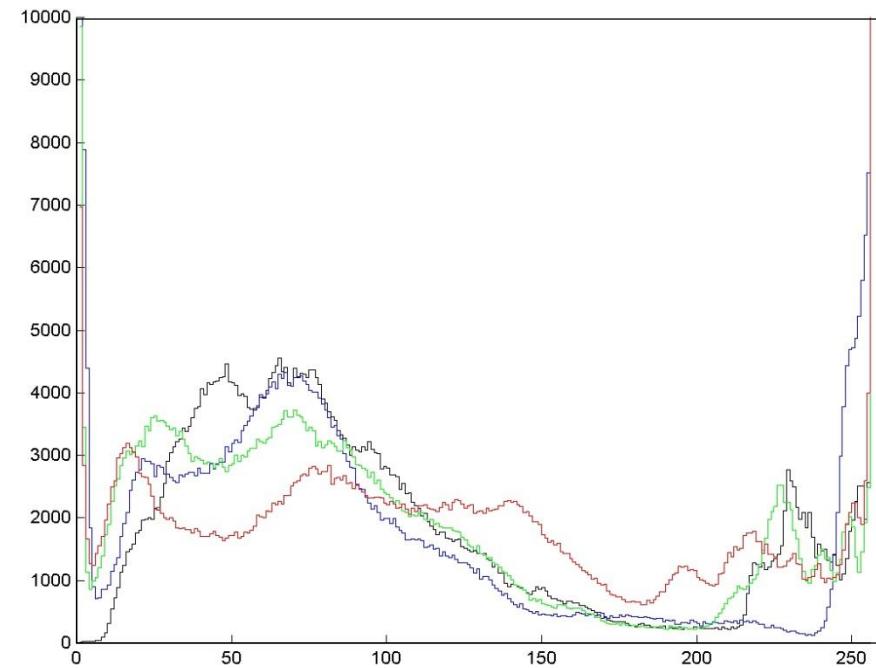




Saturation Adjustment



saturation + 50%

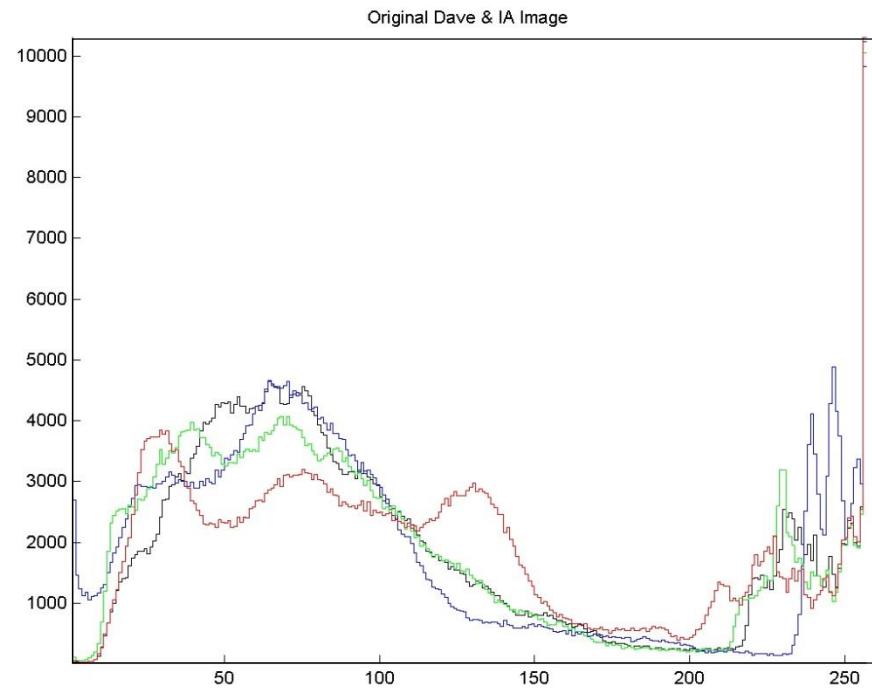


All the colors become
closer to pure primaries.



Saturation Adjustment

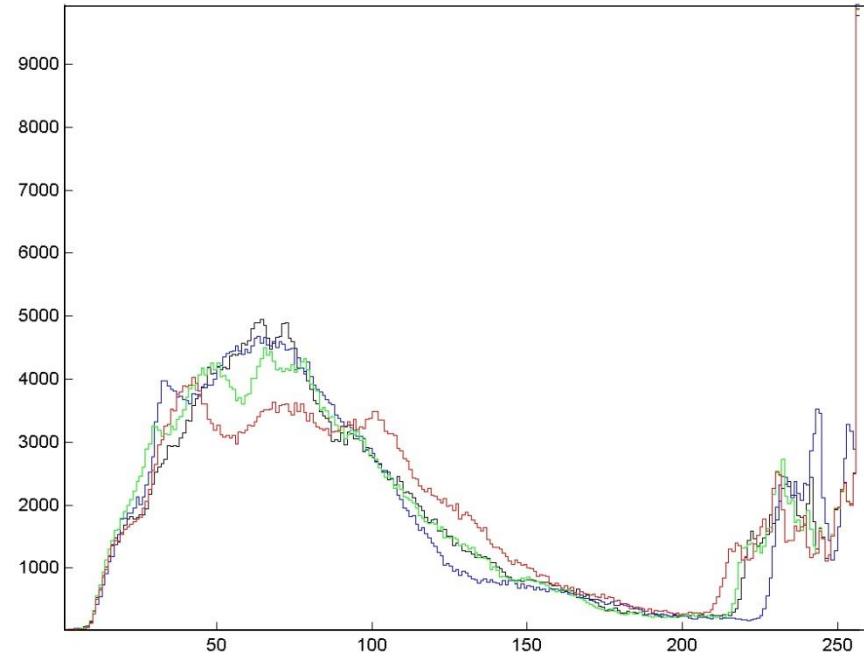
original





Saturation Adjustment

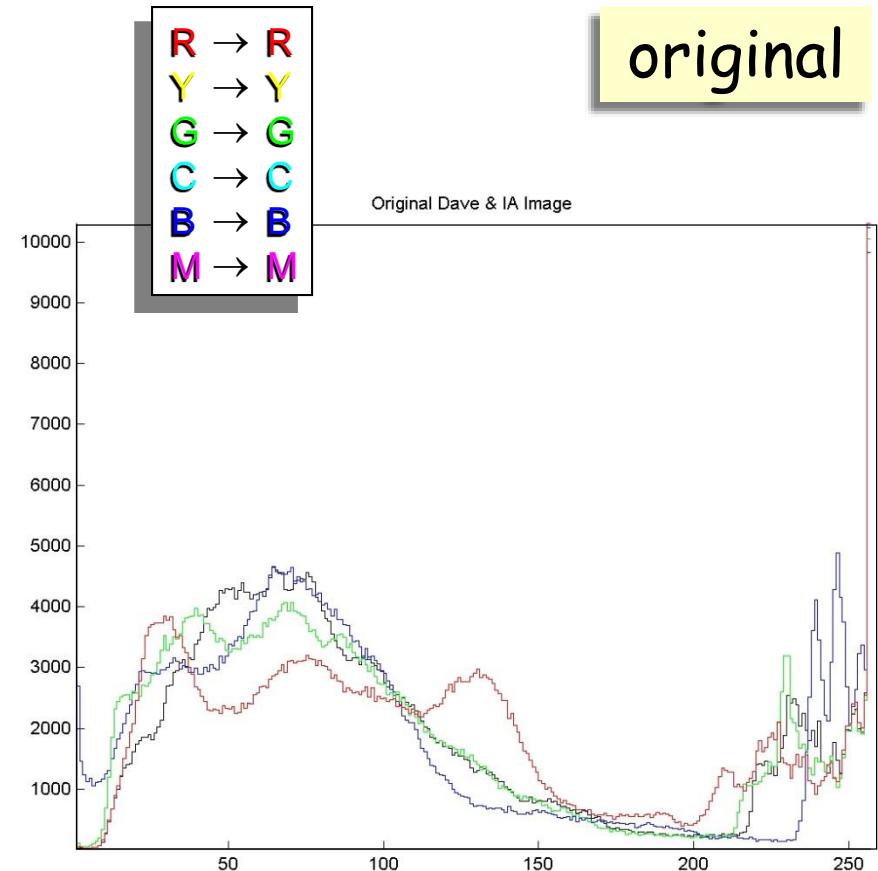
saturation - 50%



The r, g, & b histograms approach the value histogram as the color fades to grayscale.

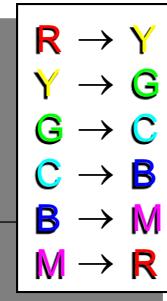


Hue Shifting

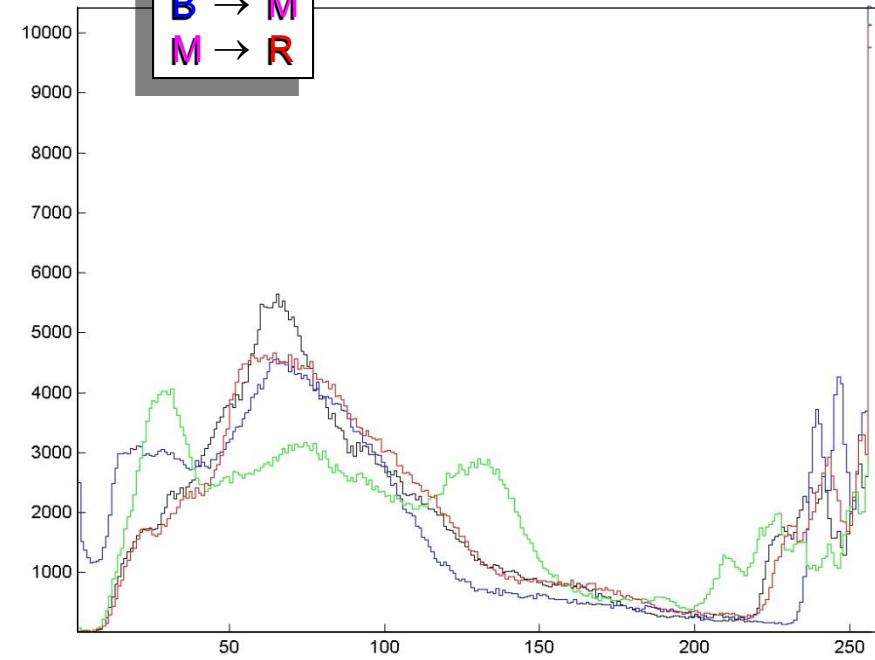




Hue Shifting



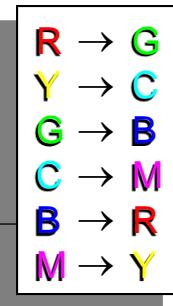
hue + 60°



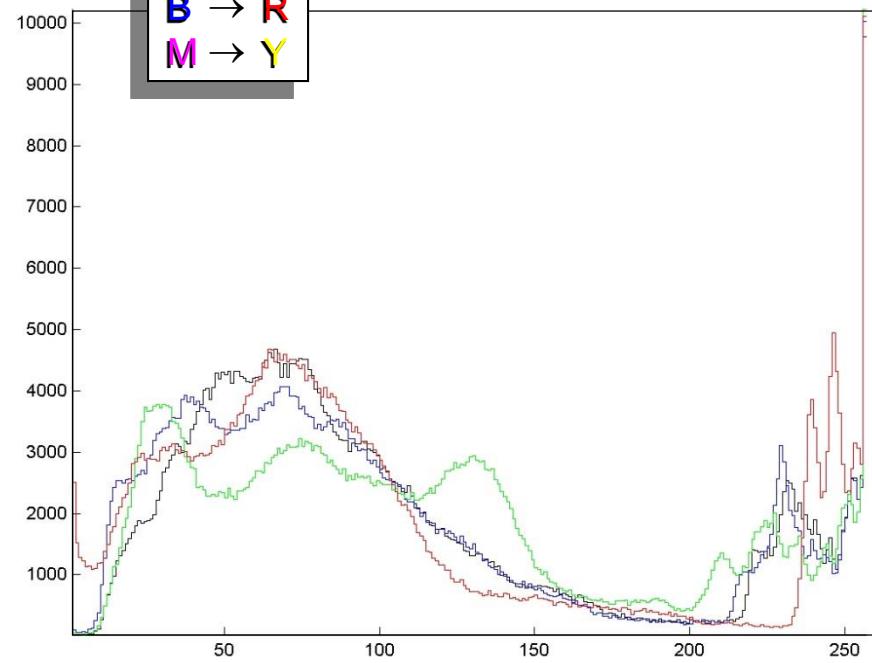
The effects of a hue shift are nonlinear. They are difficult to characterize on the r, g, & b histograms



Hue Shifting

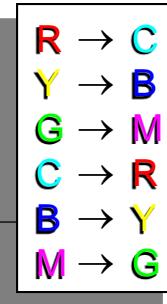
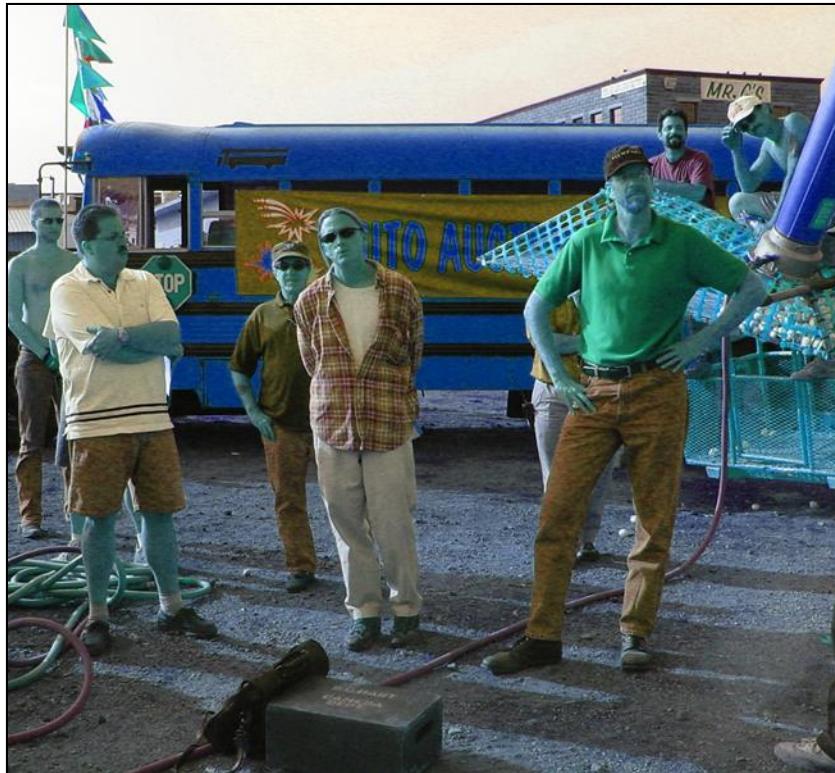


hue + 120°

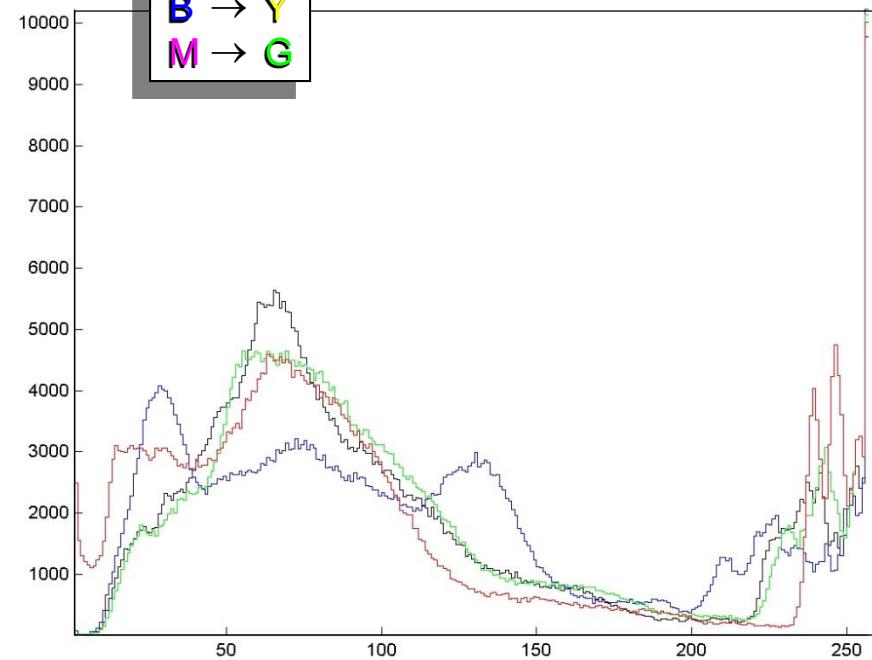




Hue Shifting

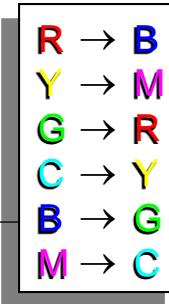


hue + 180°

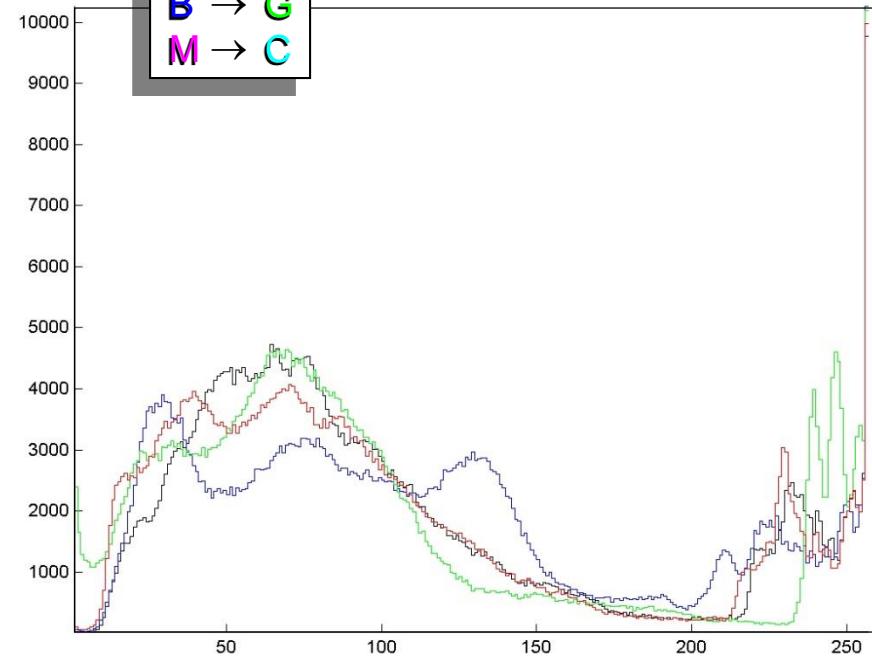




Hue Shifting

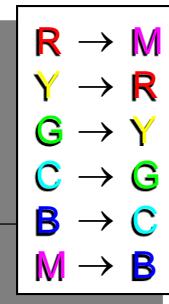


hue + 240°

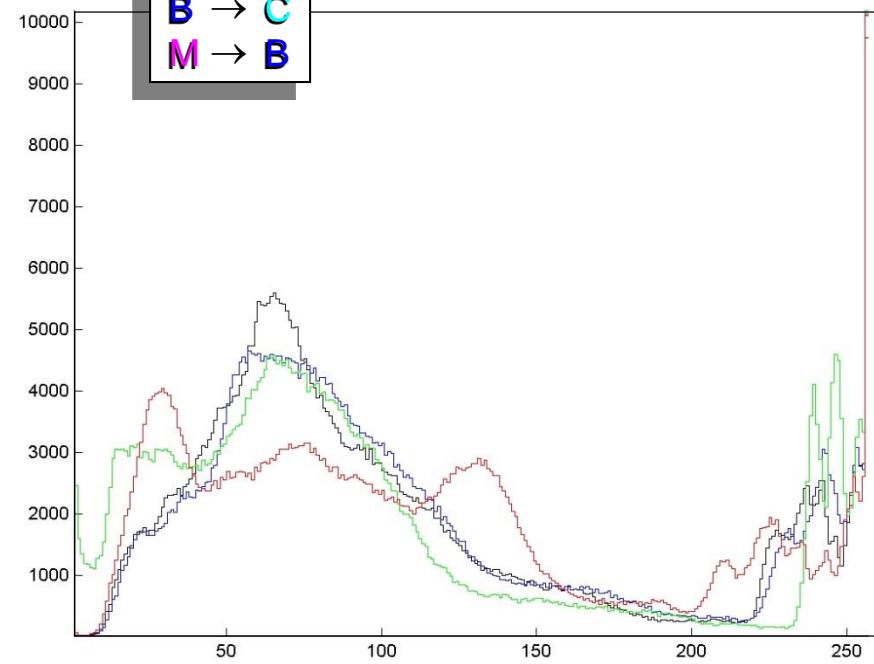




Hue Shifting

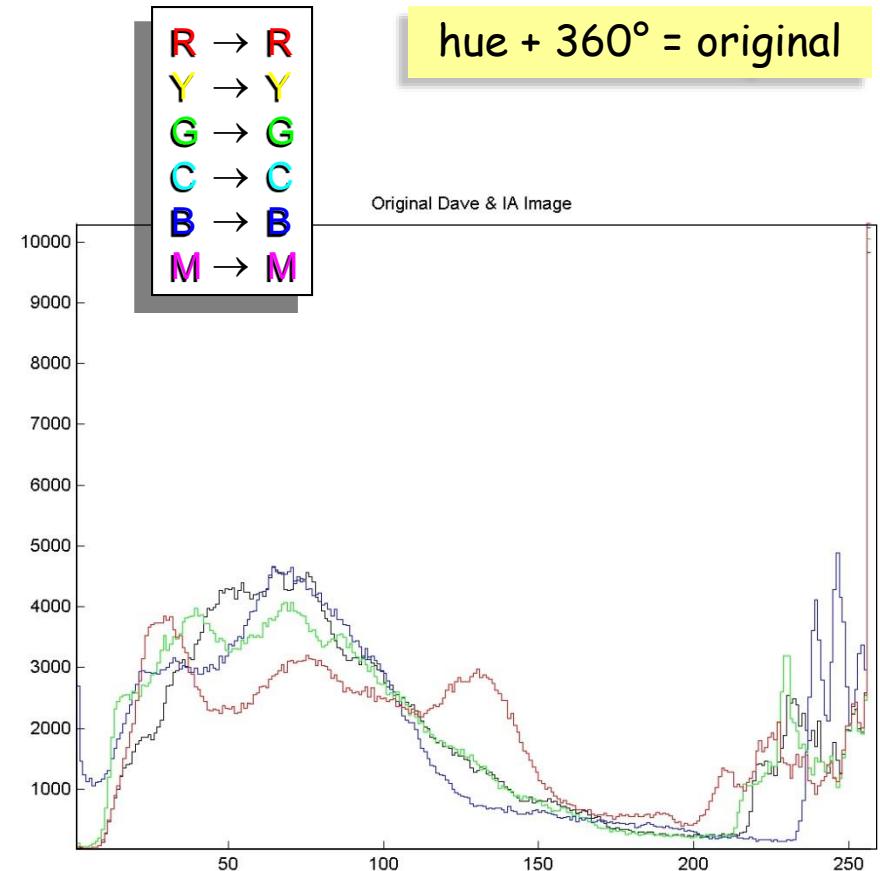


hue + 300°



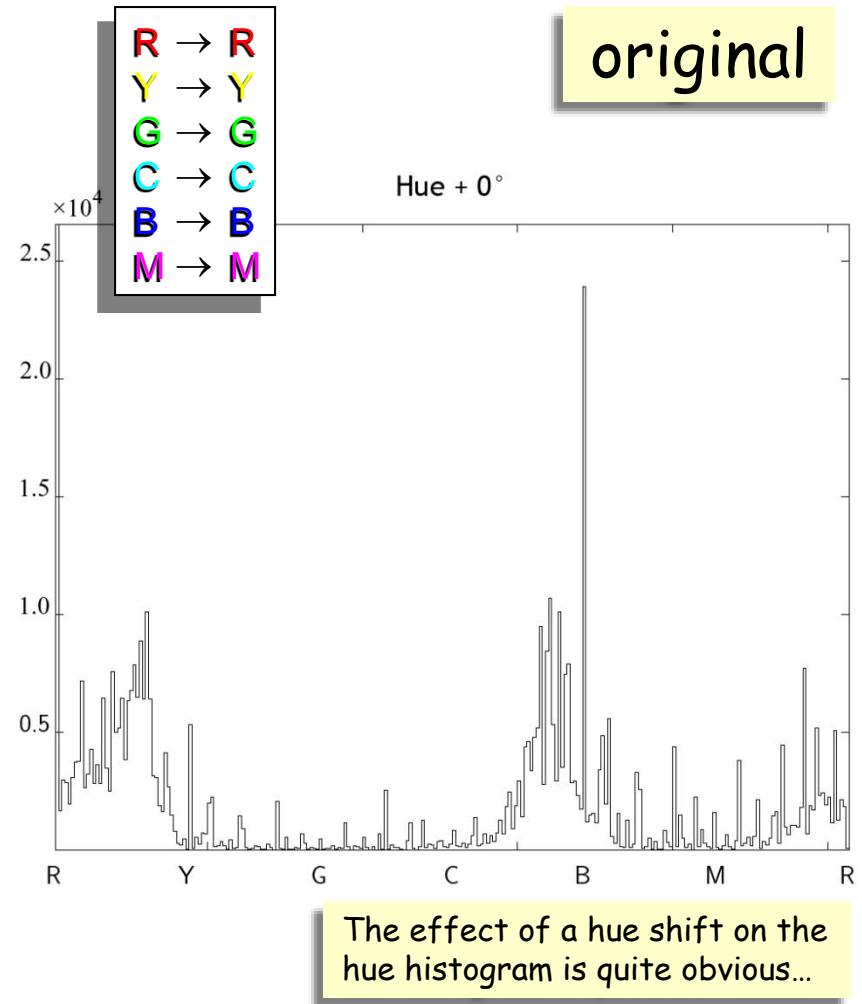


Hue Shifting



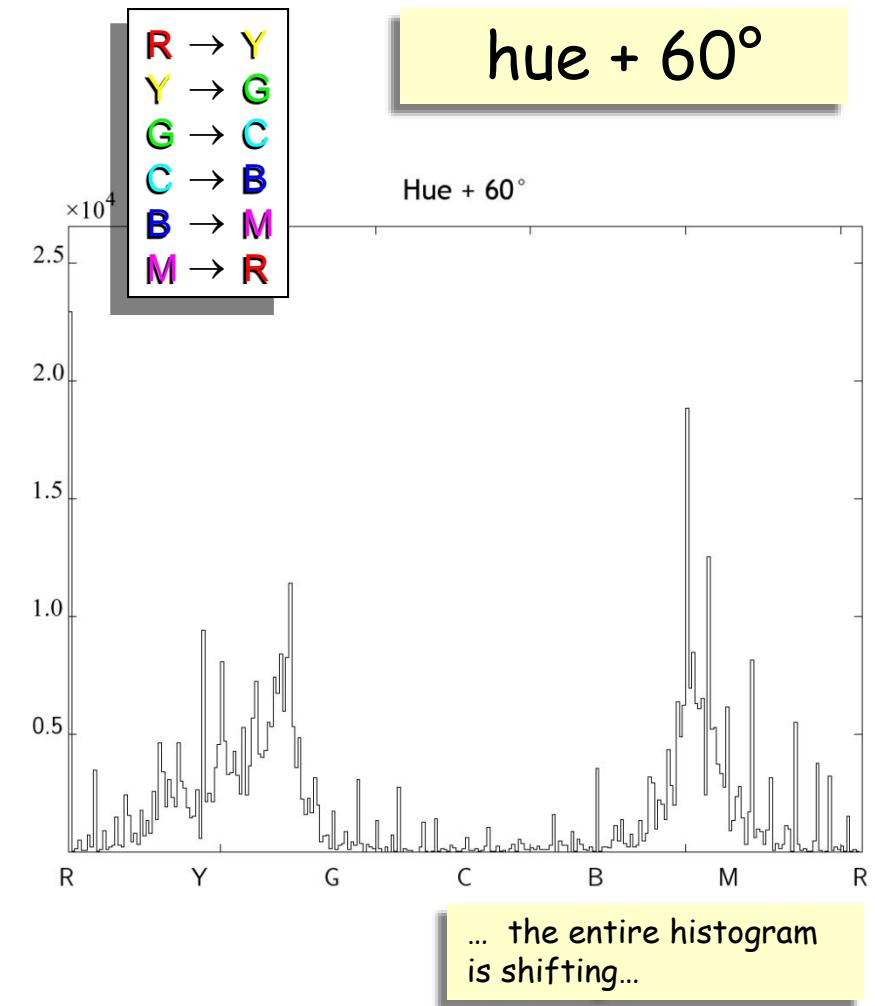


Hue Shifting



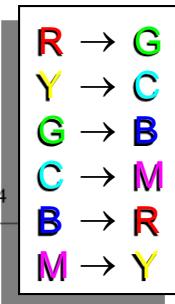


Hue Shifting

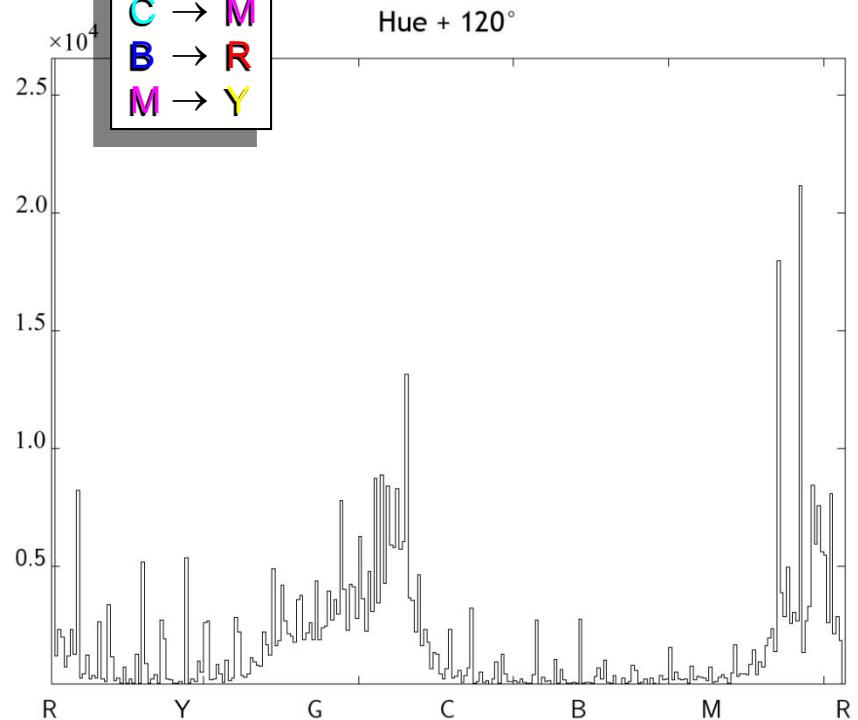




Hue Shifting



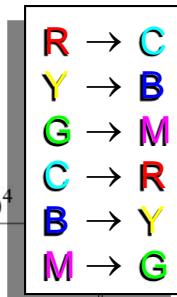
hue + 120°



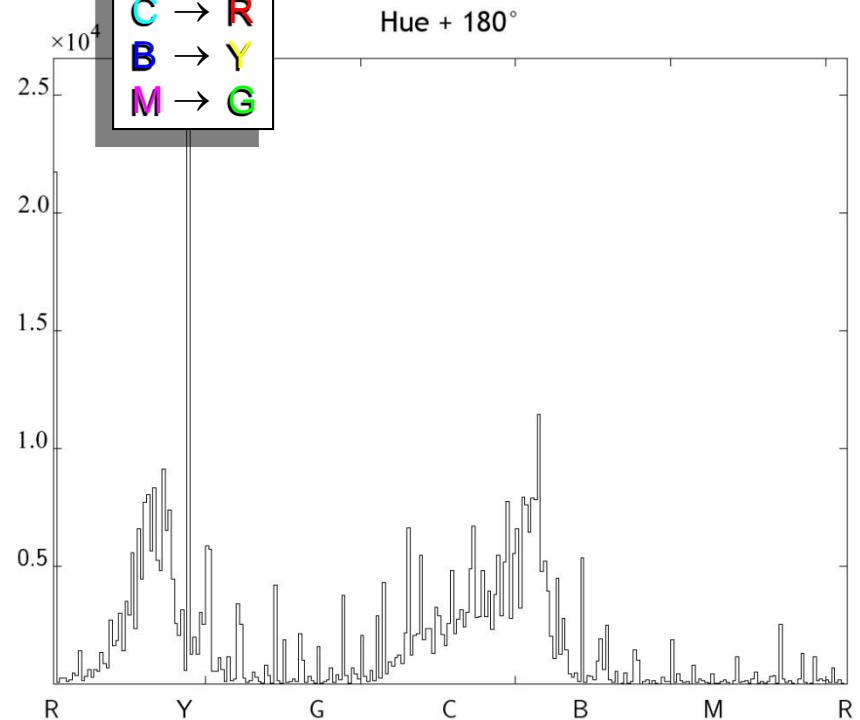
... and the shift is circular since the hue is a circular function - it is defined on a circle.



Hue Shifting



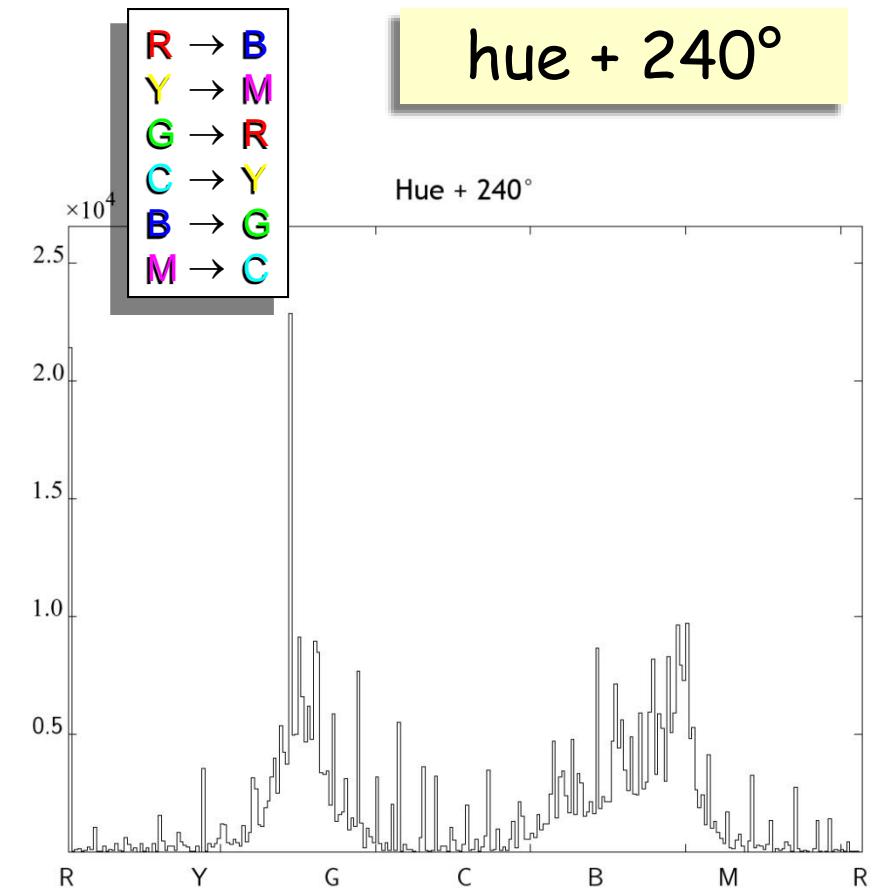
hue + 180°



The part of the histogram that leaves one side appears on the other.

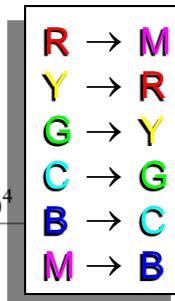


Hue Shifting

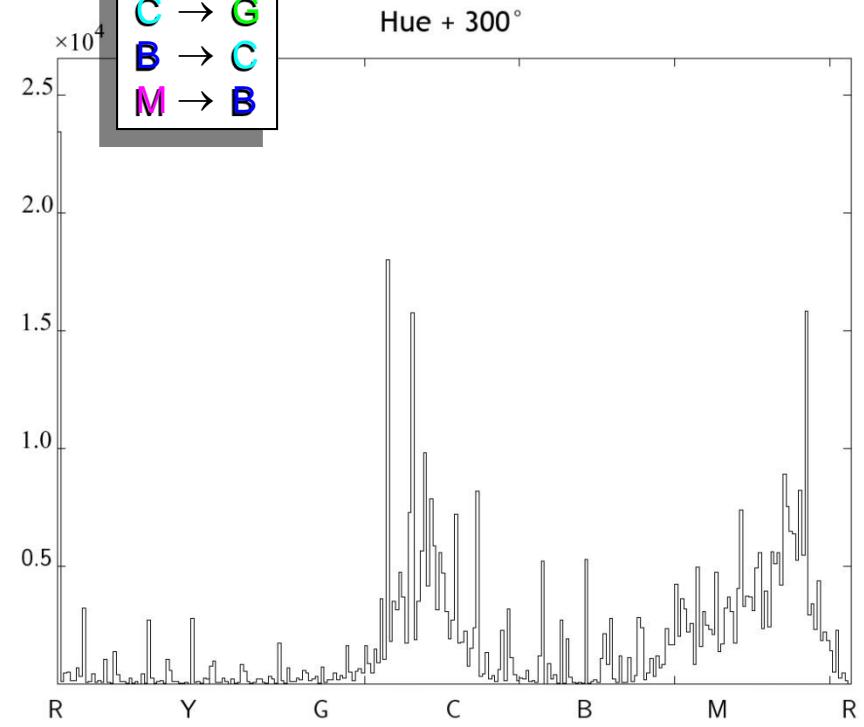




Hue Shifting

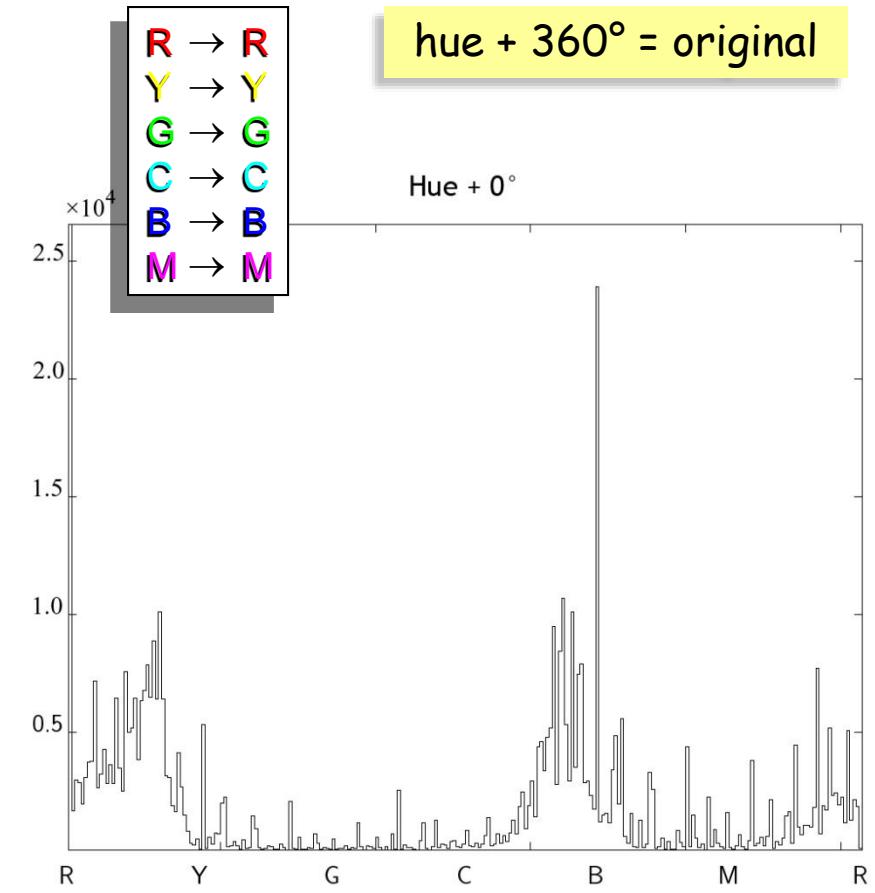


hue + 300°





Hue Shifting





Linear Transformation of Color

EECE 4353 Image Processing

Vanderbilt University School of Engineering





Color Correction via Linear Transformation

is a point process; the transformation is applied to each pixel as a function of its color alone.

$$\mathbf{J}(r, c) = \Phi[\mathbf{I}(r, c)], \quad \forall(r, c) \in \text{supp}(\mathbf{I}).$$

Each pixel is vector valued, therefore the transformation is a vector space operator.

$$\mathbf{I}(r, c) = \begin{bmatrix} \mathbf{R}_I(r, c) \\ \mathbf{G}_I(r, c) \\ \mathbf{B}_I(r, c) \end{bmatrix}, \quad \mathbf{J}(r, c) = \begin{bmatrix} \mathbf{R}_J(r, c) \\ \mathbf{G}_J(r, c) \\ \mathbf{B}_J(r, c) \end{bmatrix} = \Phi\{\mathbf{I}(r, c)\} = \Phi\left\{\begin{bmatrix} \mathbf{R}_I(r, c) \\ \mathbf{G}_I(r, c) \\ \mathbf{B}_I(r, c) \end{bmatrix}\right\}.$$



Color Vector Space Operators

Linear operators
are matrix
multiplications

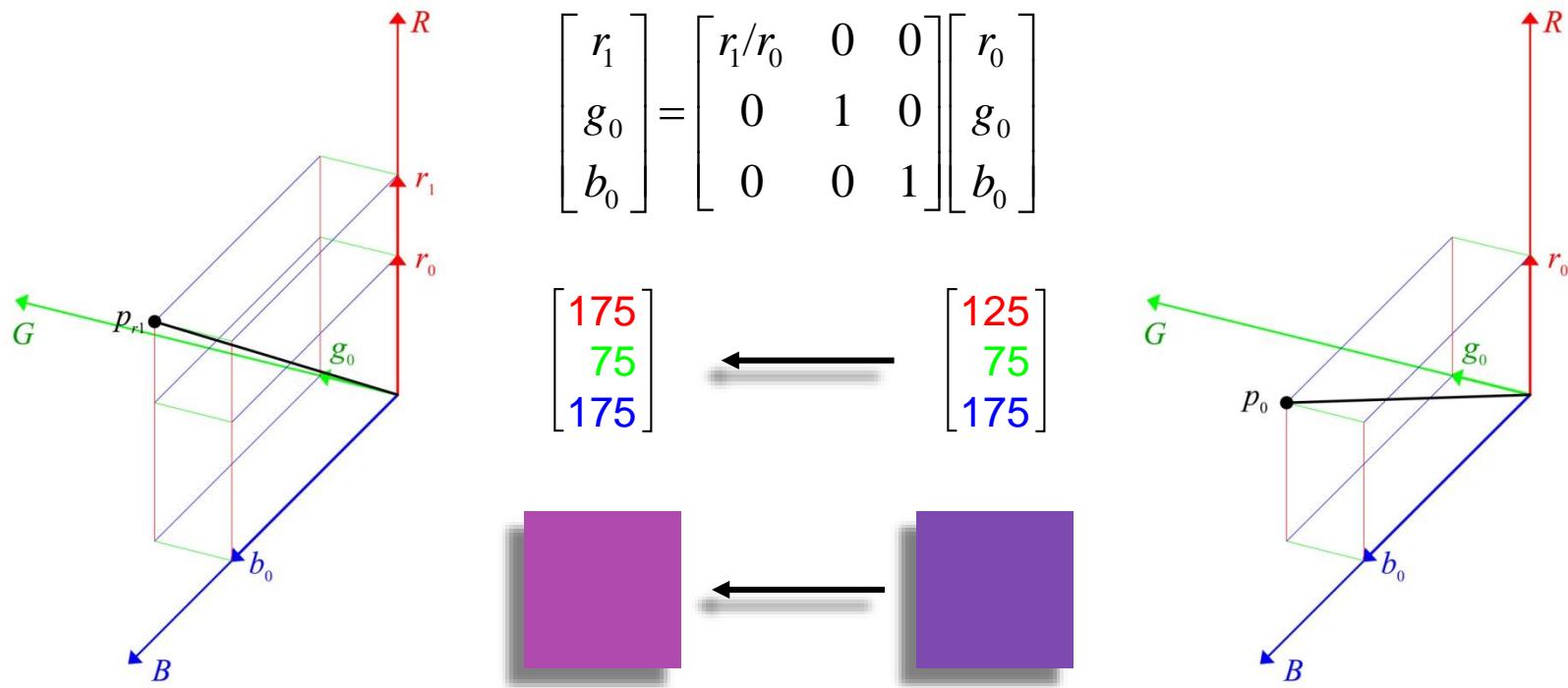
$$\begin{bmatrix} r_1 \\ g_1 \\ b_1 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} r_0 \\ g_0 \\ b_0 \end{bmatrix}$$

$$\begin{bmatrix} r_1 \\ g_1 \\ b_1 \end{bmatrix} = 255 \cdot \begin{bmatrix} (r_0 / 255)^{1/\gamma_r} \\ (g_0 / 255)^{1/\gamma_g} \\ (b_0 / 255)^{1/\gamma_b} \end{bmatrix}$$

Example of a
nonlinear operator:
gamma correction

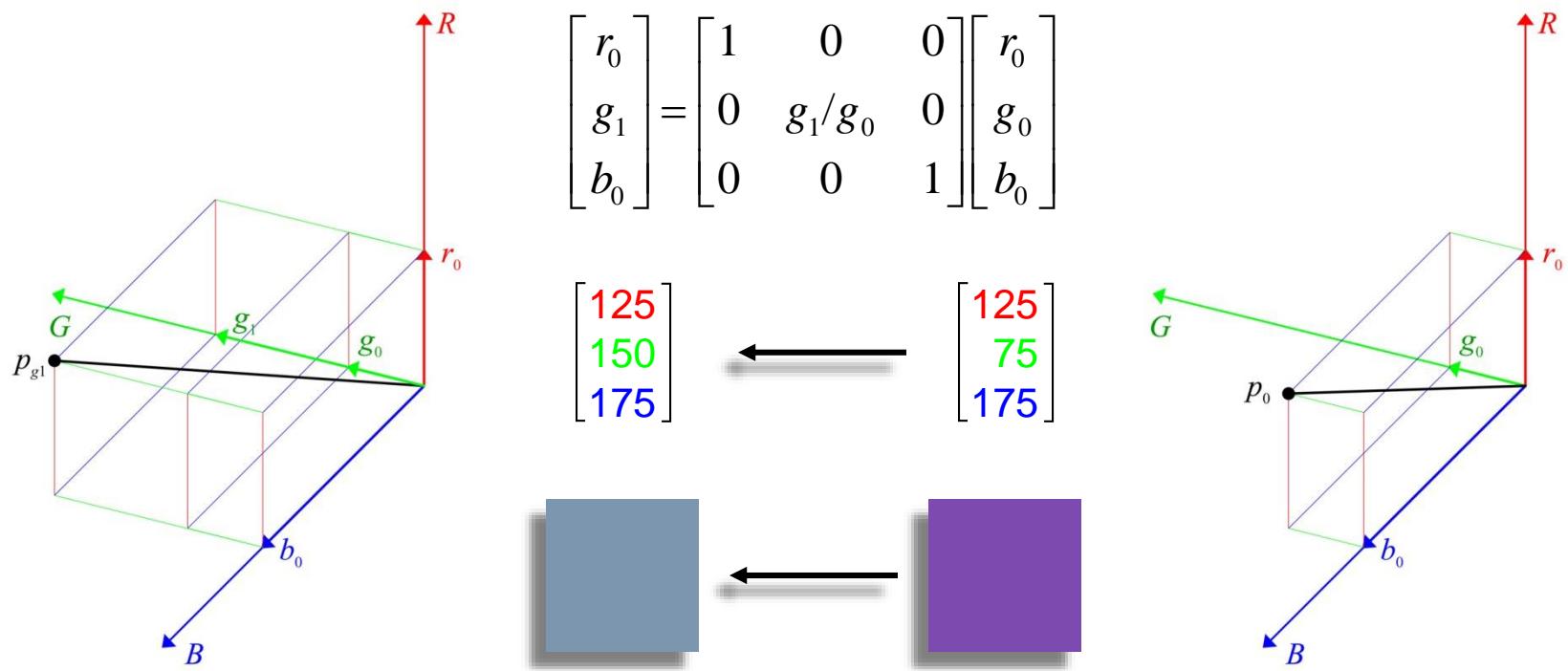


Linear Transformation of Color



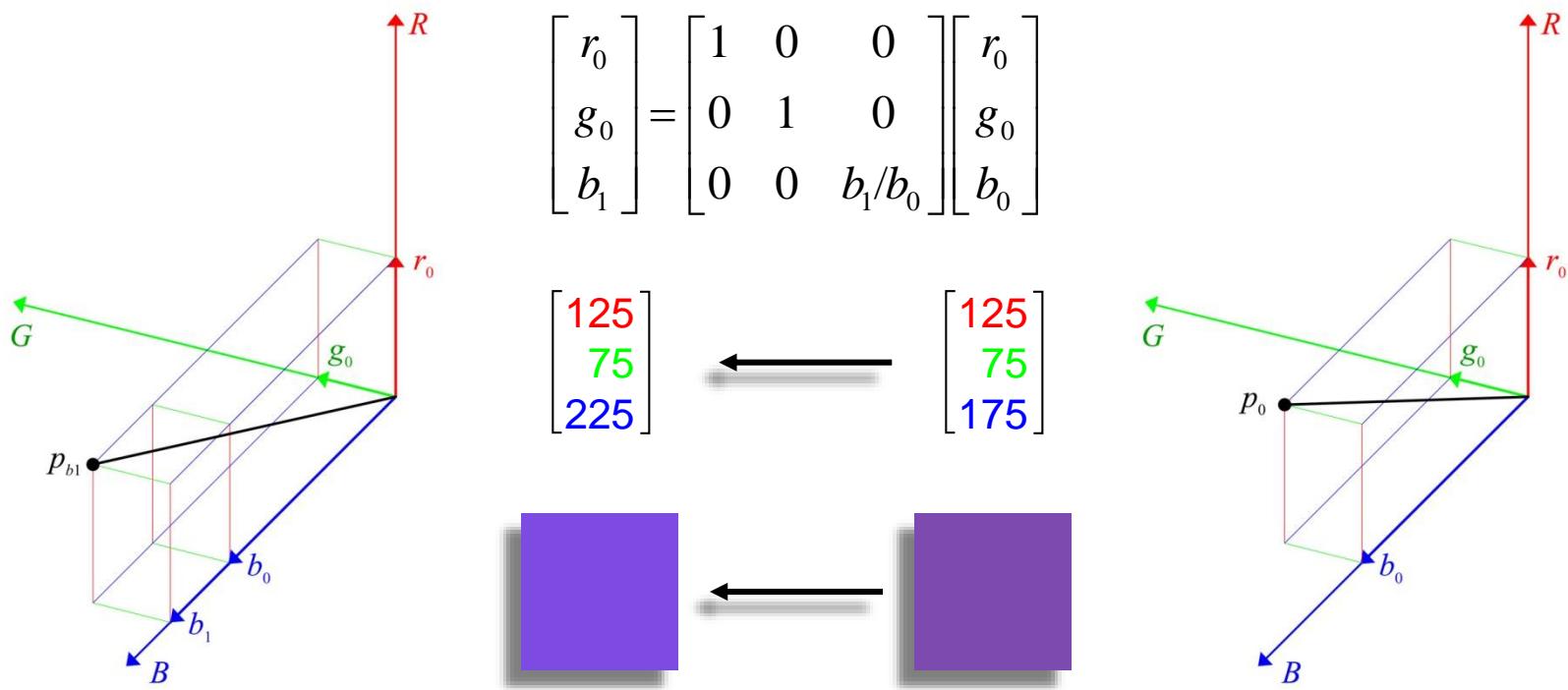


Linear Transformation of Color



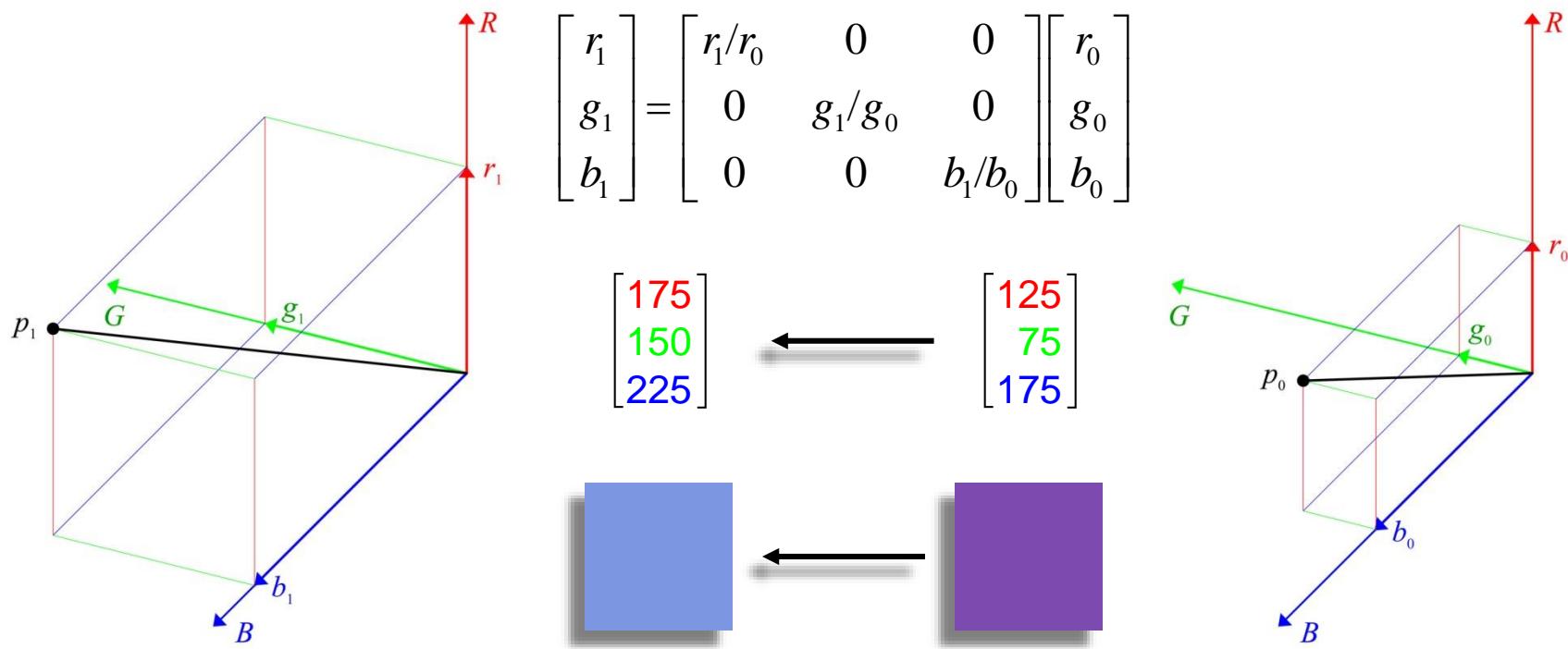


Linear Transformation of Color





Linear Transformation of Color





Color Transformation

Assume \mathbf{J} is a discolored version of image \mathbf{I} such that $\mathbf{J} = \Phi[\mathbf{I}]$. If Φ is linear then it is represented by a 3×3 matrix, \mathbf{A} :

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}.$$

Then $\mathbf{J} = \mathbf{AI}$ or, more accurately,
 $\mathbf{J}(r,c) = \mathbf{AI}(r,c)$ for all pixel locations (r,c) in image \mathbf{I} .



Color Transformation

If at pixel location (r, c) ,

$$\text{image } \mathbf{I}(r, c) = \begin{bmatrix} \rho_{\mathbf{I}} \\ \gamma_{\mathbf{I}} \\ \beta_{\mathbf{I}} \end{bmatrix} \quad \text{and}$$

$$\text{image } \mathbf{J}(r, c) = \begin{bmatrix} \rho_{\mathbf{J}} \\ \gamma_{\mathbf{J}} \\ \beta_{\mathbf{J}} \end{bmatrix},$$

then $\mathbf{J}(r, c) = \mathbf{A}\mathbf{I}(r, c)$, or

$$\begin{aligned} \begin{bmatrix} \rho_{\mathbf{J}} \\ \gamma_{\mathbf{J}} \\ \beta_{\mathbf{J}} \end{bmatrix} &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} \rho_{\mathbf{I}} \\ \gamma_{\mathbf{I}} \\ \beta_{\mathbf{I}} \end{bmatrix} \\ &= \begin{bmatrix} a_{11}\rho_{\mathbf{I}} + a_{12}\gamma_{\mathbf{I}} + a_{13}\beta_{\mathbf{I}} \\ a_{21}\rho_{\mathbf{I}} + a_{22}\gamma_{\mathbf{I}} + a_{23}\beta_{\mathbf{I}} \\ a_{31}\rho_{\mathbf{I}} + a_{32}\gamma_{\mathbf{I}} + a_{33}\beta_{\mathbf{I}} \end{bmatrix}. \end{aligned}$$



Color Transformation

The inverse transform Φ^{-1} (if it exists) maps the discolored image, \mathbf{J} , back into the correctly colored version, \mathbf{I} , *i.e.*, $\mathbf{I} = \Phi^{-1}[\mathbf{J}]$. If Φ is linear then it is represented by the inverse of matrix \mathbf{A} :

$$\mathbf{A}^{-1} = \left[a_{11}a_{22}a_{33} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} \right]^{-1} \cdot \begin{bmatrix} a_{22}a_{33} - a_{23}a_{32} & a_{13}a_{32} - a_{12}a_{33} & a_{12}a_{23} - a_{13}a_{22} \\ a_{23}a_{31} - a_{21}a_{33} & a_{11}a_{33} - a_{13}a_{31} & a_{13}a_{21} - a_{11}a_{23} \\ a_{21}a_{32} - a_{22}a_{31} & a_{12}a_{31} - a_{11}a_{32} & a_{11}a_{22} - a_{12}a_{21} \end{bmatrix}.$$



Color Correction

Assume we know n colors in the discolored image, \mathbf{J} , that correspond to another set of n colors (that we also know) in the original image, \mathbf{I} .

$$\left\{ \begin{bmatrix} \rho_{\mathbf{J}, k} \\ \gamma_{\mathbf{J}, k} \\ \beta_{\mathbf{J}, k} \end{bmatrix} \right\}_{k=1}^n$$

known
wrong
colors

$$\begin{bmatrix} \rho_{\mathbf{J}, k} \\ \gamma_{\mathbf{J}, k} \\ \beta_{\mathbf{J}, k} \end{bmatrix} \leftrightarrow \begin{bmatrix} \rho_{\mathbf{I}, k} \\ \gamma_{\mathbf{I}, k} \\ \beta_{\mathbf{I}, k} \end{bmatrix}$$

for $k = 1, \dots, n$.

known
correspondence

$$\left\{ \begin{bmatrix} \rho_{\mathbf{I}, k} \\ \gamma_{\mathbf{I}, k} \\ \beta_{\mathbf{I}, k} \end{bmatrix} \right\}_{k=1}^n$$

known
correct
colors



Color Correction

To remap the discolored image so that the result matches the original image in a linearly optimal way, we need to find the matrix, \mathbf{A} , that minimizes

$$\varepsilon^2 = \sum_{k=1}^n \left\| \begin{bmatrix} \rho_{\mathbf{I}, k} \\ \gamma_{\mathbf{I}, k} \\ \beta_{\mathbf{I}, k} \end{bmatrix} - \mathbf{A}^{-1} \begin{bmatrix} \rho_{\mathbf{J}, k} \\ \gamma_{\mathbf{J}, k} \\ \beta_{\mathbf{J}, k} \end{bmatrix} \right\|^2$$



Color Correction

To find the solution of this problem, let

$$\mathbf{Y} = \begin{bmatrix} \begin{bmatrix} \rho_{\mathbf{I},1} \\ \gamma_{\mathbf{I},1} \\ \beta_{\mathbf{I},1} \end{bmatrix} & \cdots & \begin{bmatrix} \rho_{\mathbf{I},n} \\ \gamma_{\mathbf{I},n} \\ \beta_{\mathbf{I},n} \end{bmatrix} \end{bmatrix}, \text{ and } \mathbf{X} = \begin{bmatrix} \begin{bmatrix} \rho_{\mathbf{J},1} \\ \gamma_{\mathbf{J},1} \\ \beta_{\mathbf{J},1} \end{bmatrix} & \cdots & \begin{bmatrix} \rho_{\mathbf{J},n} \\ \gamma_{\mathbf{J},n} \\ \beta_{\mathbf{J},n} \end{bmatrix} \end{bmatrix}.$$

Then \mathbf{X} and \mathbf{Y} are known $3 \times n$ matrices such that

$$\mathbf{Y} \approx \mathbf{A}^{-1}\mathbf{X},$$

where \mathbf{A} is the 3×3 matrix that we want to find.



Color Correction

The linearly optimal solution is the least mean squared solution that is given by

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{YX}^{\top} (\mathbf{XX}^{\top})^{-1}$$

where \mathbf{X}^{\top} represents the transpose of matrix \mathbf{X} .

- Notes:
1. n , the number of color pairs, must be ≥ 3 ,
 2. \mathbf{XX}^{\top} must be invertible, *i.e.*, $\text{rank}(\mathbf{XX}^{\top}) = 3$,
 3. If $n=3$, then $\mathbf{X}^{\top}(\mathbf{XX}^{\top})^{-1} = \mathbf{X}^{-1}$.

important



Color Correction

The linearly optimal solution is the shared solution that is given by

$$\text{input colors (to be changed):} \\ \begin{bmatrix} \rho_{J,1} \\ \gamma_{J,1} \\ \beta_{J,1} \\ \vdots \\ \rho_{J,n} \\ \gamma_{J,n} \\ \beta_{J,n} \end{bmatrix} \cdot \begin{bmatrix} \rho_{J,1} & \gamma_{J,1} & \beta_{J,1} \\ & \vdots & \\ \rho_{J,n} & \gamma_{J,n} & \beta_{J,n} \end{bmatrix}$$

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{YX}^{\top} (\mathbf{XX}^{\top})^{-1}$$

where \mathbf{X}^{\top} represents the transpose of matrix \mathbf{X} .

- Notes:
1. n , the number of color pairs, must be ≥ 3 ,
 2. \mathbf{XX}^{\top} must be invertible, *i.e.*, $\text{rank}(\mathbf{XX}^{\top}) = 3$,
 3. If $n=3$, then $\mathbf{X}^{\top}(\mathbf{XX}^{\top})^{-1} = \mathbf{X}^{-1}$.



Color Correction

The linearly optimal solution is the one that minimizes the squared error between the input colors and the wanted output colors. This solution that is given by

$$\text{input colors (to be changed): } \begin{bmatrix} \rho_{J,1} \\ \gamma_{J,1} \\ \beta_{J,1} \\ \vdots \\ \rho_{J,n} \\ \gamma_{J,n} \\ \beta_{J,n} \end{bmatrix}$$
$$\begin{bmatrix} \rho_{J,1} & \gamma_{J,1} & \beta_{J,1} \\ \vdots & & \\ \rho_{J,n} & \gamma_{J,n} & \beta_{J,n} \end{bmatrix}$$

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{YX}^T \left(\mathbf{XX}^T \right)^{-1}$$

where \mathbf{X}^T represents the transpose of matrix \mathbf{X} .

- Notes:
1. n , the number of color pairs, must be ≥ 3 ,
 2. \mathbf{XX}^T must be invertible, *i.e.*, $\text{rank}(\mathbf{XX}^T) = 3$,
 3. If $n=3$, then $\mathbf{X}^T(\mathbf{XX}^T)^{-1} = \mathbf{X}^{-1}$.



Color Correction

Then the image is color corrected by performing

$$\mathbf{I}(r,c) = \mathbf{B} \mathbf{J}(r,c), \text{ for all } (r,c) \in \text{supp}(\mathbf{J}).$$

In **Matlab** this is easily performed by

```
>> I = reshape(((B*(reshape(double(J),R*C,3))'))'),R,C,3);  
>> m = min(I(:));  
>> M = max(I(:));  
>> I = uint8(255*(I-m)/(M-m));
```

where $\mathbf{B}=\mathbf{A}^{-1}$ is computed directly through the LMS formula on the previous page, and R & C are the number of rows and columns in the image.



Linear Color Correction

NASA Summer Faculty Fellows at Ellington Air Force Base, Houston, TX, July 2002. Airplane is a T-38.



Original Image



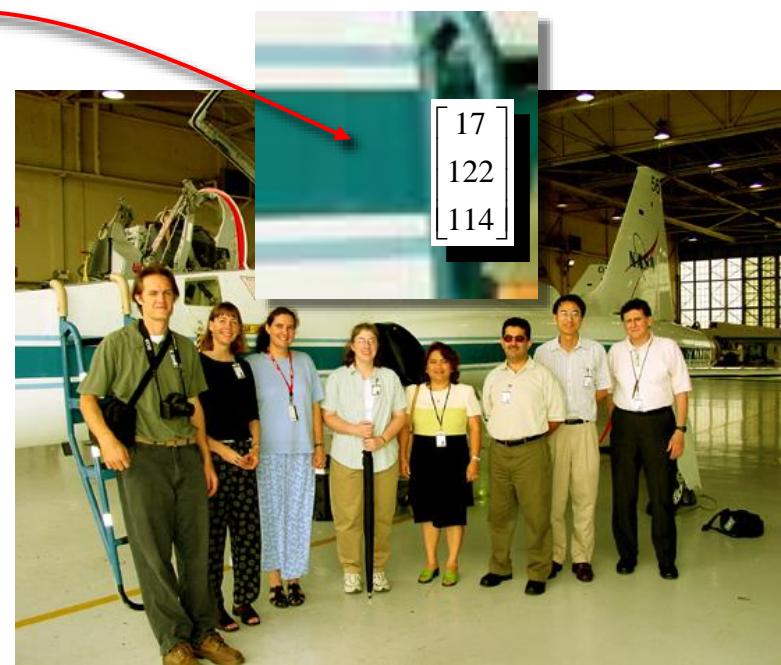
“Aged” Image



Color Mapping 1



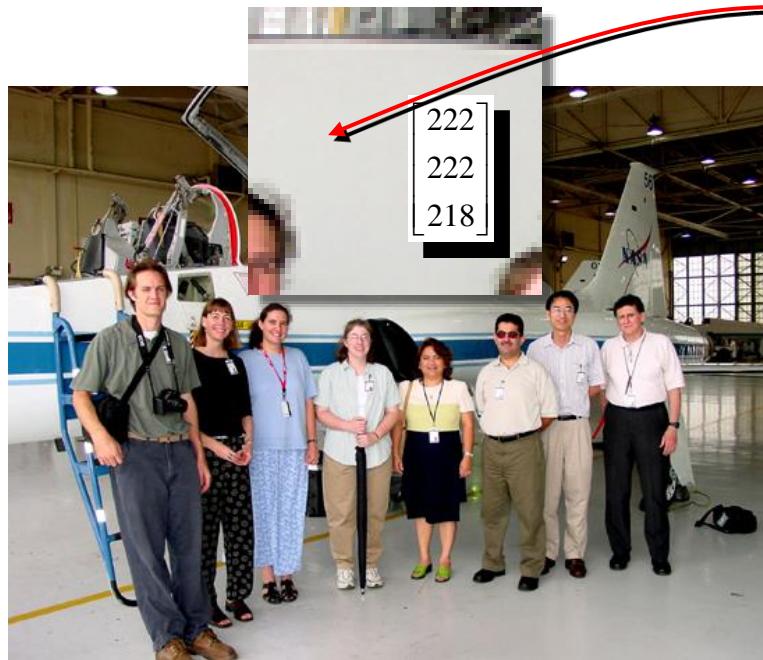
Original Image



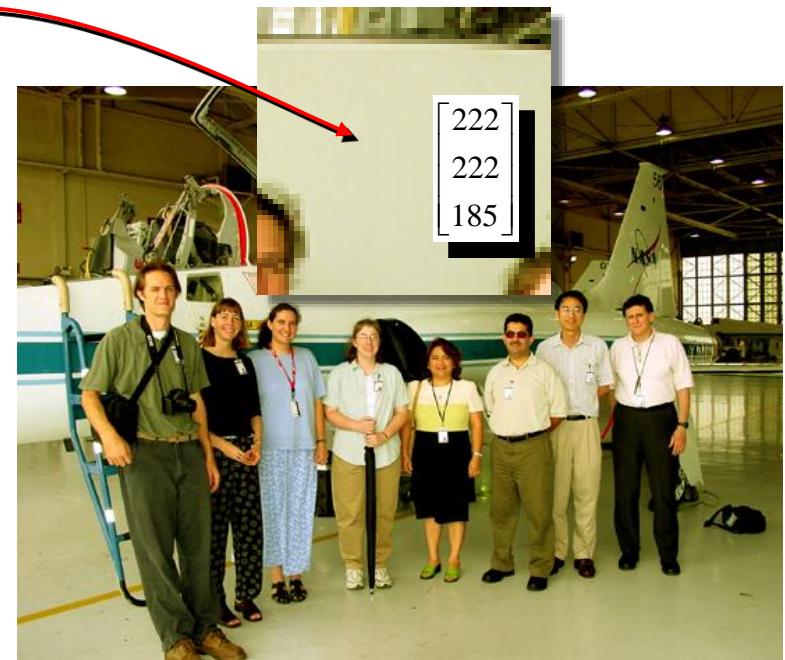
“Aged” Image



Color Mapping 2



Original Image



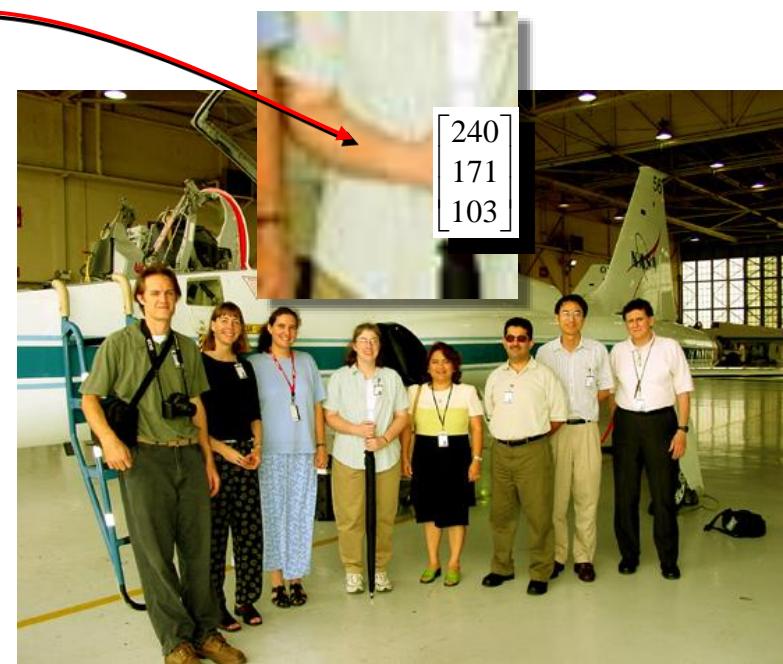
“Aged” Image



Color Mapping 3



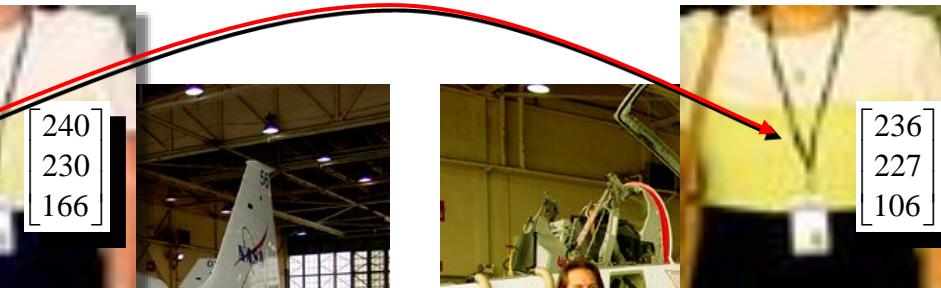
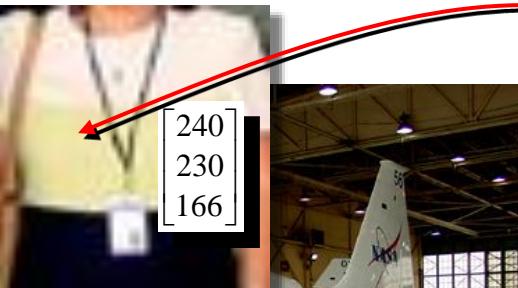
Original Image



“Aged” Image



Color Mapping 4



Original Image

“Aged” Image



Color Transformations



The aging process was a transformation, Φ , that mapped:

$$\begin{bmatrix} 17 \\ 122 \\ 114 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 17 \\ 121 \\ 171 \end{bmatrix} \right\}$$

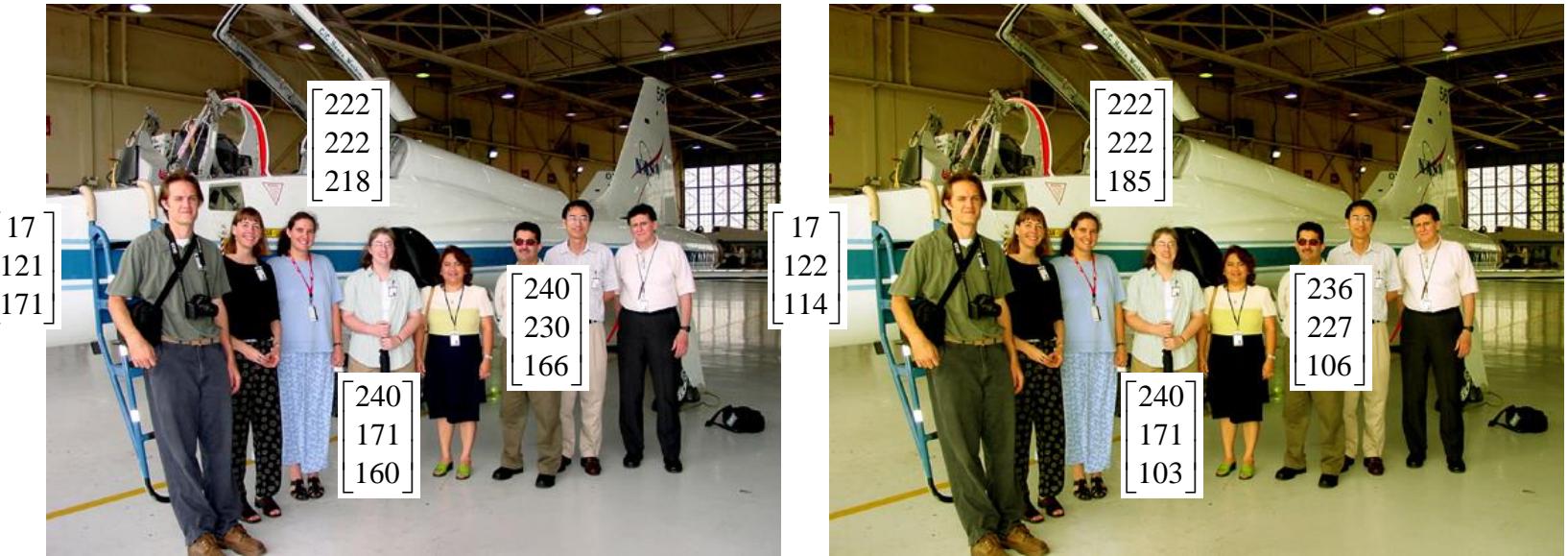
$$\begin{bmatrix} 222 \\ 222 \\ 185 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 222 \\ 222 \\ 218 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 240 \\ 171 \\ 103 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 240 \\ 171 \\ 160 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 236 \\ 227 \\ 106 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 240 \\ 230 \\ 166 \end{bmatrix} \right\}$$



Color Transformations



To undo the process we need to find, Φ^{-1} , that maps:

$$\begin{bmatrix} 17 \\ 121 \\ 171 \end{bmatrix} = \Phi^{-1} \left\{ \begin{bmatrix} 17 \\ 122 \\ 114 \end{bmatrix} \right\} \quad \begin{bmatrix} 222 \\ 222 \\ 218 \end{bmatrix} = \Phi^{-1} \left\{ \begin{bmatrix} 222 \\ 222 \\ 185 \end{bmatrix} \right\} \quad \begin{bmatrix} 240 \\ 171 \\ 160 \end{bmatrix} = \Phi^{-1} \left\{ \begin{bmatrix} 240 \\ 171 \\ 103 \end{bmatrix} \right\} \quad \begin{bmatrix} 240 \\ 230 \\ 166 \end{bmatrix} = \Phi^{-1} \left\{ \begin{bmatrix} 236 \\ 227 \\ 106 \end{bmatrix} \right\}$$



Correction Using 3 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{YX}^{-1}$$



$$\mathbf{X} = \begin{bmatrix} 222 & 17 & 240 \\ 222 & 122 & 171 \\ 185 & 114 & 103 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 222 & 17 & 240 \\ 222 & 121 & 171 \\ 218 & 171 & 160 \end{bmatrix}$$



Correction Using 3 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{YX}^{-1}$$

original



corrected



$$\mathbf{X} = \begin{bmatrix} 222 & 17 & 240 \\ 222 & 122 & 171 \\ 185 & 114 & 103 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 222 & 17 & 240 \\ 222 & 121 & 171 \\ 218 & 171 & 160 \end{bmatrix}$$



Another Correction Using 3 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{YX}^{-1}$$



$$\mathbf{X} = \begin{bmatrix} 222 & 17 & 236 \\ 222 & 122 & 227 \\ 185 & 114 & 106 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 222 & 17 & 240 \\ 222 & 121 & 230 \\ 218 & 171 & 166 \end{bmatrix}$$



Another Correction Using 3 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{YX}^{-1}$$

original



corrected



$$\mathbf{X} = \begin{bmatrix} 222 & 17 & 236 \\ 222 & 122 & 227 \\ 185 & 114 & 106 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 222 & 17 & 240 \\ 222 & 121 & 230 \\ 218 & 171 & 166 \end{bmatrix}$$



Correction Using All 4 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^T (\mathbf{X}\mathbf{X}^T)^{-1}$$



$$\mathbf{X} = \begin{bmatrix} 222 & 17 & 236 & 240 \\ 222 & 122 & 227 & 171 \\ 185 & 114 & 106 & 103 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 222 & 17 & 240 & 240 \\ 222 & 121 & 230 & 171 \\ 218 & 171 & 166 & 160 \end{bmatrix}$$



Correction Using All 4 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^T (\mathbf{X}\mathbf{X}^T)^{-1}$$

original

corrected



$$\mathbf{X} = \begin{bmatrix} 222 & 17 & 236 & 240 \\ 222 & 122 & 227 & 171 \\ 185 & 114 & 106 & 103 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 222 & 17 & 240 & 240 \\ 222 & 121 & 230 & 171 \\ 218 & 171 & 166 & 160 \end{bmatrix}$$



Random Sampling of Color Values

```
>> rr = round(R*rand([1 n])) ;  
>> rc = round(C*rand([1 n])) ;  
>> idx = [rr;rc] ;  
  
>> Y(:,1) = diag(I(rr,rc,1)) ;  
>> Y(:,2) = diag(I(rr,rc,2)) ;  
>> Y(:,3) = diag(I(rr,rc,3)) ;  
  
>> X(:,1) = diag(J(rr,rc,1)) ;  
>> X(:,2) = diag(J(rr,rc,2)) ;  
>> X(:,3) = diag(J(rr,rc,3)) ;
```

R = number of rows in image
C = number of columns in image
n = number of pixels to select

rand([1 n]) : 1 × n matrix
of random numbers
between 0 and 1.

diag(I(rr,rc,1)): vector
from main diagonal of
matrix I(rr,rc,1).



Correction Using 128 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^T (\mathbf{X}\mathbf{X}^T)^{-1}$$



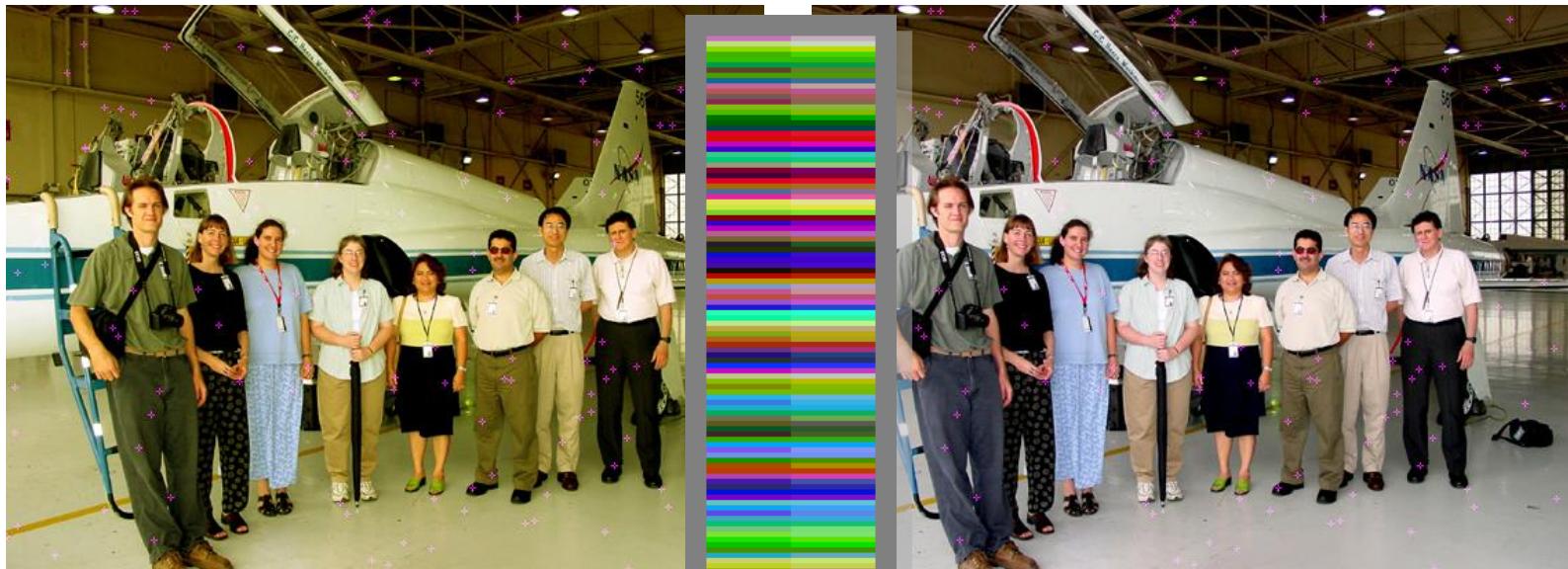
$$\mathbf{X} = \begin{bmatrix} 111 & 235 \\ 103 & \dots & 233 \\ 22 & 210 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 111 & 234 \\ 102 & \dots & 233 \\ 71 & 229 \end{bmatrix}$$



Correction Using 128 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^T (\mathbf{X}\mathbf{X}^T)^{-1}$$



$$\mathbf{X} = \begin{bmatrix} 111 & 235 \\ 103 & \dots & 233 \\ 22 & 210 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 111 & 234 \\ 102 & \dots & 233 \\ 71 & 229 \end{bmatrix}$$



Correction Using 128 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^T (\mathbf{X}\mathbf{X}^T)^{-1}$$

original

corrected



$$\mathbf{X} = \begin{bmatrix} 111 & 235 \\ 103 & \dots & 233 \\ 22 & 210 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 111 & 234 \\ 102 & \dots & 233 \\ 71 & 229 \end{bmatrix}$$



for
comparison:

Correction Using 4 Mappings

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^T (\mathbf{X}\mathbf{X}^T)^{-1}$$

original

corrected



$$\mathbf{X} = \begin{bmatrix} 222 & 17 & 236 & 240 \\ 222 & 122 & 227 & 171 \\ 185 & 114 & 106 & 103 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 222 & 17 & 240 & 240 \\ 222 & 121 & 230 & 171 \\ 218 & 171 & 166 & 160 \end{bmatrix}$$



Linear Color Transformation Program

```
function J = LinTrans(I,A)

[R C B] = size(I);

I = double(I);

J = reshape( ((A* (reshape(I,R*C,3))'))') ,R,C,3);

return;
```

This function returns an image of class double. To get a good uint8 you may have to linearly scale the result as shown on slide [53](#).