



EECE 4353 Image Processing

Lecture Notes: Frequency Filtering

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Convolution Property of the Fourier Transform

Let functions $\mathbf{f}(r, c)$ and $\mathbf{g}(r, c)$ have
Fourier Transforms $\mathbf{F}(u, v)$ and $\mathbf{G}(u, v)$.

Then,

$$\mathcal{F}\{\mathbf{f} * \mathbf{g}\} = \mathbf{F} \cdot \mathbf{G}.$$

Moreover,

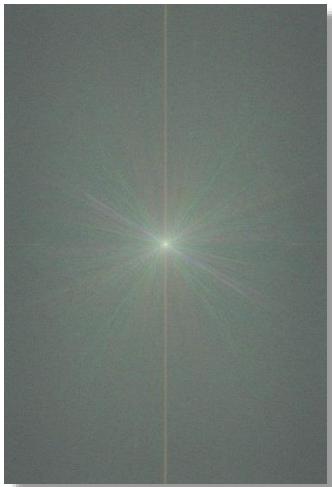
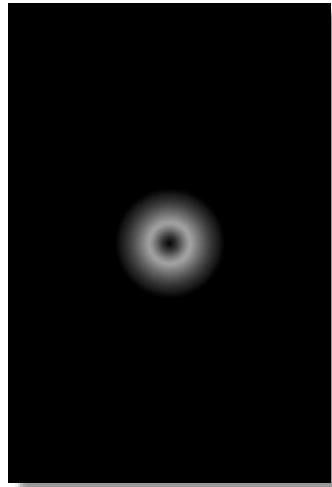
$$\mathcal{F}\{\mathbf{f} \cdot \mathbf{g}\} = \mathbf{F} * \mathbf{G}.$$

* = convolution
· = multiplication

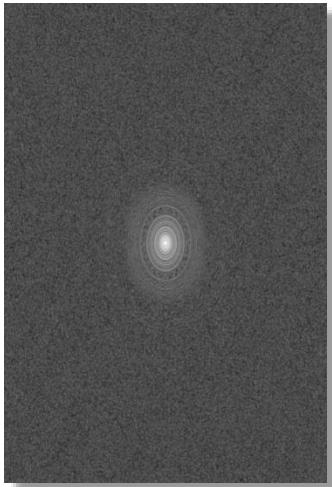
The Fourier Transform of a convolution equals the product of the Fourier Transforms. Similarly, the Fourier Transform of a product is the convolution of the Fourier Transforms



Image & Mask



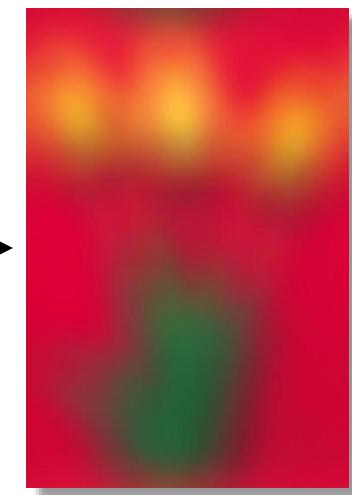
Transforms



Convolution via Fourier Transform



Pixel-wise Product



Inverse Transform



How to Convolve via FT in Matlab

1. Read the image from a file into a variable, say `I`.
2. Read in or create the convolution matrix, `h`. The matrix is usually 1-band
3. Compute the sum of the matrix: `s = sum(h(:));`
4. If `s == 0`, set `s = 1;`
5. Replace `h` with `h = h/s;`
6. Create: `H = zeros(size(I));`
7. Copy `h` into the middle of `H`.
8. Shift `H` into position: `H = ifftshift(H);`
9. Take the 2D FT of `I` and `H`: `FI=fft2(I); FH=fft2(H);`
10. Pointwise multiply the FTs: `FJ=FI.*FH;`
11. Compute the inverse FT: `J = real(ifft2(FJ));`

If `h` is a one-band matrix and `I` is multi-band, you must copy `h` into all the bands of `H`.



How to Convolve via FT in Matlab

1. Read the image from a file into a variable, say **I**.
2. Read in or create the convolution matrix, **h**.
3. Compute the sum of the matrix: **s = sum(h(:));**
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10. Pointwise multiply the FTs: **FJ=FI.*FH;**
11. Compute the inverse FT: **J = real(ifft2(FJ));**

fftshift and ifftshift must be done separately for each band.
fft2 transforms all the bands of a multiband image separately.



Coordinate Origin of the FFT

Center =
 $(\text{floor}(R/2)+1, \text{floor}(C/2)+1)$

Even

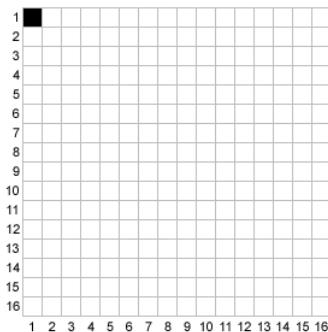


Image Origin

Odd

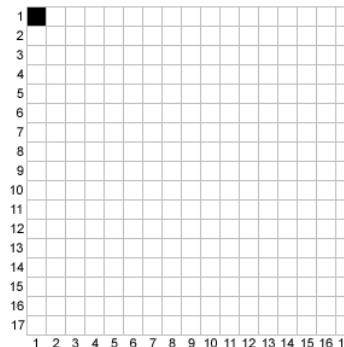
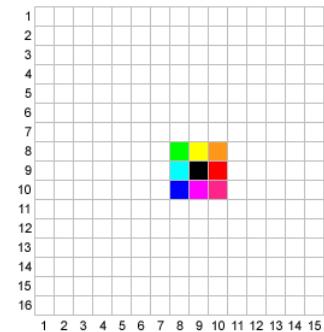


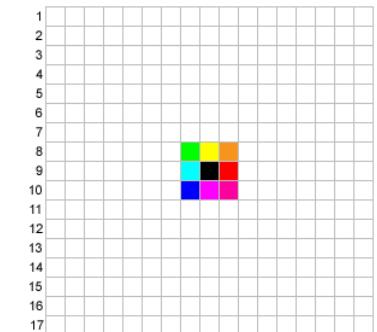
Image Origin

Even

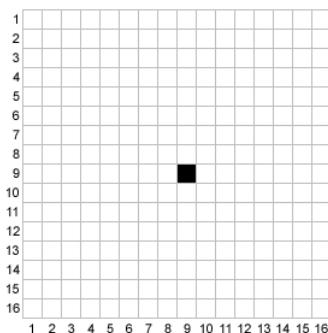


Weight Matrix Origin

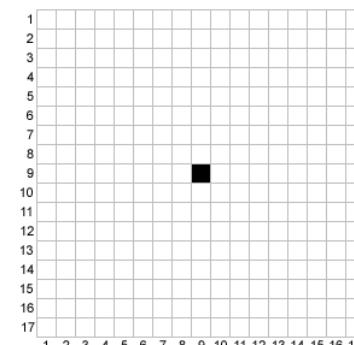
Odd



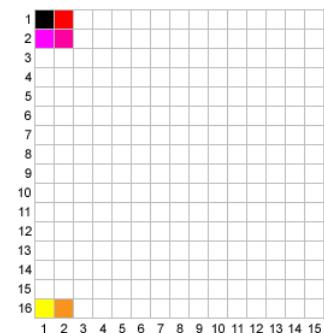
Weight Matrix Origin



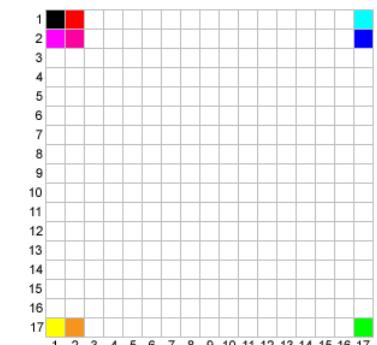
After FFT shift



After FFT shift



After IFFT shift



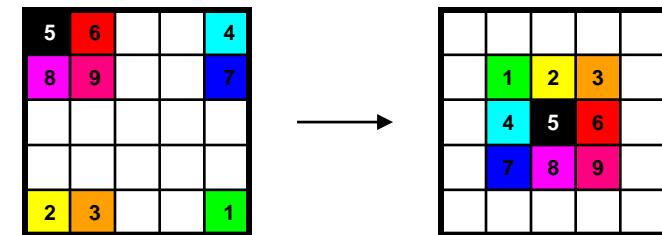
After IFFT shift



Matlab's fftshift and ifftshift

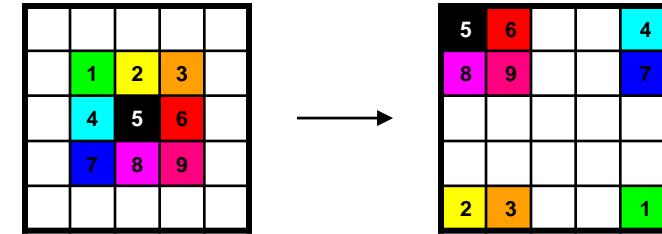
$J = \text{fftshift}(I) :$

$I(1,1) \rightarrow J(\lfloor R/2 \rfloor + 1, \lfloor C/2 \rfloor + 1)$



$I = \text{ifftshift}(J) :$

$J(\lfloor R/2 \rfloor + 1, \lfloor C/2 \rfloor + 1) \rightarrow I(1,1)$



where $\lfloor x \rfloor = \text{floor}(x)$ = the largest integer smaller than x .



Blurring: Averaging / Lowpass Filtering

Blurring results from:

- Pixel averaging in the spatial domain:
 - Each pixel in the output is a weighted average of its neighbors.
 - Is a convolution whose weight matrix sums to 1.
- Lowpass filtering in the frequency domain:
 - High frequencies are diminished or eliminated
 - Individual frequency components are multiplied by a non-increasing function of ω such as $1/\omega = 1/\sqrt{u^2+v^2}$.

The values of the output image are all non-negative.



Sharpening: Differencing / Highpass Filtering

Sharpening results from adding to the image, a copy of itself that has been:

- Pixel-differenced in the spatial domain:
 - Each pixel in the output is a difference between itself and a weighted average of its neighbors.
 - Is a convolution whose weight matrix sums to 0.
- Highpass filtered in the frequency domain:
 - High frequencies are enhanced or amplified.
 - Individual frequency components are multiplied by an increasing function of ω such as $\alpha\omega = \alpha\sqrt{u^2+v^2}$, where α is a constant.

The values of the output image could be negative.

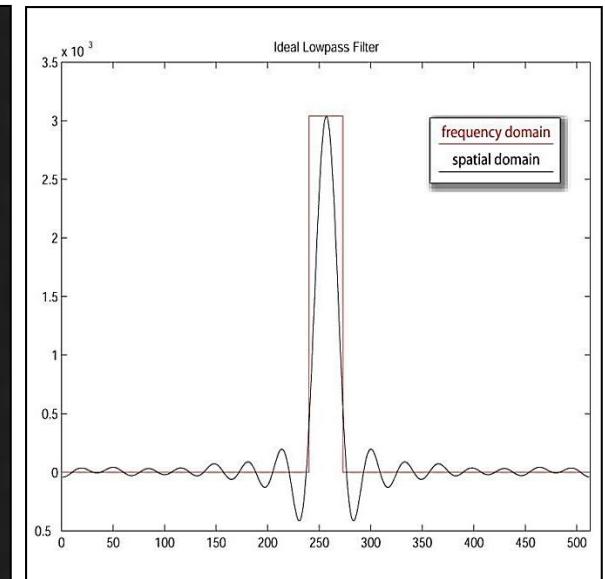
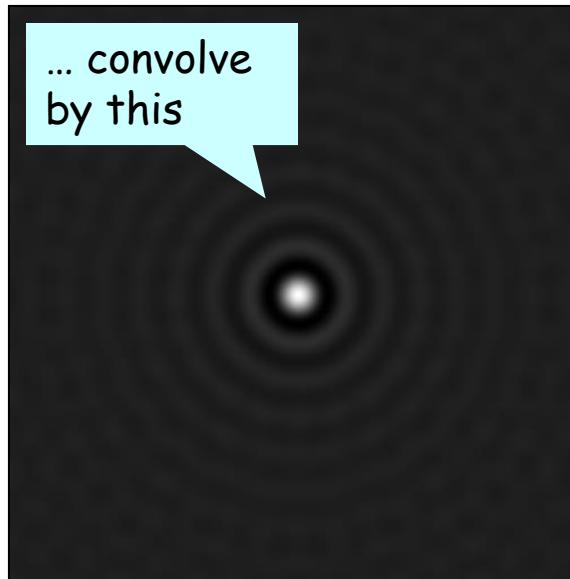
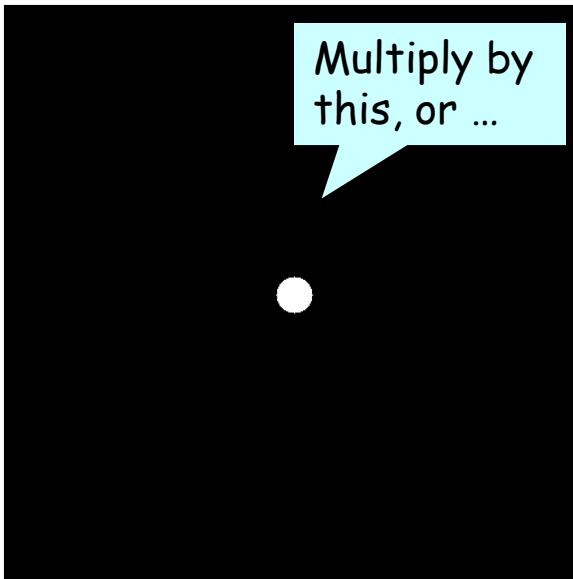


Ideal Lowpass Filter



Ideal Lowpass Filter

Image size: 512x512
FD filter radius: 16



Fourier Domain Rep.

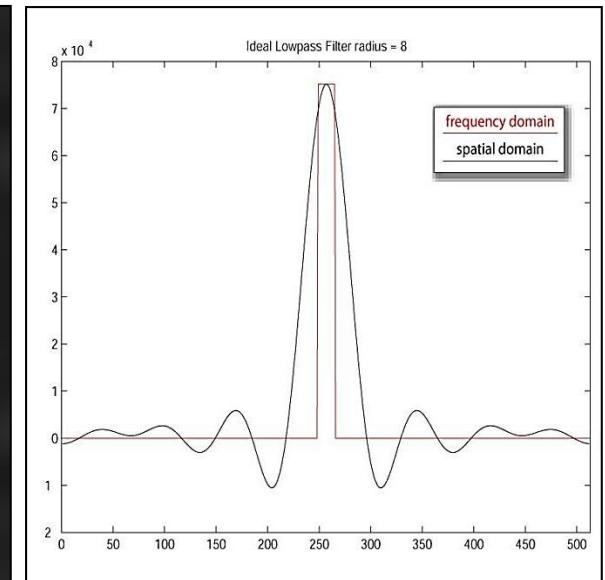
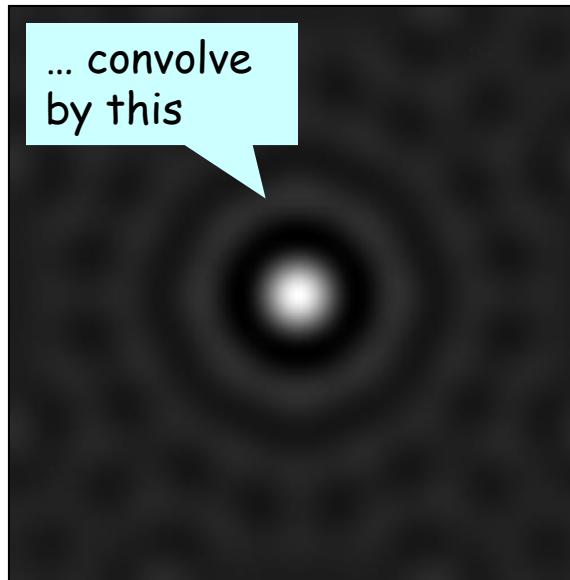
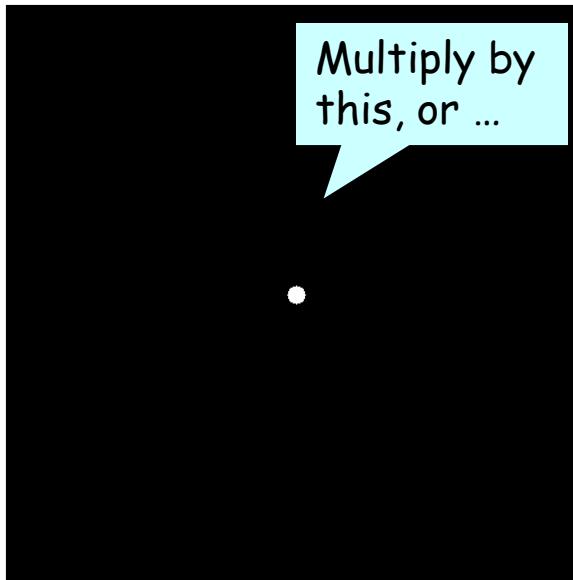
Spatial Representation

Central Profile



Ideal Lowpass Filter

Image size: 512x512
FD filter radius: 8



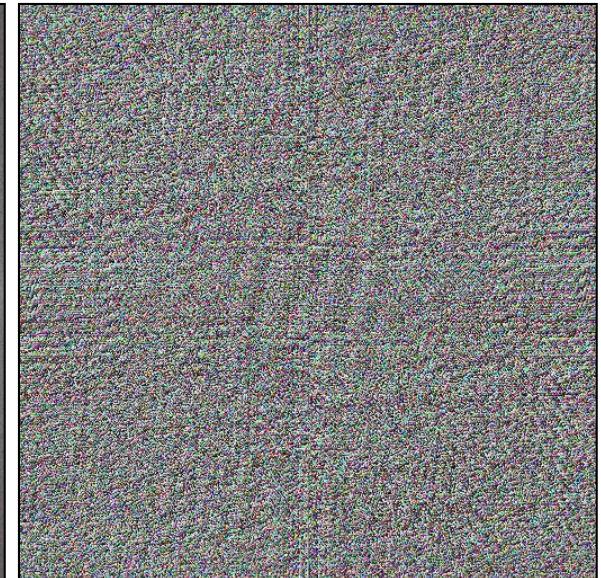
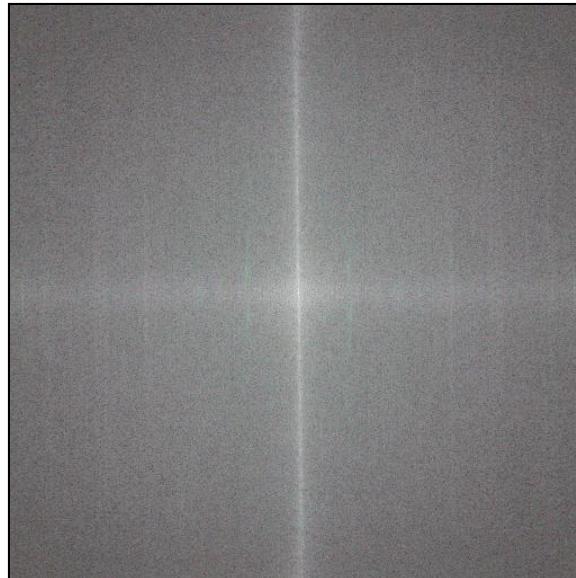
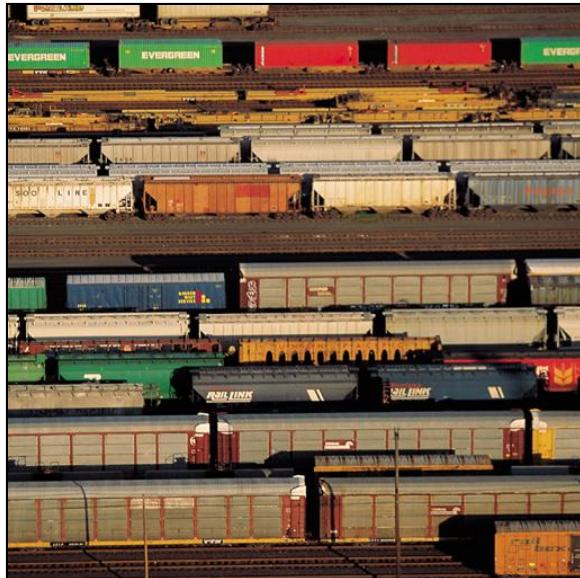
Fourier Domain Rep.

Spatial Representation

Central Profile



Power Spectrum and Phase of an Image



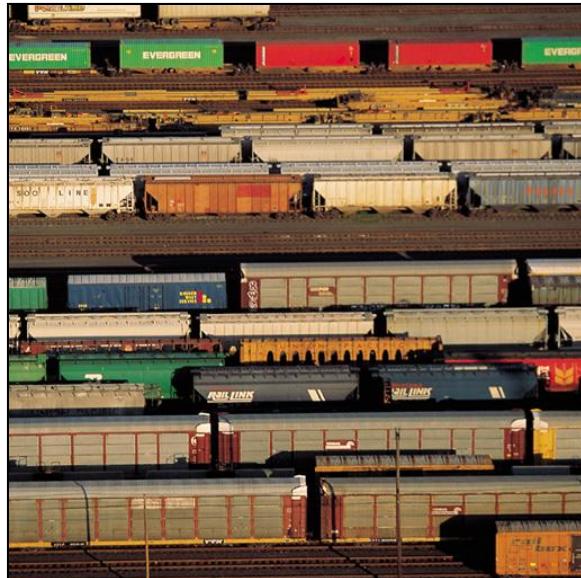
Original Image

Power Spectrum

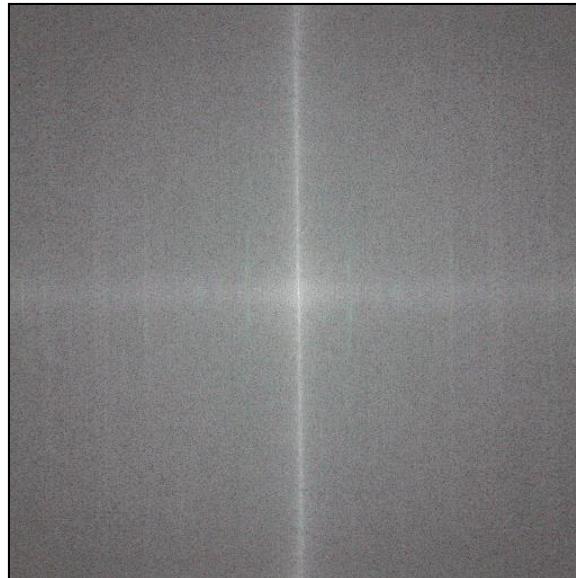
Phase



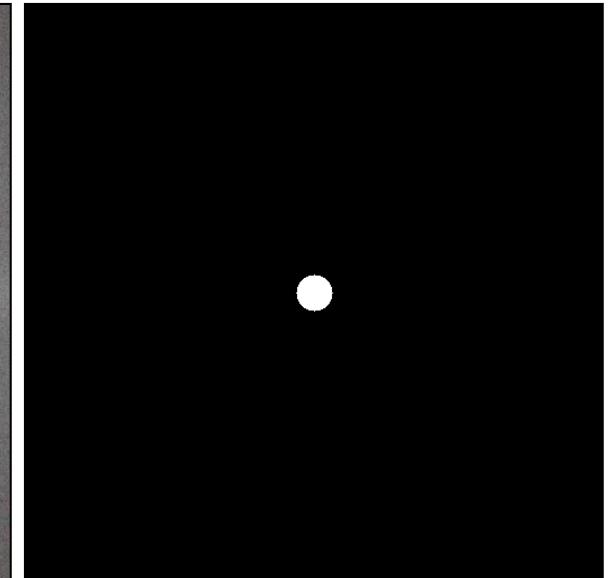
Ideal Lowpass Filter



Original Image



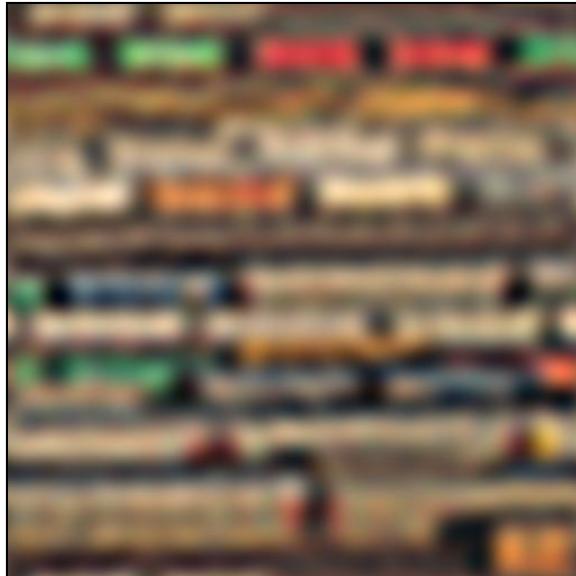
Power Spectrum



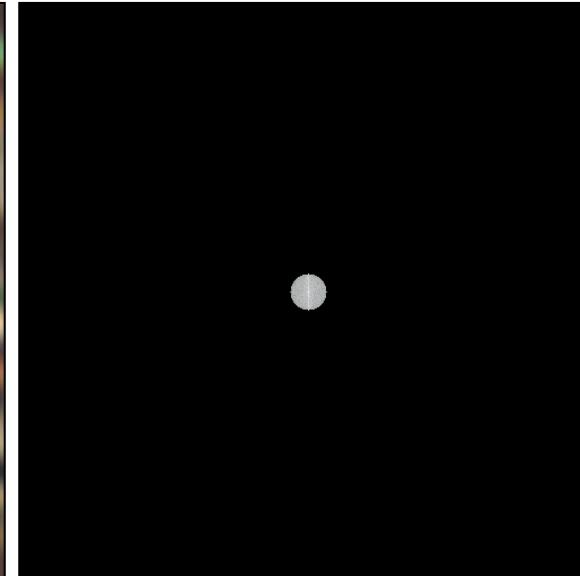
Ideal LPF in FD



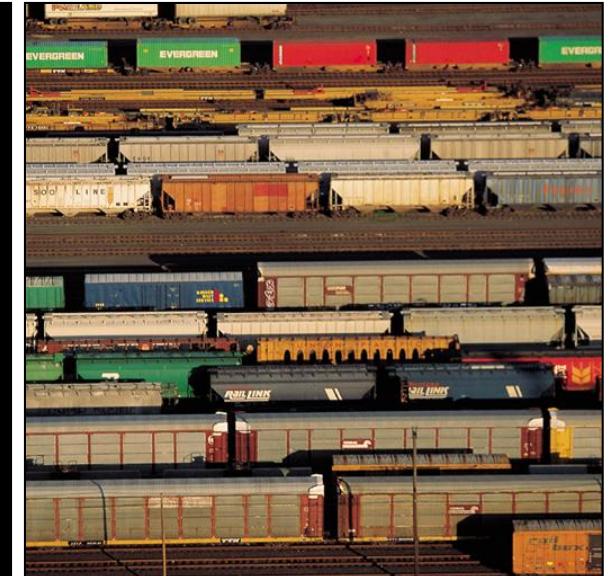
Ideal Lowpass Filter



Filtered Image



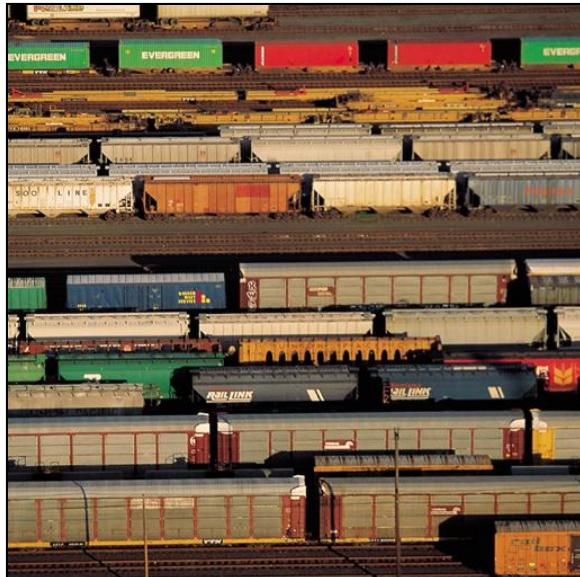
Filtered Power Spectrum



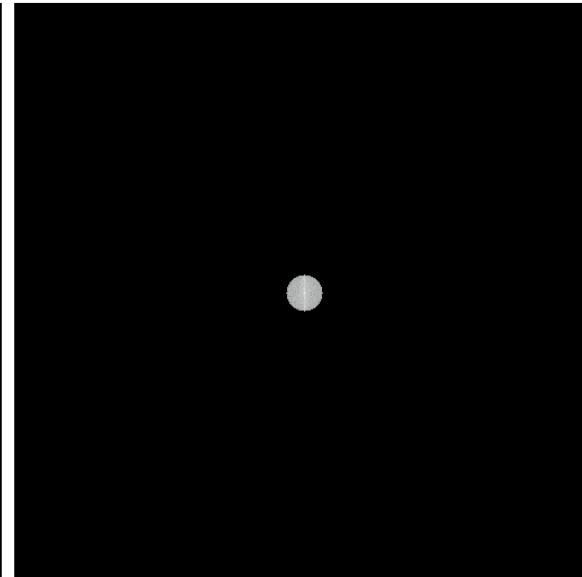
Original Image



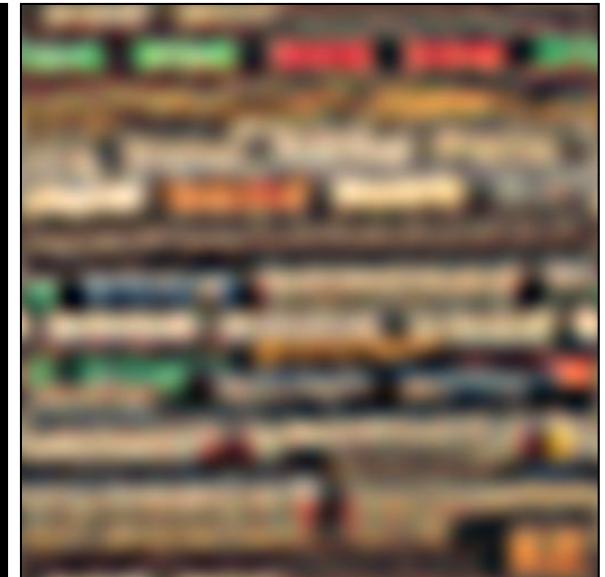
Ideal Lowpass Filter



Original Image



Filtered Power Spectrum



Filtered Image

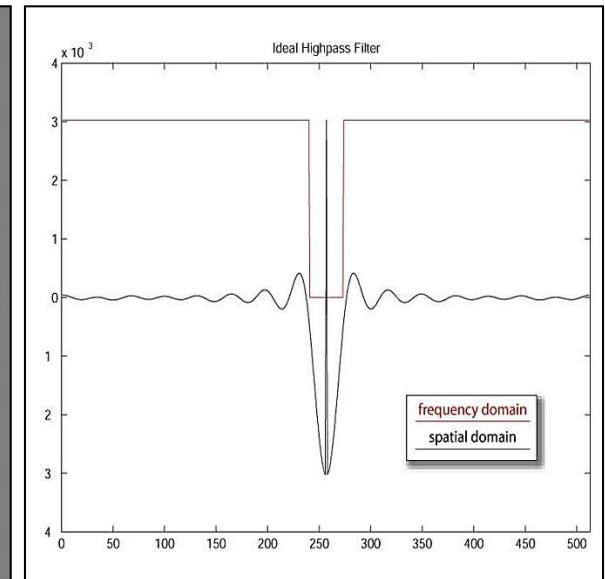
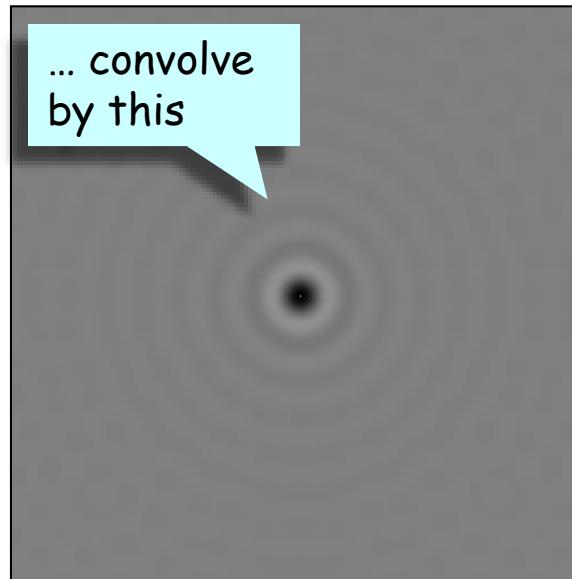
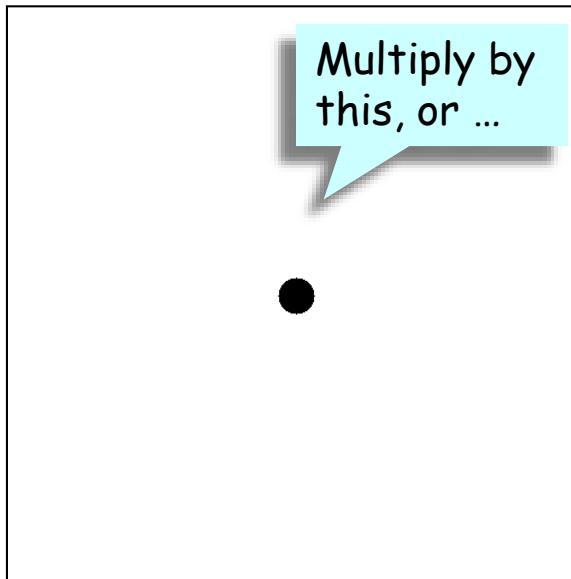


Ideal Highpass Filter



Ideal Highpass Filter

Image size: 512x512
FD notch radius: 16



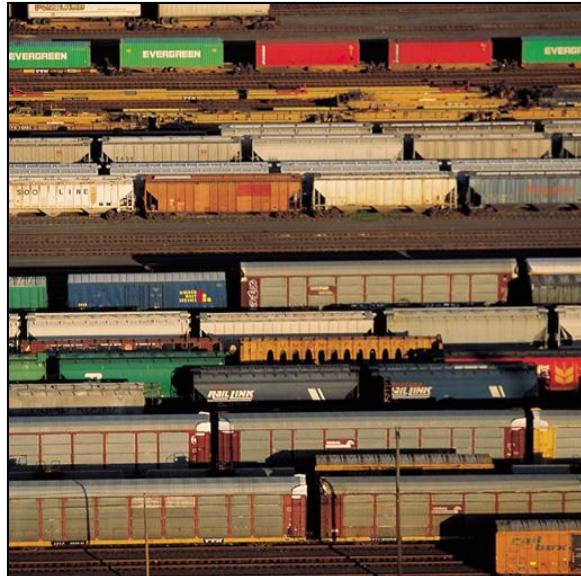
Fourier Domain Rep.

Spatial Representation

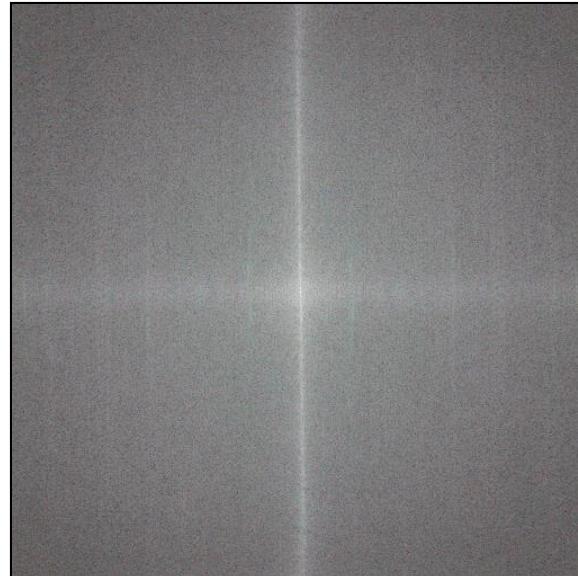
Central Profile



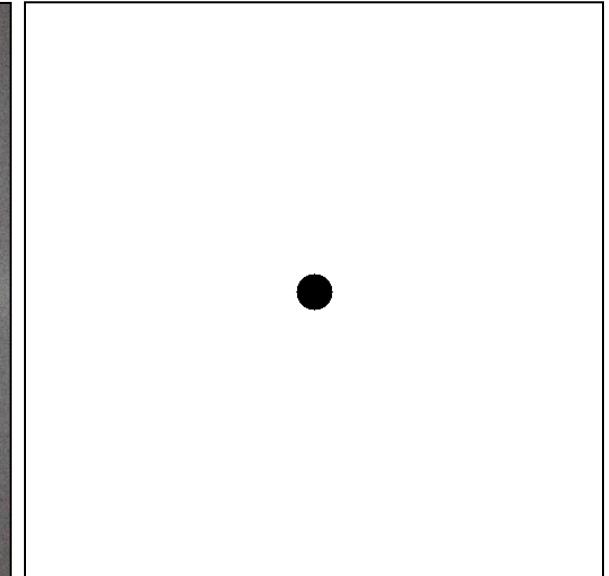
Ideal Highpass Filter



Original Image



Power Spectrum



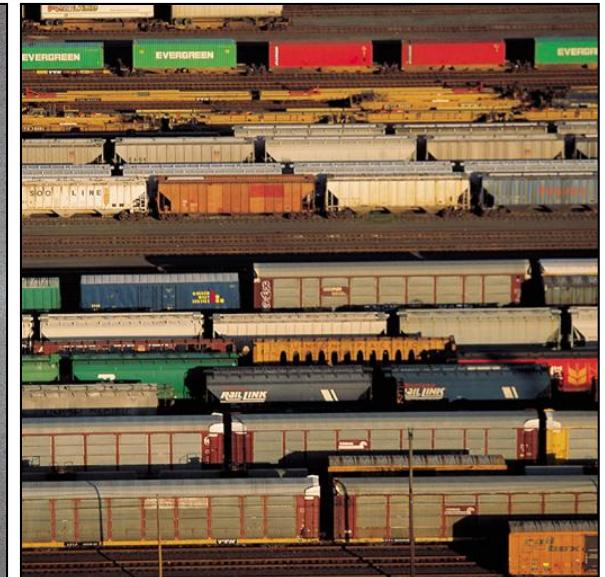
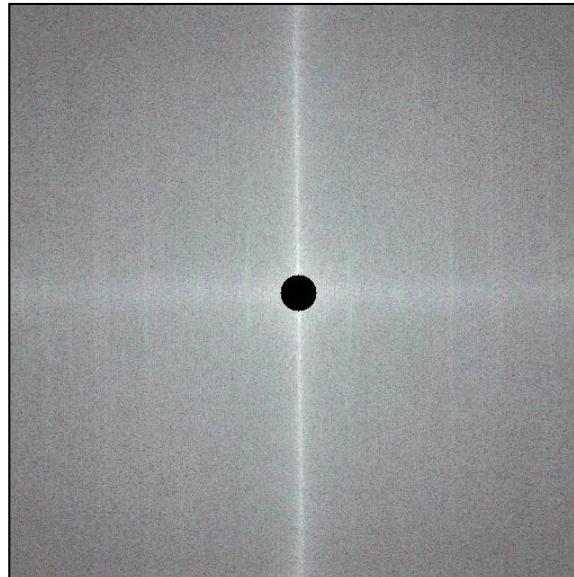
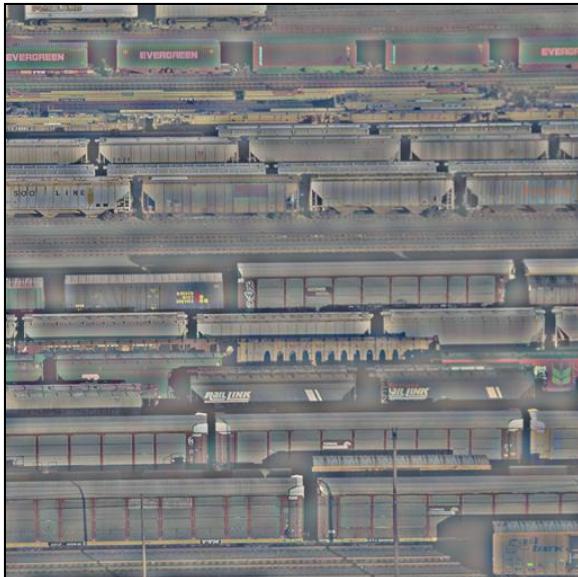
Ideal HPF in FD



*signed image:
0 mapped to 128

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Ideal Highpass Filter



Filtered Image*

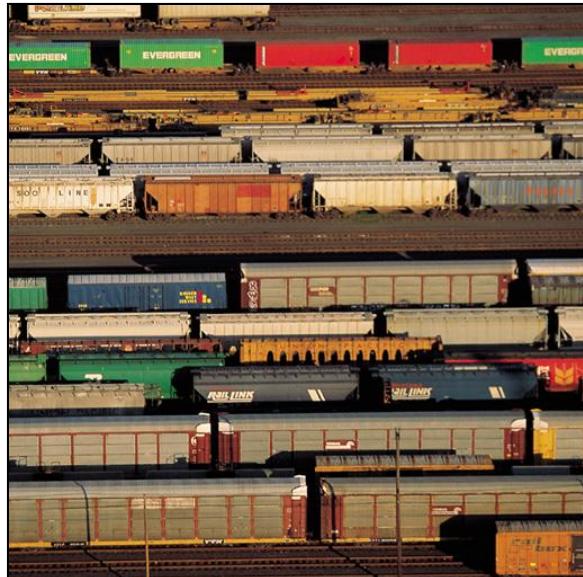
Filtered Power Spectrum

Original Image

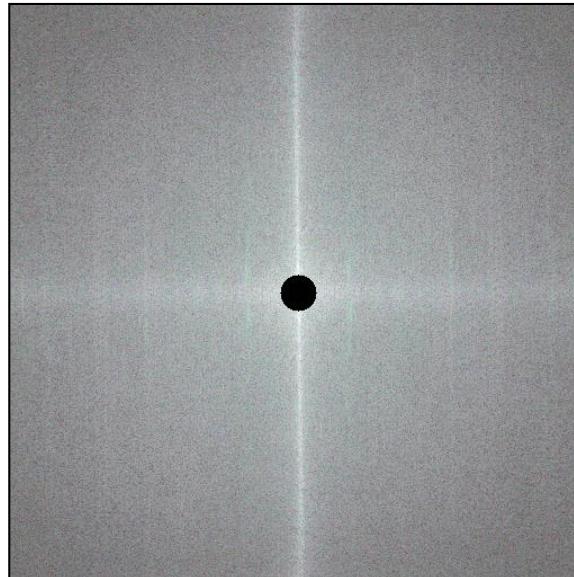


*signed image:
0 mapped to 128

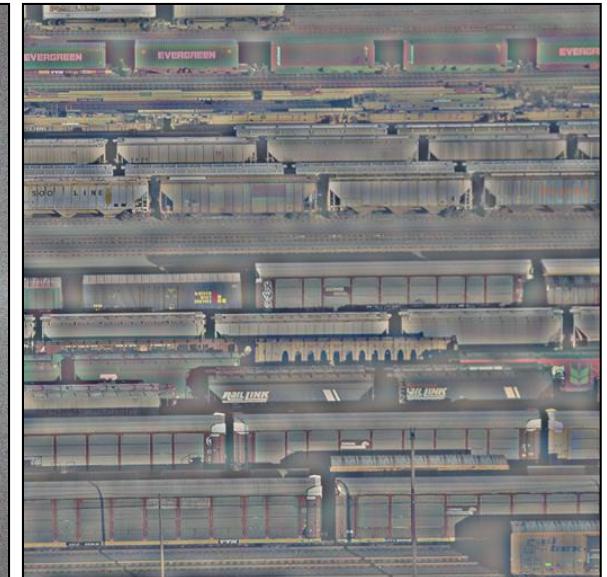
Ideal Highpass Filter



Original Image



Filtered Power Spectrum



Filtered Image*

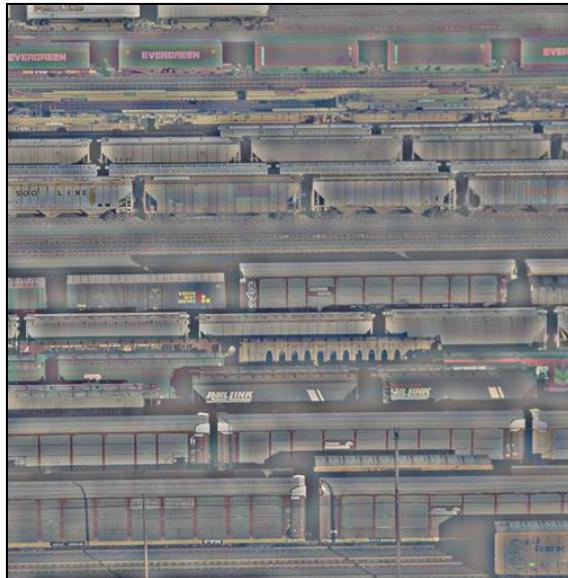


*signed image:
0 mapped to 128

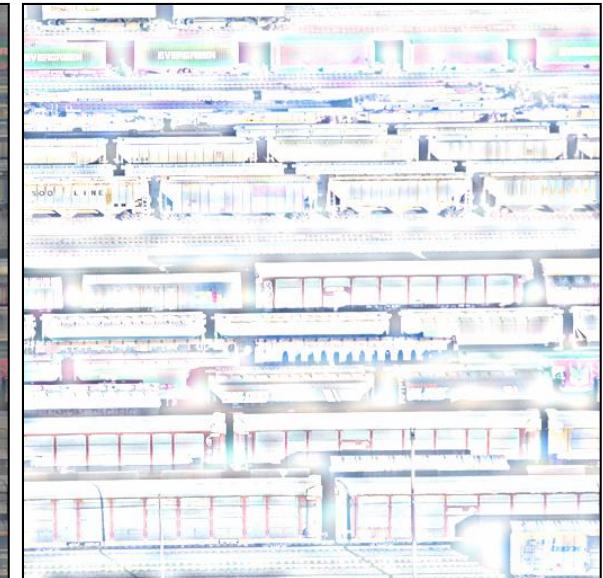
Ideal Highpass Filter



Positive Pixels



Filtered Image*



Negative Pixels



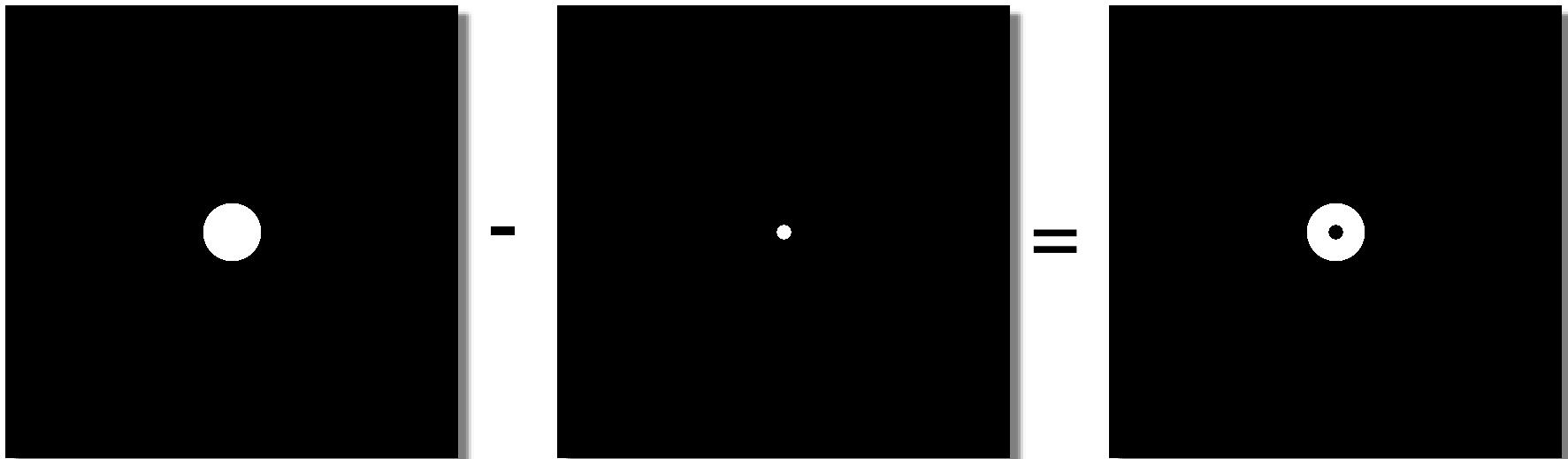
Ideal Bandpass Filter



Ideal Bandpass Filter

A bandpass filter is created by

- (1) subtracting a FD radius ρ_2 lowpass filtered image from a FD radius ρ_1 lowpass filtered image, where $\rho_2 < \rho_1$, or
- (2) convolving the image with a matrix that is the difference of the two lowpass matrixs.



FD LP matrix with radius ρ_1

FD LP matrix with radius ρ_2

FD BP matrix $\rho_1 - \rho_2$



*signed image:
0 mapped to 128

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Ideal Bandpass Filter

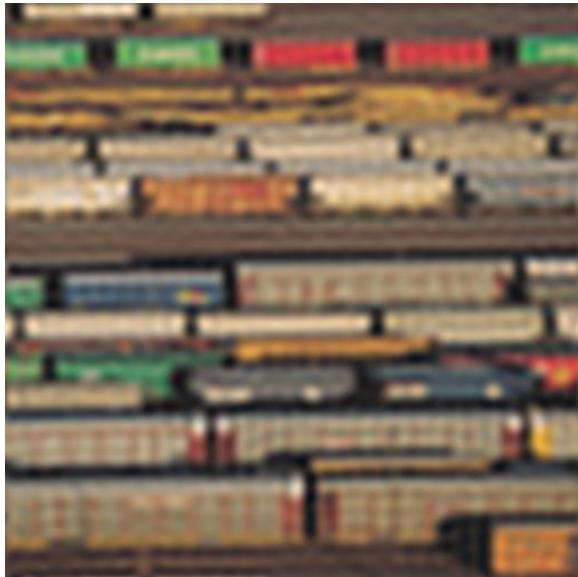


image LPF radius ρ_1

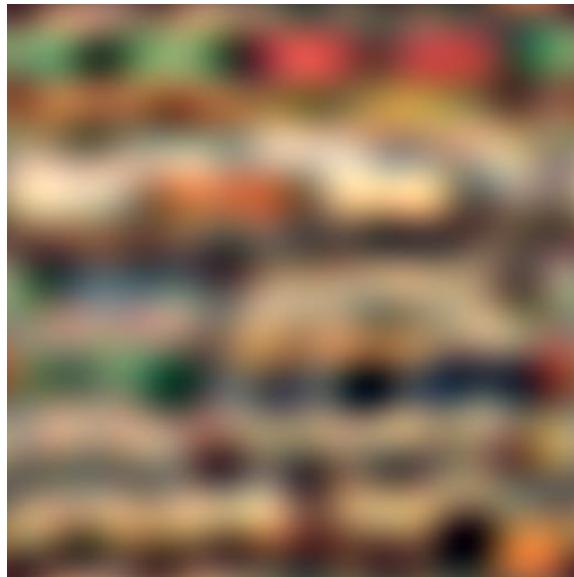


image LPF radius ρ_2

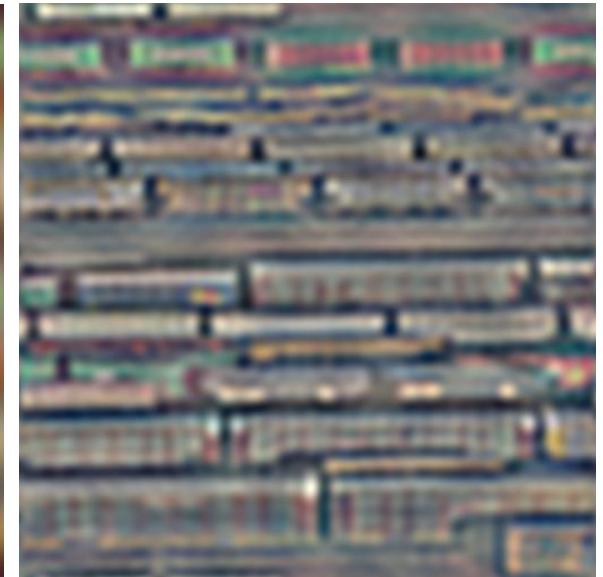
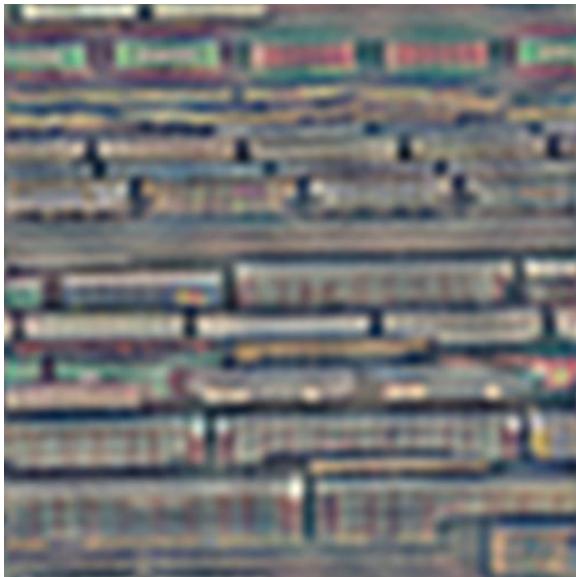


image BPF radii ρ_1, ρ_2^*

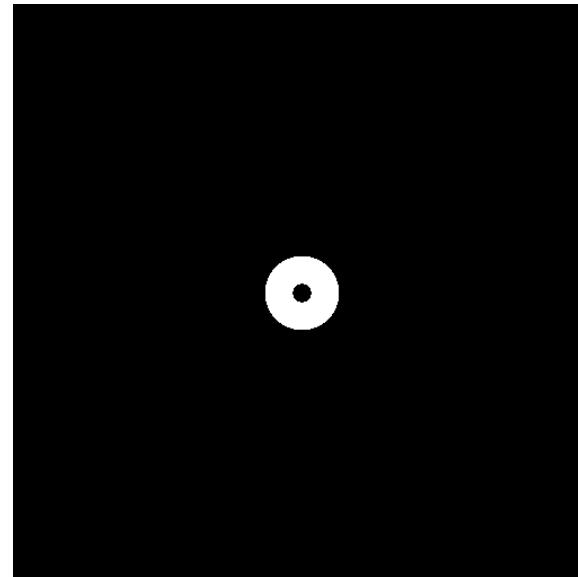


*signed image:
0 mapped to 128

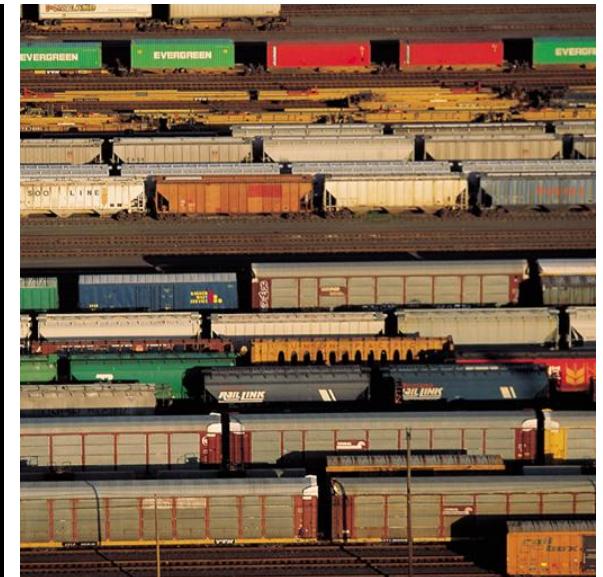
Ideal Bandpass Filter



filtered image*



filter power spectrum



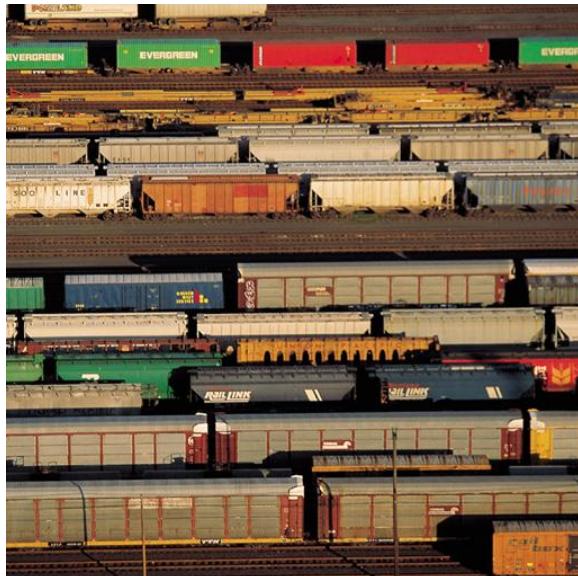
original image



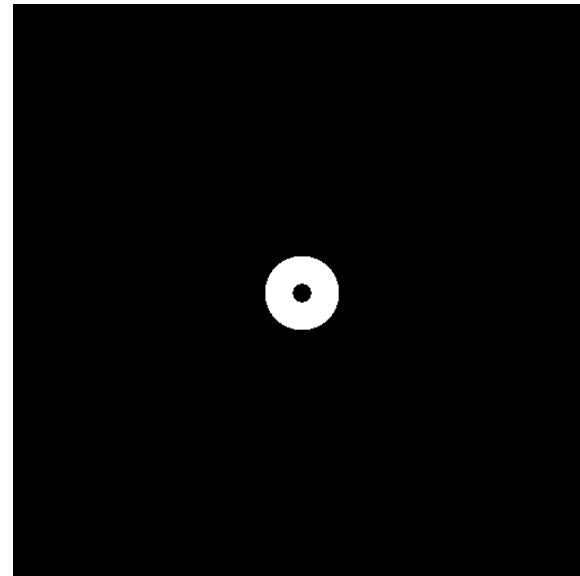
*signed image:
0 mapped to 128

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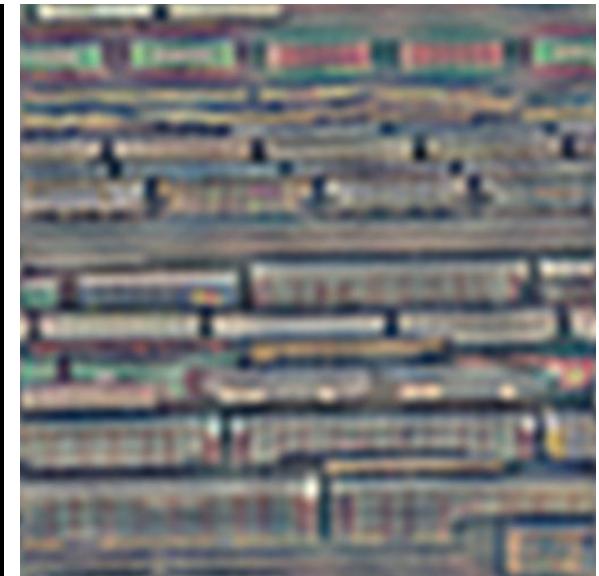
Ideal Bandpass Filter



original image



filter power spectrum

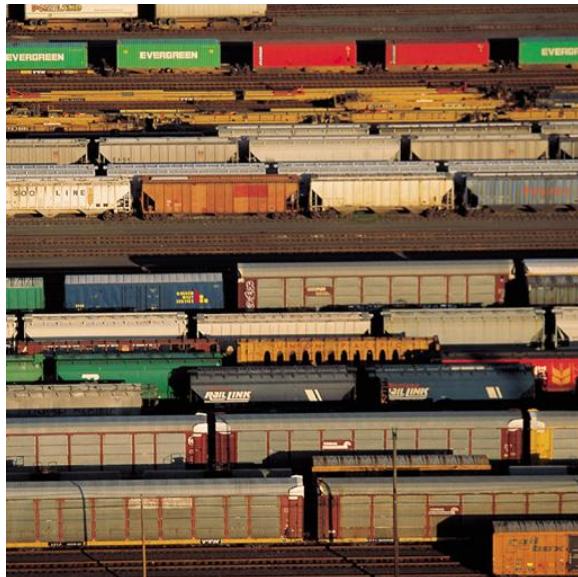


filtered image*

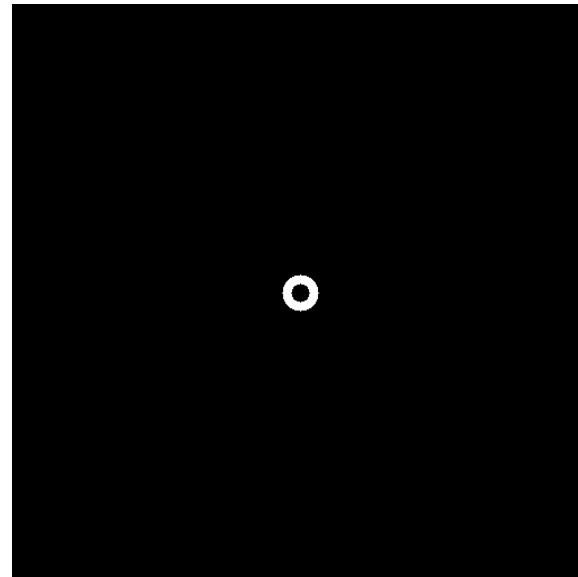


*signed image:
0 mapped to 128

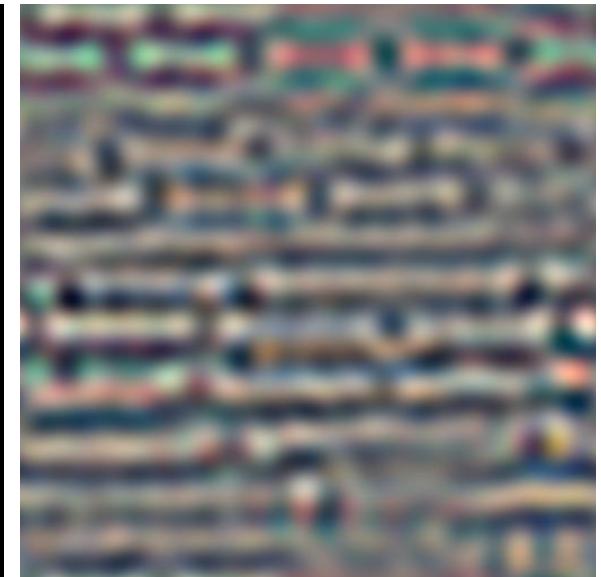
A Different Ideal Bandpass Filter



original image



filter power spectrum



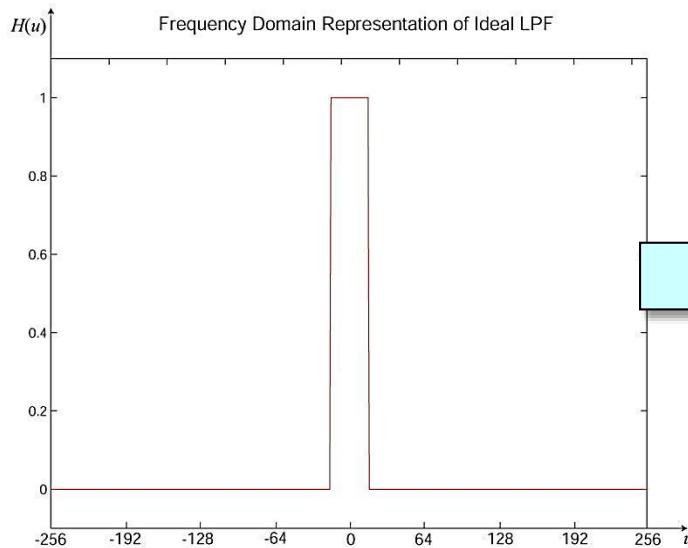
filtered image*



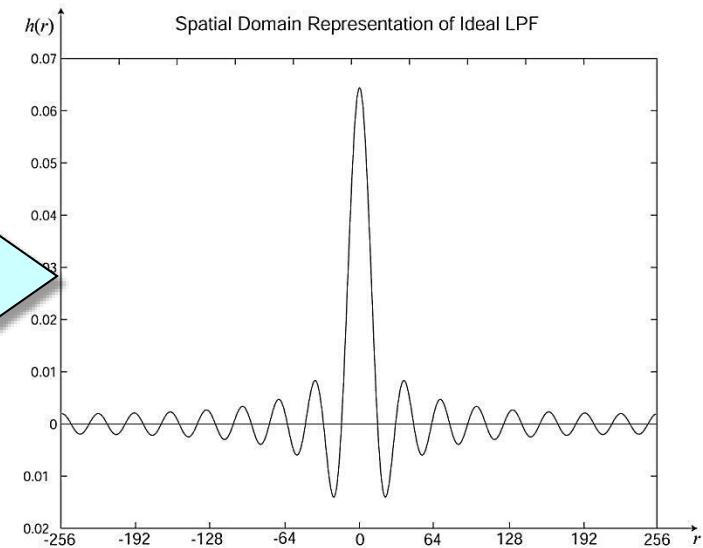
The Optimal Filter



Ideal Filters Do Not Produce Ideal Results



IFT

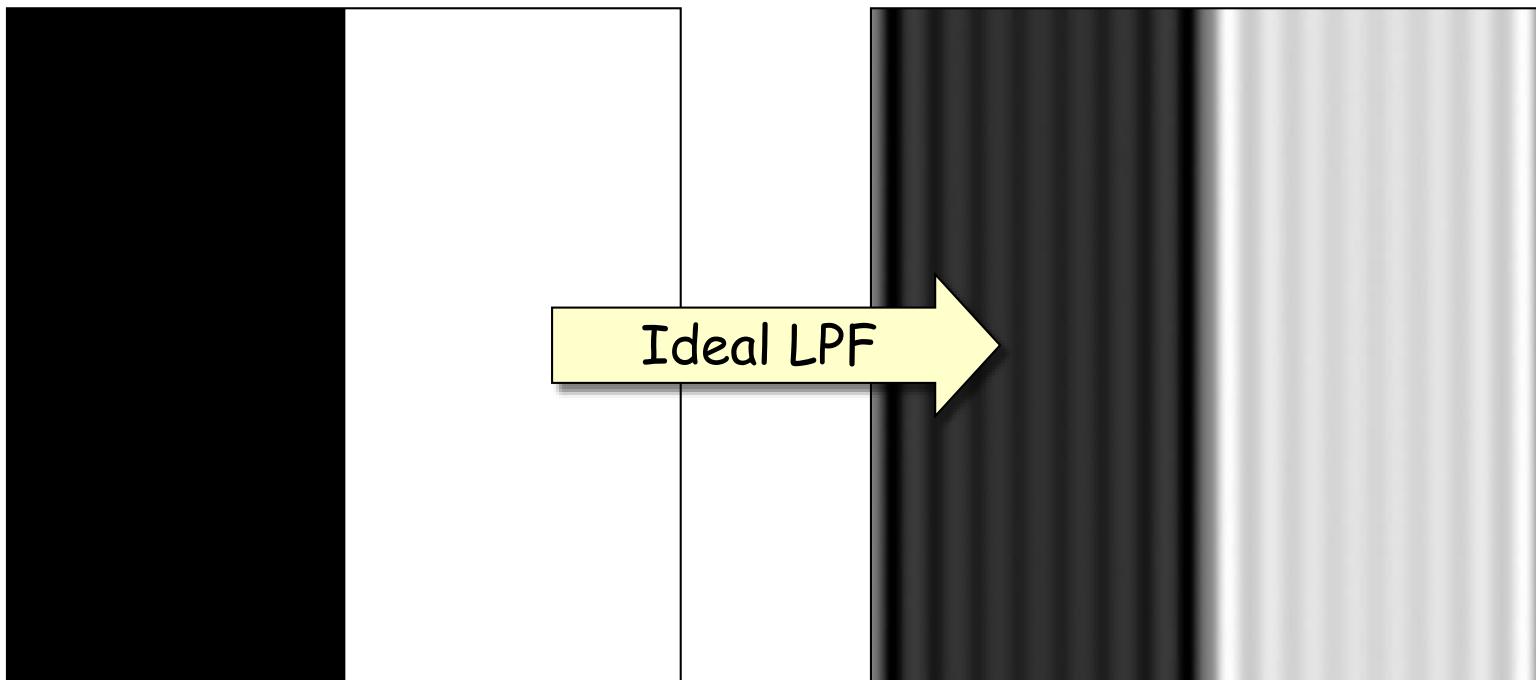


A sharp cutoff in the frequency domain...

...causes ringing in the spatial domain.



Ideal Filters Do Not Produce Ideal Results

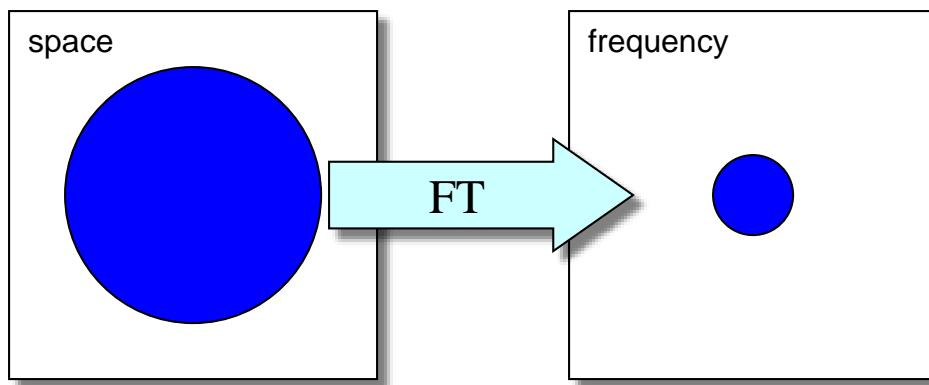
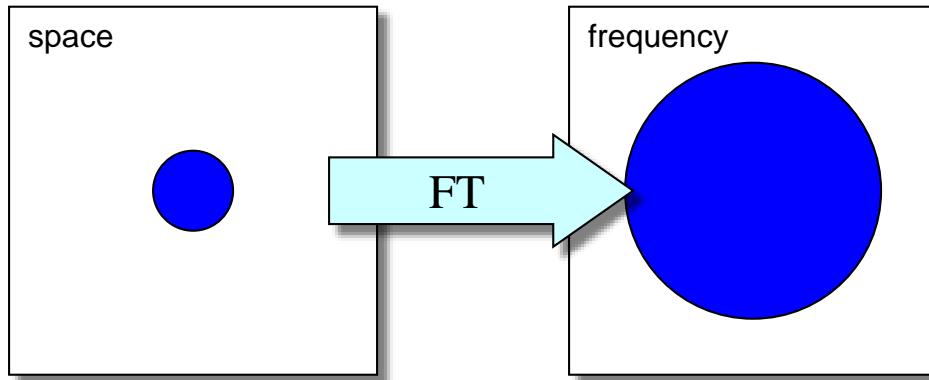


Blurring the image above
w/ an ideal lowpass filter...

...distorts the results with
ringing or ghosting.



The Uncertainty Relation



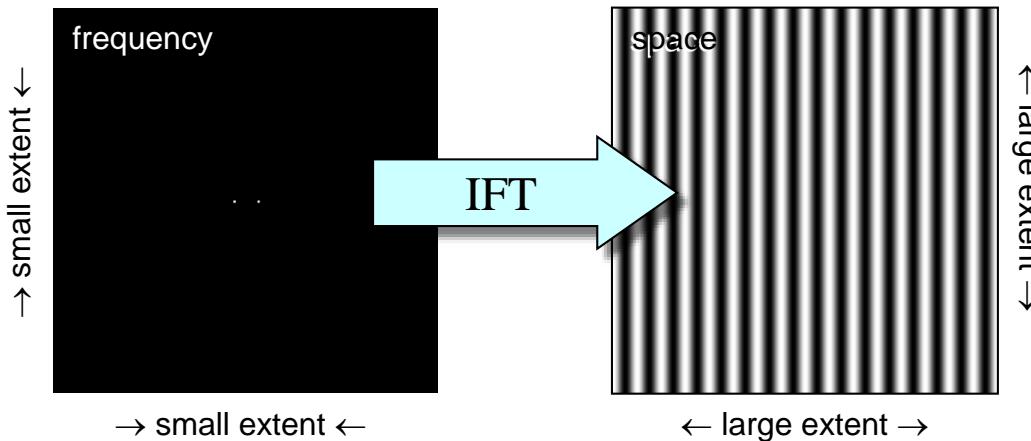
If $\Delta x \Delta y$ is the extent of the object in space and if $\Delta u \Delta v$ is its extent in frequency then,

$$\Delta x \Delta y \cdot \Delta u \Delta v \geq \frac{1}{16\pi^2}$$

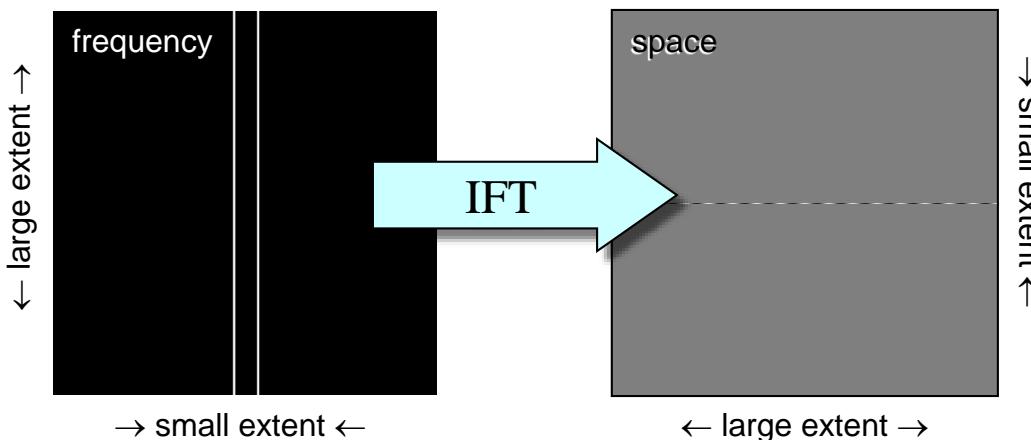
A small object in space has a large frequency extent and vice-versa.



The Uncertainty Relation



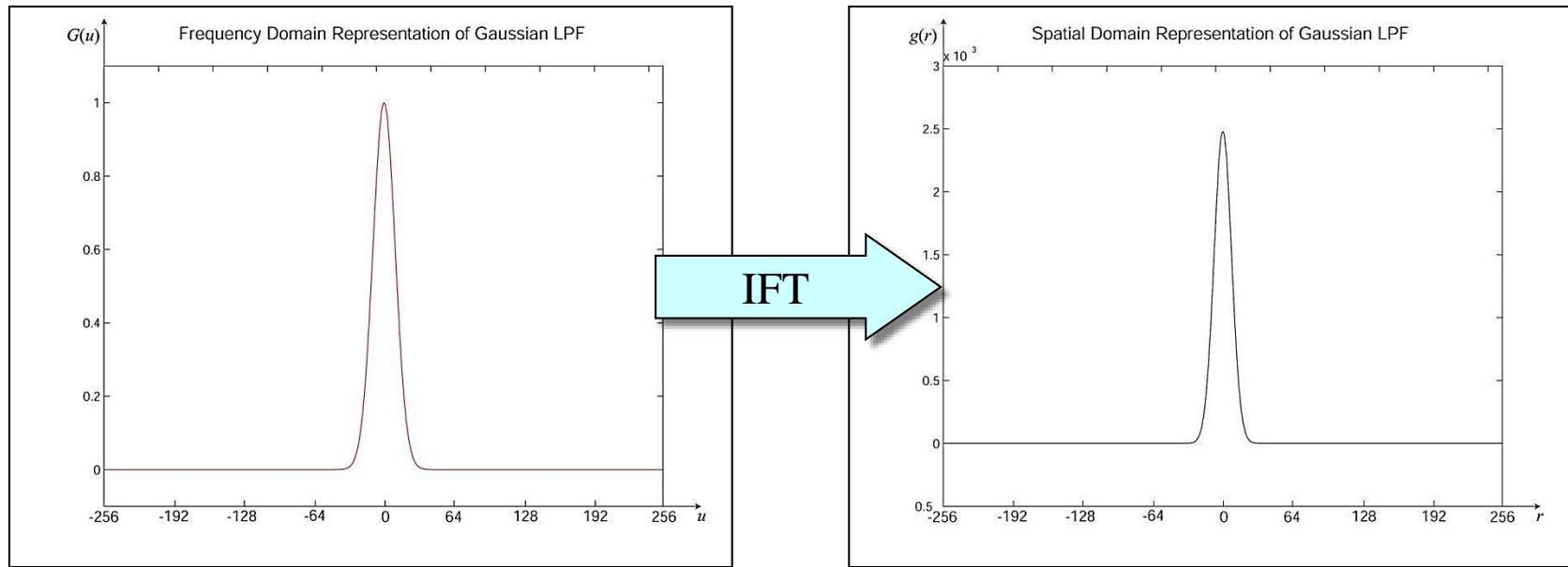
Recall: a symmetric pair of impulses in the frequency domain becomes a sinusoid in the spatial domain.



A symmetric pair of lines in the frequency domain becomes a sinusoidal line in the spatial domain.



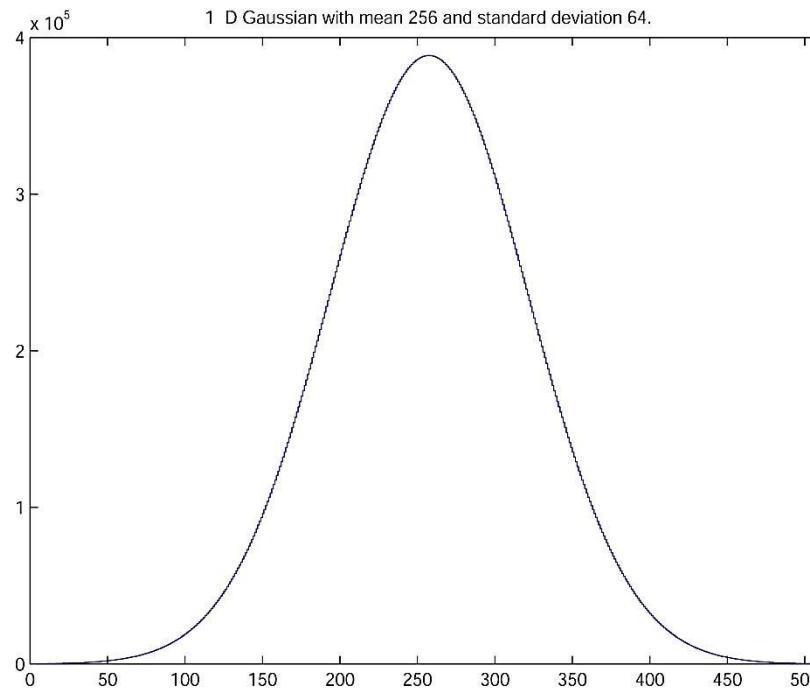
Optimal Filter: The Gaussian



The Gaussian filter optimizes the uncertainty relation. It provides the sharpest cutoff possible without ringing.



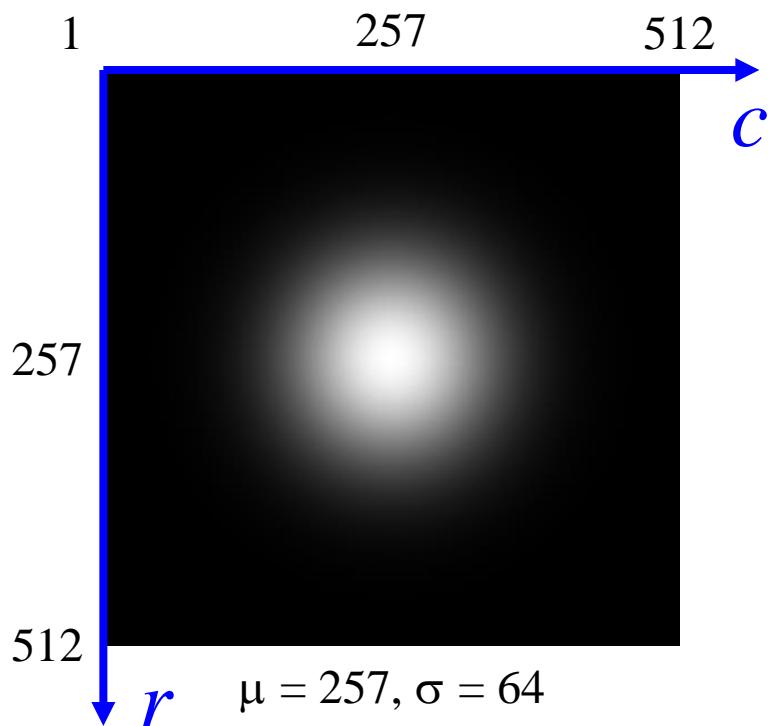
One-Dimensional Gaussian



$$g(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-(x-\mu)^2/2\sigma^2}$$



Two-Dimensional Gaussian



$$g(r, c) = g(r)g(c)$$

$$= \frac{1}{\sigma_r \sigma_c 2\pi} e^{-\frac{(r-\mu_r)^2}{2\sigma_r^2} - \frac{(c-\mu_c)^2}{2\sigma_c^2}}$$

$$= \frac{1}{\sigma_r \sigma_c 2\pi} e^{-\frac{\sigma_c^2 (r-\mu_r)^2 + \sigma_r^2 (c-\mu_c)^2}{2\sigma_r^2 \sigma_c^2}}$$

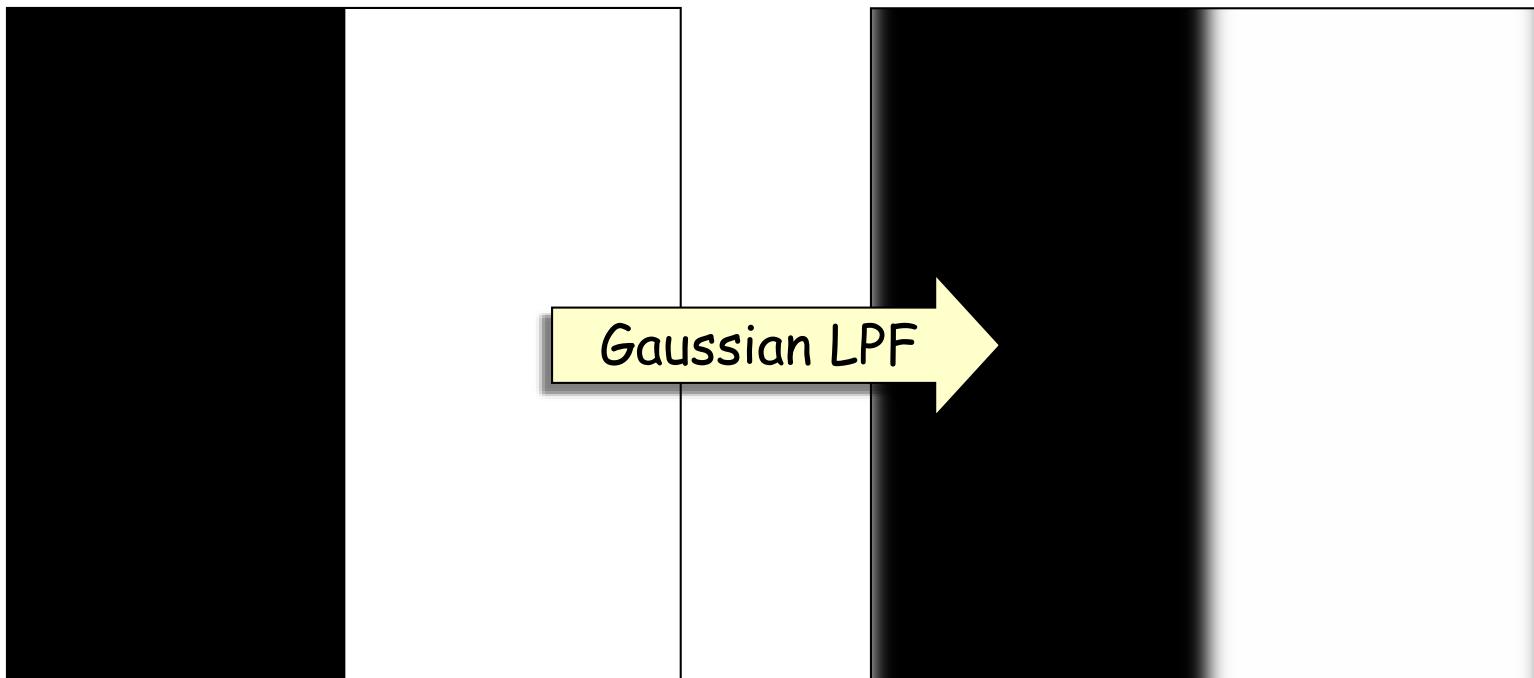
If μ and σ are different for r & c ...

...or if μ and σ are the same for r & c .

$$g(r, c) = \frac{1}{\sigma^2 2\pi} e^{-\frac{(r-\mu)^2 + (c-\mu)^2}{2\sigma^2}}$$



Optimal Filter: The Gaussian

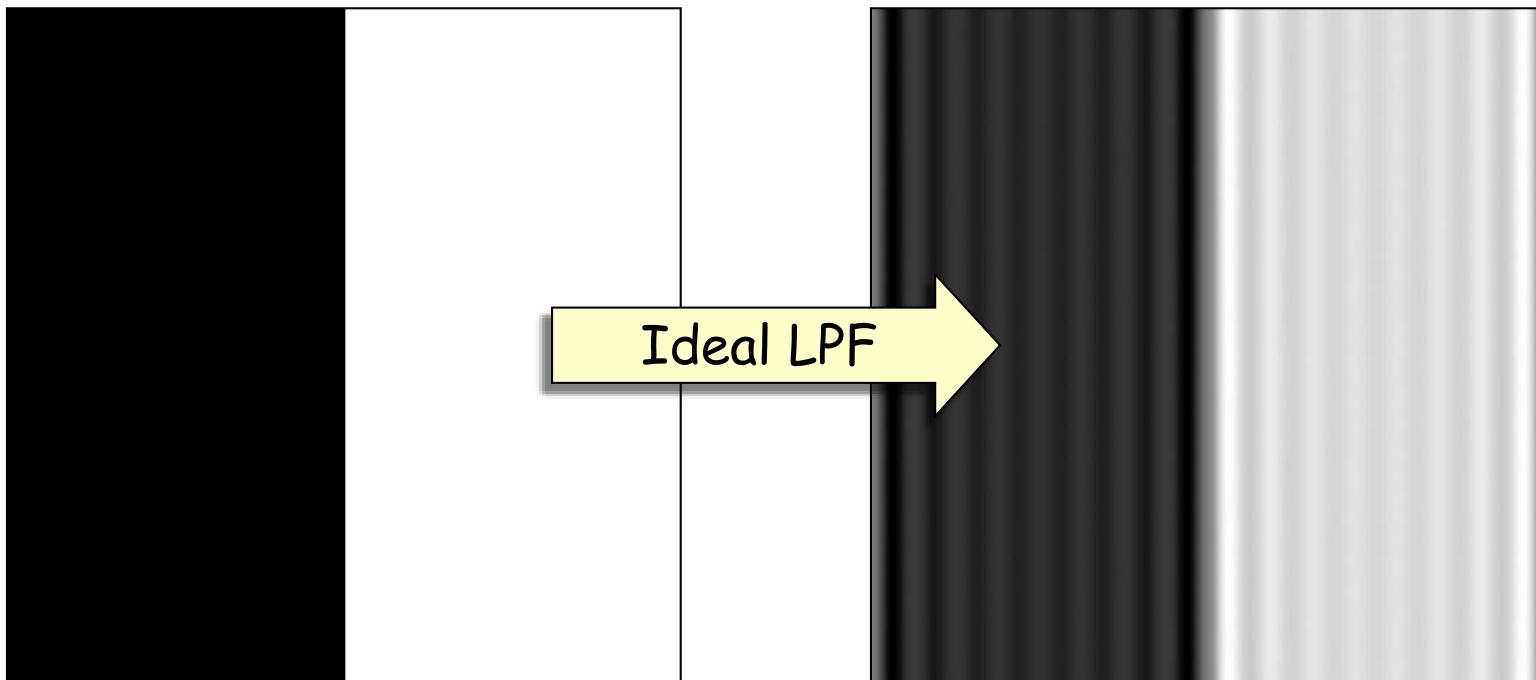


With a gaussian lowpass filter, the image above ...

... is blurred without ringing or ghosting.



Compare with an “Ideal” LPF



Blurring the image above w/
an ideal lowpass filter...

...distorts the results with
ringing or ghosting.

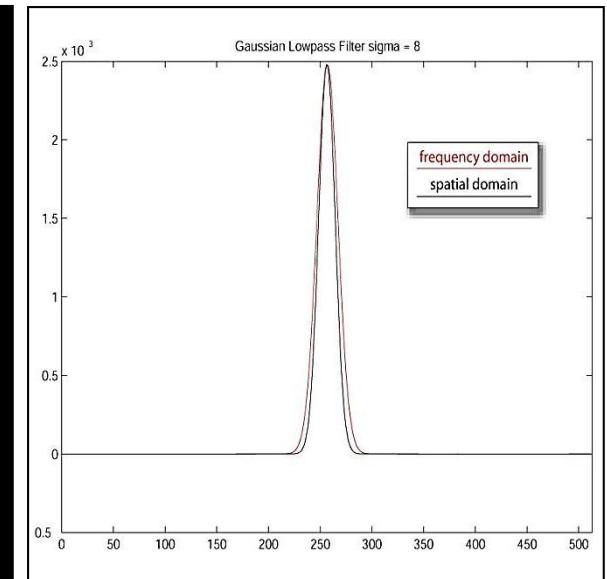
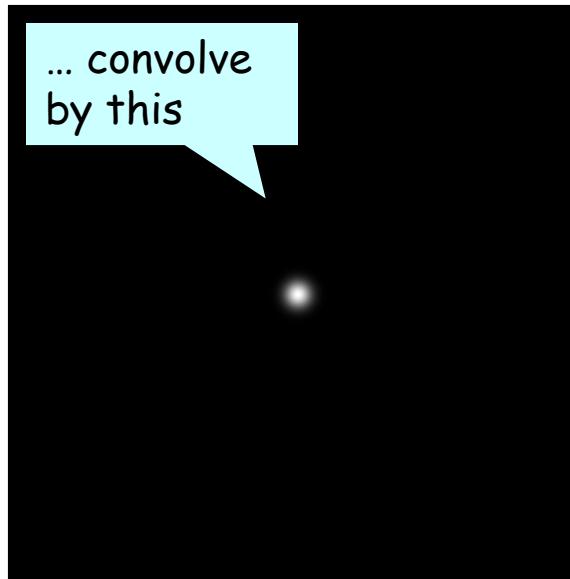
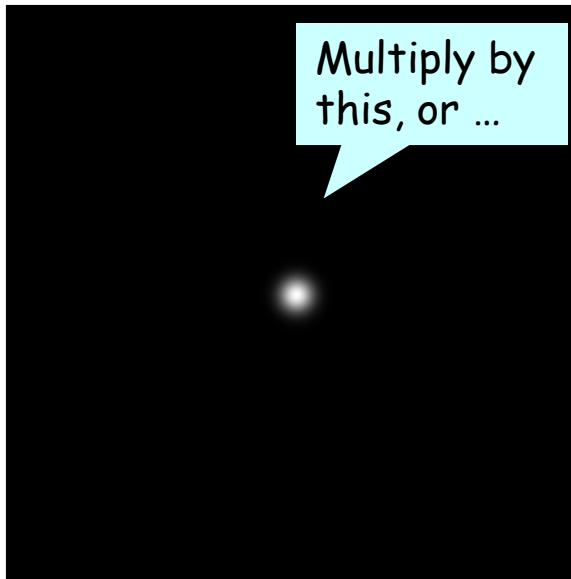


Gaussian Lowpass Filter



Gaussian Lowpass Filter

Image size: 512x512
SD filter sigma = 8



Fourier Domain Rep.

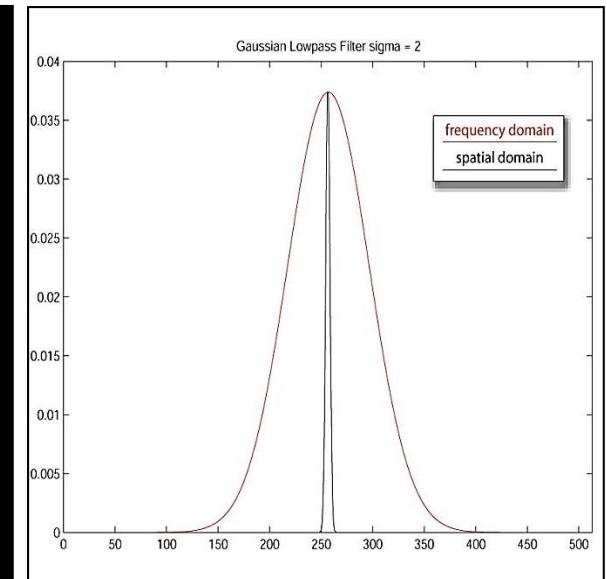
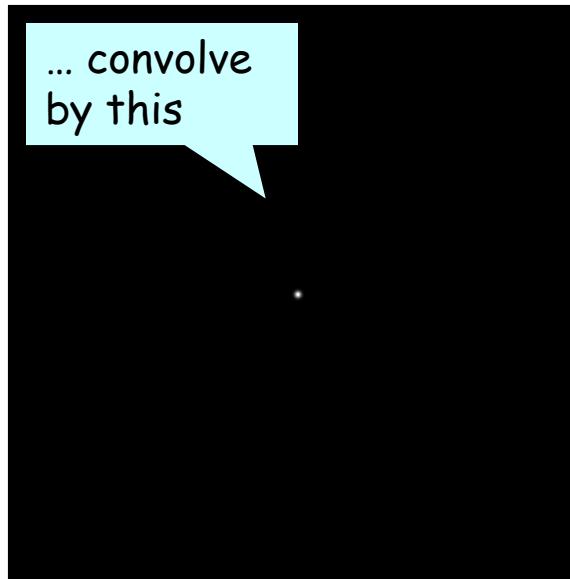
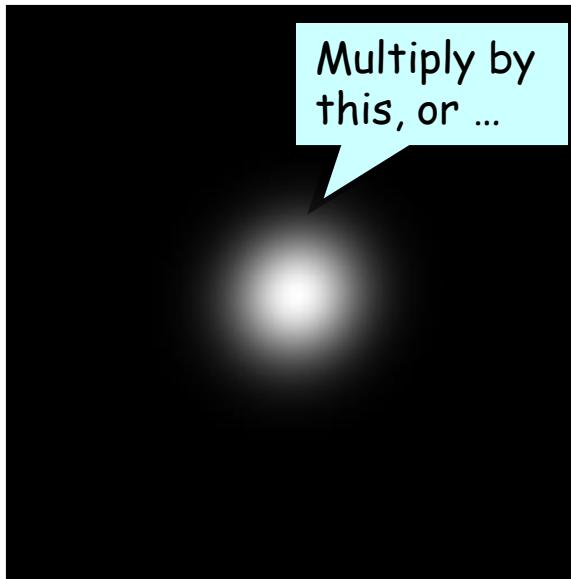
Spatial Representation

Central Profile



Gaussian Lowpass Filter

Image size: 512x512
SD filter sigma = 2



Fourier Domain Rep.

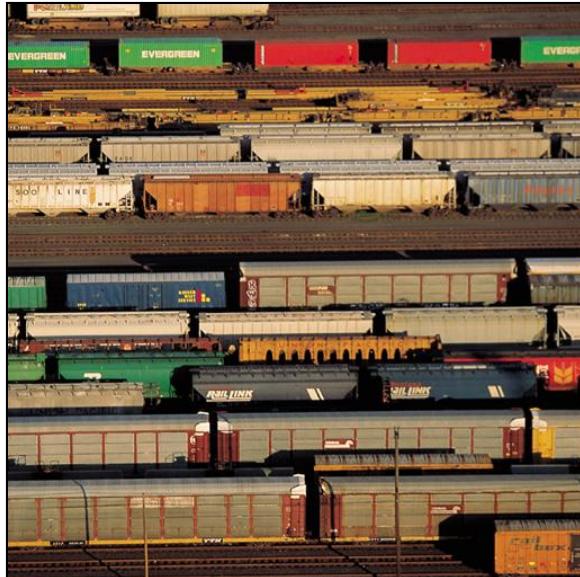
Spatial Representation

Central Profile

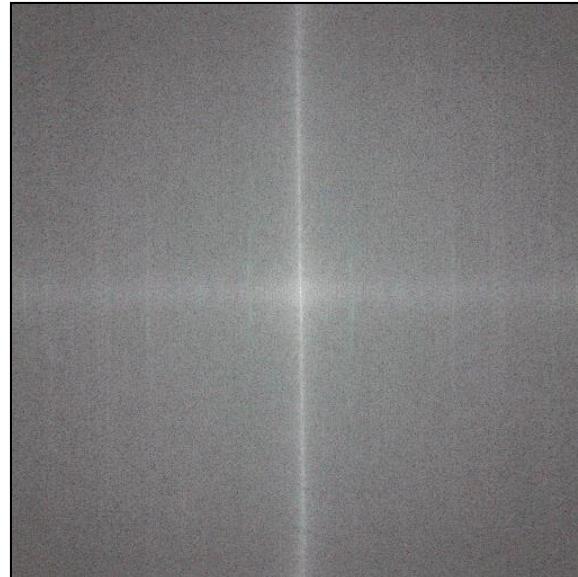


Gaussian Lowpass Filter

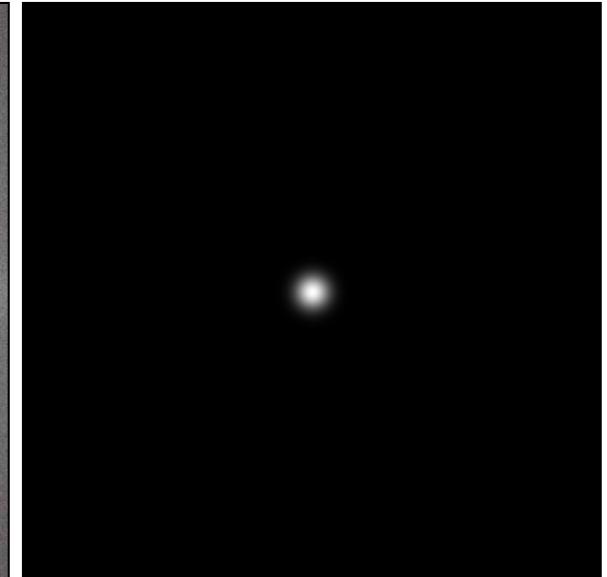
Image size: 512x512
SD filter sigma = 8



Original Image



Power Spectrum

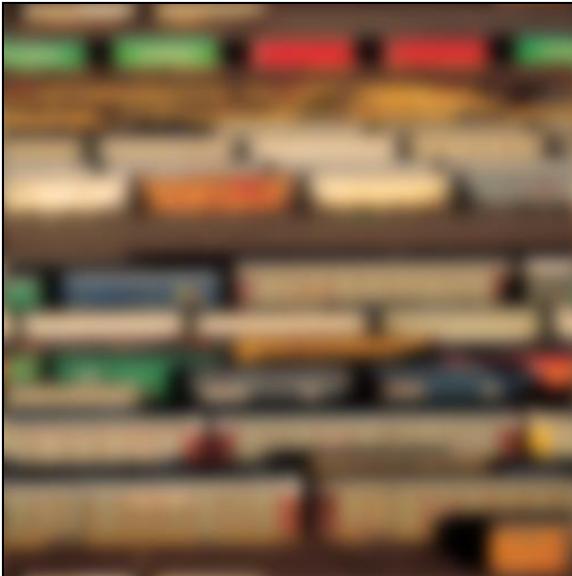


Gaussian LPF in FD

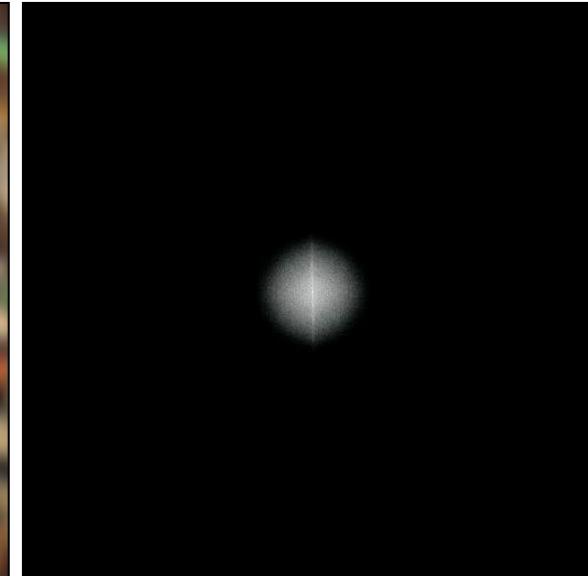


Gaussian Lowpass Filter

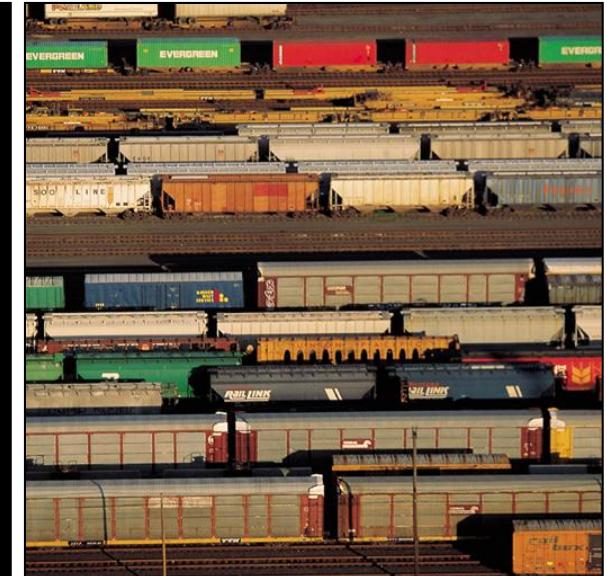
Image size: 512x512
SD filter sigma = 8



Filtered Image



Filtered Power Spectrum

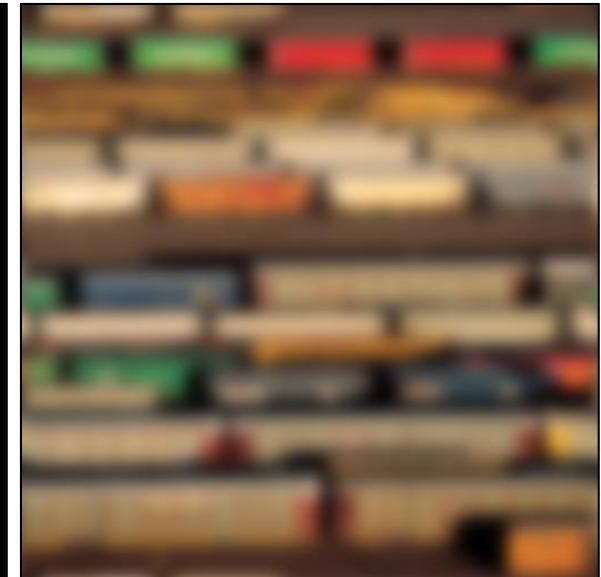
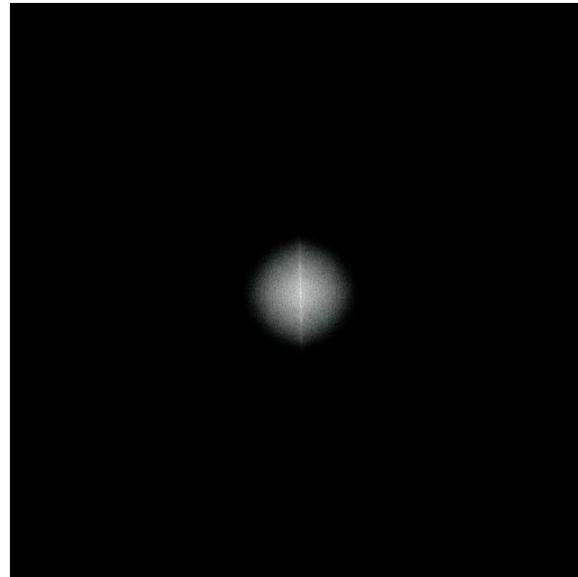
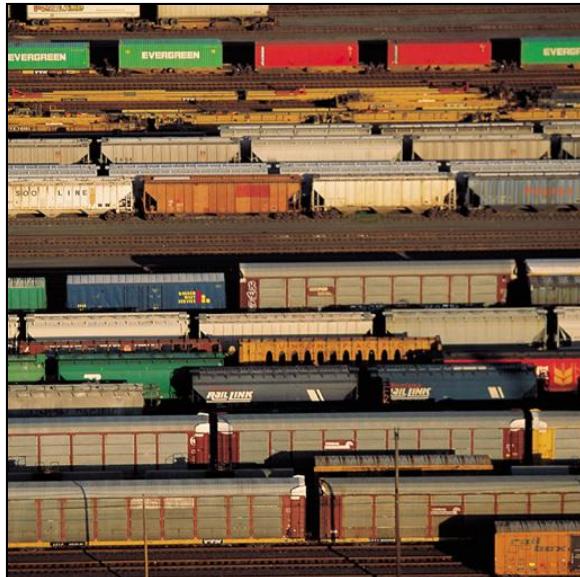


Original Image



Gaussian Lowpass Filter

Image size: 512x512
SD filter sigma = 8



Original Image

Filtered Power Spectrum

Filtered Image



Resolution Sequence

Original Image

$$\sigma_0 = 0$$





Resolution Sequence

Gaussian LPF

$$\sigma_1 = 1$$





Resolution Sequence

Gaussian LPF

$$\sigma_2 = 2$$





Resolution Sequence

Gaussian LPF

$$\sigma_3 = 4$$





Resolution Sequence

Gaussian LPF

$$\sigma_4 = 8$$





Resolution Sequence



Gaussian LPF

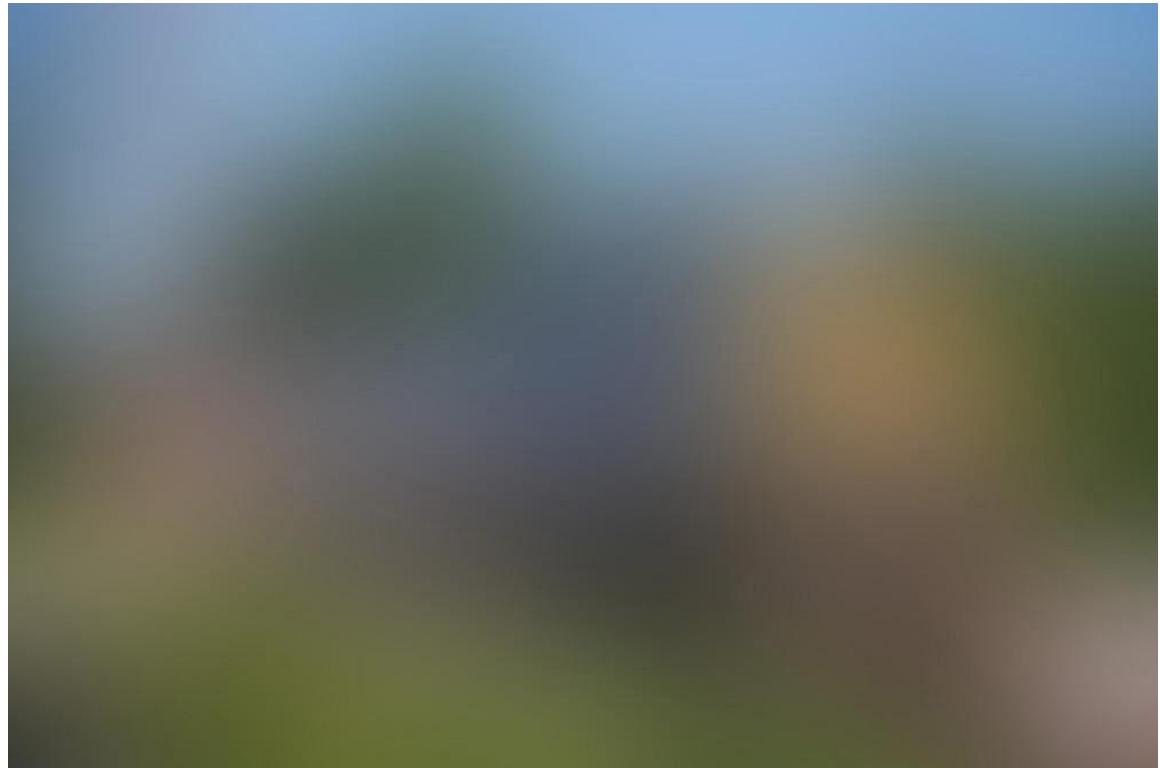
$$\sigma_5 = 16$$



Resolution Sequence

Gaussian LPF

$$\sigma_6 = 32$$

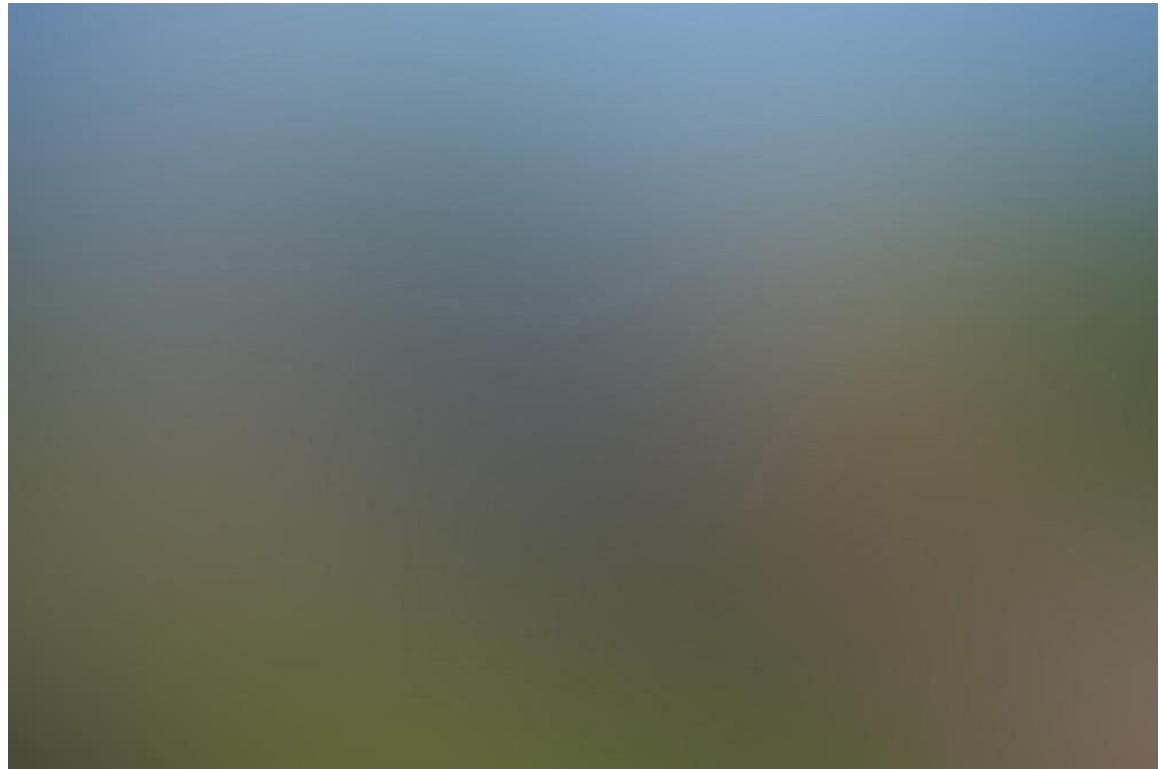




Resolution Sequence

Gaussian LPF

$$\sigma_7 = 64$$





Resolution Sequence

Gaussian LPF

$$\sigma_8 = 128$$



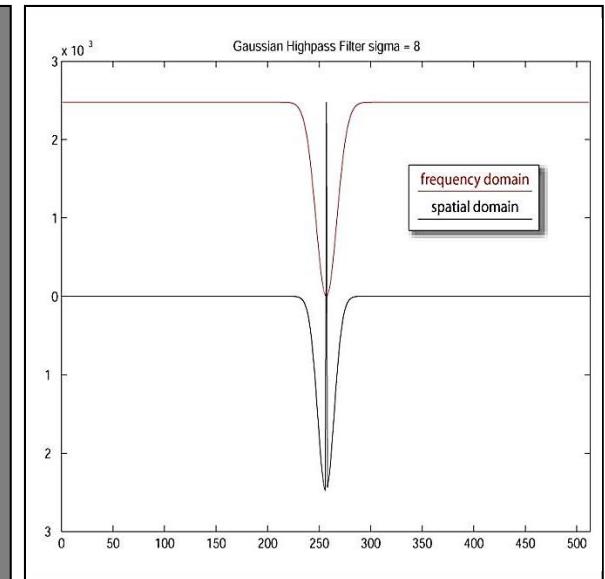
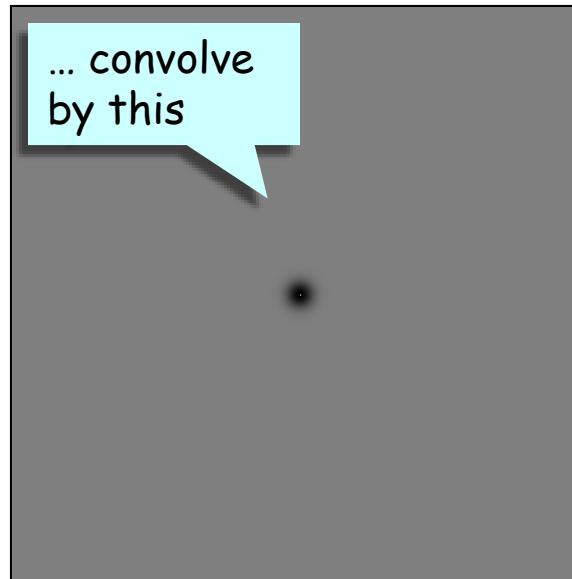
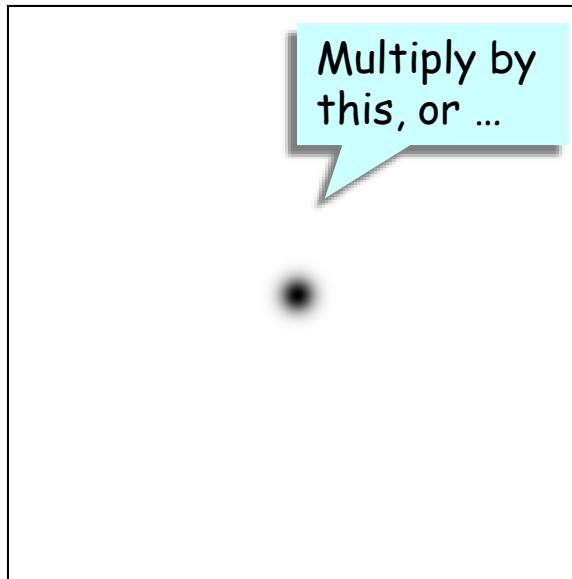


Gaussian Highpass Filter



Gaussian Highpass Filter

Image size: 512x512
FD notch sigma = 8



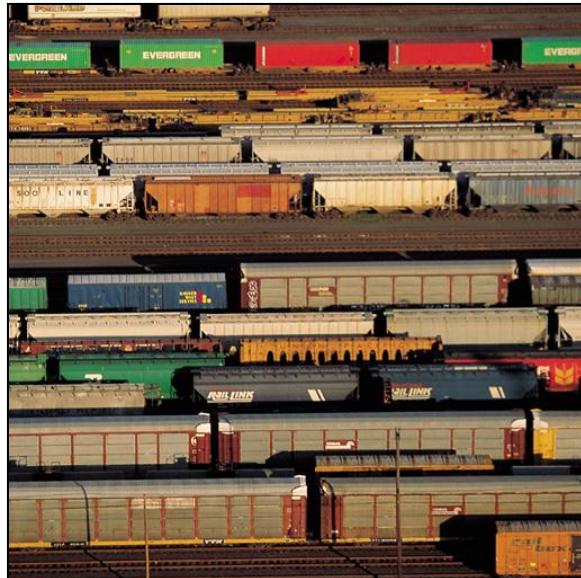
Fourier Domain Rep.

Spatial Representation

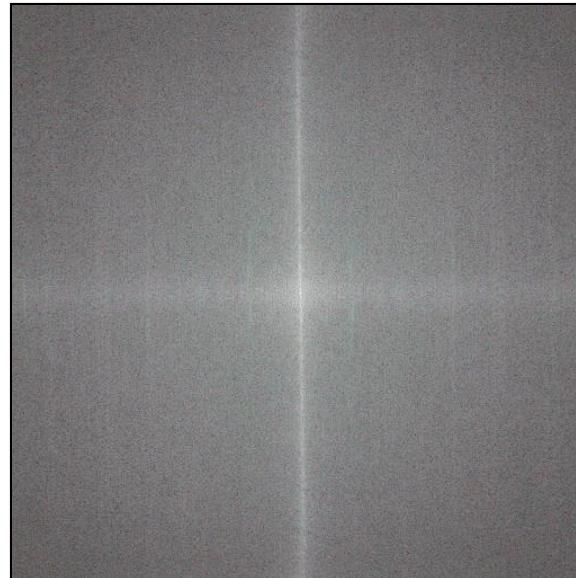
Central Profile



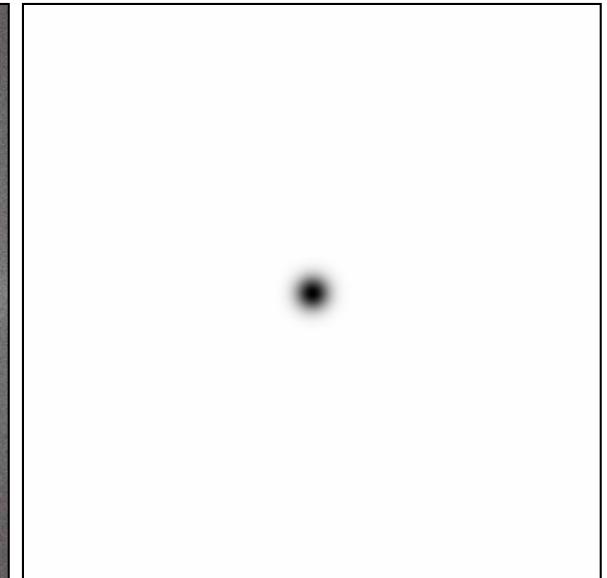
Gaussian Highpass Filter



Original Image



Power Spectrum



Gaussian HPF in FD

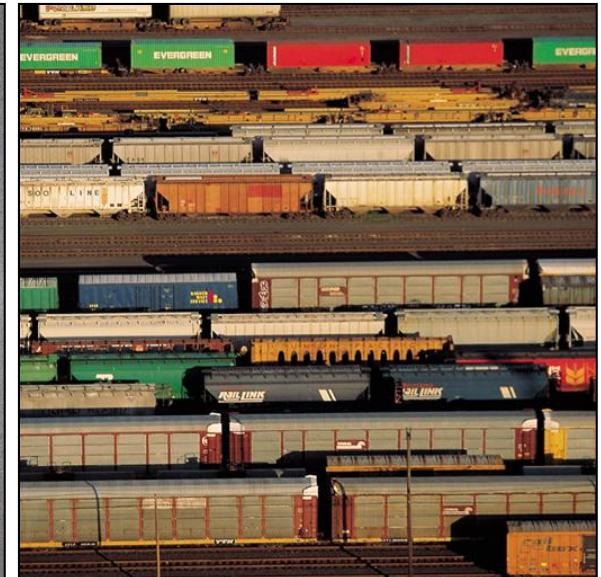
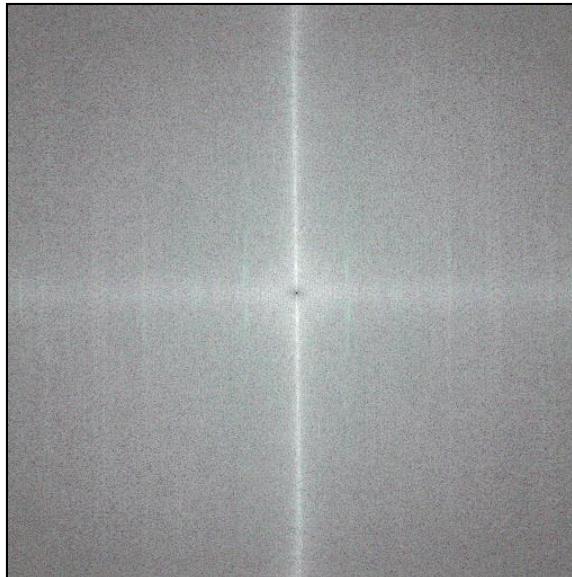
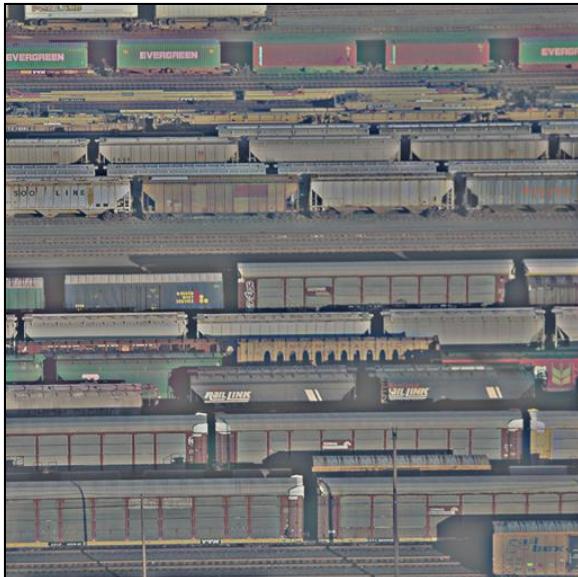


*signed image:
0 mapped to 128

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Gaussian Highpass Filter

Image size: 512x512
FD notch sigma = 8



Filtered Image*

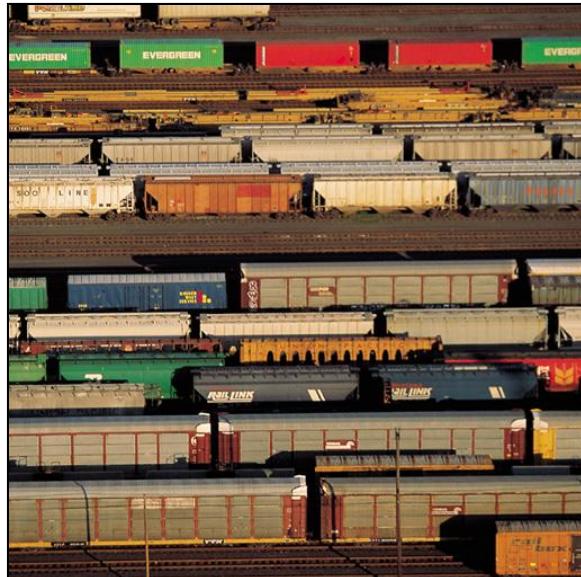
Filtered Power Spectrum

Original Image



*signed image:
0 mapped to 128

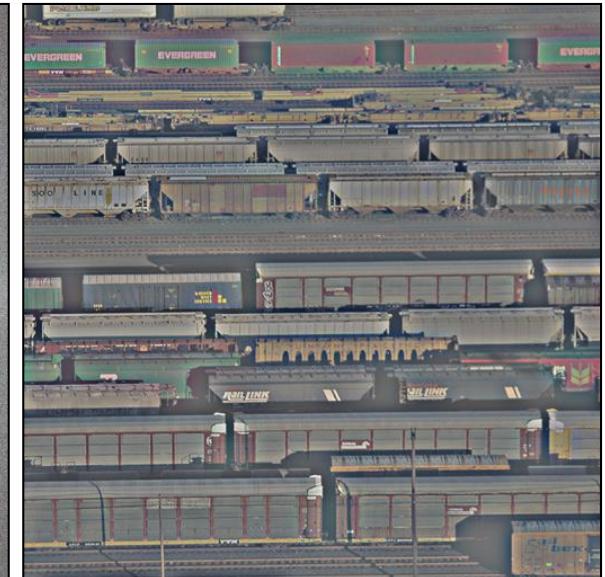
Gaussian Highpass Filter



Original Image



Filtered Power Spectrum



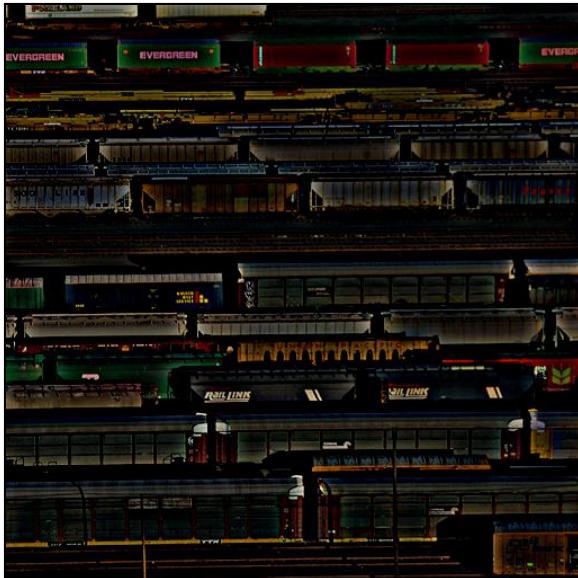
Filtered Image*



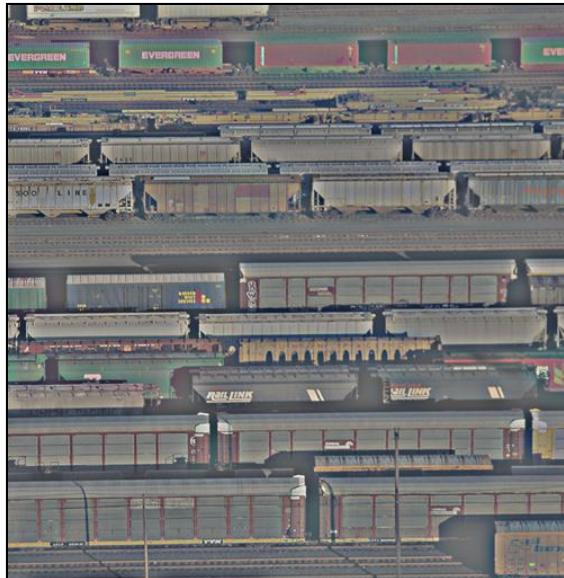
*signed image:
0 mapped to 128

Gaussian Highpass Filter

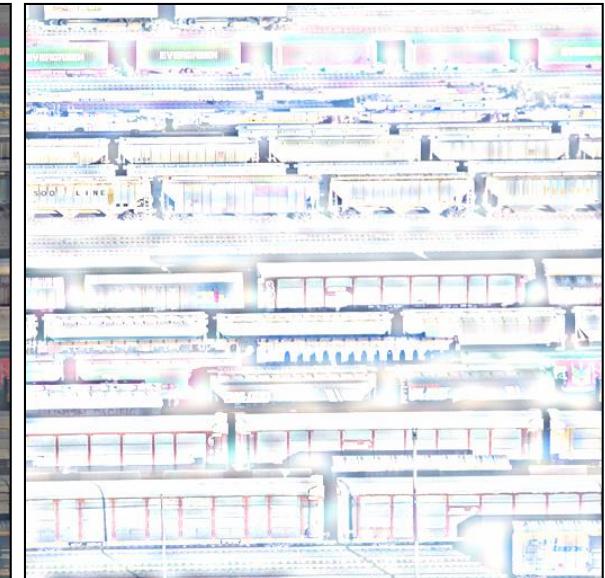
Image size: 512x512
FD notch sigma = 8



Positive Pixels



Filtered Image*

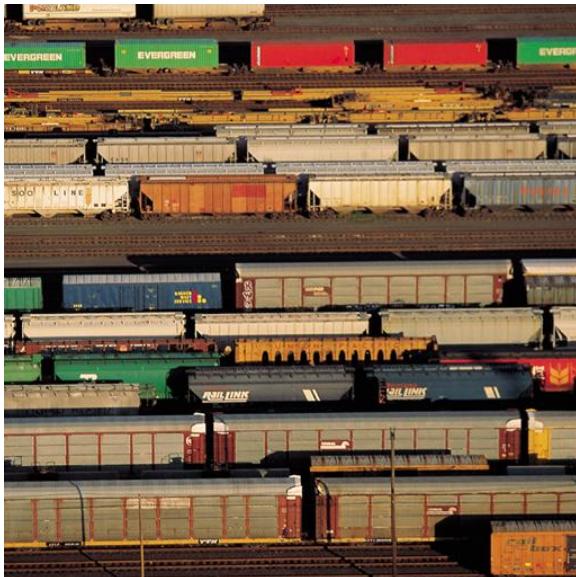


Negative Pixels

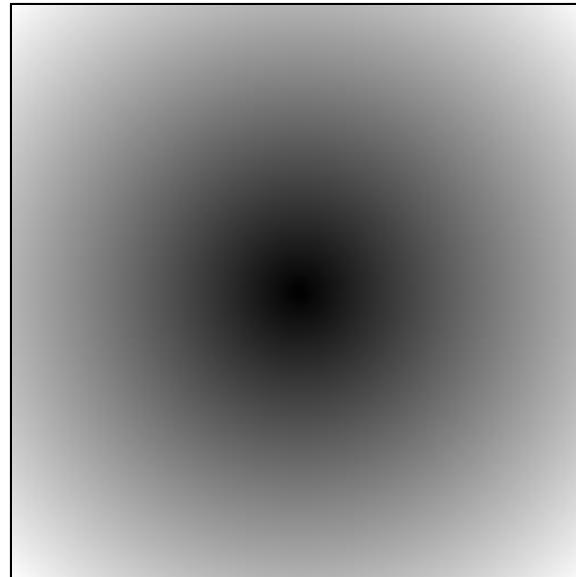


*signed image:
0 mapped to 128

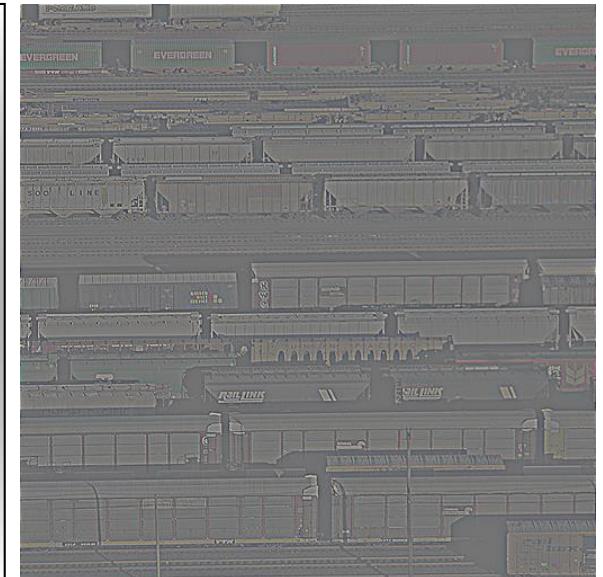
Another Gaussian Highpass Filter



Original Image



Filter Power Spectrum



Filtered Image*



Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_9 = 256$.

$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_9)].$$





Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_8 = 128$.

$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_8)].$$





Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_7 = 64$.

$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_7)].$$





Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_6 = 32$.

$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_6)].$$





Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_5 = 16$.

$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_5)].$$





Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_4 = 8$.

$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_4)].$$





Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_3 = 4$.

$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_3)].$$





Highpass Sequence

Difference between original image and Gaussian LPF image at $\sigma_2 = 2$.



$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_2)].$$



Highpass Sequence

Difference between
original image and
Gaussian LPF image
at $\sigma_1 = 1$.



$$\mathbf{J} = \mathbf{I} - [\mathbf{I} * g(\sigma_1)].$$



Highpass Sequence

Original Image

$$\sigma_0 = 0$$





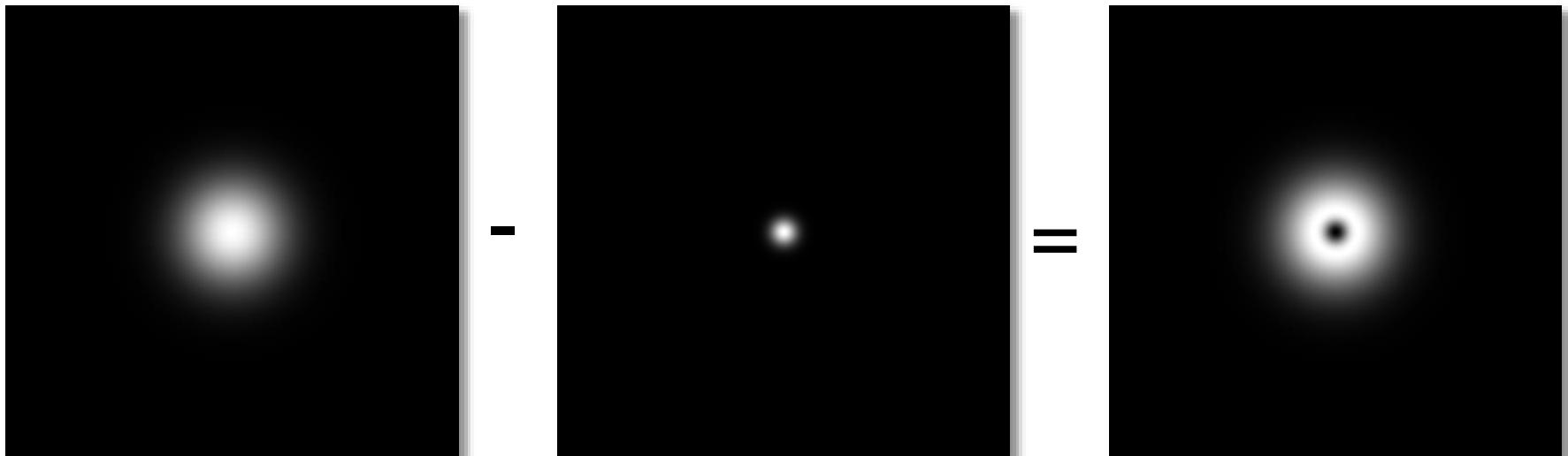
Gaussian Bandpass Filter



Gaussian Bandpass Filter

A bandpass filter is created by

- (1) subtracting a FD radius ρ_2 lowpass filtered image from a FD radius ρ_1 lowpass filtered image, where $\rho_2 < \rho_1$, or
- (2) convolving the image with a matrix that is the difference of the two lowpass matrixs.



FD LP matrix with radius σ_1

FD LP matrix with radius σ_2

FD BP matrix $\sigma_1 - \sigma_2$



*signed image:
0 mapped to 128

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Gaussian Bandpass Filter

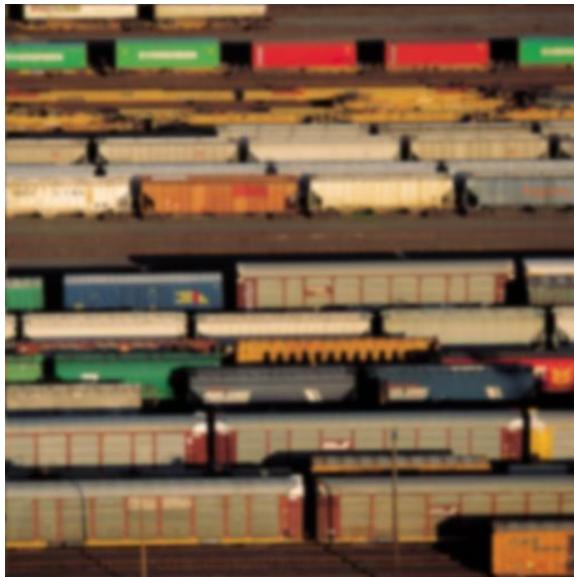


image LPF radius ρ_1

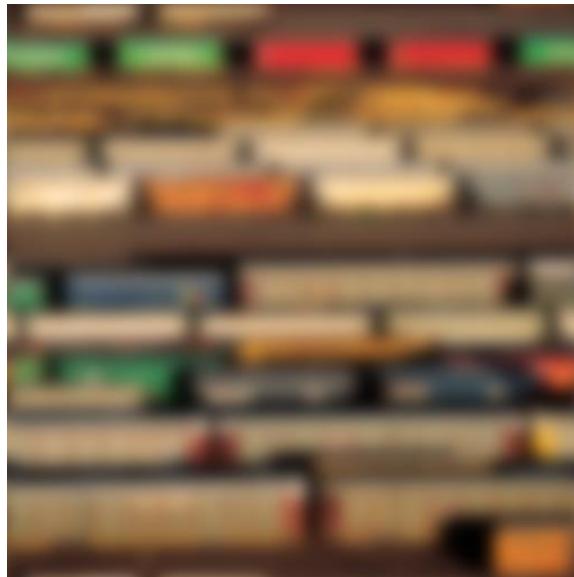


image LPF radius ρ_2

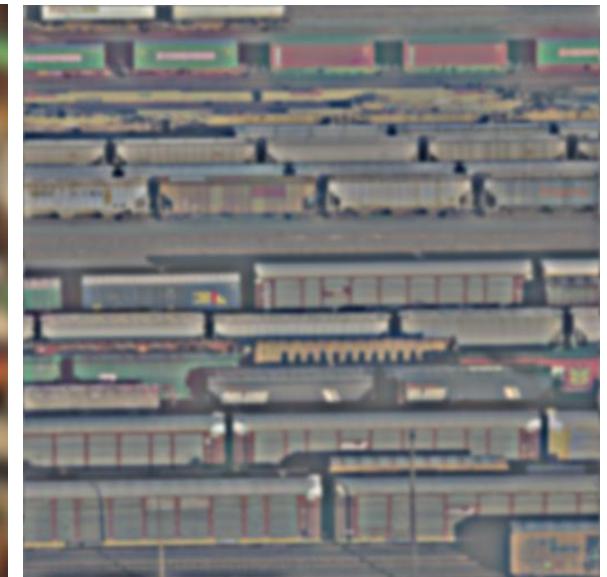
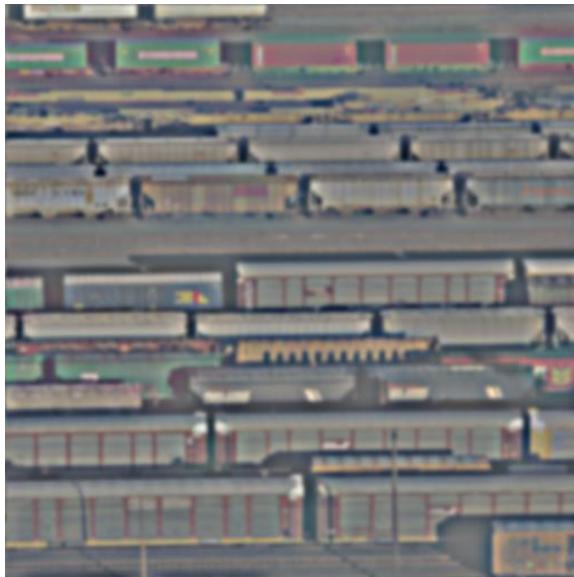


image BPF radii ρ_1, ρ_2^*

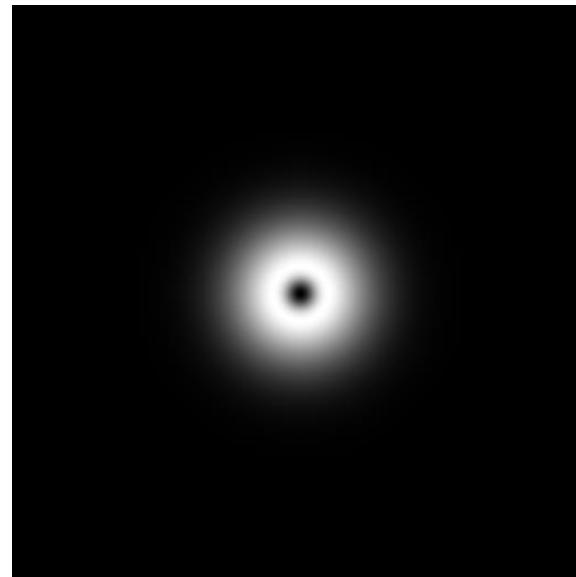


*signed image:
0 mapped to 128

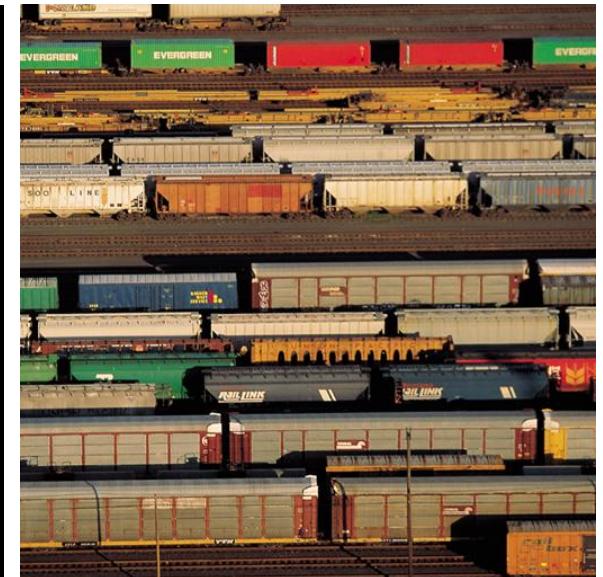
Gaussian Bandpass Filter



filtered image*



filter power spectrum

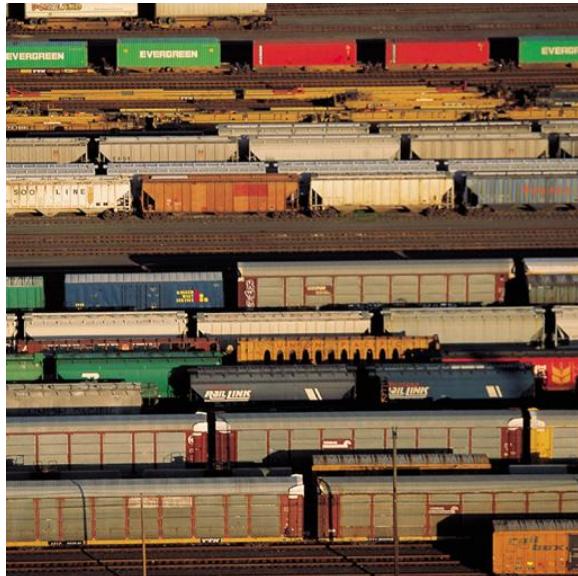


original image

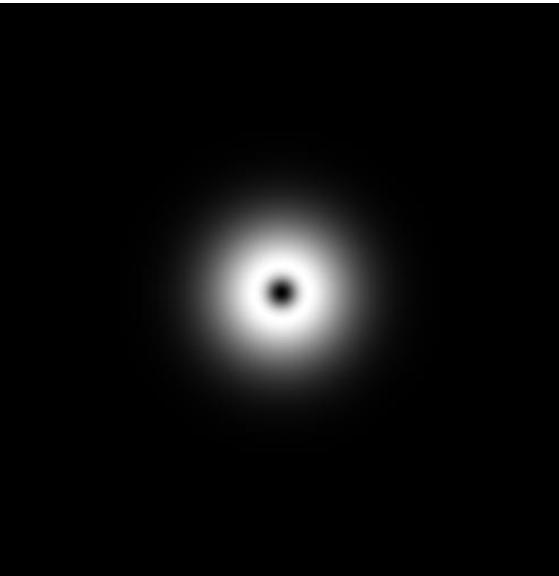


*signed image:
0 mapped to 128

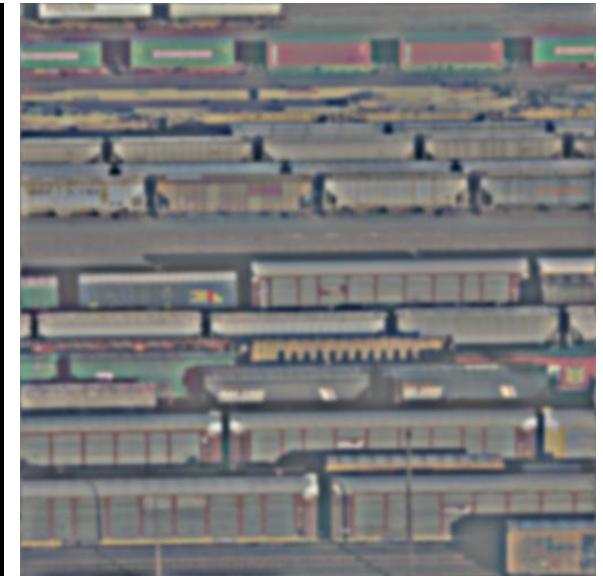
Ideal Bandpass Filter



original image



filter power spectrum

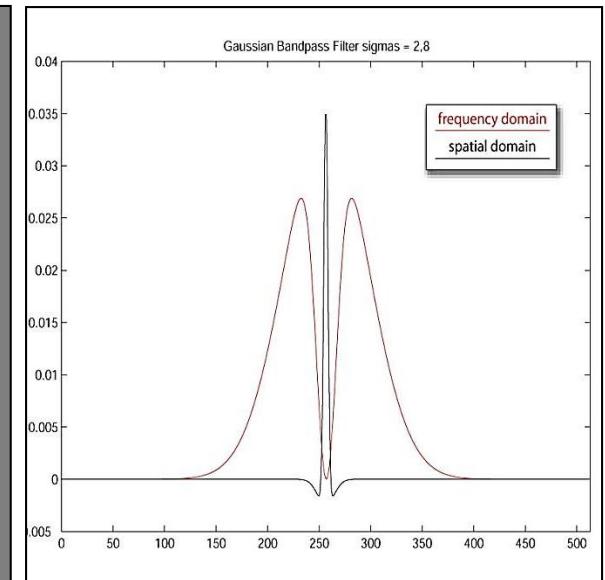
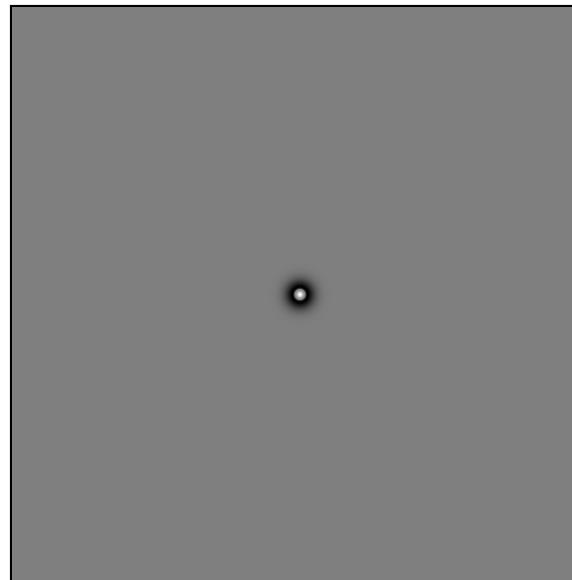
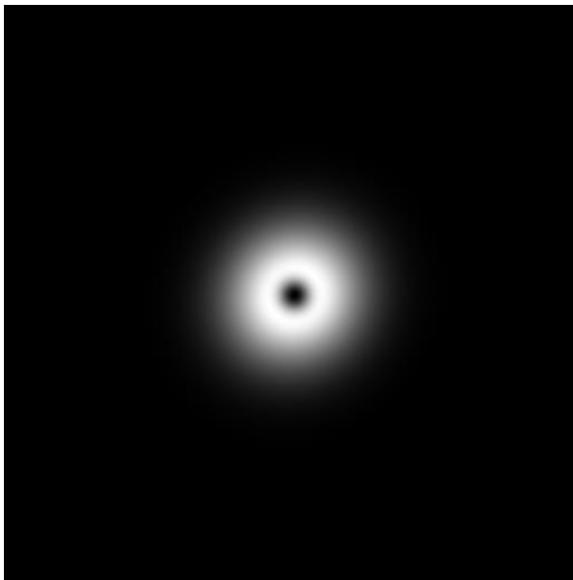


filtered image*



Gaussian Bandpass Filter

Image size: 512x512
 $\sigma = 2 - \sigma = 8$



Fourier Domain Rep.

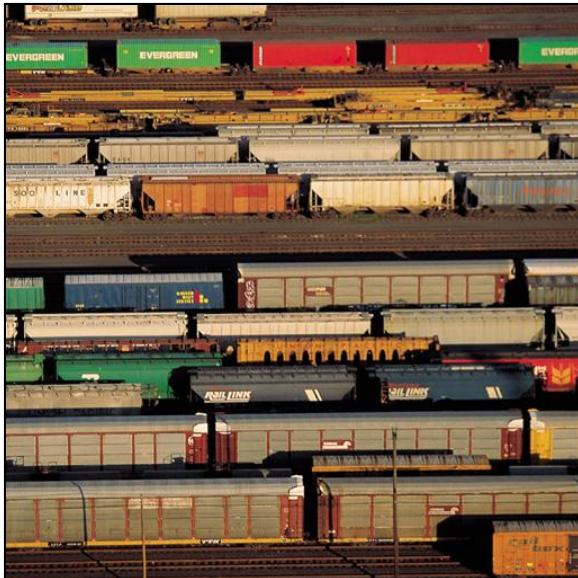
Spatial Representation

Central Profile

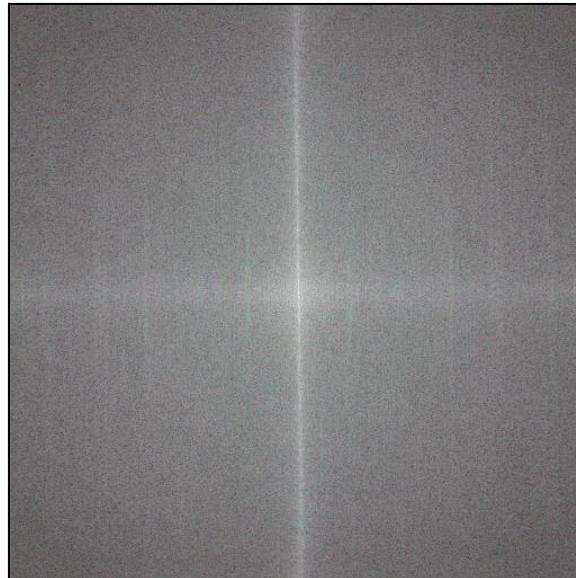


Gaussian Bandpass Filter

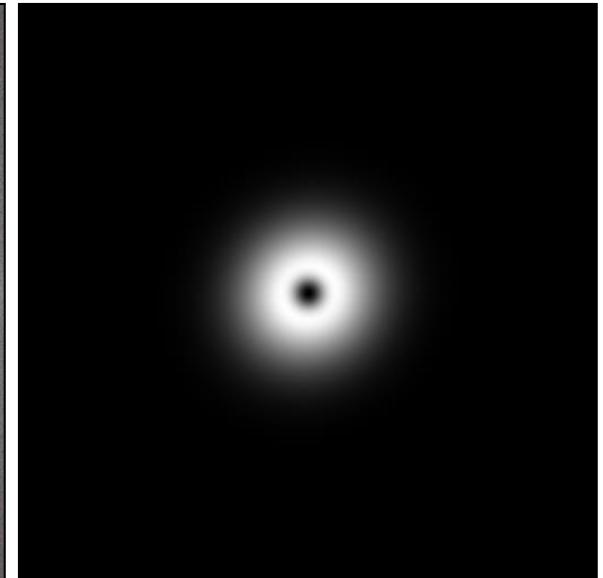
Image size: 512x512
sigma = 2 - sigma = 8



Original Image



Power Spectrum



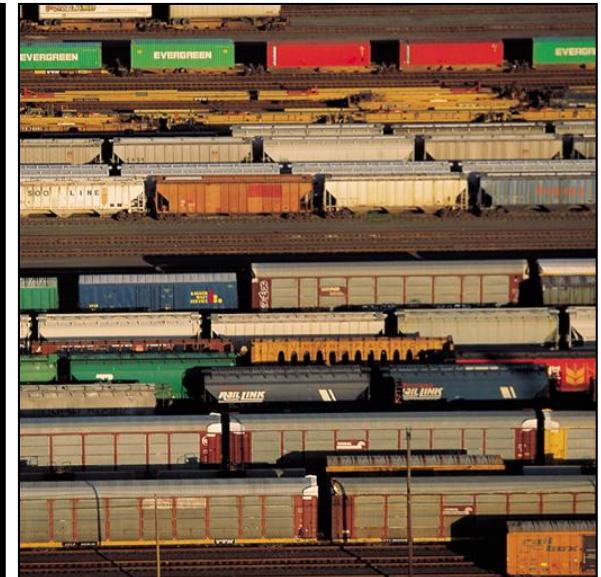
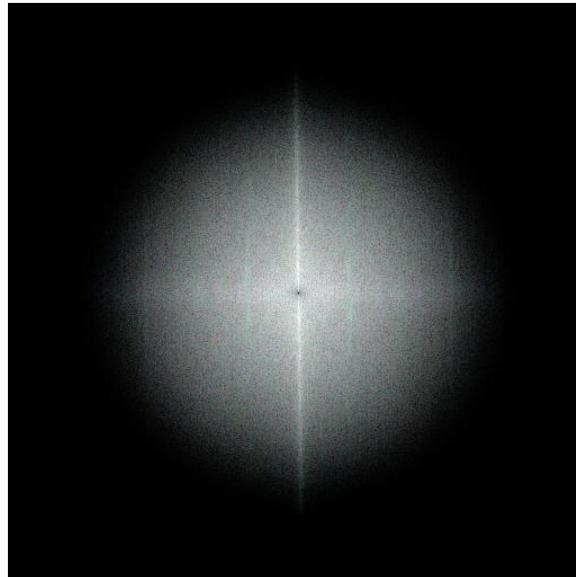
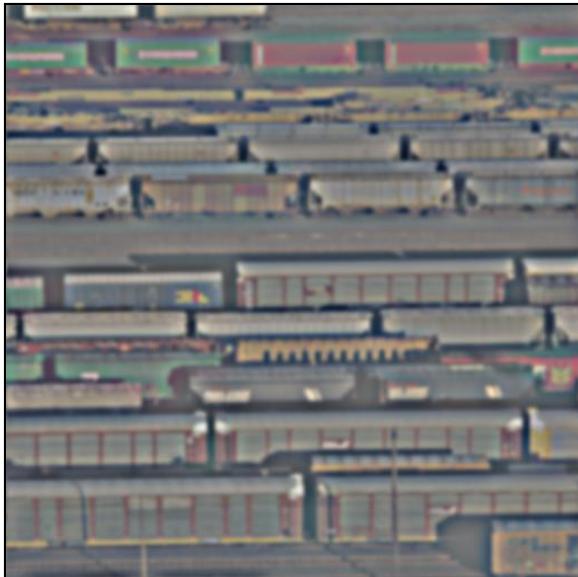
Gaussian BPF in FD



*signed image:
0 mapped to 128

Gaussian Bandpass Filter

Image size: 512x512
sigma = 2 - sigma = 8



Filtered Image*

Filtered Power Spectrum

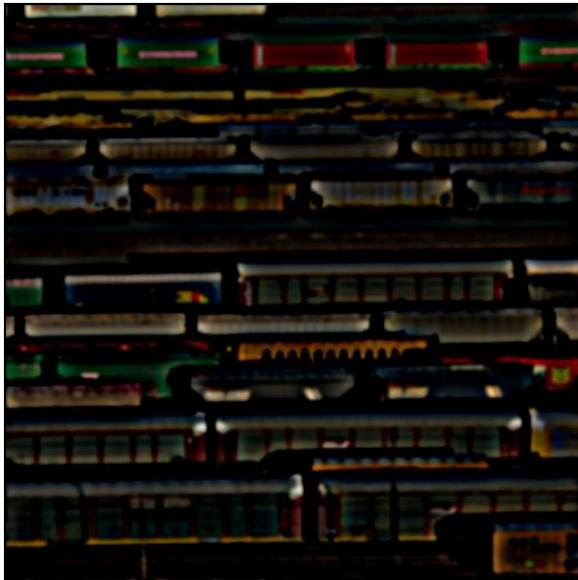
Original Image



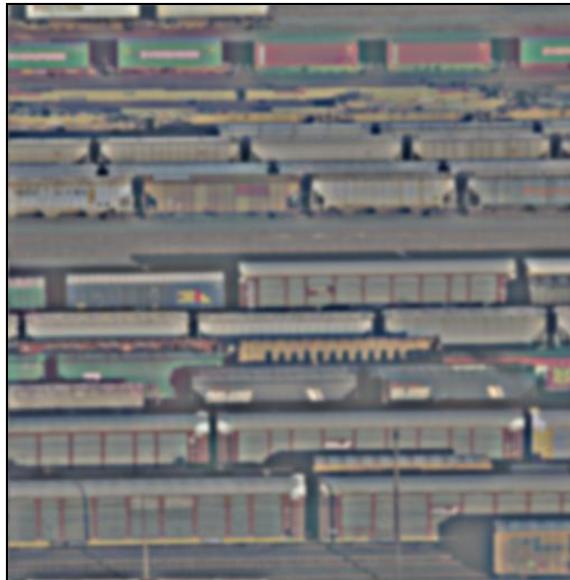
*signed image:
0 mapped to 128

Gaussian Bandpass Filter

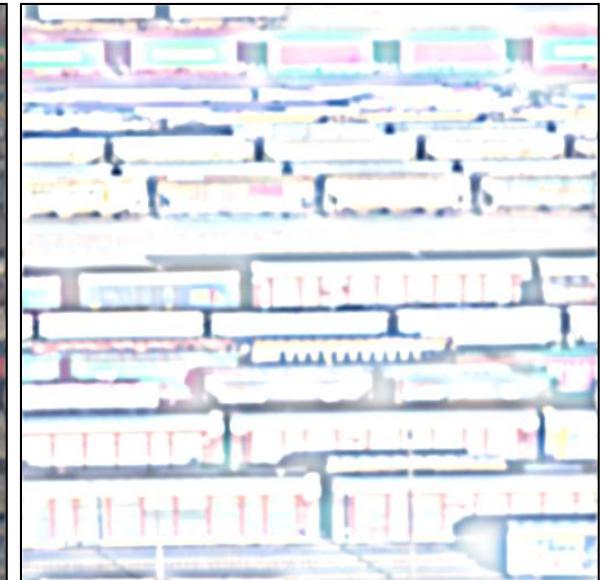
Image size: 512x512
sigma = 2 - sigma = 8



Positive Pixels



Filtered Image*

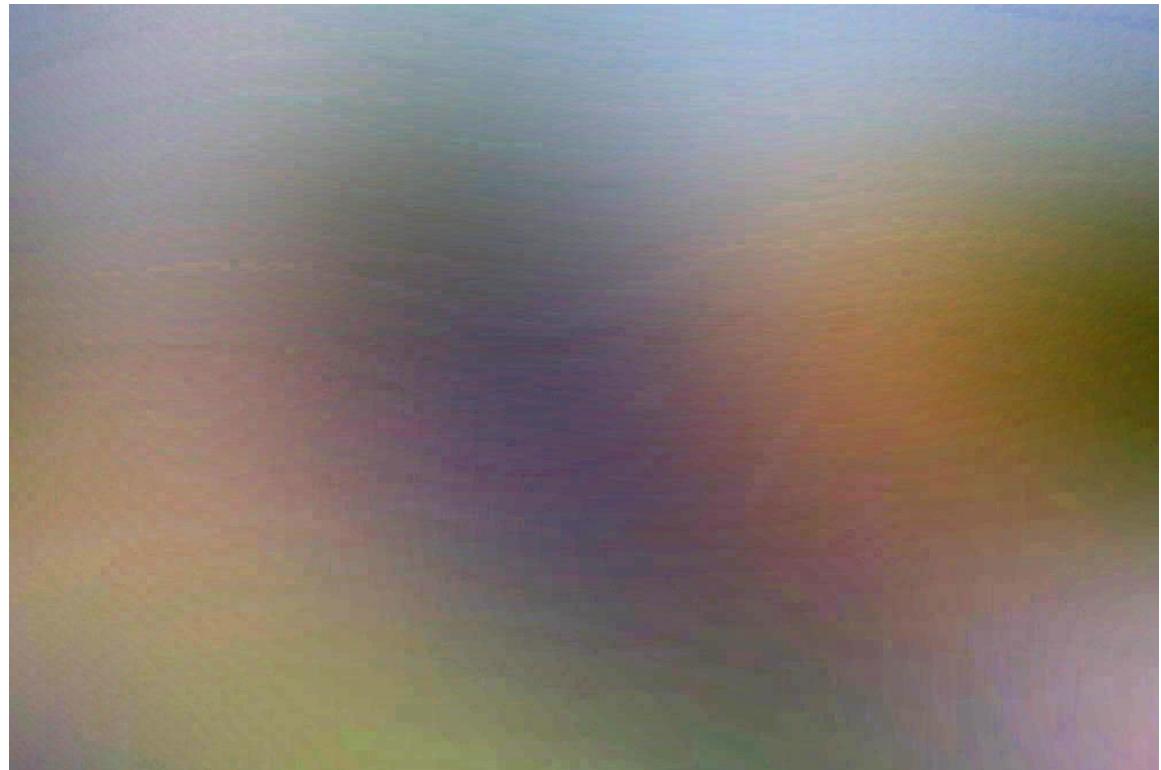


Negative Pixels



Bandpass Sequence

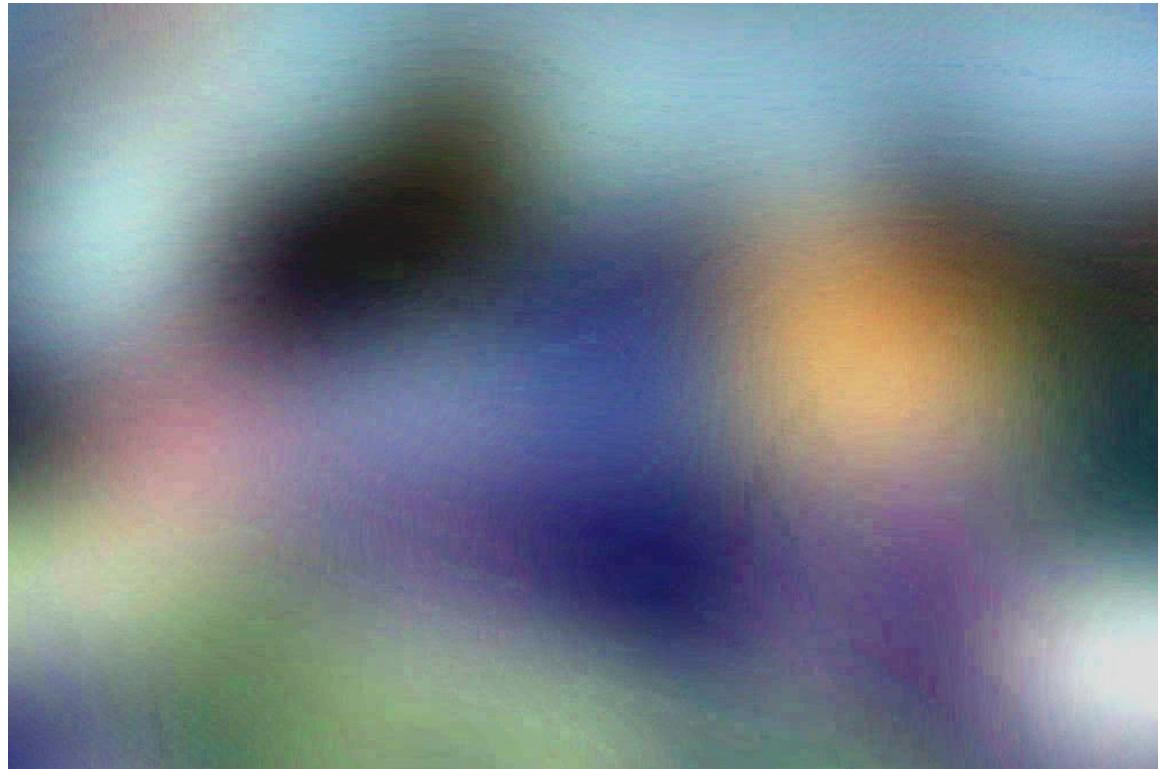
Difference between
Gaussian LPF images:
 $\sigma_8 = 128$ and $\sigma_9 = 256$.



$$\mathbf{J} = \mathbf{I} * [g(\sigma_8) - g(\sigma_9)] = [\mathbf{I} * g(\sigma_8)] - [\mathbf{I} * g(\sigma_9)].$$



Bandpass Sequence



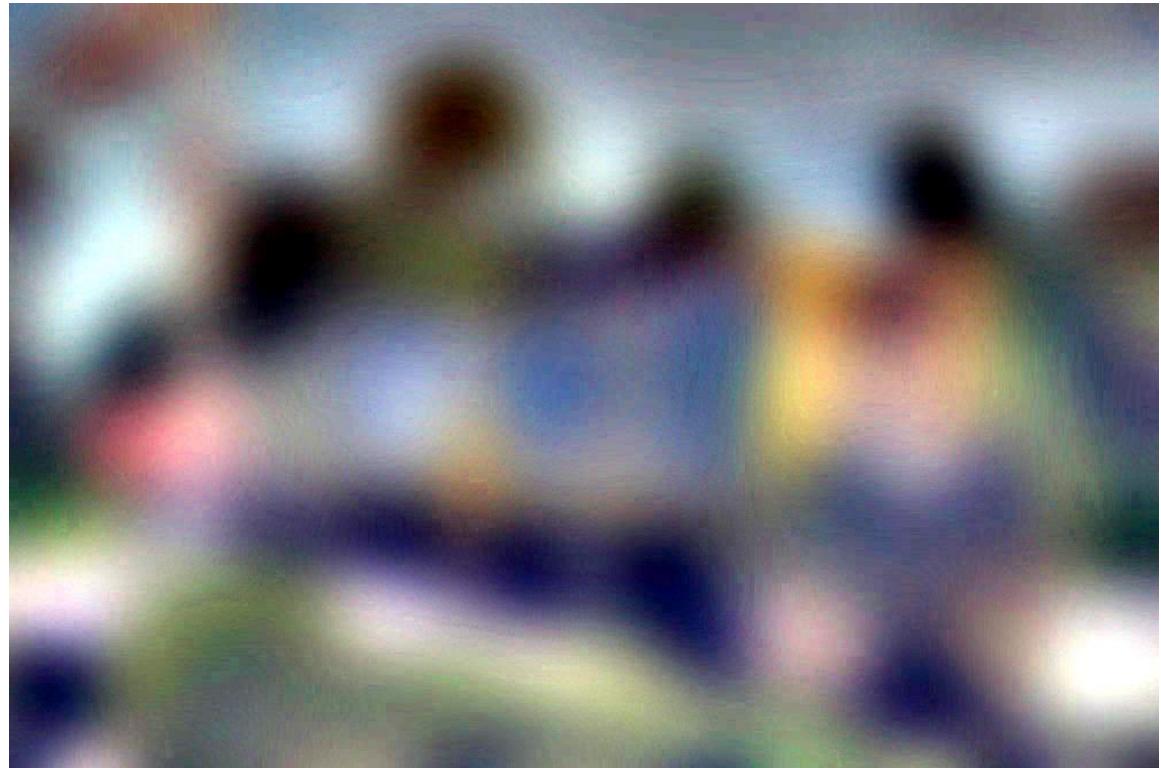
Difference between
Gaussian LPF images:
 $\sigma_7 = 64$ and $\sigma_8 = 128$.

$$\mathbf{J} = \mathbf{I} * [g(\sigma_6) - g(\sigma_7)] = [\mathbf{I} * g(\sigma_6)] - [\mathbf{I} * g(\sigma_7)].$$



Bandpass Sequence

Difference between
Gaussian LPF images:
 $\sigma_6 = 32$ and $\sigma_7 = 64$.



$$\mathbf{J} = \mathbf{I} * [g(\sigma_6) - g(\sigma_7)] = [\mathbf{I} * g(\sigma_6)] - [\mathbf{I} * g(\sigma_7)].$$



Bandpass Sequence

Difference between Gaussian LPF images:
 $\sigma_5 = 16$ and $\sigma_6 = 32$.



$$\mathbf{J} = \mathbf{I} * [g(\sigma_5) - g(\sigma_6)] = [\mathbf{I} * g(\sigma_5)] - [\mathbf{I} * g(\sigma_6)].$$



Bandpass Sequence

Difference between Gaussian LPF images:
 $\sigma_4 = 8$ and $\sigma_5 = 16$.



$$\mathbf{J} = \mathbf{I} * [g(\sigma_4) - g(\sigma_5)] = [\mathbf{I} * g(\sigma_4)] - [\mathbf{I} * g(\sigma_5)].$$



Bandpass Sequence

Difference between Gaussian LPF images:
 $\sigma_3 = 4$ and $\sigma_4 = 8$.



$$\mathbf{J} = \mathbf{I} * [g(\sigma_3) - g(\sigma_4)] = [\mathbf{I} * g(\sigma_3)] - [\mathbf{I} * g(\sigma_4)].$$



Bandpass Sequence

Difference between Gaussian LPF images:
 $\sigma_2 = 2$ and $\sigma_3 = 4$.

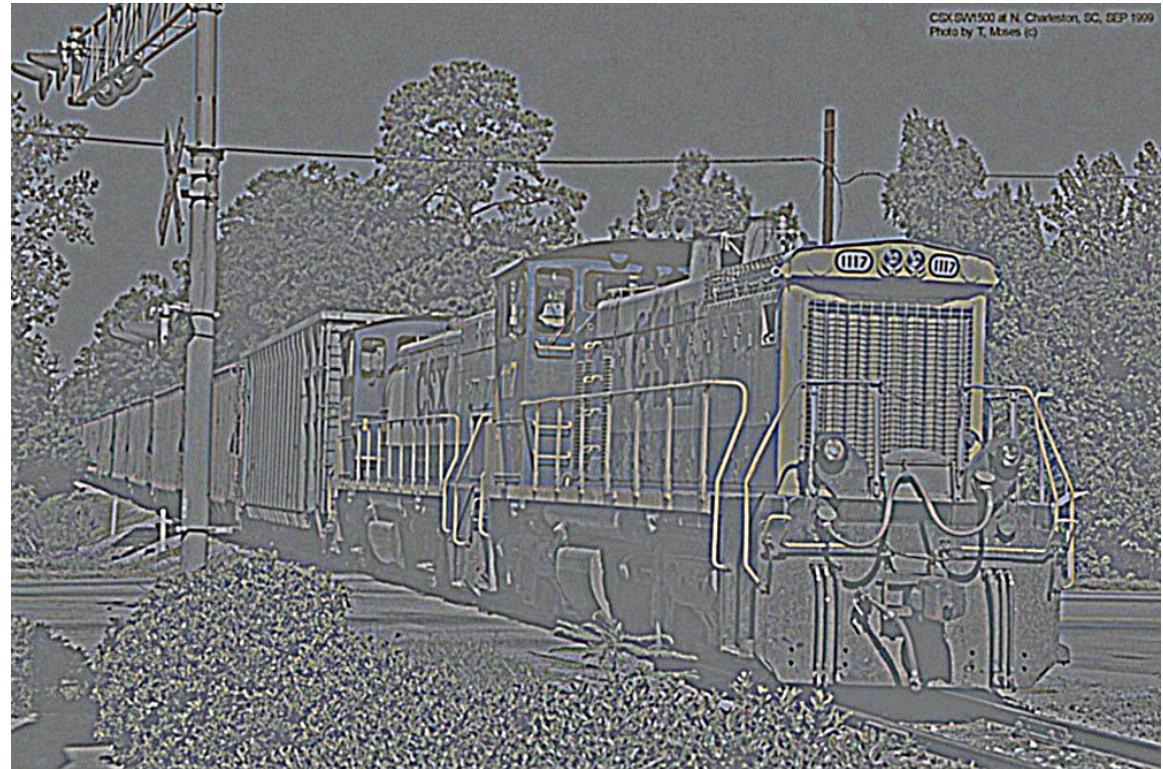


$$\mathbf{J} = \mathbf{I} * [g(\sigma_2) - g(\sigma_3)] = [\mathbf{I} * g(\sigma_2)] - [\mathbf{I} * g(\sigma_3)].$$



Bandpass Sequence

Difference between Gaussian LPF images:
 $\sigma_1 = 1$ and $\sigma_2 = 2$.

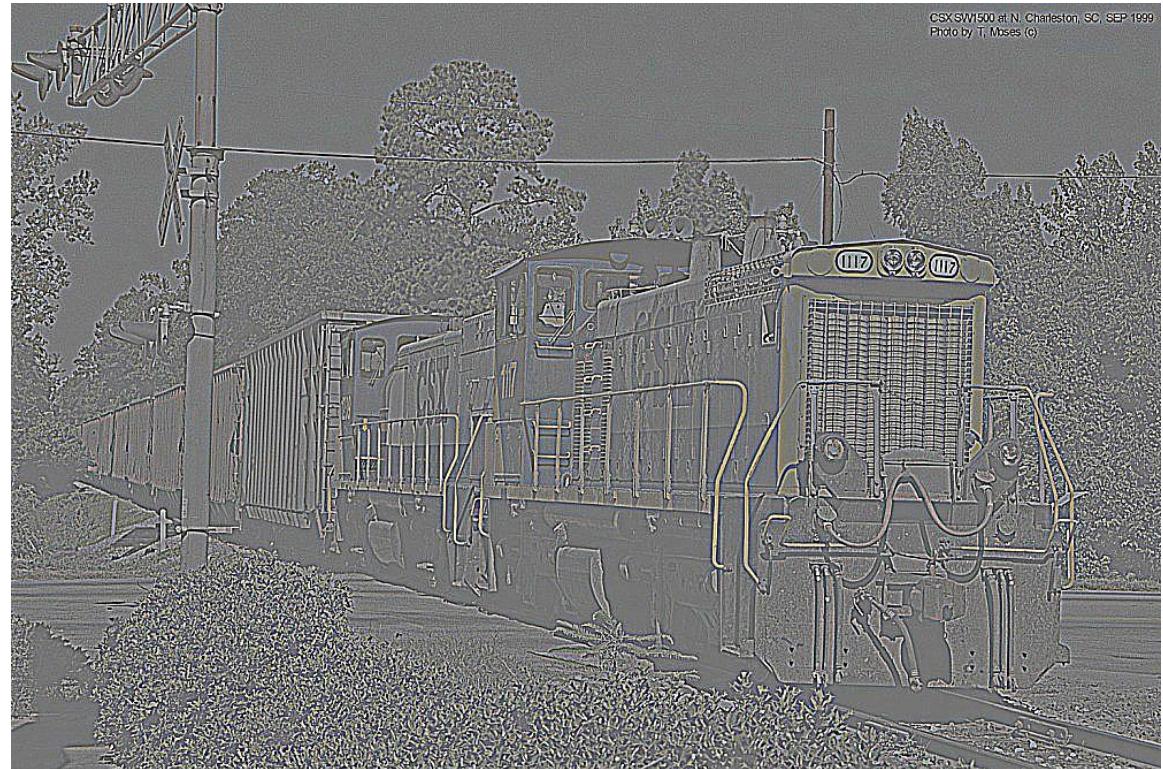


$$\mathbf{J} = \mathbf{I} * [g(\sigma_1) - g(\sigma_2)] = [\mathbf{I} * g(\sigma_1)] - [\mathbf{I} * g(\sigma_2)].$$



Bandpass Sequence

Difference between Gaussian LPF images:
 $\sigma_0 = 0$ and $\sigma_1 = 1$.



$$\mathbf{J} = \mathbf{I} * [\delta(0) - g(\sigma_1)] = \mathbf{I} - [\mathbf{I} * g(\sigma_1)].$$



Bandpass Sequence

Original Image



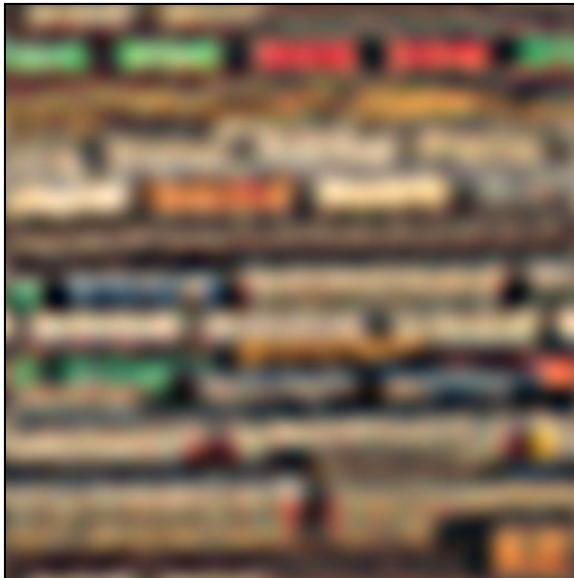


Ideal vs. Gaussian Filters

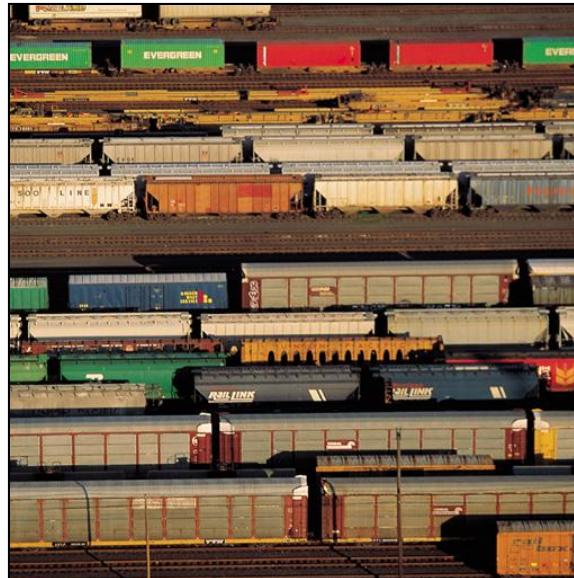


*signed image:
0 mapped to 128

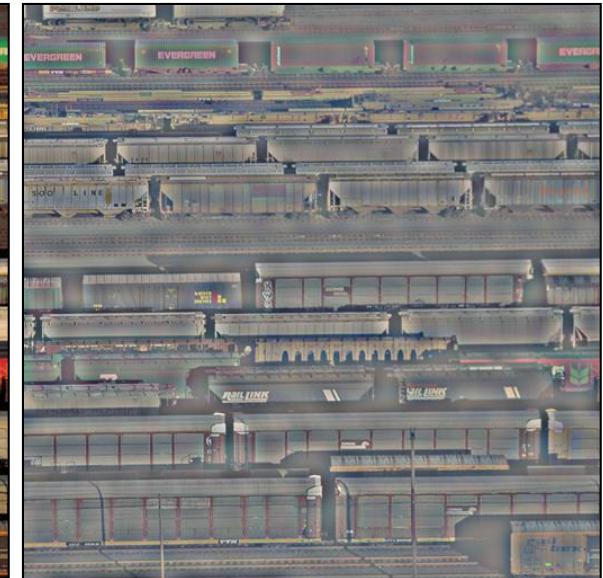
Ideal Lowpass and Highpass Filters



Ideal LPF



Original Image

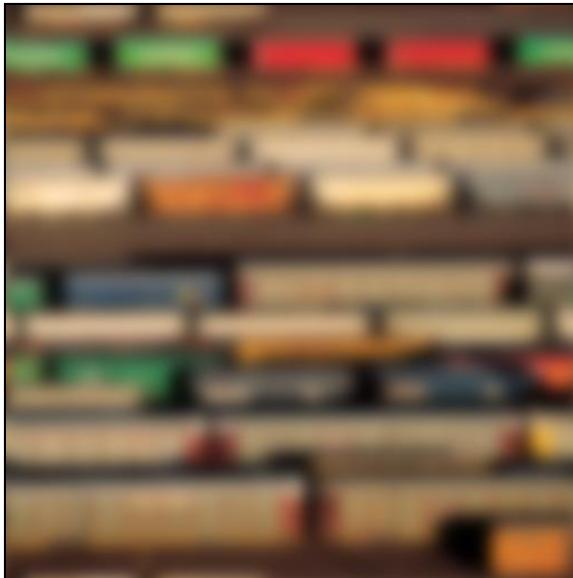


Ideal HPF*

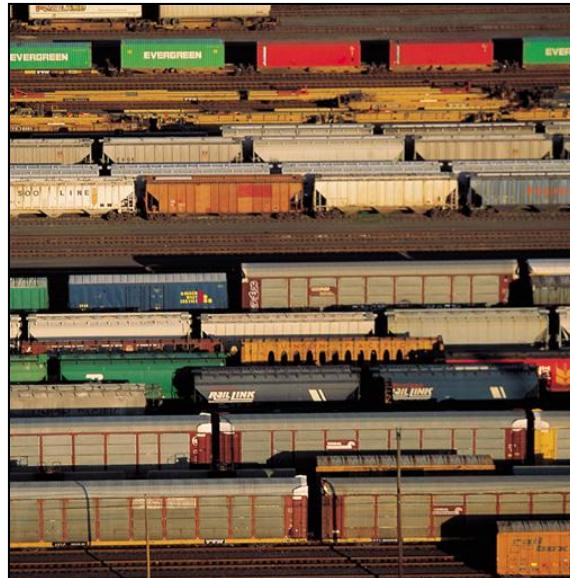


*signed image:
0 mapped to 128

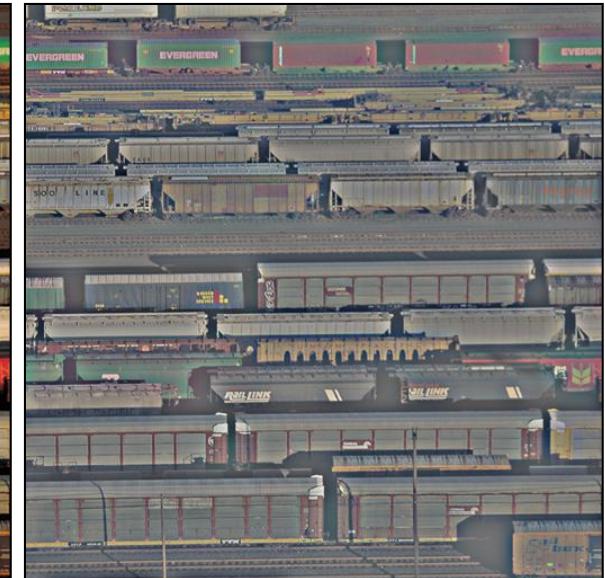
Gaussian Lowpass and Highpass Filters



Gaussian LPF



Original Image



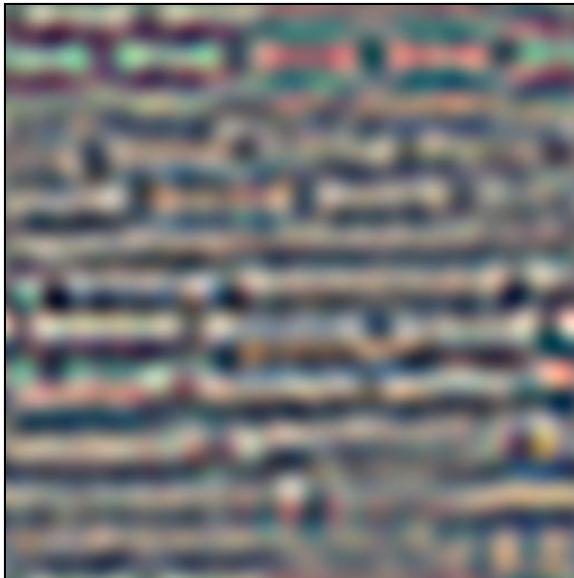
Gaussian HPF*



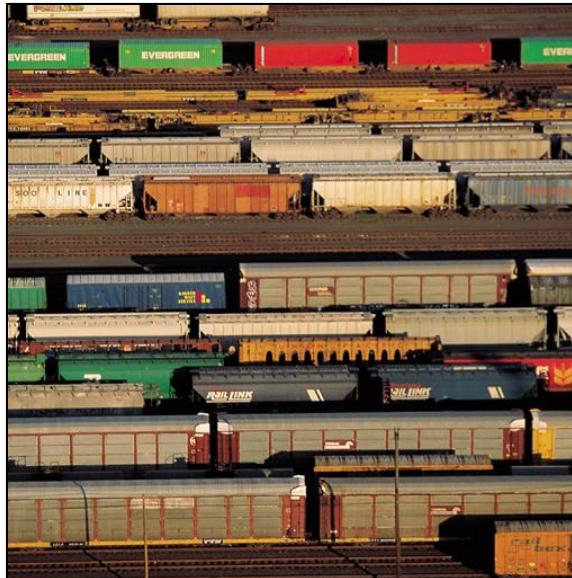
*signed image:
0 mapped to 128

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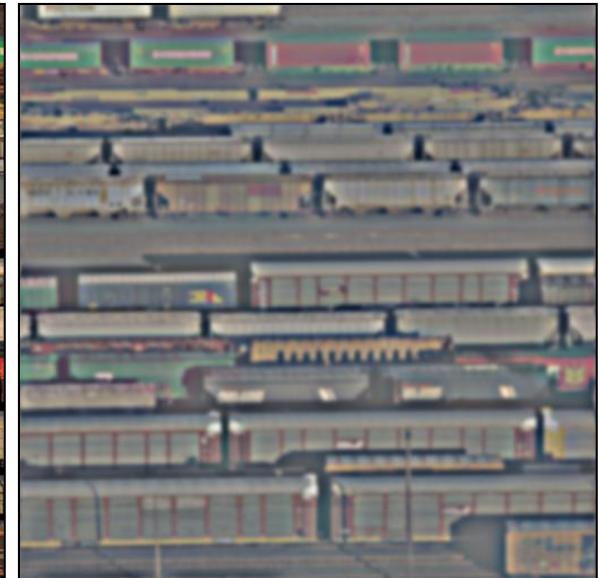
Ideal and Gaussian Bandpass Filters



Ideal BPF*



Original Image

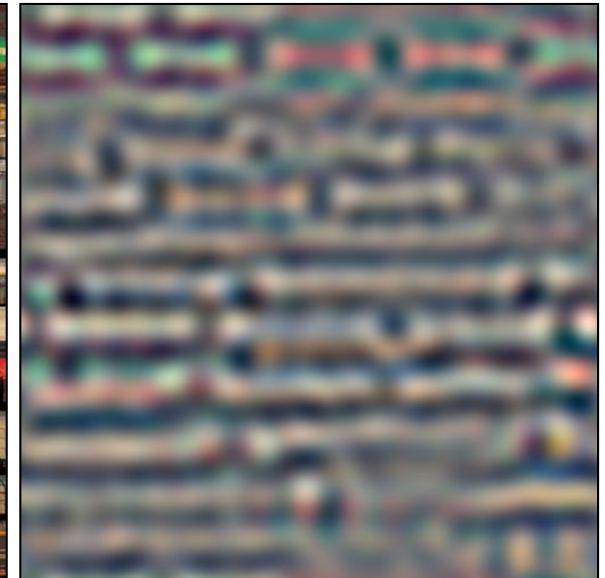
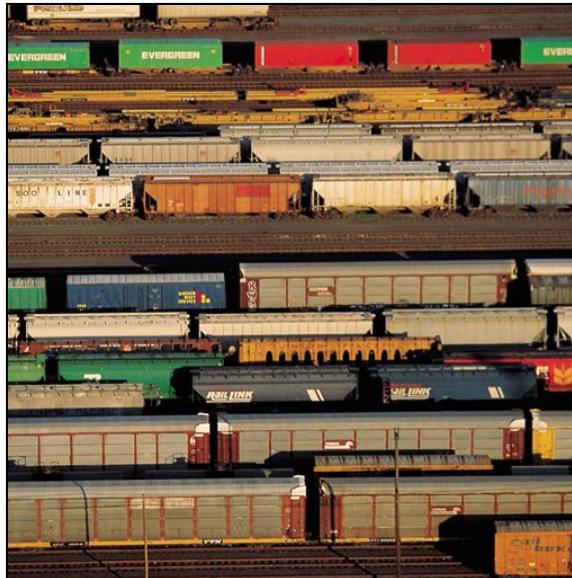
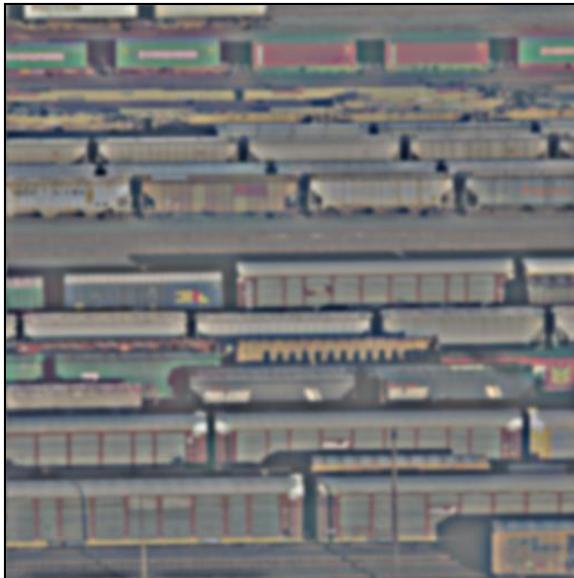


Gaussian BPF*



*signed image:
0 mapped to 128

Gaussian and Ideal Bandpass Filters



Gaussian BPF*

Original Image

Ideal BPF*



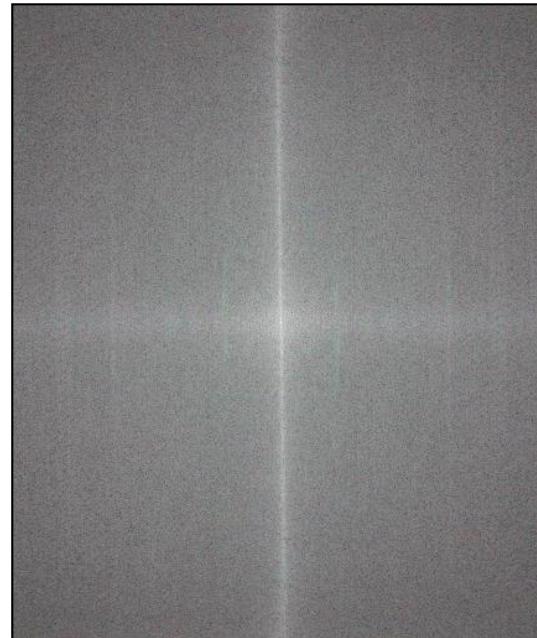
Effects on Power Spectrum



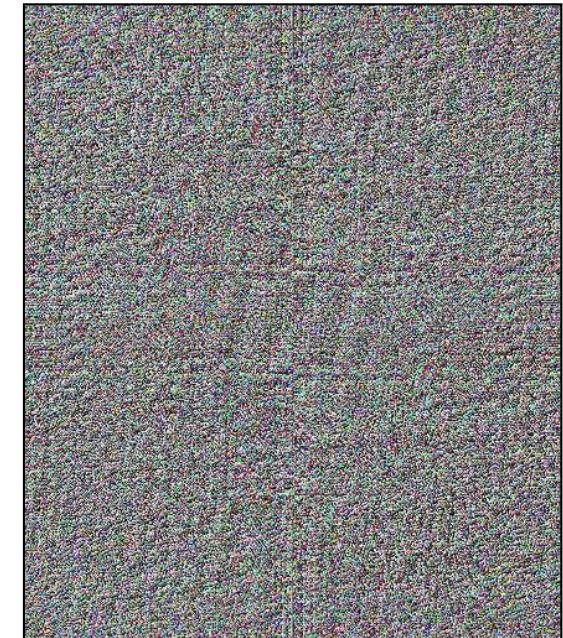
Power Spectrum and Phase of an Image



original image



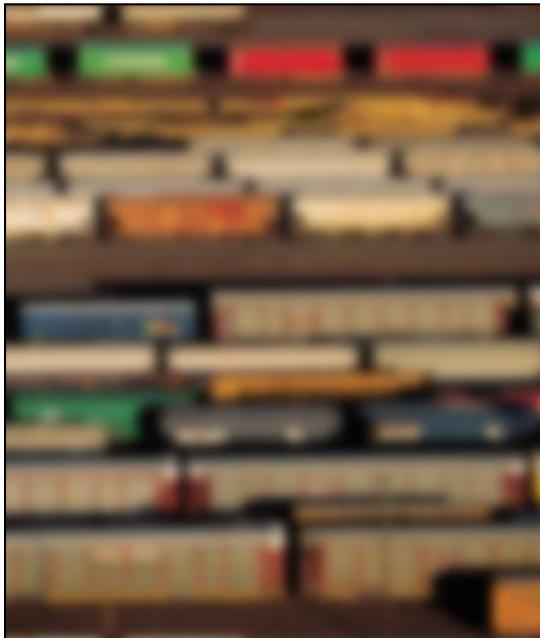
power spectrum



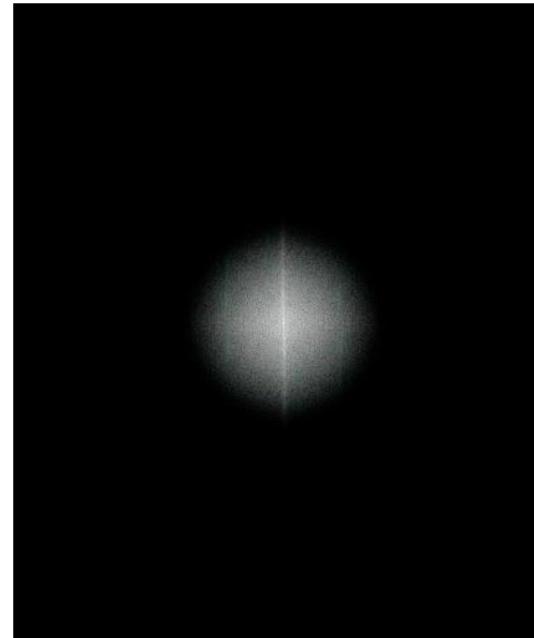
phase



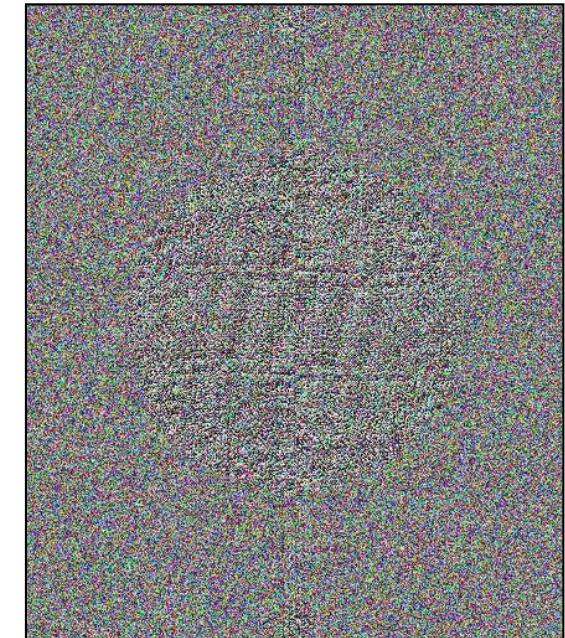
Power Spectrum and Phase of a Blurred Image



blurred image



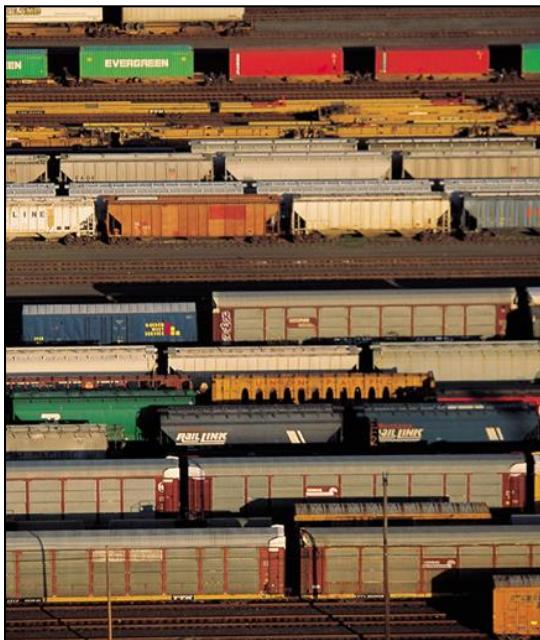
power spectrum



phase



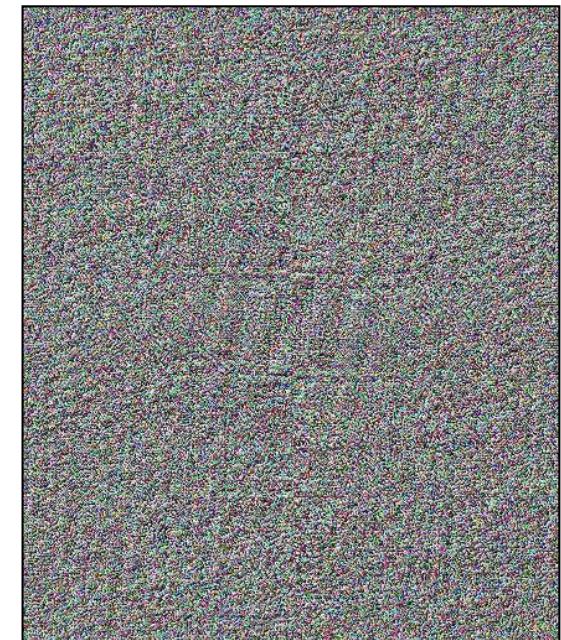
Power Spectrum and Phase of an Image



original image



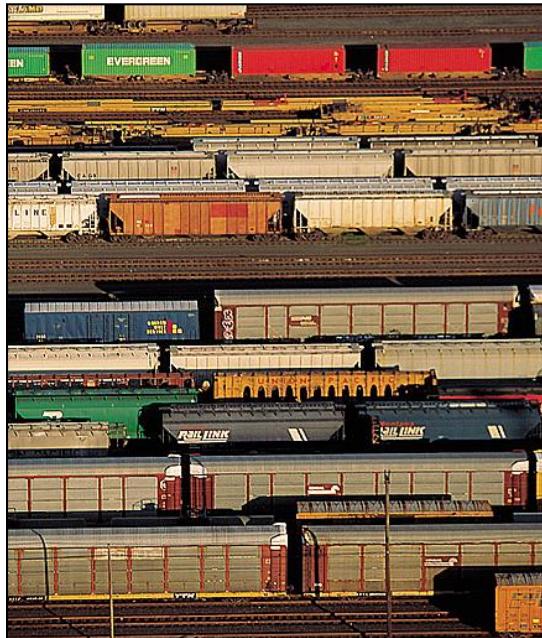
power spectrum



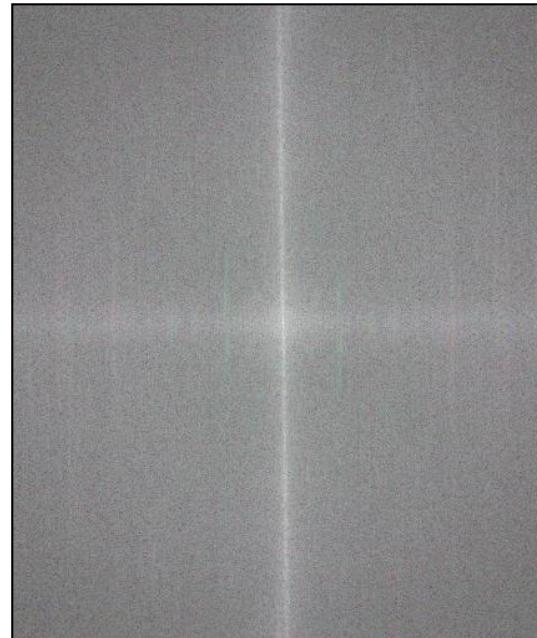
phase



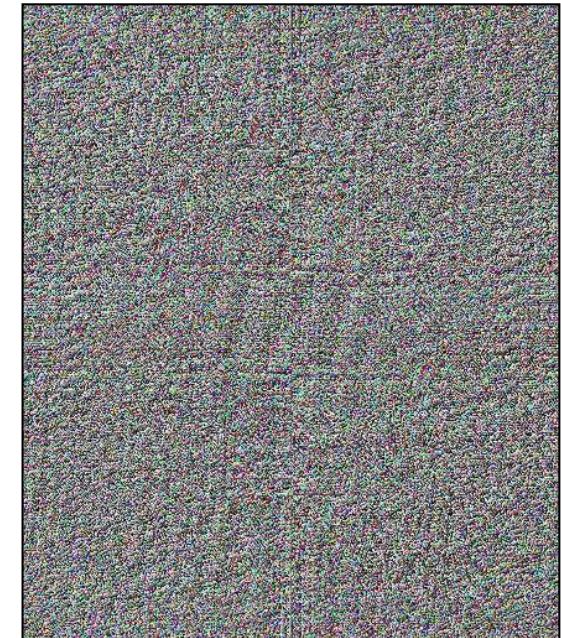
Power Spectrum and Phase of a Sharpened Image



sharpened image



power spectrum



phase