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| **Review** |

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ISSN 1678-992X **Crop Science**

**A short review: Comparisons of high-throughput phenotyping methods for detecting drought tolerance**

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| 1Jeju National University – Dept. of Plant Resources and | **ABSTRACT**: Drought is a major threat worldwide for crop production, especially due to the |
| Environment, Jejudaehak-ro 102, 63243, Jeju-si, Jeju-do – | rapid climate changes. Current drought solutions involve improving irrigation system, rainwater |
| South Korea. | harvesting, damming, cloud seeding, and changes of cultivation methods. Despite effective, |
| 2FarmHannong Ltd., Daejeon 34115 – South Korea. | each solution has economic, environmental, and temporal drawbacks. Among all solutions, the |
| 3Kyungpook National University – Major in Plant Bioscience, | most effective, inexpensive and manageable method is the use of drought-tolerant cultivars |
| Daegu 41566, South Korea. | via plant breeding. However, conventional plant breeding is a time-consuming and laborious |
| \*Corresponding author <yschung@jejunu.ac.kr> | task, especially for phenotypic data acquisition of target traits of numerous progenies. High- |
|  | throughput phenotyping (HTP) is a recently developed method and has potential to overcome |
| Edited by: Leonardo Medici | the mentioned issues. HTP offers massive, accurate, rapid, and automatic data acquisition in |
|  | the breeding procedure and can be a breakthrough for developing drought resistant/tolerant |
| Received November 11, 2019 | cultivars. This study introduces various methods of HTP to detect drought stress, which can |
| Accepted February 10, 2020 | accelerate the breeding processes of drought-tolerant cultivars to provide helpful guidelines for |
|  | breeders and researchers to choose appropriate methods. |
|  | **Keywords**: sensors, remote sensing platforms, image analysis, drought solution, plant breeding |
|  |  |

**Introduction**

Expanding global population demands crop production to double by 2050, which poses a significant challenge (Araus and Cairns, 2014). However, recent variation of drought frequency and locations are increasing tremendously due to the global warming and climate change, causing severe yield loss to crops (Spinoni et al., 2014), which could compromise food security worldwide.

Numerous studies have investigated drought effects on crops and tolerances by identifying plant physiology against drought. Therefore, characterization of plant physiology identified that the development of drought-tolerant cultivars is the most effective method to deal with the current situation by providing farmers a relatively inexpensive and manageable crop procedure (Cattivelli et al., 2008). However, to date, only few drought-tolerant cultivars have been developed. Moreover, conventional breeding takes many years, despite modern breeding processes, such as marker-assisted selection (Collard and MacKill, 2008; Tester and Langridge, 2010). To enable shorter breeding cycles, great rates of genetic gain with the sufficient number of samples and a reliable dataset are required. This has led to the advent of new field, high throughput phenotyping (HTP) (Rutkoski et al., 2016). HTP is based on various types of sensors and computing technology in order to accelerate the process of phenotypic data acquisition using accurate, fast, non-invasive, automated, and reliable manners. Therefore, it is important to review various HTP methods to evaluate drought stress in crop plants to allow researchers to identify drought-tolerant phenotypes, compare them and use them in their purposes.

In order to monitor plant performance and identify traits under drought condition, defining phenotypes of drought stresses is crucial. Screening, analyzing, comparing drought-effective phenotypes, physiological performance of plants, and their production can be helpful to determine the most appropriate traits for evaluating drought tolerance based on functional phenotyping (York, 2018). For instance, dehydration under drought conditions results in critical damage to plants by changing leaf and canopy temperature, transpiration rate, and biomass distribution influence growth rates and yields (Khodarahmpour, 2011; Passioura, 1983). As rates of changes of these traits have considerable correlations (Kimball and Bernacchi, 2006), the most efficient phenotypes and screening methods could be selected for drought studies*.* Thus, various ways to screen drought stress level with different types of sensors to screen each of those components are necessary. This article reviews HTP methods and platforms.

**High throughput phenotyping methods for drought stress in plants**

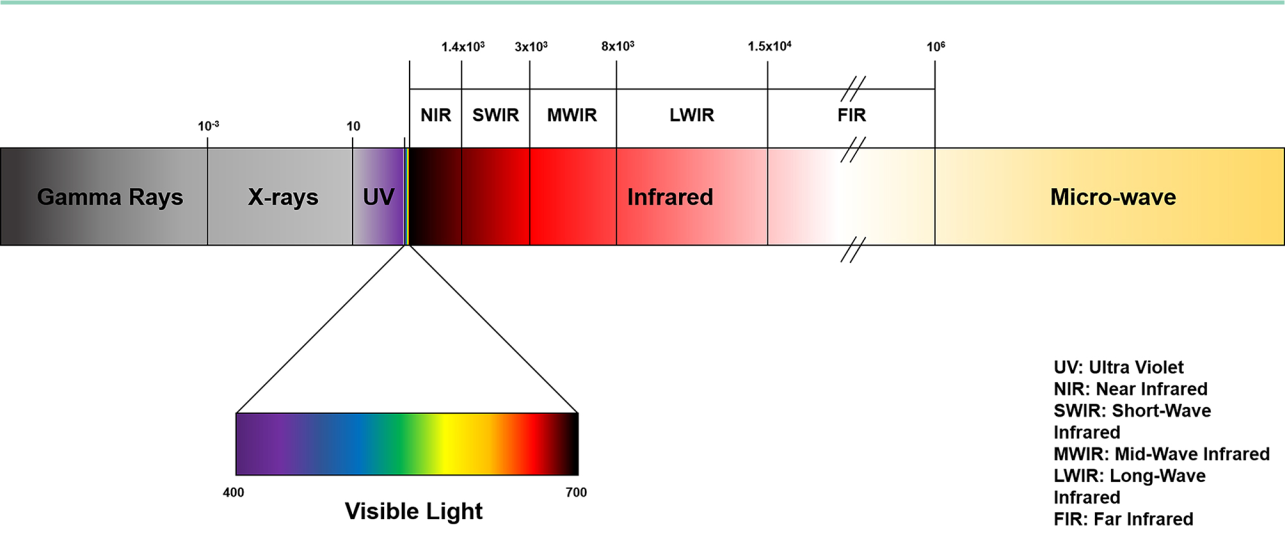
**Red, green, and blue (RGB) image**

Optical sensor is a device that applies radiometry as a source of detection and image acquisition (Holland et al., 2012). Numerous ranges of electromagnetic wavelengths are used on image processing, such as visible band (VIS), infrared (IR), and ultraviolet (UV) (Araus et al., 2018). Classification of electromagnetic wavelengths and features of applying sensors are shown in Figure 1 and Table 1. Multispectral sensors generally comprise several bands including Red, Green, Blue (RGB) channels and Near Infrared (NIR) channels



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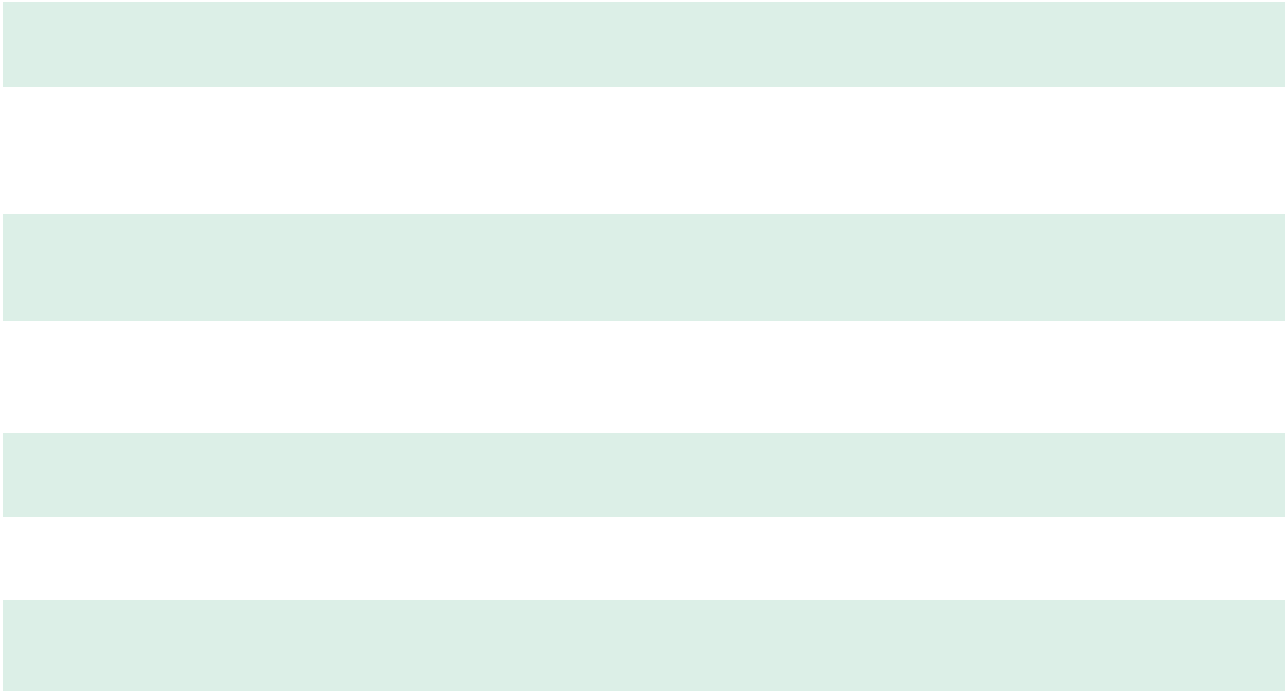
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**Figure 1** – Electromagnetic spectrum scheme (nm).

**Table 1** – Sensors for high throughput imaging and obtainable traits.

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
|  | Sensors | Wavelength | Features | Traits | Reference |  |
|  | RGB (Red, green, blue) |  | Sensing visible wavelengths. Most easily | Vegetation indices, plant height, | Kim et al. (2018); Crimmins and |  |
|  | 400~700 nm | plant structure, growth rates, and | Crimmins (2008); Deery et al. (2014); |  |
|  | sensor |  | accessible sensor. | morphological traits. | Liu et al. (2017) |  |
|  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  | Sensing highest reflectance of plant green |  | Bei et al. (2011); Bendig et al. |  |
|  | NIR (Near infrared) |  | area in 700~1300 nm, while beyond | Chlorophyll conductance, water |  |
|  | 700~1400 nm | (2015); Thiel et al. (2010); Yang et |  |
|  | sensor | 1300 nm shows more absorbance by | status, and vegetation indices. |  |
|  |  | al. (2017) |  |
|  |  |  | water than the visible spectrum. |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  | Sensing thousands of bands per pixel. | Vegetation and water indices, soil | Hamada et al. (2007); Stagakis et |  |
|  |  |  | More detailed images can be obtained | al. (2010); Zhao et al. (2013); El- |  |
|  | Hyperspectral sensor | - | than the multispectral imaging if the | cover status, photosynthesis rates, Hendawy et al. (2019a); El-Hendawy | |  |
|  |  |  | requirements are set. | and levels of phytochemicals. | et al. (2019b) |  |
|  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  | Sensing emitted radiation of object that |  | Baluja et al. (2012); Berni et al. |  |
|  | Thermal sensor | 700~106 nm | increases with the object temperature | Canopy temperature, transpiration |  |
|  | (2009); Gago et al. (2015); Leinonen |  |
|  |  |  | above absolute zero. Suitable to image | rates, and water stress responses. | et al. (2006) |  |
|  |  |  | temperature changes. |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  | Sensing fluorescence emitted by short | Chlorophyll conductance, |  |  |
| Fluorescence sensor | | 180~800 nm | wave light absorption of susceptible | photosynthetic rates, and pigment | Chaerle et al. (2006) |  |
|  |  |  | molecule. | composition. |  |  |
|  |  |  |  |  |  |  |
| LiDAR (Light Detection | |  | Surface scan of target objects and | Canopy and leaves, vegetation | Lin (2015); Eitel et al. (2014); Madec |  |
| 250~2,000 nm | distance measurement by analyzing the | cover, plant height, and nitrogen | et al. (2017); Omasa et al. (2006); |  |
| and Ranging) | |  | reflected light. | status. | Zhang and Grift (2012); |  |
|  |  |  |  |
|  |  |  |  | |  |  |
| Others | |  | Feasible to screen underground structures Water contents, stem structures, | | Capitani et al. (2009); Gosa et al. |  |
| -MRI | | - | of plant by 3D imaging and transport | root structures, transport | (2019); Pohlmeier et al. (2008); Van |  |
|  |  |  | processes in natural porous media. | processes | As and Van Dusschoten (1997) |  |
|  |  |  |  |  |  |  |
| Others | |  | Capable of measuring plant physiological | Weight, water use efficiency, | Halperin et al. (2017); Iyer-Pascuzzi |  |
| - | changes by non-imaging process. | water status, transpiration rates, | et al. (2010); Negin and Moshelion |  |
| -Gravimetric senor | |  |
|  | Requires other sensors for screening. | biomass. | (2017). |  |
|  |  |  |  |
|  |  |  |  |  |  |  |



(Kelcey and Lucieer, 2012). Relatively insensitive accessibility of spectral imagery allowed various forms of its usage. RGB band sensor is the most affordable and accessible instrument because it takes images of most morphological features of plants, such as whole image or partial image of plant, plant structure, shoot

biomass, leaf density, leaf area, height, and color. Due to its rapid measurement and affordable access, RGB has various applications. For example, wheat plant density was estimated with light platform fixed on an RGB camera (Liu et al., 2017), time series of plant phenology was monitored with an automated time-lapse

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photography (Crimmins and Crimmins, 2008), and leaf segmentation of sorghum was estimated based on the correlation between target traits and RGB values taken by camera on unmanned aerial vehicles (UAVs) (Kim et al., 2018). RGB images can also be applied to acquire sophisticated information on responses to water stress based on its shape, compactness, solidity, and other visible parameters (Deery et al., 2014).

**Infrared imaging**

Between 700 nm and 1300 nm near infrared (NIR) wavelengths, plant green area shows the highest rates of reflectance (Broge and Mortensen, 2002). NIR beyond 1300 nm is also reflected by plant tissues but with a relatively low rate . These processes cause the scattering of wavelengths within the leaf mesophyll, which lately are absorbed by water (Knipling, 1970). Such characteristics verify compatibility on meaningful parameters against drought stresses. Thiel et al. (2010) showed plant moisture measurement using NIR sensor attached to an automated conveyor platform and Bei et al. (2011) measured grapevine water potentials using a custom-made spectrophotometer and a handheld spectrometer to have significant correlation with the results of pressure chamber in fields and glasshouses by model-based estimations. Additionally, spectral reflectance indices (SRIs) based on NIR and RGB channel showed significant correlation on vegetation status. Bendig et al. (2015) and Yang et al. (2017) estimated the normalized difference vegetation index (NDVI) in order to monitor biomass in projected area with combination of RGB and NIR imagery on Unmanned Aerial Vehicles (UAVs). These sensors can be adapted to not only UAVs, but also to other platforms, such as ground vehicles and chambers to produce images of wide range and continuous images at each platform (Chapman et al., 2014; Deery et al., 2014; Gago et al., 2015).

**Hyperspectral imaging**

Hyperspectral sensors consist of hundreds and thousands of bands per one pixel compared to the other multispectral sensors (Thenkabail et al., 2002). Due to its narrow and numerous bands, which include ranges of VIS, NIR, fluorescence, thermal sensors, and so on, band selection is relatively complicated for imaging. Nevertheless, it can differentiate various responses to stress due to its viability to acquire images in high resolution and narrow spatial range. Thereby, hyperspectral imagery is often used for indoor imaging and high-altitude aerial platforms, due to its high level of details. Soil coverage status, photosynthesis rates, and levels of phytochemicals, such as nitrogen, cellulose, lignin, and pigments can be obtained due to its narrow ranges of spectral reflectance and water indices (Hamada et al., 2007; Stagakis et al., 2010; Zhao et al., 2013). Additionally, El-Hendawy et al. (2019b) showed the relationship between chlorophyll fluorescence parameters, grain yield, and SRIs of hyperspectral

sensors in wheat grown under salinity. As sensitiveness of SRIs against plant stress reactions proved its reliability, assessable SRIs might be used in drought screening. Moreover, El-Hendawy et al. (2019a) compared dry weights, water contents, aboveground biomass, grain yield, and performance of SRIs in the VIS and NIR under two irrigation regimes for more precise analyses of SRIs by hyperspectral sensors. However, lighting issues in close range and inconstant imaging by environmental changes could be problematic for HTP (Mishra et al., 2017). Nonetheless, hyperspectral imaging is an effective tool for studies on drought in crops due to its efficient capability of acquiring physiological and phytochemical parameters, such as photosynthesis rates, soil coverage status, nitrogen status, water indices, and other various SRIs for detecting drought stress (Behmann et al., 2014).

**Thermal imaging**

Thermography, also known as infrared thermography, produces images using emitted radiation of object that increases as the object temperature is above absolute zero (Shekhawat, 2016). Thermal sensor can detect temperature changes caused by the occurrence of transpiration, due to the stomatal closure, using visualized image data (Peñuelas et al., 1992). Thereby, temperature-related traits, such as water content, transpiration rate, and stomatal conductance could be measured through thermal imaging by model-based estimations (Prashar et al., 2013; Tattaris et al., 2016). For example, stomatal conductance in grapevine (Vitis vinifera) was estimated with a handheld thermometer camera (Leinonen et al., 2006) and water stress in olives was evaluated through correlation between soil and tree water status and thermal imagery (Ben-Gal et al., 2009). HTP methods with thermal imagery are often applied with other sensors to obtain comprehensive data. For instance, thermal and multispectral sensors on UAVs for vegetation monitoring (Berni et al., 2009) were used to assess water status in vineyard (Baluja et al., 2012; Gago et al., 2015). Thermal images have significant correlation with water stress indicators and are thus the most useful sensors to phenotype drought-related traits. However, environmental factors, such as solar radiation, air temperature, wind speed, and background temperature can easily influence field measurements, requiring technical expertise to overcome this limitation (Sugiura et al., 2007).

**Fluorescence imaging**

Fluorescence is luminescence of longer wavelength photons of fluorescence lifetime after photon absorption by a certain susceptible atom or molecule (Lichtman and Conchello, 2005). These longer wavelengths and lower energy photons can be measured by fluorescence lifetime through the sensor in picoseconds or nanoseconds (Berezin and Achilefu, 2010). Thus, plant fluorescence can be obtained through responses of fluorescence by irradiating chloroplasts with blue or

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actinic light. As fluorescence and chlorophyll contents are strong indicators of drought tolerance to determine the metabolic status of plants, fluorescence imaging can be effective to identify drought related traits, such as photosynthetic rate changes and pigment proportion changes (Li et al., 2006; Ögren and Öquist, 1985; Zlatev and Yordanov, 2004). However, fluorescence imaging has limitations, such as impropriety for early water stress detection, inadequacy on broad range imagery, inconsistent lighting, environmental disruptions under field conditions for remote sensing, and requirements of high electric power (Jansen et al., 2009; Shakoor et al., 2017). Nonetheless, efficiency of fluorescence imaging is proven under drought conditions by the combination with other sensors or automated facilities to screen photosynthetic rates (Chaerle et al., 2006).

**Light Detection and Ranging (LiDAR)**

LiDAR is a new remoted sensing technology that measures distance of target objects by analyzing reflected light (Lefsky et al., 2002). It acquires various parameters of canopy and leaves, such as vegetation cover, height, canopy structure, leaf area index, and nitrogen status (Eitel et al., 2014; Lin, 2015; Madec et al., 2017; Omasa et al., 2006; Zhang and Grift, 2012). Furthermore, LiDAR measuring via 3D structuring can be done in a short time. It is generally applied in aerial platforms, ground vehicles, and ground fixed & stationary platforms. UAVs show the highest potential and efficiency than the other platforms for 3D LiDAR mapping. Although LiDAR has limited application for studies on drought stress, some applications could be possible. Phenotypes that result from slow growth and wilting, due to drought stress, are based on 3D images, such as biomass and leaf area index. In summary, aerial platforms with LiDAR are effective for measuring canopy areas, while rough images might be unsuitable for accurate data for drought tolerance. To overcome this, ground based platforms are suggested with current image resolution of LiDAR.

**Other HTP sensors**

In addition to the sensors mentioned above, there are various other sensors available. HTP methods applying magnetic resonance microscopy and gravimetric sensors were studied (Gosa et al., 2019; Iyer-Pascuzzi et al., 2010). Magnetic resonance microscopy, also known as magnetic resonance imaging (MRI), is a powerful 3D-imaging tool of structures, as it transports processes in natural porous media (Van As and Van Dusschoten, 1997). Non-invasive imaging of MRI allows characterization of responses of the entire plant area against drought. Pohlmeier et al. (2008) imaged both soil water contents and root architectures through magnetic resonance microscopy and indicated that greater water content changes occurred where the highest root densities were found. Capitani et al. (2009) showed relationships between nuclear magnetic resonance

(NMR) signal and relative water content on plant leaves exposed to dehydration or to osmotic stresses, indicating that the NMR signal has correlation with plant responses against drought (e.g. plant water status and transpiration rates).

Weighing lysimeter based on gravimetric sensor is also a useful tool for studies on drought effects. However, because plant physiology differs in terms of species and varieties, this sensor cannot be used alone for the HTP process. Halperin et al. (2017) installed soil and atmosphere sensors that can effectively estimate physiology of the target plant. Thereby, numerous phenotypes, including weight, water use efficiency, water status, transpiration rates, biomass, and more, are capable of screening and comparable through this functional physiological phenotyping system. Consequently, as this system determine appropriate traits in need, known to play critical roles in responses to environmental conditions and highly related to other plant physiological responses against drought stress, it can be a powerful HTP tool (Negin and Moshelion, 2017).

**Platforms for sensors to evaluate drought tolerance**

As previously mentioned, various sensors can provide parameters for HTP. They are powerful imaging instruments that allow accurate and massive phenotyping data at a glance. However, appropriate platforms are needed, such as aircrafts, vehicles, ground fixed, and automated facilities to place sensors in order to obtain visualized parameters of plant response under drought conditions. The features and usages of platforms are compared in Table 2.

Canopy traits, such as leaf area, transpiration rates, canopy temperature, phytochemicals, and photosynthetic rates are highly related to drought effects. Among various platforms, aerial detection is the most effective and efficient way in terms of phenotyping speed. Its rapid and accurate remote sensing allows imaging massive amounts of plant in a wide area within very short time. Visible traits of the canopy area, including plant height, can be easily measured by aerial imaging with RGB sensors (Bendig et al., 2014; Jin et al., 2017). Chlorophyll contents can be estimated by NIR and Red range by aerial imaging (Bendig et al., 2015; Yang et al., 2017). Thermal sensor mounted on aerial vehicles is capable of detecting aerial water status (Baluja et al., 2012; Berni et al., 2009; Gago et al., 2015). In addition, aerial platform with high payload can apply hyperspectral sensor for phytochemical and photosynthetic traits. However, application of thermal and fluorescence sensors might be more appropriate for ground vehicles, ground fixed & stationary platforms, and indoor facilities for higher resolution images due to the issues mentioned previously (Busemeyer et al., 2013; Deery et al., 2014; Shafiekhani et al., 2017; Tisné et al., 2013).

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**Table 2** – Platforms for High Throughput Phenotyping.

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | Platforms |  | Categories | Features | Limits | References |  |  |
|  |  | Satellites | |  | Relatively low resolution images | Hamada et al. (2007); Stagakis et |  |  |
|  |  |  | than platforms on lower altitude. | al. (2010) |  |  |
|  |  |  |  | Sensing broad area rapidly. |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  | Payload limits. | Manual control requires expertise. | Chapman et al. (2014) |  |  |
|  | Aerial |  |  | Screening process is possible regardless |  |  |  |  |
|  |  |  |  | Baluja et al. (2012); Bendig et al. |  |  |
|  |  | Aircraft | | of plant height. | Easily influenced by environmental |  |  |
|  |  | (2014); Bendig et al. (2015); Berni et |  |  |
|  |  |  |  | Only orthoimages can be obtained. | factors. |  |  |
|  |  |  |  | al. (2009); Gago et al. (2015); Jin et |  |  |
|  |  |  |  |  | Relatively low payloads. |  |  |
|  |  |  |  |  | al. (2017); Yang et al. (2017) |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |
|  |  | Tractors & Buggies | | Manual or remote control. | Inappropriate to screen very tall | Deery et al. (2014); Salas Fernandez |  |  |
|  |  | et al. (2017) |  |  |
|  |  |  |  | High resolution images. | crops. |  |  |
|  |  |  |  |  |  |  |
|  |  | Bicycles | | Sensor payload is independent. |  | Liu et al. (2017) |  |  |
|  |  |  |  |  |  |  |  |  |
|  |  | Ground-Fixed & | | Suitable to time-lapsed images. | Requires endurance against | Busemeyer et al. (2013); Shafiekhani |  |  |
|  |  | More sensors are mountable than the |  |  |
| Ground | | Stationary | | outdoor conditions. | et al. (2017) |  |  |
| aerial platforms. |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  | Environmental factors can be controlled. |  | Clark et al. (2013); Iyer-Pascuzzi et |  |  |
|  |  |  |  |  | al. (2010); Hartmann et al. (2011); |  |  |
|  |  |  |  | Uncontrollable disturbances are inhibited. | Personnel limitations. |  |  |
|  |  | Indoor Facilities | | Marié et al. (2014); Taras et al. |  |  |
|  |  | Almost all sensors can be applied. |  |  |  |
|  |  |  |  |  | (2012); Tisné et al. (2013); Wasaya |  |  |
|  |  |  |  | Capable of root phenotyping. |  |  |  |
|  |  |  |  |  | et al. (2018) |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |



Despite the benefits for HTP, the detectable area of aerial platforms is limited to the top canopy area. Therefore, drought-related phenotypes below the canopy area, such as stem structure, biomass, and branching need to be remotely sensed by ground vehicles (Salas Fernandez et al., 2017), ground fixed & stationary (Busemeyer et al., 2013; Shafiekhani et al., 2017), and indoor (Hartmann et al., 2011) platforms. Ground vehicles are relatively less expensive than other two kinds of ground-based platforms, while the images they acquire need to undergo analyses, similar to images from aerial platforms (Deery et al., 2014). Ground vehicles are also advantageous for their capacity of loading heavier sensors than aerial platform. However, phenotyping speed is much slower than that of images acquired from aerial platform. Indoor platforms have benefits of controlling the target environment due to the inhibition of other uncontrollable disturbances. By restricting interference of extrinsic factors, almost all sensors are available on this platform. Proper posture rectified for each imaging sensor can make the measurement more accurate and rapid with easier operation. Ground fixed & stationary platforms have the advantage of producing time-lapsed image easily due to their fixed imaging angle and constant imaging time; however, they have to be highly durable under the outdoor conditions. Indoor facilities are also capable of phenotyping roots formed under drought conditions, providing important hints to drought tolerance (Wasaya et al., 2018). However, personnel limitations, high cost, and environmental settings are drawbacks. Cylinder growth systems, hydroponic growth systems, aeroponic growth systems, X-rays, nuclear magnetic resonance microscopy, magnetic resonance imaging, and laser scanning are currently available for indoor phenotyping (Clark et al., 2013; Marié et al., 2014; Taras et al., 2012).

**Final Remarks**

Droughts are some of the main factors of food crisis worldwide, which can be overcome by the development of drought-tolerant cultivars via plant breeding. Since droughts occur more often in severe forms, the breeding cycle should be significantly shortened. To achieve this, massive and accurate phenotypic data are crucial. Given that responses to drought stress are related to various morphological and physiological traits, numerous methods could be applied using sensors, such as multispectral, hyperspectral, thermal, fluorescence sensors, and laser sensors on various platforms.

In this study, recently developed HTP methods and platforms were reviewed for drought screening. For instance, researchers searching for a cost-effective HTP drought screening method, RGB and NIR imaging with aerial platform or ground vehicle might be a proper selection. In order to screen in-field conditions, aerial platforms are more efficient in large area screening while having low payloads for sensors. Unlike aerial platforms, ground vehicles are more efficient in narrow areas and capable of carrying multiple sensors. However, for more accurate and consistent screening, ground fixed and stationary platforms might be a suitable selection. Despite its high cost, users willing to use in strictly controlled environmental conditions and various sensors, indoor platform might be a proper choice. In addition, remotely controlled ground vehicles and indoor phenotyping systems can provide below canopy area images with various sensors by user’s choices and financial constraints. Our objective was to help researchers who need to conduct HTP for drought responses. We sincerely hope that this article could help those who consider studying drought response or breeding drought-tolerant cultivars.

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**Authors’ Contributions**

**Conceptualization:** Chung, Y.S. **Writing and**

**editing:** Kim, J.Y.; Kim, K.S.; Kim, Y.H.

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