

## Q2

July 8, 2022

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[1]: import numpy as np
import math
import matplotlib.pyplot as plt

# do integration on func(x,y,arg1,...), from x = a to b, y from gfun(x) to
↪ hfun(x)
def dblquad(func, a, b, gfun, hfun, args=(), x_step = 0.01, y_step = 0.01):
    x = a
    result = 0
    while (x < b):
        y = gfun(x)
        y_max = hfun(x)
        while (y < y_max):
            result += (func(x,y,*args) * y_step * x_step)
            y += y_step
        x += x_step
    return result
epsilon_0 = 8.8541878128*(10**-12)
k = 1 / (4* np.pi * epsilon_0)

# define a point class
class Point:
    def __init__(self, x: float, y: float, z: float):
        self.x = x
        self.y = y
        self.z = z

# calculate x-distance between two points
def disX(p1: Point, p2: Point):
    return p1.x-p2.x

# calculate y-distance between two points
def disY(p1: Point, p2: Point):
    return p1.y-p2.y

# calculate z-distance between two points
def disZ(p1: Point, p2: Point):
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    return p1.z-p2.z

# calculate distance between two points
# require: p1 != p2
def dis(p1: Point, p2: Point):
    return math.sqrt((p1.x-p2.x)**2+(p1.y-p2.y)**2+(p1.z-p2.z)**2)

# the integrand of the result for x-component
def inte_x(y, x, p):
    q = Point(x,y,0)
    return disX(p, q)/(dis(q, p)**3)

# the integrand of the result for y-component
def inte_y(y, x, p):
    q = Point(x,y,0)
    return disY(p, q)/(dis(q, p)**3)

# the integrand of the result for z-component
def inte_z(y, x, p):
    q = Point(x,y,0)
    return disZ(p, q)/(dis(q, p)**3)

# the x-component of E at p from the rectangle of (a,b), ignoring the constants
def Ex(a, b, p):
    return dblquad(inte_x, -a/2, a/2, lambda x: -b/2, lambda x: b/2, args=(p,))

# the y-component of E at p from the rectangle of (a,b), ignoring the constants
def Ey(a, b, p):
    return dblquad(inte_y, -a/2, a/2, lambda x: -b/2, lambda x: b/2, args=(p,))

# the z-component of E at p from the rectangle of (a,b), ignoring the constants
def Ez(a, b, p):
    return dblquad(inte_z, -a/2, a/2, lambda x: -b/2, lambda x: b/2, args=(p,))

# get the field at p generated from the rectangle of (a,b) and density delta
# require: p is not on the rectangle, a,b >0
def rectangleField(p: Point, a, b, delta, silent = False):
    if (p.z == 0 and p.x <= a/2 and p.x >= -a/2 and p.y <= b/2 and p.y >= -b/2):
        print("Error: the point is on the rectangle")
        return 0
    C = delta * k
    E_x = Ex(a, b, p)
    E_y = Ey(a, b, p)
    E_z = Ez(a, b, p)
    E_size = math.sqrt(E_x**2 + E_y**2 + E_z**2) * C
    E_x *= C
    E_y *= C

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E_z *= C
# print the result
if not silent:
    print("The rectangle is {}*{}, the field at point ({} , {} , {}) is {}x, {}y, {}z, with size {}".format(a, b, p.x, p.y, p.z, E_x, E_y, E_z, E_size))
    return E_x, E_y, E_z, E_size

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[2]: # Q3
# try some examples
# p = (4,3,0), a = 1, b = 1, delta = 1
delta = 1
p = Point(4,3,0)
a = 1
b = 1
rectangleField(p, a, b, delta)

# p = (4,3,3), a = 1, b = 1, delta = 1
delta = 1
p = Point(4,3,3)
a = 1
b = 1
rectangleField(p, a, b, delta)

# p = (4,0,3), a = 1, b = 1, delta = 1
delta = 1
p = Point(4,0,3)
a = 1
b = 1
rectangleField(p, a, b, delta)

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The rectangle is 1\*1, the field at point (4,3,0) is 288221765.9275177x, 216242227.14645335y, 0.0z, with size 360322754.1463835  
The rectangle is 1\*1, the field at point (4,3,3) is 180788211.97337925x, 135644105.54040807y, 136422961.3546347z, with size 263997964.65343636  
The rectangle is 1\*1, the field at point (4,0,3) is 286106584.21990496x, 357134.3337067172y, 216458060.3973014z, with size 358763427.60916376

[2]: (286106584.21990496, 357134.3337067172, 216458060.3973014, 358763427.60916376)

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[4]: # Q4 Compare with the formula on central axis, with height h
# for the sake of simplicity, set the constant delta to 1
delta = 1
def planeField(delta, h):
    E_z = delta/(2*epsilon_0)
    print("The field at point ({} , {} , {}) is {}, {}, {}".format(0, 0, h, 0, 0, E_z))
    return E_z

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# large plane
h = 0.01
p = Point(0,0,h)
a = 10
b = 10
_, _, _, E1 = rectangleField(p, a, b, delta)
Ez2 = planeField(delta, h)
print("the relative difference is {}".format(abs((E1-Ez2)/Ez2)))

# smaller plane
h = 0.01
p = Point(0,0,h)
a = 1
b = 1
_, _, _, E1 = rectangleField(p, a, b, delta)
Ez2 = planeField(delta, h)
print("the relative difference is {}".format(abs((E1-Ez2)/Ez2)))

```

The rectangle is 10\*10, the field at point (0,0,0.01) is 0.009480480882536226x, 0.009491984174046104y, 56823095526.54007z, with size 56823095526.54007  
The field at point (0,0,0.01) is 0, 0, 56470453368.65096  
the relative difference is 0.006244719793322444  
The rectangle is 1\*1, the field at point (0,0,0.01) is 254072952.2688889x, 254072952.26890674y, 55907935637.810875z, with size 55909090257.41479  
The field at point (0,0,0.01) is 0, 0, 56470453368.65096  
the relative difference is 0.009940828836125671

Note that when the rectangle is smaller, the difference from an infinite plane is larger, but still very small ( $<0.01$ ), as long as the height is much smaller than the area

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[7]: # plot symmetry
ax = plt.figure().add_subplot(projection='3d')
# Make the grid
x, y, z = np.meshgrid(np.arange(-10, 10, 2),
                      np.arange(-10, 10, 2),
                      np.arange(-10, 10, 4))

# wrapper for diskField, but take constant delta=1, a = 5, b=7, and x,y,z
↳ instead of a point p
def recField1(x,y,z):
    p = Point(x,y,z)
    return rectangleField(p,5,7,1,True)

u,v,w = [], [], []
for i in np.arange(len(x)):
    u.append([])
    v.append([])

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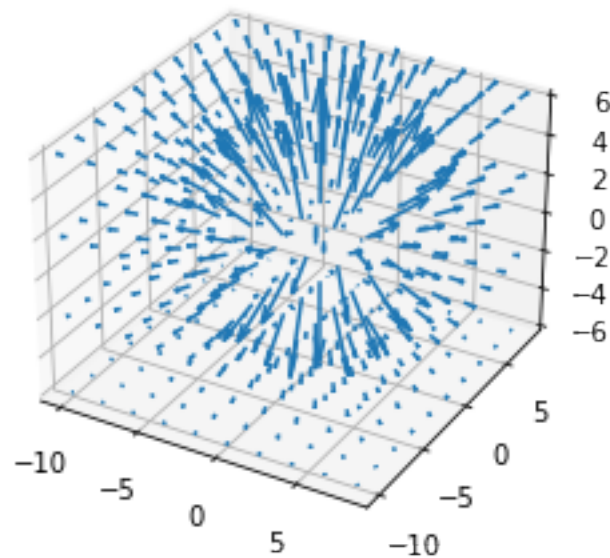
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w.append([])
for j in np.arange(len(x[0])):
    u[-1].append([])
    v[-1].append([])
    w[-1].append([])
    for k in np.arange(len(x[0][0])):
        # after investigation on the meshgrid function, it very wierdly is
        → in the form y-x-z loop
        E_x, E_y, E_z, __ = recField1(x[i][j][k], y[i][j][k], z[i][j][k])
        u[-1][-1].append(E_x)
        v[-1][-1].append(E_y)
        # Ez is way too large in comparison to the other two, divide by
        → constant just to show symmetry
        w[-1][-1].append(E_z)

ax.quiver(x, y, z, u, v, w, length=0.7, normalize=False)

plt.show()

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