```
┌─────────────────────────────────┐
│        view_frames Result       │
│                                 │
│  Recorded at time: 1663555953.134 │
└─────────────────────────────────┘
```

(world)

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1663555953.134 sec old)
Buffer length: 0.000 sec

(pedestal_Link)

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1663555953.134 sec old)
Buffer length: 0.000 sec

(base_link)

Broadcaster: /robot_state_publisher
Average rate: 32.519 Hz
Most recent transform: 1663555953.103 (0.030 sec old)
Buffer length: 4.920 sec

(shoulder_Link)

Broadcaster: /robot_state_publisher
Average rate: 32.519 Hz
Most recent transform: 1663555953.103 (0.030 sec old)
Buffer length: 4.920 sec

(upperArm_Link)

Broadcaster: /robot_state_publisher
Average rate: 32.519 Hz
Most recent transform: 1663555953.103 (0.030 sec old)
Buffer length: 4.920 sec

(foreArm_Link)

Broadcaster: /robot_state_publisher
Average rate: 32.519 Hz
Most recent transform: 1663555953.103 (0.030 sec old)
Buffer length: 4.920 sec

(wrist1_Link)

Broadcaster: /robot_state_publisher
Average rate: 32.519 Hz
Most recent transform: 1663555953.103 (0.030 sec old)
Buffer length: 4.920 sec

(wrist2_Link)

Broadcaster: /robot_state_publisher
Average rate: 32.519 Hz
Most recent transform: 1663555953.103 (0.030 sec old)
Buffer length: 4.920 sec

(wrist3_Link)