

Configured drive

Motor - DCX32L GB KL 12V Gearhead - GPX32UP 111:1 Sensor - ENX 10 EASY XT 1024IMP

Part number: B7BAA6D15634 Revision number 1

Orders are processed and shipped from Switzerland within 11 working days.

General Terms and Conditions: https://www.maxongroup.ch/maxon/view/content/terms_and_conditions_page

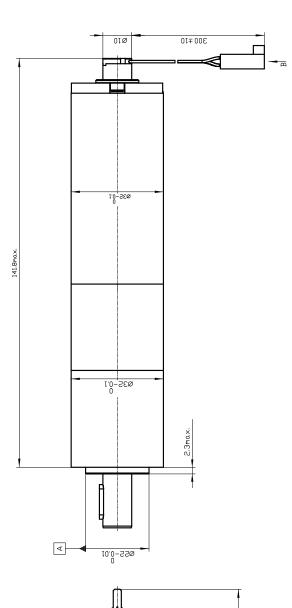


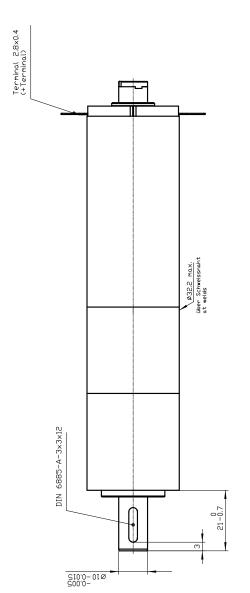
To open the integrated CAD file, please save this document and open it in Acrobat Reader. The STEP file is available after a double-click on the pin icon.

B7BAA6D15634.stp (STP AP 214)

Open configuration: https://www.maxongroup.com/maxon/view/configurator/?ConfigID=B7BAA6D15634

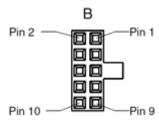
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Connector type, encoder			
Molex 2	2-55-2102		
Pin 1	NC		
Pin 2	VCC		
Pin 3	GND		
Pin 4	NC		
Pin 5	NC		
Pin 6	Channel A		
Pin 7	NC		
Pin 8	Channel B		
Pin 9	NC		
Pin 10	Channel I		



Summary of your selected configurationTotal weight of the drive: 618 g

	DCX32L GB KL 12V	
Product detail		
	Commutation	Graphite brushes
	Nominal voltage	12 V
	Motor bearings	Preloaded ball bearing
	GPX32UP 111:1	
Product detail		
	Gearhead type	Ultra Performance
	Reduction	111
	Number of stages	3
	ENX 10 EASY XT 1024IMP	
Product detail		
	Counts per turn	1024

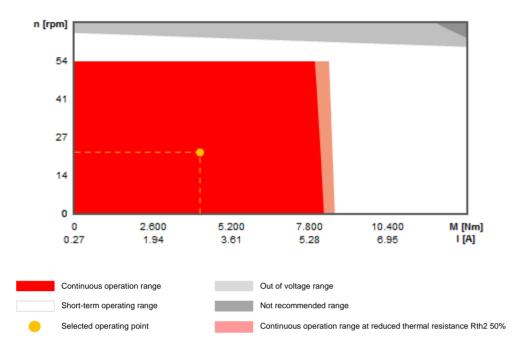


Legend for part designation

EB	Precious metal brushes	GB	Graphite brushes	CLL	Spark suppression	BL	Brushless
Α	Hall sensors	В	Sensorless	KL	Ball bearings	SL	Sintered bearings
GPX	Planetary gearhead	ENX	Encoder	ENC	Encoder	IMP	Pulses
ST	Number of stages	HP	High Power	S/M/L	Short/medium/long	HS	High Speed
STE	Sterilizable	INT	integ.	STD	Standard	SP	Speed
ABS	Absolute	LN	Reduced noise level	Α	Standard	LZ	Reduced backlash
С	Ceramic bearing			STEC	Sterilizable, Ceramic		
					bearing		

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Drive disposition



	Combination details		
Your entries			
	Available voltage	12 V	
	Speed	21.62 min ⁻¹	
	Torque	4.16 Nm	
Values of the d	rive at available voltage Available voltage	12 V	
	Max. speed at given load	54 min ⁻¹	
	Max. continuous torque	8.93 Nm	
	Max. continuous current	6.00 A	
Required electr	ical data for your operating point		
	Speed	21.62 min ⁻¹	

Required electrical data for your operating point		
Speed	21.62 min ⁻¹	
Torque	4.16 Nm	
Required voltage	4.39 V	
Required current	2.94 A	



DCX32L GB KL 12V



Product specifica	ntion	
Values at nominal voltage		
Nominal voltage		12 V
No load speed		7120 min ⁻¹
No load current		274mA
Nominal speed		6560 min ⁻¹
Nominal torque (max.	continuous torque)	89.4 mNm
Nominal current (max.	continuous current)	6 A
Stall torque		1730 mNm
Stall current		111 A
Max. efficiency		85.5 %

Characteristics		
	Max. output power continuous	90.2 W
	Terminal resistance	0.108 Ω
	Terminal inductance	0.0336 mH
	Torque constant	15.6 mNm A ⁻¹
	Speed constant	612 min ⁻¹ V ⁻¹
	Speed/torque gradient	4.24 min ⁻¹ mNm ⁻¹
	Mechanical time constant	3.44ms
	Rotor inertia	77.6 gcm ²

Thermal data		
	Thermal resistance housing-ambient	7.28 KW ⁻¹
	Thermal resistance winding-housing	2.3 KW ⁻¹
	Thermal time constant of the winding	45 s
	Thermal time constant of the motor	837 s
	Ambient temperature	-40100 °C
	Max. winding temperature	155 °C

Mechanical data	
Max. permissible speed	11300 min ⁻¹
Axial play	00.1 mm
Preload	7 N
Radial backlash	0.02 mm
Max. axial load (dynamic)	7 N
Max. force for press fits (static)	22.6 N



Static, supported shaft	2510 N
Max. radial load 5 mm from flange	65.3 N
Measurement from the flange	5 mm

Further specifications			
Number of pole pairs	1		
Number of commutator segments	11		
Motor weight	323.1 g		
Motor length	71.9 mm		
Typical noise level	47 dBA (min ⁻¹)		

Information about motor data: https://www.maxongroup.com/medias/CMS_Downloads/DIVERSES/12_049_EN.pdf



GPX32UP 111:1



	Product specification	
Gearhead data		
	Reduction	111:1
	Absolute reduction	357075/3211
	Number of stages	3
	Max. continuous torque	10.40 Nm
	Max. intermittent torque	13 Nm
	Direction of rotation, drive to output	=
	Max. efficiency	90 %
	Average backlash no-load	0.9 °
	Mass inertia	10.82 gcm ²
	Max. transmittable power (continuous)	70 W
	Max. short-time transferable output	85 W

Technical data		
	Output shaft bearing	Ball bearings
	Max. radial play, 5 mm from flange	max. 0.1 mm
	Axial play	00.2 mm
	Max. permissible radial load, 10 mm from flange	250 N
	Max. permissible axial load	110 N
	Max. permissible force for press fits	200 N
	Max. continuous input speed	6000 min ⁻¹
	Max. intermittent input speed	7500 min ⁻¹
	Recommended temperature range	-40100 °C

Information about gearhead data: https://www.maxongroup.com/medias/CMS_Downloads/DIVERSES/12_203_EN.pdf



ENX 10 EASY XT 1024IMP



	Product specification	
Sensor data		
	Counts per turn	1024
	Number of channels	3
	Line Driver	No
	Max. electrical speed	90000 min ⁻¹
	Max. mechanical speed	30000 min ⁻¹

Technical data		
	Supply voltage Vcc	5 V ±10 %
	Output signal	INC
	Output signal driver	Single Ended / EIA RS 422
	Output current per channel	-2020 mA
	State length	20160 °el
	Signal rise time/Signal fall time	20/20 ns
	Min. state duration	125 ns
	Direction of rotation	A before B CW
	Index position	A low & B low
	Index synchronously to AB	Yes
	Index pulse width	90 °el
	Typical current draw at standstill	22 mA
	Max. moment of inertia of code wheel	0.09 gcm ²
	Operating temperature range	-55125 C°
	Number of autoclave cycles	0

Datasheet: https://www.maxongroup.com/medias/CMS_Downloads/DIVERSES/ENXEASY_EN.pdf



EPOS4 Module 50/5



	Product specification	
Motor		
	DC motors up to	250 W
	EC motors up to	250 W
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Sensor		
	Without sensor (DC motors)	Yes
	Sensorless (EC motors)	
	Digital incremental encoder (2-channel, single-ended)	Yes
	Digital incremental encoder (2-channel, differential)	Yes
	Digital incremental encoder (3-channel, differential)	Yes
	Digital Hall sensors (EC motors)	Yes
	SSI absolute encoder	Yes
	Analog incremental encoder (2-channel, differential)	Yes
Operating modes		
	Current controller	Yes (Torque)
	Speed controller (open loop)	
	Speed controller (closed loop)	Yes
	Positioning controller	Yes
Floatiscal data		
Electrical data	Operation voltage VCC	10 F0 VDC
	Operating voltage VC	1050 VDC 1050 VDC
	Logic supply voltage VC optional Max. output voltage (factor * VCC)	0.9 *
	Max. output current Imax	15 A
	Max. duration of peak output current Imax	3 s
	Continuous output current Icont	5 A
	Switching frequency of the power stage	50 kHz
	Sampling rate, PI current controller	25 kHz
	Sampling rate, P1 current controller Sampling rate, P1 speed controller (closed loop)	2.5 kHz
	Sampling rate, PID positioning controller	2.5 kHz
	Max. efficiency	97 %
	Max. speed (DC motors)	100000 min-1
	Max. speed (1 pole pair), block commutation	100000 min-1
	Max. speed (1 pole pair), sinusoidal commutation	50000 min-1
	Built-in motor choke per phase	uH
	2 sstor strong per prides	···
Inputs		
	Hall sensor signals	H1, H2, H3
	Encoder signals	A, A B, B I, I\
	Max. encoder input frequency	6.2 MHz
	Digitale Eingänge	8



	Functionality of digital inputs	limit switch, reference switch, general purpose, touch probe
	Analog inputs	2
	Resolution, range, circuit	12-bit, -10+10V, differential
	Functionality of inputs	General Purpose, Set Value Current, Set Value Velocity
	Potentiometers	
	Functionality of the potentiometers	
	DIP switch	
	Functionality of the DIP switch	
Outputs		
	Digital outputs	3
	Functionality of digital outputs	holding brake, general purpose
	Analog outputs	2
	Resolution, range	12-bit, -4+4V
	Functionality of analog outputs	General Purpose
Vallana		
Voltage outputs	Hall conner cumply veltage	aca "Canaar aunnhu valtaga"
	Hall sensor supply voltage	see "Sensor supply voltage"
	Encoder supply voltage	see "Sensor supply voltage"
	Auxiliary output voltage	+5 VDC, max. 150 mA
	Output voltage (reference)	
Ambient conditions		
Ambient conditions	Temperature – operation	-30 45 °C
	Temperature – storage	-40 85 °C
	Temperature – extended range	+45+75 °C, Derating: -0.167 A/°C
	Humidity (non-condensing)	5 %
	Trainiary (non-contactioning)	0 /v
Mechanical data		
	Weight	17 g
	Dimensions (L x W x H)	53.8 x 38.8 x 11.1 mm
	Mounting	mountable on socket terminal strips pitch 1.27 mm, mounting holes for M2.5 screws