

UNIVERSITY OF BURGUNDY

Software Engineering Project Weekly Report

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1 Task completed

As from the continuation of previous week, we finally are able to acquire the depth images using Kinect, as shown in Figure 1.

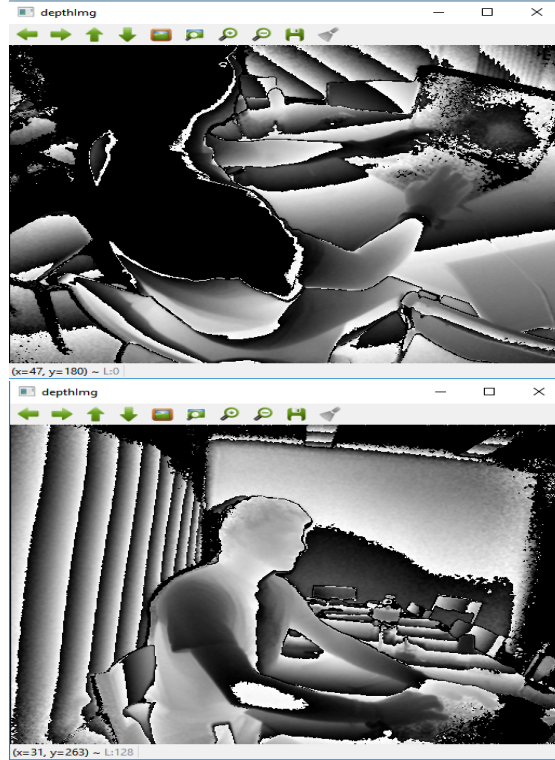


Figure 1: Acquired Depth images

2 Work in progress

The main task is now to acquire RGB as well as Depth images to get the point cloud out of them. As both image types are not of the same size so we also have to look into this issue. Also the depth images are not that good so we have to fix this as well.