

# 1. From Neurons to Networks



#### From Neurons to Networks

#### biological neurons (very brief)

- single neurons
- synapses and networks
- synaptic plasticity and learning

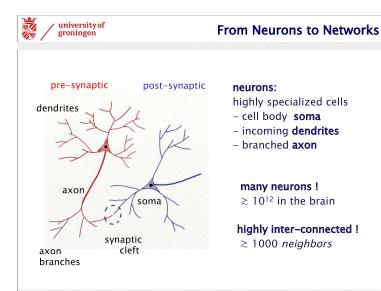
#### simplified description

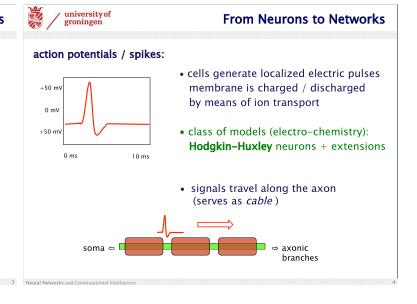
- modelling of biological neurons/networks
- inspiration for artificial neural networks

#### artificial neural networks

- unrealistic simplifications
- architectures and types of networks:
   recurrent attractor neural networks (associative memory)
   Example: The Hopfield model
   feed-forward neural networks (classification/ regression)

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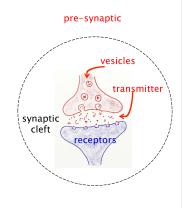


#### From Neurons to Networks

#### synapse:

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- · arriving pre-synaptic spike triggers release of neuro-transmitters
- · different kinds of synapses play specific roles:
- pre-synaptic pulse at excitatory /inhibitory synapse triggers / hinders post-synaptic spike generation



post-synaptic

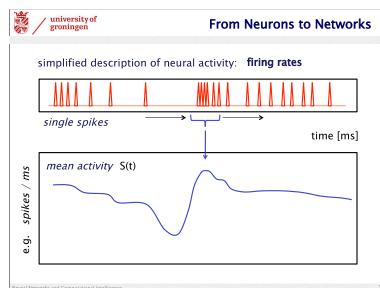


#### From Neurons to Networks

- increase (excitatory) membrane potential • incoming pulses decrease (inhibitory)
- all or nothing response

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- potential exceeds threshold postsynaptic neuron fires potential is sub-threshold postsynaptic neuron rests
- important class of models: Integrate-and-Fire neurons and networks
  - no details of spike generation and signal propagation
  - neuron as simple threshold element,
- excitatory and inhibitory connections with other units (see additional material)





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#### From Neurons to Networks

(mean) **local potential** at neuron i (with activity  $S_i$ )

$$\sum_j w_{ij} S_j$$
 weighted sum of incoming activities

Note:  $w_{ii}=0, \quad w_{ij} 
eq w_{ji}$  (in general) connections  $i \rightarrow j$  and  $j \rightarrow i$  are unrelated.



#### **Activation Function**

# non-linear response: $S_i = h \left[ \sum_j w_{ij} S_j \right]$

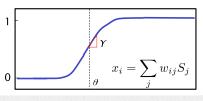
- · minimal activity
- $h(x \rightarrow -\infty) \equiv 0$  $h(x \rightarrow +\infty) \equiv 1$ important class of fcts.: · maximal activity sigmoidal activation
- monotonic increase h'(x) > 0

$$h(x_i) = \frac{1}{2} \Big( 1 + \tanh \left[ \gamma(x_i - \theta) \right] \Big)$$

gain parameter Y local threshold  $\theta$ Remark:

just one example:

do not confuse  $\theta$  with threshold for single spike generation!



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# Symmetrization (I)

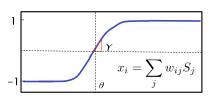
non-linear response:  $S_i = g \left[ \sum_j w_{ij} S_j \right]$ 

- minimal activity  $g(x \rightarrow -\infty) \equiv -1$
- maximal activity  $g(x \rightarrow +\infty) \equiv 1$ 
  - sigmoidal activation
- monotonic increase g'(x) > 0

just one example:

$$g(x_i) = \tanh \left[ \gamma(x_i - \theta) \right]$$

gain parameter Y local threshold heta



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# Symmetrization (I)

$$-1 \le S_i = g\left[\sum_j w_{ij} S_j\right] \le +1$$

$$S_j > 0, w_{ij} > 0$$
 excitation

$$S_j < 0, w_{ij} < 0$$

$$S_j > 0, w_{ij} < 0$$

$$S_j < 0, w_{ij} > 0$$

(plausible)

(unrealistic)

#### symmetric treatment of low / high activity

- not suitable for realistic modelling of biological neurons, absence of spikes cannot excite activity etc. (further consequences discussed below)
- convenient in bio-inspired artificial neural networks (more drastic simplifications to come)



### McCulloch Pitts Neurons

an extreme case: **infinite gain**  $\gamma \rightarrow \infty$ 

$$g(x_i) = \tanh \left[ \gamma(x_i - \theta) \right] \to \operatorname{sign} \left[ x - \theta \right] = \begin{cases} +1 & \text{for } x \ge \theta \\ -1 & \text{for } x < \theta \end{cases}$$

#### McCulloch Pitts [1943]:

model neuron is either quiescent or maximally active do not consider graded response

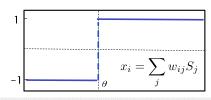
local threshold heta

Remark:

this is not the

all-or-nothing response in single spike







# **Synaptic Plasticity**

# Symmetrization (II)

#### D. Hebb [1949]

consider - presynaptic neuron

- postsynaptic neuron B

- excitatory synapse  $W_R$ 



### Hypothesis: Hebbian Learning

If A and B (frequently) fire at the same time the excitatory synaptic strength  $\left.w_{\text{BA}}\right.$  increases

→ memory-effect will favor joint activity in the future high activity of A will trigger high activity at B correlations of activity stored in the network



change of synaptic strength  $\ \Delta w_{BA} \propto S_A S_B$ 

beyond Hebb's hypothesis: symmetric treatment

- of high/low activity
- of pre- postsynaptic activity

$S_A$	$S_E$

high	high ] strengthens	excitatory
low	low weakens	inhibitory
high	low [ ] weakens	excitatory
low	high strenghtens	inhibitory

synapse  $w_{BA}$ 

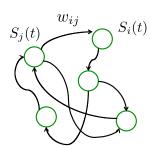
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# Artificial Neural Networks



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- assembled from simple firing rate neurons
- connected by weights, real valued synaptic strenghts
- various architectures and types of networks e.g.: attractor neural networks, feed-forward networks



here:
number of neurons N=5
partial connectivity:
7 directed synapses

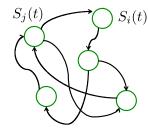


## **Attractor Neural Networks**

#### training phase:

dynamics of weights (synapses), given the network activity

$$w_{ij}(t+\Delta t)=w_{ij}+\eta S_i(t)S_j(t)$$
 (Hebbian Learning)



for example: sequence of **activity patterns**, memorization of frequent states, external stimuli etc.

$$\mathbf{S}(t) \in \left\{ \boldsymbol{\xi}^{\mu} \right\}_{\mu=1}^{P}$$



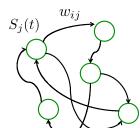
#### **Attractor Neural Networks**

# of Attractor Neural Networks

## working phase:

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dynamics of neurons, given the weights



$$S_i(t + \Delta t) = g \left[ \sum_j w_{ij} S_j(t) \right]$$

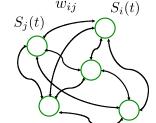
#### variants:

- sequential update i=1,2,3,...
- random sequential update
- parallel update

retrieval of patterns: from incomplete / noisy state  $\,{f S}(0)\,$  approach original pattern  $\,{f S}(t o \infty) = {m \xi}^{\nu}$ 

### extreme example: Little-Hopfield model

- symmetric Hebbian interactions  $w_{ij}=w_{ji}=rac{1}{P}\sum_{\mu=1}^{P}\xi_i^{\mu}\,\xi_j^{\mu}$ 



- McCulloch Pitts neurons

$$S_i(t + \Delta t) = \operatorname{sign}\left[\sum_j w_{ij} S_j(t)\right]$$

parallel (Little)
 random sequential (Hopfield)
 dynamics of neurons

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#### **Attractor Neural Networks**

consider a single pattern  $~{m \xi}^1~w_{ij} \propto \xi_i^1 \xi_j^1$ 

show:  $\mathbf{S}(t) = \boldsymbol{\xi}^1$  is reproduced under the dynamics!

$$S_i(t + \Delta t) = \operatorname{sign}\left(\sum_j w_{ij} \xi_j^1\right) = \operatorname{sign}\left(\xi_i^1 \sum_j \underbrace{\xi_j^1 \xi_j^1}_{>0}\right) = \xi_i^1$$

fixed point: unchanged under system dynamics

(?) stable fixed point: small deviations from patterns vanish retrieved from similar initial states

much more difficult to show: set of random (zero mean) patterns

$$\left\{ oldsymbol{\xi}^{\mu}
ight\} _{\mu=1}^{P} \ \ ext{with} \ P=lpha N \qquad \ \ ext{is retrieved, if} \ \ lpha \ \ ext{is not too big}$$

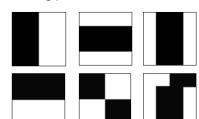
*N* neurons (with  $\sim N^2$  weights) memorize  $\sim \mathcal{O}(N)$  activity patterns



# **Demo: Associative Memory**

- consider a **Hopfield network** of 2500 neurons
- visualized as array of 50\*50 neurons note: there is no spatial structure imposed, every neuron is connected with every other neuron!

#### training patterns:



+ (994) random patterns with activity +/- 1 with equal probability

saved as 'pattern.mat'



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#### **Demo: Associative Memory**

 calculate synaptic matrices saved in jmats.mat (load by load jmats.mat)

$$w_{ij} = w_{ji} = \frac{1}{P} \sum_{\mu=1}^{P} \xi_i^{\mu} \xi_j^{\mu}$$

P=10 (jmat10) P=100 (jmat100) P=1000 (jmat1000)

hopf (jmat, inipat, q, stps) e.g. hopf(jmat10,1,0.4,100)

- jmat synaptic matrix to be used

inipat index of pattern used as initial state
 q fraction of flipped spins in initial state
 stps number of steps per neuron in the system



### **Demo: Associative Memory**

regime of low 'memory load' (here: P=10)







noisy initial state

dynamics

(almost) perfect retrieval

- distributed memory

- robust system!

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one can show: set of random (zero mean) patterns

 $\left\{ oldsymbol{\xi}^{\mu}
ight\} _{\mu=1}^{P} \ \ \mathrm{with} \ P=lpha N \ \ \mathrm{is} \ \mathrm{retrieved} \ \mathit{successfully} \ \mathrm{for} \ \ lpha\leq0.14$ 

*N* neurons (with  $\sim N^2$  weights) memorize  $\sim \mathcal{O}(N)$  activity patterns



# **Demo: Associative Memory**

intermediate load (e.g. P=100)







noisy initial state

dynamics

- distributed memory

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noise dependent retrieval state potential 'confusion'

- robust system!

one can show: besides the original patterns,

'spurious states' are also stabilized, e.g. mixtures of different patterns

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**Demo: Associative Memory** 

overloaded memory (e.g. P=1000)





?

noisy initial state

dynamics

no retrieval patterns unstable

- distributed memory

- robust system!

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#### **Remarks**

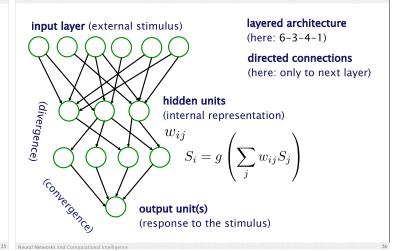
- the above is, strictly speaking, only true for 'uncorrelated patterns'
- one can improve the Hopfield network by decorrelating, i.e.

$$w_{ij} = \frac{1}{P} \sum_{\mu=1}^{P} \left( \xi_i^{\mu} - \langle \xi_i^{\mu} \rangle \right) \left( \xi_i^{\mu} - \langle \xi_j^{\mu} \rangle \right)$$

- improved training prescriptions: iterative learning, e.g. perceptron algorithm
- Hopfield model serves as a basic model of learning and retrieval
- other 'recurrent networks' are used in applications
- more sophisticated and detailed models for biological modelling
- different architectures, e.g. 'Feed-forward' networks for regression/classification tasks

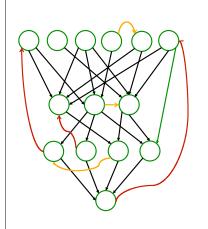


#### Feed-Forward Networks





#### Feed-Forward Networks



modifications:

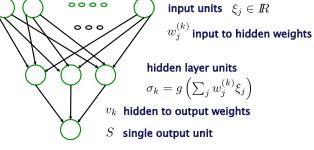
(still) feed-forward weights input/output relation

intra-layer connections internal dynamics

feed-back connections recurrent networks, intermediate connectivity



#### Feed-Forward Networks



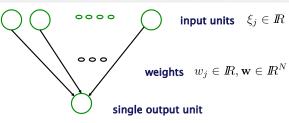
output = **non-linear function** of input variables:

$$S = g_{out}\left(\sum_{k=1}^{K} v_k \sigma_k\right) = g_{out}\left(\sum_{k=1}^{K} v_k g\left(\sum_{j} w_j^{(k)} \xi_j\right)\right)$$

parameterized by set of all weights (and threshold)



### The Perceptron



$$S = \operatorname{sign}\left(\sum_{j=1}^{N} w_j \xi_j - \theta\right)$$

output = "linear separable function" of input variables parameterized by the weight vector  ${\bf w}$  and threshold  ${\boldsymbol \theta}$ 



#### Feed-Forward Networks

#### training phase:

adaptation of parameters

based on a set of example data  $D = \left\{ \boldsymbol{\xi}^{\mu}, S^{\mu} \right\}_{\mu=1}^{P}$ 

working phase

**generalization**, i.e. appl. of hypothesis to novel input  $\xi \to S$ 

possible aims:

**classification**: S is a discrete label (e.g.  $S \in \{1, 2, \dots, C\}$ )

which assigns vectors  $\xi$  to one of  $\mathbf{C}$  classes

**regression**: S is a continuous response (e.g  $S \in I\!\!R$ )

which describes a property of  $\xi$  quantitatively

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#### Feed-Forward Networks

supervised learning (e.g. in feedforward networks)
classification / regression problems

- which are difficult to formulate as a simple set of rules (unknown or too complex)
- for which it is relatively simple to obtain example data (by observation or consulting an expert)

just a few examples:

- ·handwritten character (digit) recognition
- prediction of protein structure from amino acid sequences
- analysis of spectra (e.g. infrared spectra -> fat content of meat)
- prediction of customer interests (e.g. at amazon.com)
- adaptive engine control (driver dependent)
- medical data/image analysis (diagnosis, risk prediction etc.)
- · fault identification in technical processes
- ... many more ...