

1. Given an input image of size $N \times N$, filter size of $f \times f$, stride of s , and zero padding of z pixels in each direction, give an expression in terms of these variables for the size of the first hidden layer. (3 points)
2. Given an input image of $25 \times 25 \times 3$, that is, a color image of size 25×25 , what size filter is needed to get a first hidden layer of size 21×21 ? Assume no zero padding, and stride=1. (2 points)
3. What is weight decay? How does it relate to our previous optimization problem of minimizing L with respect to w ? Remember one example of L was $L(y, \hat{y}) = \frac{1}{2}(y - \hat{y})^2 + \frac{\lambda}{2}||w||^2$. (2 points)
4. What is the result of 2×2 Max Pooling on the following input? (3 points)

5	1	4	1	9
5	1	4	1	9
5	1	4	1	9
5	1	4	1	9
5	1	1	1	9

1. As the amount of training data increases, how do traditional machine learning methods compare to deep learning? Explain. (2 points)

2. What is the result of 2x2 Max Pooling on the following input? (3 points)

5	1	4	1	9
5	1	4	1	9
5	1	4	1	9
5	1	4	1	9
5	1	1	1	9

3. I am trying to create a neural network to predict whether a word is a noun or a verb. Should I use a softmax, sigmoid cross-entropy, or euclidean loss? Explain. (2 points)
4. Consider a CNN with an input image of size 10x10. The output of the network is 8x8. The network has only one layer. Assume no zero padding, and a stride of 1. How many parameters are there in a CNN with this input and output? Explain. (3 points)