1 Notation

• Sets:

I — elective surgeries (index i); B — OR–day blocks (index t).

• Parameters (scalars):

 b_i (booked time), d_i (nominal duration), c^{OT} , c^{IT} , c^{REJ} (unit costs), Cap = 480 minutes (regular capacity).

• Decision variables:

 $Z_{it} \in \{0, 1\}, R_i \in \{0, 1\} \text{ (first stage)}; OT_t, IT_t \ge 0 \text{ (second stage)}.$

• Uncertain durations:

 $\mathbf{D} = (D_i)_{i \in I} \in \mathbb{R}_+^{|I|}$ is a random vector with distribution $\mathbb{P}_{\mathbf{D}}$; realizations are denoted as \mathbf{d} .

• Covariates for CSO:

 $X \in \mathbb{R}^{d_x}$ is a random covariate vector revealed before scheduling, with realization x and joint law $\mathbb{P}_{X,\mathbf{D}}$.

2 Deterministic Baseline MILP

The baseline assumes actual durations d_i are known a priori.

$$\min_{Z,R,OT,IT} \sum_{t \in B} \left(c^{OT}OT_t + c^{IT}IT_t \right) + c^{REJ} \sum_{i \in I} b_i R_i$$
 (1)

s.t.
$$\sum_{t \in B} Z_{it} + R_i = 1 \qquad \forall i \in I, \tag{2}$$

$$\sum_{i \in I} d_i Z_{it} - \text{Cap} = OT_t - IT_t \qquad \forall t \in B,$$
 (3)

 $Z_{it}, R_i \in \{0, 1\}, \ OT_t, IT_t \ge 0.$

3 Introducing Uncertainty

At allocation time the true durations are unknown; we therefore model $\mathbf{D} \sim \mathbb{P}_{\mathbf{D}}$ and observe \mathbf{d} after choosing (Z, R). All expectations below are taken with respect to this distribution.

4 Two-Stage Stochastic Program

We now select (Z, R) to minimize the expected total cost, recognizing that OT and IT are adjusted in a second stage after the duration is realized.

First stage.

$$\min_{Z,R} \quad c^{REJ} \sum_{i \in I} b_i R_i + \mathbb{E}_{\mathbb{P}_{\mathbf{D}}} [Q(Z, R; \mathbf{D})]$$
 (4)

s.t.
$$\sum_{t \in B} Z_{it} + R_i = 1$$

$$\forall i \in I,$$

$$Z_{it}, R_i \in \{0, 1\}.$$
 (5)

Second stage. After having a realization $\mathbf{d} = (d_i)_{i \in I}$ we solve:

$$Q(Z, R; \mathbf{d}) = \min_{OT, IT \ge 0} \sum_{t \in B} \left(c^{OT} OT_t + c^{IT} IT_t \right)$$
 (6)

s.t.
$$\sum_{i \in I} d_i Z_{it} - \text{Cap} = OT_t - IT_t, \ \forall t \in B.$$
 (7)

5 Sample-Average Approximation (SAA)

When $\mathbb{P}_{\mathbf{D}}$ is unknown, we estimate the expectation in (4) using N i.i.d. samples of vectors $\mathbf{d}^{(1)}, \dots, \mathbf{d}^{(N)} \sim \mathbb{P}_{\mathbf{D}}$. With second–stage variables $OT_t^{(n)}, IT_t^{(n)}$ for each sample n:

$$\min_{Z,R,OT^{(n)},IT^{(n)}} c^{REJ} \sum_{i \in I} b_i R_i + \frac{1}{N} \sum_{n=1}^{N} \sum_{t \in B} \left(c^{OT} OT_t^{(n)} + c^{IT} IT_t^{(n)} \right)$$
(8)

s.t.
$$\sum_{t \in B} Z_{it} + R_i = 1 \qquad \forall i \in I, \tag{9}$$

$$\sum_{i \in I} d_i^{(n)} Z_{it} - \text{Cap} = OT_t^{(n)} - IT_t^{(n)} \qquad \forall t \in B, \ n = 1, \dots, N,$$
(10)

 $Z_{it}, R_i \in \{0, 1\}, \ OT_t^{(n)}, IT_t^{(n)} \ge 0.$

6 Contextual Stochastic Optimization

Covariate information x—for example day-of-week, surgeon, or patient status—often helps anticipate durations. Let $\mathbb{P}_{\mathbf{D}|X=x}$ denote the *true* conditional distribution of \mathbf{D} given X=x. For each observed x we solve

$$z^{\star}(x) = \underset{Z,R}{\operatorname{arg\,min}} \quad c^{REJ} \sum_{i \in I} b_i R_i + \mathbb{E}_{\mathbb{P}_{\mathbf{D} \mid X = x}} [Q(Z, R; \mathbf{D})]$$
s.t.
$$\sum_{t \in P} Z_{it} + R_i = 1 \qquad \forall i \in I, \qquad Z_{it}, R_i \in \{0, 1\}.$$

Problem (11) is structurally identical to (4): only the expectation is now conditional on the covariate. Data-driven approximations (e.g. contextual SAA or predict-then-optimize) replace $\mathbb{P}_{\mathbf{D} \mid X=x}$ with an empirical or learned model; these will be developed in later sections.