

### LTE eNodeB

### AZCMCK2KBXB1 Baseband Unit BBU Platform SW Installation Manual

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### **Azcom Technology srl**

Headquarter: Centro Direzionale Milanofiori Strada 6, Palazzo N/2 20089 Rozzano (MI) – Italy Tel.: +39 02 82450311

Website: <a href="www.azcom.it">www.azcom.it</a></a><br/>E-mail: <a href="mailto:info@azcom.it">info@azcom.it</a>



### **REVISION HISTORY**

Rev.	Date	Description
1.0	25-Mar-2016	Changed template
1.1	29-Jun-2016	New platform 2.0
1.2	13-Jun-2019	Chapter 5 added, describing recovery system upgrade procedure. Chapter 6 added, describing new automatic exit from recovery feature.



### **ABBREVIATIONS AND ACRONYMS**

ARM Advanced RISC Machine

BBU Base Band Unit

CCS Code Composer Studio

ETH Ethernet

EVM Evaluation Module

FPGA Field Programmable Gate Array

PC Personal Computer

SSH Secure Shell SW Software

TFTP Trivial File Transfer Protocol

UBIFS Unsorted Block Image File System

USB Universal Serial Bus



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## 1 Introduction

This document describes the procedure of Platform SW installation for the following boards:

- Azcom Kepler BBU (AZCMCK2KBXB1), hereinafter < soc > substituted with bb-kepler
- Texas Instruments EVM-Kepler, hereinafter <*soc*> substituted with *evmk2k*



# ${\bf 2} \ {\bf Platform} \ {\bf distribution} \ {\bf package} \ {\bf content}$

Distribution Package is organized as follow:

platform_ <version>.tar</version>					
platform_ <version>.txt</version>	Release manifest				
images/bootcore-bb-kepler.img	Bootcore Image				
images/u-boot-bb-kepler.img	Operative Bootloader				
images/u-boot-recovery-bb-kepler.img	Recovery Bootloader				
images/boot-bb-kepler.azubi	UBIFS Main boot partition				
	(Device Tree, Kernel, RootFS)				
images/pers-bb-kepler.azubi	UBIFS persistent partition				
	(Application packages,				
	configuration)				
images/drec-bb-kepler.azubi	UBIFS Disaster Recovery				
	partition(Device Tree,				
	Recovery kernel, Recovery				
	RootFS)				
packages/platform-tws8300bbu_2.2.3.azpkg	Platform package				
	(Bootloader, FPGA bitstream,				
	Device Tree, Kernel, RootFS				
packages/recovery-tws8300bbu_2.2.3.azpkg	Recovery package				
	(Bootloader, FPGA bitstream,				
	Device Tree, Recovery Kernel,				
	Recovery Rootfs				



### **3** Host configuration

Windows 7 (or higher) PC or Ubuntu 16.04 (or higher) is required.

### 3.1 Serial port configuration

The following parameters are needed to connect to the serial console:

o Speed (baud rate): 115200

o Bits: 8

Parity: NoneStop Bits: 1

o Flow Control: None

### 3.2 Network configuration

To execute the update procedure is necessary that Host Computer and Kepler BBU Ethernet port are reachable via IP protocol.

For example, we describe a direct connection between Host Computer and Kepler BBU:

- Kepler BBU IP address: 192.168.1.1
- Host IP address: 192.168.1.254
- Network netmask 255,255,255.0

Connect the Ethernet cable to ETH RJ-45 connector.

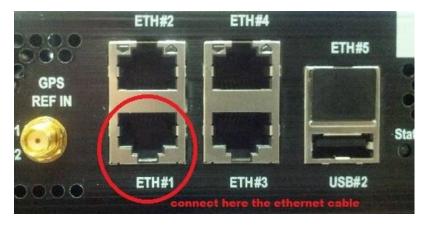


Figura 1 Kepler BBU ETH port

### 3.3 File transfer

The preferred method to transport packages files to Kepler BBU is Secure Copy protocol (scp). This copy protocol is native on Linux PC and is available on Windows PC via WinSCP application, freely downloadable at <a href="https://winscp.net/eng/index.php">https://winscp.net/eng/index.php</a>



## 4 Update of BBU Platform Software

From Platform 2.0.0 and successive there is a new method to upgrade whole system without affecting applications (eNB and EPC) and configurations.

The system is now composed by different packages:

- Platform
- o eNB
- o EPC

There is also a separate layer to make local configuration persistent between upgrades. These packages are updatable independently and are decoupled each other: this means that updating platform packages do not affect other packages and configuration.

### 4.1 Platform command

Platform package deployment is executed in a two-step procedure using 'platform' command after a valid package is uploaded in machine /tmp directory.

These are the steps to complete the platform update operation:

- 1. Upload a valid platform package in product /tmp directory via scp command or WinSCP application
- 2. From Kepler BBU command line execute 'platform retrieve' command.

This should be the console output:

```
platform retrieve
                                               [PRESENT]
                                                [DONE]
                                                [DONE]
                                                [VALID]
Parse OS release
                                                [DONE]
                                                [2.0.0]
Deploying skern
                                                [DONE]
Deploying kernel
                                                [DONE]
                                                [DONE]
Deploying initrd
Deploying rootfs
Deploying fpga
Deploying uboot
Deploying configuration file
                                                [DONE]
                                                [DONE]
Platform is now ready to be upgraded
```



3. At this point is possible to upgrade the system platform issuing 'platform upgrade' command.

This is the expected output if no u-boot or no FPGA needs update:

```
Check for platform status [VALID]

Verifying skern [DONE]

Verifying kernel [DONE]

Verifying devicetree [DONE]

Verifying initrd [DONE]

Verifying rootfs [DONE]

Verifying fpga [DONE]

Verifying uboot [DONE]

Verifying configuration [DONE]

Check u-boot version [SAME VERSION]

Check fpga version [SAME VERSION]

Mark system to be upgraded
```

4. Now the machine will reboot and initial ram-disk will complete the procedure. This means that a second reboot after initial ram-disk update is expected, but there is no need for any user interaction.

After second reboot the machine is updated as expected.

In case also FPGA needs to be updated 'platform upgrade' command will prompt to power cycle the board.

### 4.2 Platform Information

From Platform 2.0.0 and successive there is a method to get information about the current platform installed. Executing the command 'platform info' will report this information.

#### 4.3 Platform Status

From Platform 2.2.3 there is a method to know if the current system is in Normal Mode or Recovery Mode. Executing the command *'platform status'* you will get the following information

If executed in Normal Mode:

<pre>\$ platform status</pre>	
Type:	main

• If executed in Recovery Mode:

\$ platform status
Type: recovery

### 4.4 Platform Type

From Platform 2.2.3 there is a method to switch from main and recovery system with a user friendly interface.

The Normal Mode System can switch to Recovery System executing:

```
$ platform type recovery
Set Next Boot on Recovery System: [DONE]
$ reboot
The system is going down for reboot NOW!
```

The Recovery System can switch to Normal Mode System executing:

```
$ platform type main
Setting boot as safe [DONE]
root@AZB_NCOM_4300:~# reboot
The system is going down for reboot NOW!
```



## **5** Update of BBU Recovery Platform Software

From Platform 2.2.3 there is a procedure to upgrade the recovery system.

**Warning**: The update of the recovery partition is a critical operation. Please be sure that the system is connected to a stable power supply to avoid unrecoverable system corruption.

### 5.1 Recovery command

Recovery package deployment is executed using 'recovery' command after a valid package is uploaded in machine /tmp directory.

These are the steps to complete the recovery update operation:

- 1. Upload a valid recovery package in product /tmp directory via scp command or WinSCP application
- 2. From Kepler BBU command line execute 'recovery upgrade' command.

This should be the console output:

```
Continue upgrade? [y/N]
                                                [PRESENT]
                                                [DONE]
                                                [DONE]
                                                [VALID]
                                                [DONE]
                                                [DONE]
Copy new recovery
                                                [DONE]
                                                [DONE]
                                                [DONE]
                                                [DONE]
Erase U-Boot flash partition:100% |################ Time: 0:00:00 105.14 MB/s
Write U-Boot flash partition:100% |################ Time: 0:00:00 4.09 MB/s
Sync filesystem
Umount recovery filesystem (rw)
                                                [DONE]
Jpgrade ended successfully
```

### **5.2 Recovery Information**

From Platform 2.2.3 there is a method to get information about the current recovery system installed. Executing the command '*recovery info*' will report this information.

\$ recovery info
Codename: tws8300bbu
Version: 2.2.3
Bootloader: 2013.01.14.r6.6
Build: 6



## **6** Automatic Reboot from Recovery Mode

From Platform 2.2.3 release, an automatic procedure to restart the machine when falling in Recovery Mode has been introduced. The feature behaviour is the following:

- 1. When the system starts in Recovery Mode, a timer is armed (60 secs).
- 2. In case the timer expires, system restart is triggered to end-up in Normal Mode.
- 3. The command 'backtomainstop' is available for operator to stop the automatic restart (see next paragraph); in case the operator interrupts the countdown, system remains in recovery mode.
- 4. A counter is maintained to prevent an infinite loop of restart in recovery (in case the system is not able to restore normal operation after the restart); after 3 restarts the system remains in Recovery Mode.
- 5. When the system starts in Normal Mode, recovery loop counter is reset.

### **6.1 Stop Automatic Reboot**

In order to stop the automatic reboot feature and remain in Recovery Mode an operator can execute the 'backtomainstop' command.



## 7 Update device to New Filesystem Layout (Platform 2.0)

### 7.1 Setup

#### 7.1.1 Hardware

Updating device from Platform version 1 to Platform version 2 needs the following hardware:

- PC running Linux or Windows with Ethernet and a serial port or a serial adapter (es. USB to Serial)
- Straight pin-to-pin serial cable with D-Sub 9pin female connectors on both ends
- Cat5e Ethernet cable with RJ45 connectors

#### 7.1.2 Software

To execute the update from Platform version 1 to Platform version 2 is necessary the following software:

- Serial port communication program
  - o Windows: Teraterm or Putty
  - o Linux: minicom (in command line)
- TFTP server:
  - o Windows: TFTPd (64 or 32 bit version)
  - o Linux: xinetd TFTPd service or tftpd-hpa daemon

### 7.1.3 Configuration

In following points there will be the configuration of the PC needed to complete the update:

Serial Port

o Speed: 115200

o Data: 8

Parity: NoneStop bits: 1

• TFTP Server Ethernet Port

Address: 192.168.1.254Netmask: 255.255.255.0

o Gateway: None

• TFTP Server directory structure:

/ (tftp root directory)

- platform\_2.0
  - boot-bb-kepler.azubi
  - bootcore-bb-kepler.img
  - drec-bb-kepler.azubi
  - pers-bb-kepler.azubi
  - u-boot-bb-kepler.img
  - u-boot-recovery-bb-kepler.img
  - platform-tws8300bbu\_2.0.0.azpkg



### 7.2 Procedure

- 1) Enter in recovery bootloader:
  - a) Power up the machine
  - b) Enter in u-boot console by pressing a key during the countdown:

```
Hit any key to stop autoboot: 0
AZB NCOM 4300 #
```

c) Reset 'safeboot' variable and restart:

```
AZB_NC0M_4300 # safeboot reset
Safeboot successfully reset
AZB_NC0M_4300 # reset
resetting ...
```

d) Enter in u-boot recovery console by pressing a key during the countdown:

```
Hit any key to stop autoboot: 0
AZB NCOM 4300 #
```

e) Verify u-boot recovery console finding 'U-Boot 2013.01.14-RECOVERY' in version command:

```
AZB_NCOM_4300 # ver

U-Boot 2013.01.14-RECOVERY-r18-gitr+552e236 (May 14 2016 - 03:10:23)

arm-azcom-linux-gnueabi-gcc (GCC) 4.9.1

GNU ld (GNU Binutils) 2.24

AZB NCOM 4300 #
```

If 'RECOVERY' is not in bootloader version please repeat steps from 1.c to 1.e

- 2) Set u-boot IP networking:
  - a) Set machine IP address to 192.168.1.1:

```
AZB NCOM 4300 # setenv ipaddr 192.168.1.1
```

b) Set TFTP server IP address:

```
AZB NCOM 4300 # setenv serverip 192.168.1.254
```

c) Set IP gateway (if direct connection use same IP address of TFTP server):

```
AZB NCOM 4300 # setenv gatewayip 192.168.1.254
```

d) Set netmask:

```
AZB NCOM 4300 # netmask=255.255.255.0
```

e) Set transfer type:

```
AZB NCOM 4300 # setenv tftp cmd tftp
```

f) Set TFTP root directory:

```
AZB NCOM 4300 # setenv tftp root "platform 2.0"
```



### 3) Flash new bootcore and recovery bootloader:

### a) Update bootcore:

### b) Update recovery bootloader:

#### c) Restart the machine:

```
AZB_NCOM_4300 # reset resetting ...
```

### d) Enter in u-boot console by pressing a key during the countdown:

```
Hit any key to stop autoboot: 0
AZB_NCOM_4300 #
```

### 4) Reset environment parameters to default

#### a) Reset environment variables:

```
AZB_NCOM_4300 # env default -a ## Resetting to default environment AZB NCOM 4300 #
```



- 5) Set u-boot IP networking:
  - a) Set machine IP address:

```
AZB NCOM 4300 # setenv ipaddr 192.168.1.1
```

b) Set TFTP server IP address:

```
AZB NCOM 4300 # setenv serverip 192.168.1.254
```

c) Set IP gateway (if direct connection use same IP address of TFTP server):

```
AZB NCOM 4300 # setenv gatewayip 192.168.1.254
```

d) Set netmask:

```
AZB NCOM 4300 # netmask=255.255.255.0
```

e) Set transfer type:

```
AZB NCOM 4300 # setenv tftp cmd tftp
```

f) Set TFTP root directory:

```
AZB NCOM 4300 # setenv tftp root "platform 2.0"
```

- 6) Re-Flash filesystem with New Filesystem Layout:
  - a) Erase whole NAND flash:

```
AZB_NCOM_4300 # nand erase.chip

NAND erase.chip: device 0 whole chip
Skipping bad block at 0x0ff00000
Skipping bad block at 0x2ff00000
Erasing at 0x3ffe0000 -- 100% complete.
OK
AZB NCOM 4300 #
```

#### b) Update bootcore:



### c) Update recovery bootloader:

### d) Update main bootloader:



### e) Update boot partition:

```
AZB NCOM 4300 # run get ubiboot net burn ubiboot
  1.7 MiB/s
Bytes transferred = 33947648 (2060000 hex)
```



### f) Update Disaster Recovery (drec) partition:

```
AZB NCOM 4300 # run get ubidrec net burn ubidrec
  ******************
  ******************************
  ******************************
  ******************************
  ******************************
  ******************************
  #######
```

### g) Update persistent partition:



h) Set 'safeboot' variable and restart:

```
AZB_NCOM_4300 # safeboot set
Safeboot successfully set
AZB_NCOM_4300 # reset
resetting ...
```

- 7) Now the machine is update to platform 2.0. We need now to upgrade the system using new platform packaging, so if FPGA needs to be updated it will be done automatically. This is the procedure:
  - a) Login to main system:

```
Azcom (Azcom Technology Reference Distro) 2.0.0rc15 AZB_NCOM_4300 /dev/ttyS0 AZB_NCOM_4300 login: root
```

b) Download platform package to machine /tmp directory, for example using scp command.

Remember to substitute '<user>' with the correct TFTP Server user name

```
root@AZB_NCOM_4300:~# scp <user>@192.168.1.254:/tftpboot/platform_2.0/platform-
tws8300bbu_2.0.0.azpkg /tmp/
<user>@192.168.1.254's password:
platform-tws8300bbu_2.0.0.azpkg 100% 32MB 8.0MB/s 00:04
root@AZB_NCOM_4300:~#
```

c) Retrieve platform with 'force' optional argument:

```
root@AZB_NCOM_4300:~# platform retrieve --force
Serch for platform [PRESENT]
Clean deploy directory [DONE]
Get configuration file [DONE]
Parse OS release [DONE]
Check tws8300bbu compatibility [VALID]
Parse OS release [DONE]
Check platform version [2.0.0]
Deploying skern [DONE]
Deploying kernel [DONE]
Deploying devicetree [DONE]
Deploying initrd [DONE]
Deploying initrd [DONE]
Deploying rootfs [DONE]
Deploying toom [DONE]
Deploying configuration [DONE]
Deploying configuration [DONE]
Sync filesystem [DONE]
Platform is now ready to be upgraded

root@AZB NCOM 4300:~#
```



### d) Upgrade platform:

```
root@AZB_NCOM_4300:~# platform upgrade
Check for platform status [VALID]
Verifying skern [DONE]
Verifying kernel [DONE]
Verifying devicetree [DONE]
Verifying initrd [DONE]
Verifying rootfs [DONE]
Verifying fpga [DONE]
Verifying devicetree [DONE]
Verifying fpga [DONE]
Verifying the [DONE]
Verifying uboot [DONE]
Verifying configuration [DONE]
Check u-boot version [SAME VERSION]
Check fpga version [SAME VERSION]
Mark system to be upgraded [DONE]

Platform is now rebooted to be upgraded
```

After upgrade procedure (see chapter 4.1) the platform is now updated to version 2.0.0



# 8 Dip-switch configuration

Condition	Dip #4	Dip #5	Dip #6
No Boot	OFF	OFF	OFF
Nand Boot	OFF	OFF	ON

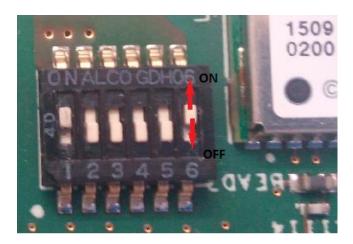


Figure 2 Kepler BBU DIP switch



## **9** Update PIC firmware

It is possible to update the firmware of the Microchip PIC. For this updating you need:

- The Microchip software "AN1310 bootloader"
   <a href="http://ww1.microchip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13">http://ww1.microchip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13</a>
   <a href="http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13">http://ww1.microchip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13</a>
   <a href="http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13">http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13</a>
   <a href="http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13">http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13</a>
   <a href="http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13">http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13</a>
   <a href="http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13">http://ww1.nicrochip.com/downloads/en/AppNotes/Serial%20Bootloader%20AN13</a>
   <a href="http://www.nicrochip.com/downloads/en/AppNotes/Bootloader%20AN13">http://www.nicrochip.com/downloads/en/AppNotes/Bootloader%20AN13</a>
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   <a href="http://www.nicrochip.co
- SSH client for windows (Putty, WinSCP or equivalent)
- A serial cable connected between PC window and the serial line of the Azcom Kepler BBU
- An Ethernet cable connected between PC windows and the ETHO of
- The new binary file of the PIC application (picappl-bb-kepler\_XXX.hex)

After installing of the AN1310 software please follows the following steps:

- Connect to SOC via SSH
- At the linux prompt executes the following commands
  - o fpga -w 0x86 1
  - o sync
- SSH disconnect
- Start **Teraterm** application (or equivalent) and select the serial line connected to the board:
  - o press the key <**R>** to send this character to the PIC
  - o if the PC receives this character, the PICLED lights up in **RED color**: this means that PIC will reboot in 10 seconds
- Within 10 seconds, close the Teraterm and starts AN1310 v1.5r
- From this app:
  - Press <F3> key (= Break/Reset mode)
  - o Wait for the PIC rebooting: when the PICLED will light up WHITE
  - Press <F4> key (= Bootloader mode): it will be show the bootloader version of the PIC (=1.05)
  - Press <**F7**> key (= Erase Device): PIC will erase the application flash partition
  - Press <F6> key (= Write Device): the application will ask the filename of the new binary application picappl-bb-kepler\_XXX.hex
  - At the end of the transfer, press the <F2> key (= Run Mode) and wait the PICLED will light up YELLOW
  - o Close the AN1310 app.
- Turn off the board (PIC included)
- Start again the Teraterm application selecting the same serial line
- Turn on the board
- Press the PIC button (if it is not already pressed) and wait for the linux "login"
- At the prompt executes the command *picinfo* to verify the new version of the PIC.