

Part 1. Loading the data

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In [75]: import pandas as pd
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.linear_model import Perceptron
from sklearn.metrics import accuracy_score
import numpy as np
from sklearn.neural_network import MLPClassifier
```

```
In [76]: train_data = pd.read_csv('Task2B_train.csv') #Loading the training data
test_data = pd.read_csv('Task2B_test.csv') #Loading the testing data
```

```
In [77]: train_data
```

```
Out[77]:
```

	feature1	feature2	label
0	1.517571	0.424917	1
1	0.304268	0.999691	0
2	0.485924	-0.222913	1
3	-0.933579	-0.093579	0
4	0.684210	-0.436912	1
...
1995	0.295214	0.108314	1
1996	0.356255	-0.425519	1
1997	-0.997532	0.737404	0
1998	0.772409	-0.894220	1
1999	0.300576	0.052587	1

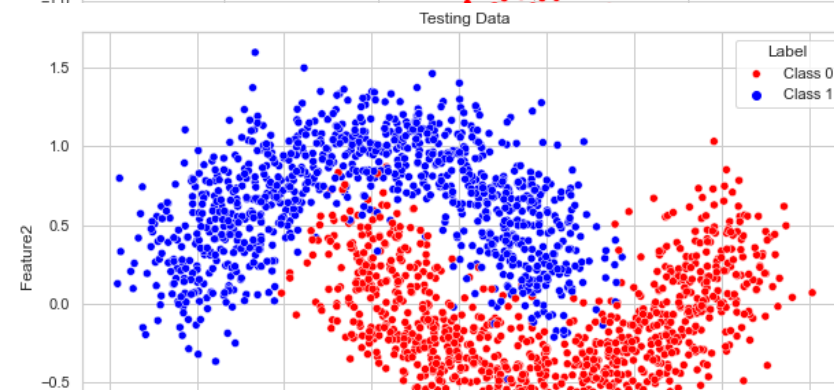
2000 rows × 3 columns

Plotting both the training and testing data in two different plots

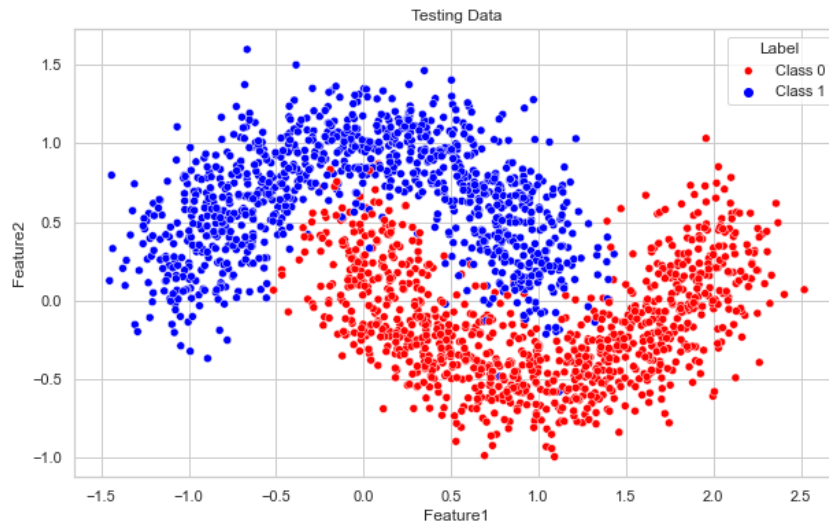
```
In [78]: sns.set(style="whitegrid") #plotting the training data using seaborn library
plt.figure(figsize=(10, 6))
sns.scatterplot(data=train_data, x='feature1', y='feature2', hue='label', palette=
plt.title('Training Data') #adding title and other labels and legend
plt.xlabel('Feature1')
plt.ylabel('Feature2')
plt.legend(title='Label', loc='upper right', labels=['Class 0', 'Class 1'])
plt.show()
```



```
In [79]: plt.figure(figsize=(10, 6)) #plotting the testing data using seaborn library
sns.scatterplot(data=test_data, x='feature1', y='feature2', hue='label', palette=
plt.title('Testing Data') #adding title and other labels and legend
plt.xlabel('Feature1')
plt.ylabel('Feature2')
plt.legend(title='Label', loc='upper right', labels=['Class 0', 'Class 1'])
plt.show()
```



```
In [79]: plt.figure(figsize=(10, 6)) #plotting the testing data using seaborn library
sns.scatterplot(data=test_data, x='feature1', y='feature2', hue='label', palette='102', palette=
plt.title('Testing Data') #adding title and color labels and legend
plt.xlabel('Feature1')
plt.ylabel('Feature2')
plt.legend(title='Label', loc='upper right', labels=['Class 0', 'Class 1'])
plt.show()
```



PART 2

```
In [80]: train_data['label'] = 2 * train_data['label'] - 1 #changing the Labels from
test_data['label'] = 2 * test_data['label'] - 1 #change the Labels from 0,
```

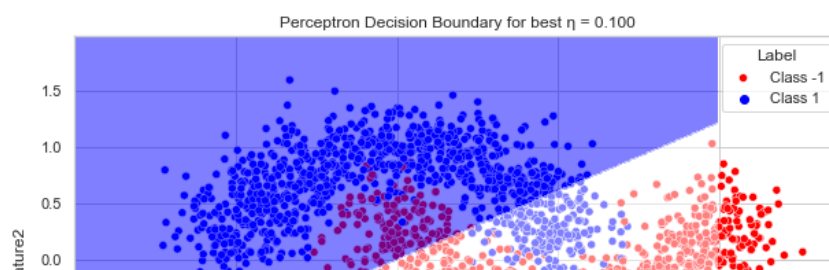
```
In [81]: X_train, y_train = train_data[['feature1', 'feature2']].to_numpy(), train_data
# Extracting the features and Labels for training data
X_test, y_test = test_data[['feature1', 'feature2']].to_numpy(), test_data['la
# Extracting the features and Labels for testing data
learning_rates = [0.1, 1.0] #Learning rates as given in the question
test_errors = []
for eta in learning_rates:
    perceptron = Perceptron(eta0=eta, max_iter=1000) #initializing the Percept
    perceptron.fit(X_train, y_train) #fitting the perceptron model on the tr
    y_pred = perceptron.predict(X_test) # Predicting the Labels on the testing
    test_error = 1 - accuracy_score(y_test, y_pred) # Calculating the test er
    test_errors.append(test_error) #storing the test errors in a List
best_eta = learning_rates[np.argmax(test_errors)] # Finding the best Learning
best_model = Perceptron(eta0=best_eta, max_iter=1000) #Finding the model with
best_model.fit(X_train, y_train) #Fitting the model with the best Learning ra
```

Out[81]: Perceptron(eta0=0.1)

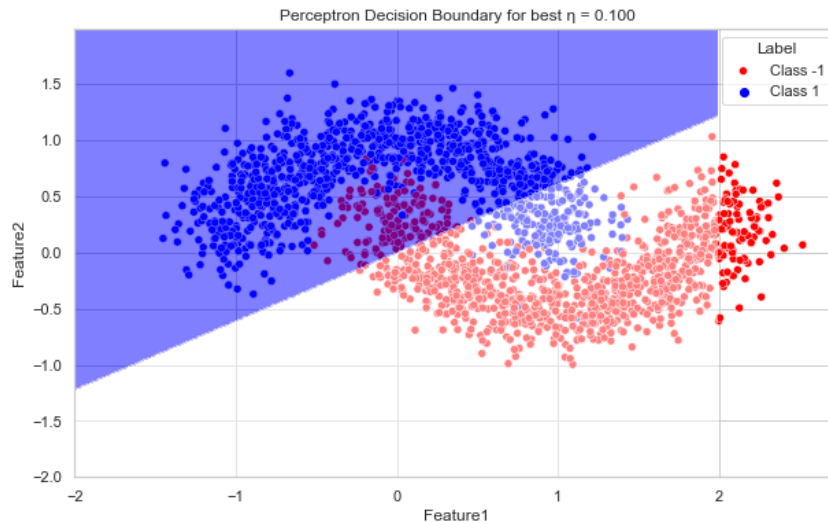
```
In [82]: ' The best  $\eta$  is = {:.3f}'.format(best_eta)
```

Out[82]: ' The best η is = 0.100'

```
In [83]: plt.figure(figsize=(10, 6)) #Defining the size of the plot for plotting the dec
sns.scatterplot(data=test_data, x='feature1', y='feature2', hue='label', palet
plt.title('Perceptron Decision Boundary for best  $\eta$  = {:.3f}'.format(best_eta))
plt.xlabel('Feature1')
plt.ylabel('Feature2')
xx, yy = np.meshgrid(np.arange(-2, 2, 0.01), np.arange(-2, 2, 0.01)) # Definin
Z = best_model.predict(np.c_[xx.ravel(), yy.ravel()]) #using the best model t
Z = Z.reshape(xx.shape)
plt.contourf(xx, yy, Z, levels=[-1, 0, 1], colors=['blue', 'white', 'red'], al
plt.legend(title='Label', loc='upper right', labels=['Class -1', 'Class 1']) #
plt.show()
```



```
In [83]: plt.figure(figsize=(10, 6)) #Defining the size of the plot for plotting the decision boundary
sns.scatterplot(data=test_data, x='feature1', y='feature2', hue='label', palette='1')
plt.title('Perceptron Decision Boundary for best  $\eta = {:.3f}$ '.format(best_eta))
plt.xlabel('Feature1')
plt.ylabel('Feature2')
xx, yy = np.meshgrid(np.arange(-2, 2, 0.01), np.arange(-2, 2, 0.01)) # Defining the grid
Z = best_model.predict(np.c_[xx.ravel(), yy.ravel()]) #using the best model to predict
Z = Z.reshape(xx.shape)
plt.contourf(xx, yy, Z, levels=[-1, 0, 1], colors=['blue', 'white', 'red'], alpha=0.5)
plt.legend(title='Label', loc='upper right', labels=['Class -1', 'Class 1']) #
plt.show()
```

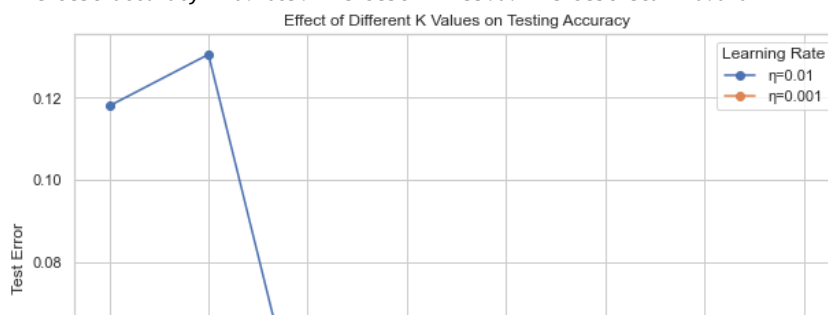


PART 3

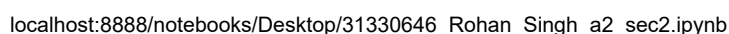
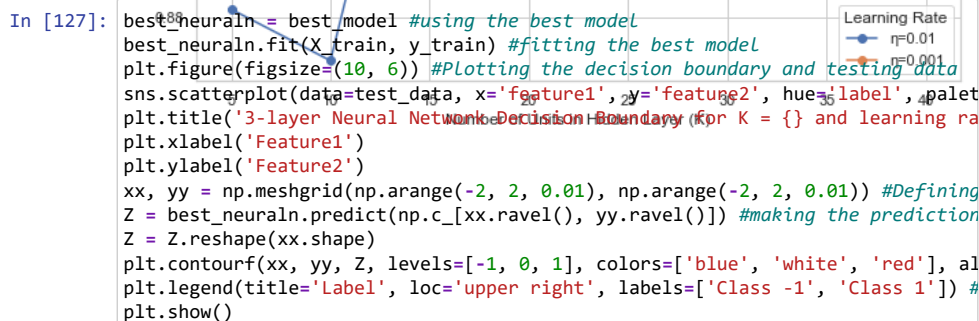
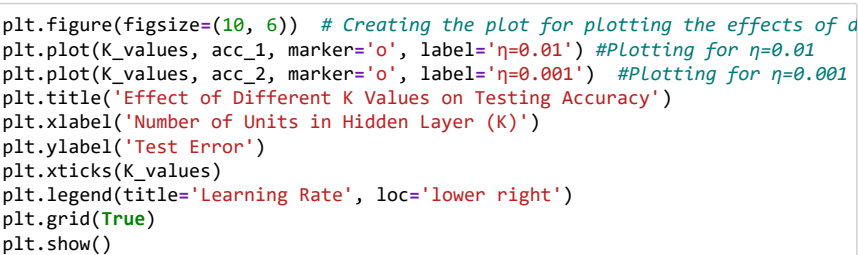
```
In [120]: K_values = range(5, 41, 5)
learning_rates = [0.01, 0.001]
test_errors_1 = []
test_errors_2 = []
acc_1 = []
acc_2 = []
best_accuracy = 0
best_K = 0
best_eta = 0
best_model = None
for K in K_values:
    for eta in learning_rates:
        neuraln = MLPClassifier(hidden_layer_sizes=(K,), learning_rate_init=eta)
        # Creating the 3-layered neural network
        neuraln.fit(X_train, y_train) #Fitting the 3-layered neural network
        y_pred = neuraln.predict(X_test) # Predicting on the testing data
        accuracy = accuracy_score(y_test, y_pred) # Calculating the accuracy
        test_error = 1 - accuracy # Calculating the testing error
        if eta == 0.01:
            test_errors_1.append(test_error) #Storing the test errors
            acc_1.append(accuracy)
        else:
            test_errors_2.append(test_error) #Storing the test errors
            acc_2.append(accuracy)
            if accuracy > best_accuracy: #Finding the K, eta and model with the best accuracy
                best_K = K
                best_eta = eta
                best_model = neuraln

In [123]: plt.figure(figsize=(10, 6)) # Creating the plot for plotting the effects of a
plt.plot(K_values, test_errors_1, marker='o', label='η=0.01') #Plotting for η=0.01
plt.plot(K_values, test_errors_2, marker='o', label='η=0.001') #Plotting for η=0.001
plt.title('Effect of Different K Values on Testing Accuracy')
plt.xlabel('Number of Units in Hidden Layer (K)')
plt.ylabel('Test Error')
plt.xticks(K_values)
plt.legend(title='Learning Rate', loc='upper right')

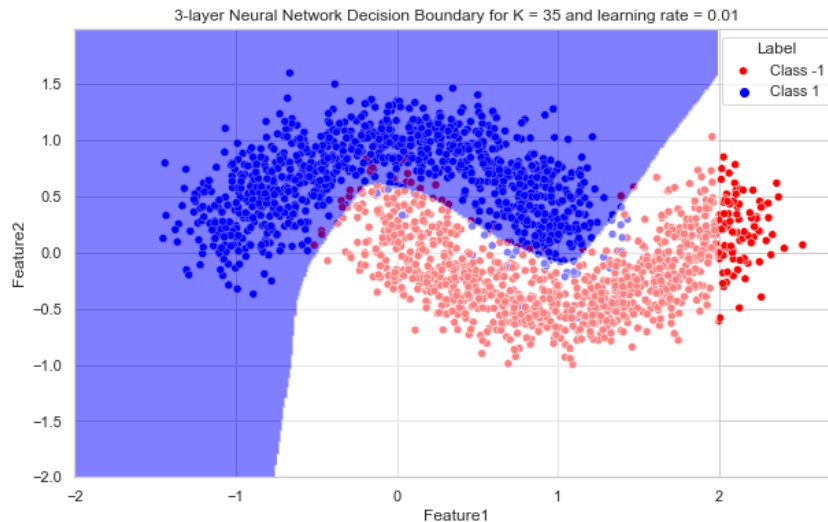
In [128]: print('The best accuracy = {:.4f}. The best K = {:.1f}. The best eta = {:.3f}'.format(
plt.show()
Out[128]: The best accuracy = 0.9685. The best K = 35.0. The best eta = 0.010'
```



```
Out[128]: 'The best accuracy = 0.9685. The best K = 35.0. The best eta = 0.010'
```



```
In [127]: best_neuraln = best_model #using the best model
best_neuraln.fit(X_train, y_train) #fitting the best model
plt.figure(figsize=(10, 6)) #Plotting the decision boundary and testing data
sns.scatterplot(data=test_data, x='feature1', y='feature2', hue='label', palette='vibrant')
plt.title('3-layer Neural Network Decision Boundary for K = {} and learning rate = {}'.format(K, lr))
plt.xlabel('Feature1')
plt.ylabel('Feature2')
xx, yy = np.meshgrid(np.arange(-2, 2, 0.01), np.arange(-2, 2, 0.01)) #Defining the grid
Z = best_neuraln.predict(np.c_[xx.ravel(), yy.ravel()]) #making the prediction
Z = Z.reshape(xx.shape)
plt.contourf(xx, yy, Z, levels=[-1, 0, 1], colors=['blue', 'white', 'red'], alpha=0.5)
plt.legend(title='Label', loc='upper right', labels=['Class -1', 'Class 1'])
plt.show()
```



PART 4

The difference between the perceptron and the 3-layer Neural Network can be explained by examining the plots and considering the model assumptions and characteristics of each approach.

1. Perceptron model: It can only create linear decision boundaries. This means it can separate data into two classes using straight lines only and so cannot create complex and nonlinear boundaries. This is because Perceptron's mathematical model is based on a linear combination of features and it makes predictions based on whether this combination is above or below a threshold. We can see this in the plot as the decision boundary is a straight line.
2. 3-layer Neural Network model: It can create complex and nonlinear boundaries. This is because it uses multiple layers which also includes one or more hidden layers and then uses nonlinear activation functions like ReLU between them. These nonlinear activation functions allow the network to model and capture intricate relationships within the data. So the decision boundary in the Neural Network plot is not a simple straight line and takes on more complex shapes as we can see in the plot and so captures nonlinear patterns in the data.

So as the Perceptron is a linear model while the 3-layer Neural Network is a nonlinear model it has the ability to capture complex patterns. This is why the Perceptron's decision boundary is a straight line and the Neural Network's decision boundary takes on a more precise shape.