

National Institute of Technology Calicut

Office of Dean (R & C)

Status Report : (OCTOBER (Month) - 2021 (Year))

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Name of the Guide(s) & Department(s)	Dr. SUDHEER A P – Mechanical Department Dr. K SEKAR – Mechanical Department
Title of the Project	Robot Based Automation for Vertical Farming
Summary of Work Done in the previous months (In bulleted points)	 Conceptual designs of Manipulator and Lift are completed Created a virtual environment for simulation of Manipulator Implemented a deep learning model for vegetable detection. Optimized the manipulator model and mechanism for lift. Created CAD designs of end effectors for gripper and harvesting.
Work Done in this month (in bulleted points) (Please specify what part of objective(s) or outcome you are currently working)	 Performed static force analysis on the developed cad model for grippers. Performed simulation of the mobile base in the virtual environment. Improved the object detection algorithm with new datasets. Currently working on the optimization of end effector design for harvesting and collection of new datasets.

Whether the goals are achieved or not as per the plan (If No, specify the reason)	No Currently working on the new designs of end effector for harvesting. We started working on simulation, creating virtual environment and development of AI algorithms.
Signature of Project Members with Date	Foith 5/12/21 A. Sai Manor K. Vedantham 5/12/21
Signature of Guide(s) with Date	Dr.Sudheer.A.P