



National Institute of Technology Calicut

Office of Dean (R & C)

Funding Scheme for UG/PG Students to Carry Out Innovative Projects Application Format - 2021

1	Name of the applicants	Roll No	Branch of study	Mobile Number & email id
	<ul style="list-style-type: none"> Maximum 4 students for B. Tech/B. Arch students Individual projects for PG students 			
	POOLA ROHITH	B180712ME	MECHANICAL	9441120187 rohith18p@gmail.com
	AKONDI SAI MANOJ	B180161ME	MECHANICAL	6303364524 manojakondi25@gmail.com
	MAMIDI THEJONATH	B180129ME	MECHANICAL	9441214164 tejonathg21@gmail.com
	KURAGANTI VEDANTHAM	B180473ME	MECHANICAL	9381222285 vedantham_b180473me@nitc.ac.in
2	Name of the project leader (one of the students shall be the project leader)	POOLA ROHITH		
	Mobile Number & email id	9441120187 rohith18p@gmail.com		
	Name of FA/PC	Dr. Ashesh Saha		
3	Title of the project proposal	Robot Based Automation for Vertical Farming		

4	Expected outcome of the project-point wise (details shall be given in attached proposal)	<ul style="list-style-type: none"> Fully automated robotic system for vertical farming. Automation of planting, watering, inspection, conditioning and harvesting of crops. Patents for the innovation or publishing of SCI Journal. 	
5	Deliverables - research paper in SCI journal or patent/copyright of novel idea to be filed or a novel product to be commercialized or technology transfer	Patents / Research paper in SCI journal	
6	Total fund requested (Rs)	100000	
7	Name of guide(s)	Students from different depts. or doing interdisciplinary projects can provide guides from appropriate discipline.	
	Name of guide(s)/co-guide	Dept.	Mobile No & email id
	Dr. A P Sudheer	Mechanical	9961450987 apsudheer@nitc.ac.in
	Dr. K Sekar	Mechanical	9746562695 sekar@nitc.ac.in
8	Significance of the proposed project (details shall be given in attached proposal)	Implementation of vertical farming and Hydroponics which are the future of agriculture. Automating the Vertical farming by robot-based system and artificial intelligence has wide impact and greater advantages and flexibilities than the conventional farming.	

9	Expected time required for completion of project (attach semester wise targets)	10 months (until 31-MAR-2022)	<p>SEVENTH SEMESTER</p> <ul style="list-style-type: none"> Finalizing the project details and idea. Complete design and development of CAD model. Simulation and analysis <p>EIGHTH SEMESTER</p> <ul style="list-style-type: none"> Prototype fabrication and assembly. Complete control and automation.
10	<u>Split-up of Budget in Rs</u> Software packages Minor equipment * Consumables Contingencies Others if any Mechanical Components Electronic components Total	Stage 1 (first six months) - - - - - - -	Stage 2 (remaining period) - - 17000 20000 10000 53000 100000

(Give details of all the students sequentially in the case of a group. For a group with students from different departments, recommendation from the concerned head of department of all students shall be obtained)

- Name & Signature of the applicant(s):

1. POOLA ROHITH

P. Rohith.

2. AKONDI SAI MANOJ

A Sai Manoj

3. MAMIDI TEJONATH

M. T. J.

4. KURAGANTI VEDANTHAM

K. Vedantham

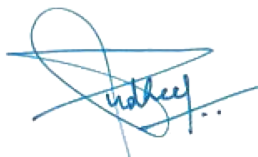
- Name & Signature of project guide(s): I/we have gone through the proposal and guidelines.

GUIDE:

Dr. SUDHEER A. P.

Assistant Professor

Mechanical department



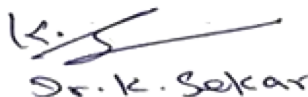
27/05/2021

CO-GUIDE:

Dr. K Sekar

Assistant Professor

Mechanical department



- Recommendation from the Head of the Department:

Dr. JOSE MATHEW

Professor (HAG)

Mechanical Department

Notes:

(1) A detailed proposal must be attached along with this application giving the objectives, significance of the work, expected outcomes, literature review (including patent search), methodology and work plan, budget with justifications and any other relevant information in support of the proposal

(2) The aim of this funding scheme is to promote research culture in UG students and accordingly through the research, they shall develop an innovative product. This can also lead to commercialization and start-up or patenting the novelty. Minimum an SCI journal publication shall come from the project. The financial assistance will be provided to carry out the related activities (to meet the expenses related to fabrication/assembly charges, consumables and contingency). * minor equipment /tools may be permitted, if very specific and essential. No major equipment is permitted under this scheme.

PROJECT PROPOSAL

TITLE: ROBOT BASED AUTOMATION FOR VERTICAL FARMING

Proposed by

Poola Rohith	B180712ME
Akondi Sai Manoj	B180161ME
Mamidi Thejonath	B180129ME
Kuraganti Vedantham	B180473ME

Guide

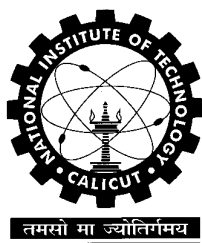
Dr. A P Sudheer
Assistant Professor
Mechanical Department

Co-Guide

Dr. K Sekar
Assistant Professor
Mechanical Department

Head of the department

Dr. Jose Mathew
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1. INTRODUCTION

The world population is growing at an alarming rate. According to the world census, the world population will rise from 7.3 billion today to 9.3 billion by 2050. Farmers will face serious pressure to keep up with demand. To this problem of ever-growing population, vertical farming emerged as a powerful solution. In implementing and maintaining the vertical farms there is a huge requirement of labour and skilled workers in some domains which will be hard for investing as well as maintaining such huge workers and work flow. Solution for this problem is automation of the vertical farms with robots which is the prior idea of our project. This minimizes the labour to a great extent, increases accuracy and precision of tasks to be performed while farming, also increases productivity as robots can work the entire time. We further innovate this idea by including Hydroponics to the vertical farming. Hydroponics is an alternative and best replacement to the soil in agriculture.

2. SIGNIFICANCE & MOTIVATION

Vertical farming is the practice of growing crops in vertically stacked layers. Usually vertical farming involves a growing crop in a controlled environment which aims to optimize the plant growth and soilless farming techniques such as hydroponics, aquaponics and aeroponics. As of 2020, there is the equivalent of 30ha (74 acres) of operational vertical farming in the world. Current applications of vertical farming coupled with other state-of-the-art technologies, such as specialized LED lights, have resulted in over 10 times the crop yield than would receive through traditional farming methods.



The idea of using Hydroponics instead of soil is a major breakthrough in the field of agriculture. In traditional farming there are lot of disadvantages such as losing the fertility and nutrient content in the soil, water wastage, uncontrollable environment conditions etc. Recent statistics have proved that 67% of water used in agriculture is going waste through evaporation and run outs which will be a major concern for water scarcity in future. But Hydroponics use 90% less water for farming and which is 10 times lesser than water used in traditional agriculture.



This project proposal aims to build a fully automated vertical domestic farm utilizing state of the art technologies like AI, Robotics, deep learning and computer vision. This project theme is to develop a small-scale device that is embedded with an autonomous robotic system such that it can yield fresh vegetables sufficient for a family with 4-5 members. The same model can be scaled up and implemented for large scale production of vegetables in large restaurants, green houses, etc.

3. OBJECTIVES

The objective of this project is to develop a robot-based automation system for vertical farming, which includes:

- Development of Autonomous 3 DOF serial robotic manipulator.
- Integration of a mobile platform and the manipulator for the vertical motion.
- Automation of vertical farming at domestic level for minimizing human intervention in farming and reducing the utilization of water.
- To minimize the requirement of pesticides and opt for Soilless agriculture
- To get a tight hold over the parametric conditions of crop environment such as humidity, temperature, air ventilation etc.

4. LITERATURE REVIEW

The main purpose of the project is to automate vertical farming by implementing hydroponics. A preliminary literature review shows that many recent studies and innovations are primarily focused on vertical farming implementation, hydroponics usage and their individual automation.

There have been many innovative works in the same area, which includes, ‘System for indoor plant cultivation’ where a cabinet is designed for farming which can maintain all the growth conditions of the plant, but the farming part is not automated in this system [1]. This project partially includes the above-mentioned idea of inspecting and maintaining the growth of plants in an indoor environment.

‘Domestic Autonomous Vertical Farm that is movable in stackable units’, [2] This patented project focused on developing portable equipment for an

autonomous vertical farm which can be easily installed. The automation includes only the environment conditioning part like lighting, humidity etc., but it doesn't completely automate the farming such as planting and harvesting of the crops.

'Indoor Hydroponics systems', [3] This innovation includes the idea of vertical farming and hydroponics. The project is to develop a closed cabinet which controls and monitors the growth of the plants, environment conditions and nurtured by hydroponics. It can be closely related to the similar work [4], Hydroponic Plant grow Cabinet. All the recent works on automation of vertical farming focused on automating the growth monitoring and conditioning.

The recent studies evident that vertical farming will be the future of agriculture. The research work [5] has mentioned the feasibility and main advantages of vertical farming over conventional agriculture which is one of the key motivations for our innovation. Our idea includes using the suitable features of the existing innovations and further innovating to implement the complete automation of vertical farming.

5. METHODOLOGY

5.1. ENVIRONMENT & SET UP

The idea of Vertical farming using Hydroponics is implemented in a closed environment. The prototype consists of multiple layers of plants which are stacked one above the other. The whole setup will be contained in a closed box like cabinet with the inputs of electricity and little amount of water. The required conditions of the farming can be completely controlled in a closed environment by using respective sensors. The humidity in the closed environment can be monitored and controlled. As

the farming is being implemented in indoor space the lighting required for the photosynthesis can also be maintained with the help of LED grow lights as an alternative to the sunlight. The setup also includes cameras for monitoring the plants, navigation of robot, etc.

5.2. HYDROPONICS AND CONTROL

Hydroponics is a type of horticulture and a subset of hydroculture which involves growing plants without soil, by using mineral nutrient solutions in an aqueous solvent. Hydroponics offers many advantages, notable decrease in water usage in agriculture.



The nutrient rich water is pumped into the stacks using external water supply through the inlet port of the prototype cabinet. The nutrient level in the water is frequently monitored and supplied in case of any deficiencies. An outlet port is also provided with the connection from every stack through which the nutrient less water can be collected and reused.

5.3. ROBOTIC MANIPULATION

The idea is to implement a 3 DOF manipulator along with a mobile base which can navigate inside the box along the rows in each stack. The manipulator is designed with an end effector which is capable of planting

as well as harvesting. There will be a small platform at one of the corners of the cabinet which performs the function of a lift for carrying the robot to any of the stacked layers. The prototype also consists of a provision for collection of the harvested products.

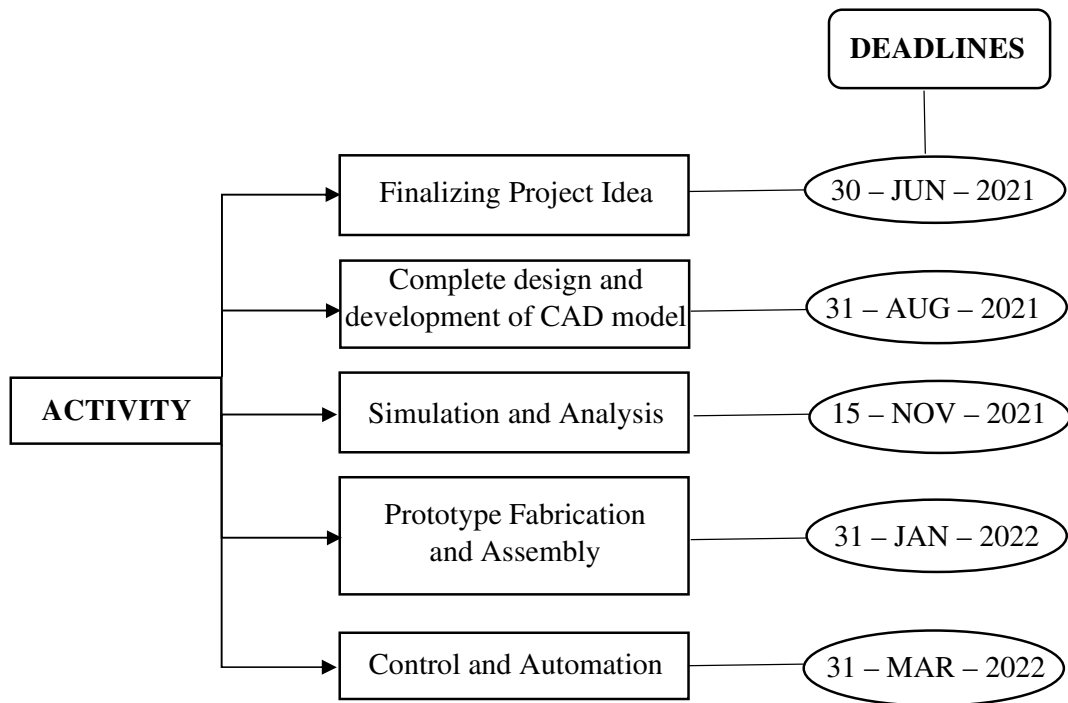
5.4. IMPLEMENTATION OF ARTIFICIAL INTELLIGENCE

The state-of-the-art AI algorithms can help in recognizing the ripen products and can guide the robot to perform the harvesting task. It can also help in detecting the plant's health. Since we are going to equip the whole system with cameras, an enormous amount of data can also be collected to perform self-supervised learning. This data can also be utilized for training machine learning models which could predict the parameters like spectra of light, photoperiod (day/night cycles), intensity of light, irrigation schedules, nutrients, airflow, temperature, humidity, and CO₂.

6. EXPECTED OUTCOMES

- Prior aim is to implement vertical farming and hydroponics which are water and space efficient compared to traditional agricultural methods.
- Fully automated pipeline which involves minimum/no human intervention. The automation includes planting, watering, inspection and harvesting.
- The prototype developed can be easily accommodated in houses and an Eco-friendly appliance
- Absolutely certain towards yielding as every factor will be controlled as per the requirement.
- Applying patents for the innovation or publishing Journal paper.

7. WORK PLAN:



8. BUDGET:

SL.NO	COMPONENT	QUANTITY	ESTIMATED COST (INR)
1.	G.I. pipes	20m	3000
2.	Aluminum extrusions	5m	5000
3.	Wood floor	3 sq.m	1000
4.	PVC parts	-	1000
5.	Couplings, leadscrews, etc.	-	2000
6.	Hydroponics	-	10000
7.	Motors	8	24000
8.	Motor drivers	8	10000
9.	PCB	2	4000
10.	Camera	3	5000
11.	Jetson nano	1	10000
12.	Other consumables	-	5000
13.	Contingency	-	20000
		TOTAL	100000

9. REFERENCES

- [1] Lepp.M.T., Pedastsaar.P.E., 2016. *System for indoor plant application*. US2016/0316646 A1.
- [2] Loo.C.E., Zhang.T., Yau.C., 2018. *Domestic Autonomous Vertical farm that is moveable in stackable units*. WO 2018/131016 A2.
- [3] Argento.O., Elmhurst.E., 2016. *Indoor Hydroponic System*. US2016/0212954 A1
- [4] Chakwan Lu.G.F., Kapp.L., 2017. *Hydroponic Plant Grow Cabinet*. US 10,499,574B2
- [5] Rameshkumar.D., Jagathjothi.N., Easwari.S., Rajesh.R., Muthuselvi.R., P. Naveen Kumar.P., Krishnakumare.B., Minithra.R., Suresh.R.,2020. *Vertical Farming-Future of Agriculture*. *Indian Farmer*. 7(11), 1013-1017.
- [6] Rangelov.V., Staykova.D., 2020. *Vertical Farms*. World Science. 7(59).