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1. Write the python program to solve 8-Puzzle problem.
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Program:
import copy
from heapq import heappush, heappop
n = 3
row = [1, 0, -1, 0]
col = [0, -1, 0, 1]
class priorityQueue:
       def __init__(self):
               self.heap = []
       def push(self, k):
               heappush(self.heap, k)
       def pop(self):
               return heappop(self.heap)
       def empty(self):
               if not self.heap:
                      return True
               else:
                      return False
class node:
       def __init__(self, parent, mat, empty_tile_pos,
                              cost, level):
               self.parent = parent
               self.mat = mat
               self.empty_tile_pos = empty_tile_pos
               self.cost = cost
               self.level = level
```

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def __lt__(self, nxt):
              return self.cost < nxt.cost
def calculateCost(mat, final) -> int:
       count = 0
       for i in range(n):
              for j in range(n):
                      if ((mat[i][j]) and
                             (mat[i][j] != final[i][j])):
                             count += 1
       return count
def newNode(mat, empty_tile_pos, new_empty_tile_pos,
                      level, parent, final) -> node:
                                                KNURF
       new_mat = copy.deepcopy(mat)
       x1 = empty\_tile\_pos[0]
       y1 = empty_tile_pos[1]
       x2 = new_empty_tile_pos[0]
       y2 = new empty tile pos[1]
       new_mat[x1][y1], new_mat[x2][y2] = new_mat[x2][y2], new_mat[x1][y1]
       cost = calculateCost(new_mat, final)
       new_node = node(parent, new_mat, new_empty_tile_pos,
                                     cost, level)
       return new_node
def printMatrix(mat):
       for i in range(n):
              for j in range(n):
                      print("%d " % (mat[i][j]), end = " ")
              print()
def isSafe(x, y):
       return x \ge 0 and x < n and y \ge 0 and y < n
```

```
def printPath(root):
       if root == None:
               return
       printPath(root.parent)
       printMatrix(root.mat)
       print()
def solve(initial, empty tile pos, final):
       pq = priorityQueue()
       cost = calculateCost(initial, final)
       root = node(None, initial,
                              empty_tile_pos, cost, 0)
       pq.push(root)
       while not pq.empty():
               minimum = pq.pop()
               if minimum.cost == 0:
                      printPath(minimum)
                      return
               for i in range(4):
                      new_tile_pos = [
                              minimum.empty_tile_pos[0] + row[i],
                              minimum.empty_tile_pos[1] + col[i], ]
                      if isSafe(new_tile_pos[0], new_tile_pos[1]):
                              child = newNode(minimum.mat,
                                                            minimum.empty_tile_pos,
                                                            new tile pos,
                                                            minimum.level + 1,
                                                            minimum, final,)
                              pq.push(child)
initial = [[1, 2, 3],
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[5, 6, 0],

[7, 8, 4]]

final = [[1, 2, 3],

[5, 8, 6],

[0, 7, 4]]

empty_tile_pos = [1, 2]

solve(initial, empty_tile_pos, final)
```

OUTPUT:

```
IDLE Shell 3.10.4
                                                                     File Edit Shell Debug Options Window Help
   Python 3.10.4 (tags/v3.10.4:9d38120, Mar 23 2022, 23:13:41) [MSC v.1929 64 bit (
   AMD64)] on win32
   Type "help", "copyright", "credits" or "license()" for more information.
   === RESTART: C:/Users/Rohith kumar/OneDrive/Desktop/AI LAB/decision tree 1.py ==
   ========= RESTART: C:\Users\Rohith
   kumar\OneDrive\Desktop\AI LAB\8-Puzzle problem.py ==============================
   5 6 0
   7 8 4
   1 2 3
   5 0 6
   5 8 6
     7 4
>>>
```