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10. Write the python program to implement A* algorithm.
Program:
class Node():
  """A node class for A* Pathfinding"""
  def init (self, parent=None, position=None):
     self.parent = parent
    self.position = position
    self.g = 0
    self.h = 0
    self.f = 0
  def eq (self, other):
     return self.position == other.position
def astar(maze, start, end):
  """Returns a list of tuples as a path from the given start to the given end in the given maze"""
  start node = Node(None, start)
  start node.g = start node.h = start node.f = 0
  end_node = Node(None, end)
  end node.g = end node.h = end node.f = 0
  open_list = []
  closed_list = []
  open_list.append(start_node)
  while len(open_list) > 0:
    current_node = open_list[0]
     current index = 0
    for index, item in enumerate(open_list):
       if item.f < current_node.f:
          current_node = item
          current_index = index
     open_list.pop(current_index)
     closed_list.append(current_node)
    if current_node == end_node:
       path = []
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current = current node
       while current is not None:
          path.append(current.position)
          current = current.parent
       return path[::-1]
     children = []
     for new_position in [(0, -1), (0, 1), (-1, 0), (1, 0), (-1, -1), (-1, 1), (1, -1), (1, 1)]: # Adjacent
squares
       node_position = (current_node.position[0] + new_position[0], current_node.position[1] +
new position[1])
       if node position[0] > (len(maze) - 1) or node position[0] < 0 or node position[1] >
(len(maze[len(maze)-1]) -1) or node_position[1] < 0:
          continue
       if maze[node_position[0]][node_position[1]] != 0:
          continue
       new_node = Node(current_node, node_position)
       children.append(new node)
     for child in children:
       for closed child in closed list:
          if child == closed_child:
             continue
       child.g = current node.g + 1
       child.h = ((child.position[0] - end_node.position[0]) ** 2) + ((child.position[1] -
end_node.position[1]) ** 2)
       child.f = child.g + child.h
       for open_node in open_list:
          if child == open node and child.g > open node.g:
             continue
       open list.append(child)
def main():
```

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maze = [[0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
       [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
       [0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
  start = (0, 0)
  end = (7, 6)
  path = astar(maze, start, end)
  print(path)
if __name__ == '__main__':
  main()
OUTPUT:
lDLE Shell 3.10.4
                                                                                       X
ile Edit Shell Debug Options Window Help
   Python 3.10.4 (tags/v3.10.4:9d38120, Mar 23 2022, 23:13:41) [MSC v.1929 64 bit (
   AMD64)] on win32
   Type "help", "copyright", "credits" or "license()" for more information.
>>
   == RESTART: C:/Users/Rohith kumar/OneDrive/Desktop/AI LAB/A star algorithm.py ==
   [(0, 0), (1, 1), (2, 2), (3, 3), (4, 3), (5, 4), (6, 5), (7, 6)]
>>
```