```
// 23. Implementation of Shortest Path Algorithms using Dijkstra's Algorithm
#include <stdio.h>
#define INFINITY 9999
#define MAX 10
void Dijkstra(int Graph[MAX][MAX], int n, int start);
void Dijkstra(int Graph[MAX][MAX], int n, int start) {
 int cost[MAX][MAX], distance[MAX], pred[MAX];
 int visited[MAX], count, mindistance, nextnode, i, j;
 for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
    if (Graph[i][i] == 0)
     cost[i][j] = INFINITY;
    else
     cost[i][j] = Graph[i][j];
 for (i = 0; i < n; i++) {
  distance[i] = cost[start][i];
  pred[i] = start;
  visited[i] = 0;
 }
 distance[start] = 0;
 visited[start] = 1;
 count = 1;
 while (count < n - 1) {
  mindistance = INFINITY;
  for (i = 0; i < n; i++)
    if (distance[i] < mindistance && !visited[i]) {
     mindistance = distance[i];
     nextnode = i;
    }
  visited[nextnode] = 1;
  for (i = 0; i < n; i++)
    if (!visited[i])
     if (mindistance + cost[nextnode][i] < distance[i]) {</pre>
      distance[i] = mindistance + cost[nextnode][i];
      pred[i] = nextnode;
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}
  count++;
 }
 for (i = 0; i < n; i++)
  if (i != start) {
    printf("\nDistance from source to %d: %d", i, distance[i]);
  }
}
int main() {
 int Graph[MAX][MAX], i, j, n, u;
 n = 7;
 Graph[0][0] = 0;
 Graph[0][1] = 0;
 Graph[0][2] = 1;
 Graph[0][3] = 2;
 Graph[0][4] = 0;
 Graph[0][5] = 0;
 Graph[0][6] = 0;
 Graph[1][0] = 0;
 Graph[1][1] = 0;
 Graph[1][2] = 2;
 Graph[1][3] = 0;
 Graph[1][4] = 0;
 Graph[1][5] = 3;
 Graph[1][6] = 0;
 Graph[2][0] = 1;
 Graph[2][1] = 2;
 Graph[2][2] = 0;
 Graph[2][3] = 1;
 Graph[2][4] = 3;
 Graph[2][5] = 0;
 Graph[2][6] = 0;
 Graph[3][0] = 2;
 Graph[3][1] = 0;
 Graph[3][2] = 1;
 Graph[3][3] = 0;
 Graph[3][4] = 0;
 Graph[3][5] = 0;
```

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Graph[3][6] = 1;
 Graph[4][0] = 0;
 Graph[4][1] = 0;
 Graph[4][2] = 3;
 Graph[4][3] = 0;
 Graph[4][4] = 0;
 Graph[4][5] = 2;
 Graph[4][6] = 0;
 Graph[5][0] = 0;
 Graph[5][1] = 3;
 Graph[5][2] = 0;
 Graph[5][3] = 0;
 Graph[5][4] = 2;
 Graph[5][5] = 0;
 Graph[5][6] = 1;
 Graph[6][0] = 0;
 Graph[6][1] = 0;
 Graph[6][2] = 0;
 Graph[6][3] = 1;
 Graph[6][4] = 0;
 Graph[6][5] = 1;
 Graph[6][6] = 0;
 u = 0;
 Dijkstra(Graph, n, u);
 return 0;
}
```

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D:\data structures lab\dijkstras algorithm.c - [Executing] - Dev-C++ 5.11
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                                    // 23. Implementation of Shortest Path Algorithms using Dijkstra's Algorithm #include <stdio.h>
                                    #define INFINITY 9999
#define MAX 10
                                    void Dijkstra(int Graph[MAX][MAX], int n, int start);
                                % void Dijkstra(int Graph[MAX][MAX], int n, int start) {
9    int cost[MAX][MAX], distance[MAX], pred[MAX];
10    int visited[MAX], count, mindistance, nextnode, i, j;
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                                       for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
    if (Graph[i][j] == 0)
        cost[i][j] = INFINITY;</pre>
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                                       while (count < n - 1) {
  mindistance = INFINITY;</pre>
                                           for (i = 0; i < n; i++)
if (distance[i] < mindistance && !visited[i]) {
  mindistance = distance[i];
  nextnode = i;
}</pre>
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 Project Classes Debug binary search 1.c merge sort.c merge sort.c quick sort.c heap sort.c alv tree.c breadth first search.c depth first search.c dijkstras algorithm.c
                              visited[nextnode] = 1;
for (i = 0; i < n; i++)
if (!visited[i])
if (mindistance + cost[nextnode][i] < distance[i]) {
    distance[i] = mindistance + cost[nextnode][i];
    pred[i] = nextnode;
}</pre>
                                        for (i = 0; i < n; i++)
   if (i != start) {
      | printf("\nDistance from source to %d: %d", i, distance[i]);
   }
}</pre>
                               52
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                               55 ☐ int main() {
                                        int Graph[MAX][MAX], i, j, n, u;
n = 7;
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                                        Graph[0][0] = 0;
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Graph[0][4] = 0;
Graph[0][5] = 0;
Graph[0][6] = 0;
                                        Graph[1][0] = 0;
Graph[1][1] = 0;
Graph[1][2] = 2;
Graph[1][3] = 0;
Graph[1][4] = 0;
Graph[1][5] = 3;
Graph[1][6] = 0;
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