CMP329/IFT303: Data Structures and Algorithms Analysis (3 units)

Lecture 1: Introduction

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Course Outline

- ▶ Introduction and review
- ▶ Introduction to Arrays, Lists, stacks, and queues, Trees, Graphs
- ► Algorithm Efficiency Analysis Framework
- Algorithm design Techniques
- Sorting and Searching algorithms
- ▶ Tree Algorithm
- Graph Algorithms

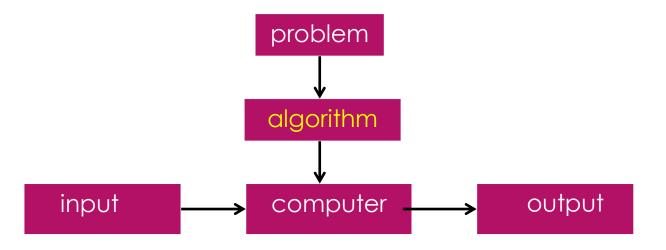
M. Yusuf 4/14/2020

Outline

- What is an Algorithm?
 - ▶ Properties of Algorithms
- Algorithm design and analysis process.
 - ► How to Understand program development problem
 - ► Algorithm Design Techniques
 - **...**
- ► Important Problem Types
- Fundamental Data Structure

What is an Algorithm?

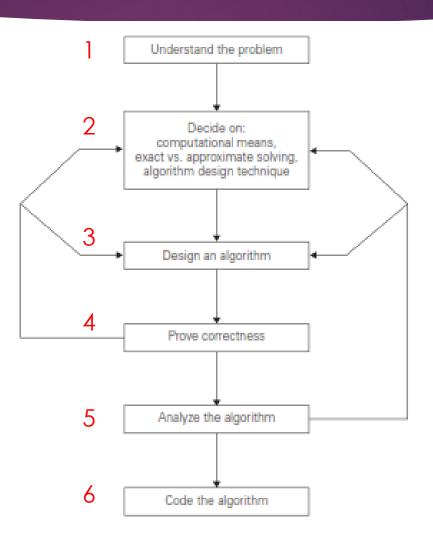
A sequence of **unambiguous** instruction for solving a problem that is, for obtaining a required **output** for any legitimate **input** in a **finite** amount of time.



Properties of Algorithms

- Finiteness: terminates after a finite number of steps.
- ▶ **Definiteness:** each step must be rigorously and unambiguously specified, e.g., "stir until lumpy"
- ▶ Input: valid inputs must be clearly specified
- Output: data that result upon completion of the algorithm must be specified
- ▶ Effectiveness: steps must be simple and basic, e.g., check if m is prime

Algorithm Design and Analysis Process.



Algorithm Design and Analysis Process. Con't

- 1. Understanding the Problem
 - Ask questions, do a few small examples by hand, think about special cases, etc.
 - ▶ An input is an instance of the problem the algorithm solves
 - Specify exactly the set of instances the algorithm needs to handle
- 2.1 Decide on Exact vs. approximate solution
 - ► Approximate solution cannot solve exactly, e.g., extracting square roots, solving definite integrals, etc.
 - Algorithms for exact solution can be unacceptably slow

Algorithm Design and Analysis Process. Con't

2.2 Algorithm Design Techniques

- ▶ is a general approach to solving problems algorithmically that is applicable to a variety of problems from different areas of computing such as.
- ▶ Brute force (Chapter 3)
- Decrease and Conquer (Chapter 4)
- ▶ Divide and Conquer (Chapter 5)
- ▶ Transform and Conquer (Chapter 6)
- Space and time tradeoffs (Chapter 7)
- Dynamic Programming (Chapter 8)

Algorithm Design and Analysis Process. Con't

- 3. Algorithm Design and Data Structure
 - ► Programs = Algorithms + Data Structures
 - ▶ Data structures: List, Array, Dictionary, Set, Queue, Stack, etc.
- 4. Prove correctness of the algorithm
 - ▶ Algorithm yields required output for every legitimate input in finite time
 - ▶ Technique for proving correctness of;
 - ► Exact algorithm Mathematical induction can be used due to natural sequence of steps in an algorithm
 - ► Approximate algorithm show that the error produced by the algorithm does not exceed a predefined limit

Algorithm Design and Analysis Process. Con't

5. Analyzing an Algorithm

- ▶ Time efficiency: how fast it runs
- ▶ **Space efficiency:** How much extra memory it uses
- ▶ **Simplicity:** easier to understand, usually contains fewer bugs, sometimes simpler is more efficient, but not always!
- ▶ **Generality:** of the problem algorithm solves or the set of inputs it accepts

6. Coding Algorithm Write in a programming language for a real machine

- Standard tricks:
 - ► Compute loop invariant (which does not change value in the loop) outside loop
 - ▶ Replace expensive operation by cheap ones
 - ▶ E.g., check if n is even n%2 == 0 is more expensive than (n & 1) == 0
- Algorithm's optimality. Actually, this question is not about the efficiency of an algorithm but about the complexity of the problem it solves: min effort exert to solve a problem.
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Important Problem Types

- Sorting
- Searching
- String Processing
- ▶ Graph Problem
- Combinatorial Problem
- ► Geometric Problem
- ► Numerical Problem

Sorting

- ► The sorting problem is to rearrange the items of a given list in nondecreasing order.
- Properties of sorting Algorithms
 - ▶ An algorithm is said to be **stable** if it preserves the **relative order** of any **two equal elements** in its input
 - ▶ An algorithm is said to be **in-place** if it does not require **extra memory**, except, for a few memory units
- ▶ Statement of problem: rearrange the number is a given order
 - ▶ Input: a sequence of N numbers $\langle a_1, a_2, ..., a_N \rangle$
 - ▶ Output: a reordering of the input sequence $<a'_1, a'_2, ..., a'_N>$ so that $a'_i \le a'_j$ whenever i < j
 - ▶ Instance: the sequence <5, 3, 2, 8, 3> becomes <2, 3, 3, 5, 8> after sorting
- ► Algorithm: Bubble sort, Selection sort, Insertion sort, Merge sort, Quick sort

Searching

- ► The searching problem deals with finding a given value, called a search key, in a given set.
- > Statement of problem: search a key number is a given set
 - ▶ Input: a sequence of N numbers $\langle a_1, a_2, ..., a_N \rangle$ search key $\langle k \rangle$
 - ▶ Output: the key <k> from the input sequence <a'₁, a'₂, ..., a'_N>
 - ▶ Instance: the sequence <5, 3, 2, 8, 3> search for 2 becomes return 2 or null if 2 doesn't exist
- ► Algorithm: sequential search, binary Search

String Processing

- ▶ A **string** is a sequence of characters from an alphabet.
- String matching. Is a particular problem of searching for a given word in a text.
- ▶ Text strings: letters, numbers, and special characters
- ▶ Bit strings: sequence of 0's and 1's
- ► Gene sequence: string of characters from four-character alphabet {A, C, G, T} for Adenine, Cytosine, Guanine, and Thymine, constituents of DNA
- ▶ String matching: search for a given word/pattern in a text or gene sequence

Graph Problem

- ▶ A graph can be thought of as a collection of points called **vertices**, some of which are connected by line segments called **edges**.
- ► The traveling salesman problem (TSP) is the problem of finding the shortest tour through n cities that visits every city exactly once. Shortest-path
 - Circuit board and VLSI chip fabrication, X-ray crystallography,
- ▶ The **graph-coloring problem** seeks to assign the smallest number of colors to the vertices of a graph so that no two adjacent vertices are the same color.
 - event scheduling
- ► Graph traversal (how to reach all points in a network?)
- ▶ Topological sorting (is a set of courses with prerequisites consistent?)

Combinatorial Problem

- These are problems that ask, explicitly or implicitly, to find a combinatorial object such as
 - a permutation,
 - ▶ a combination,
 - ▶ or a subset—

that satisfies certain constraints.

- ▶ Generally speaking, combinatorial problems are the most difficult problems in computing, from both a theoretical and practical standpoint.
 - the traveling salesman problem
 - graph-coloring problem

Geometric Problem

- ▶ **GP** Deal with geometric objects such as points, lines, and polygons.
- ▶ The ancient Greeks were very much interested in developing procedures for solving a variety of geometric problems,
 - ▶ Including problems of constructing simple geometric shapes triangles, circles, and so on with an unmarked ruler and a compass.
- ▶ The *closest-pair* problem is self-explanatory: given n points in the plane, find the closest pair among them.
- ► The convex-hull problem asks to find the smallest convex polygon that would include all the points of a given set.

Numerical Problem

- ▶ NP are problems that involve mathematical objects of continuous nature:
 - solving equations and systems of equations,
 - computing definite integrals,
 - evaluating functions, and so on.
- Principal difficulty stems from the fact that such problems typically require manipulating real numbers, which can be represented in a computer only approximately
- Since new applications require primarily algorithms for information storage, retrieval, transportation through networks, and presentation to users
 - ▶ NP has lost its place in the computing industry

Fundamental Data Structures

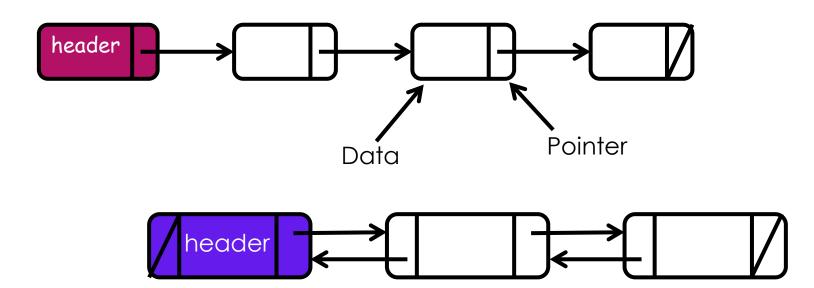
- ► Linear Data Structures
 - ► Array, Linked List, Stacks and Queues
- ▶ Graphs
- ▶ Trees

Linear Data Structures: Array

▶ Array: A sequence of n items of the same data type, stored contiguously in memory and made accessible through array indices.

Linear Data Structures: Linked List

- ► Linked List
 - ▶ A sequence of nodes with links (called pointers) to neighbors
 - ► Singly or Doubly linked lists



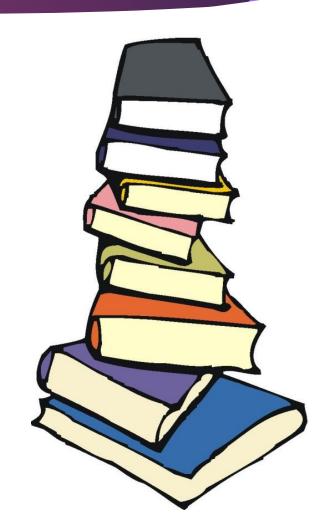
Linear Data Structures: Array vs Linked List

Differences between Array and Array List

Features	Array	Array List
Access time	Fixed	Variable
Update Cost	Higher	Lower
Storage Anticipation	Needed	Not Needed

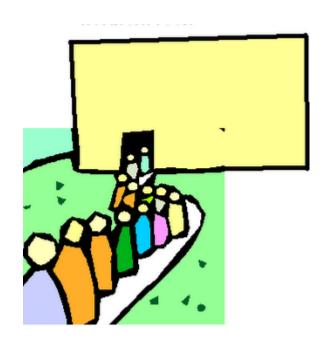
Linear Data Structures: Stack

- Stack
 - ▶ Insertion/deletion only at the top
 - ▶ Last In First Out (LIFO)
 - ▶ Two operations: push and pop
 - ► E.g., recursion needs stack
 - ▶ java.util.Stack



Linear Data Structures: Queue

- Queue
 - ▶ Insertion from rear, deletion from front
 - First In First Out (FIFO)
 - ▶ Two operations: enqueue, dequeue

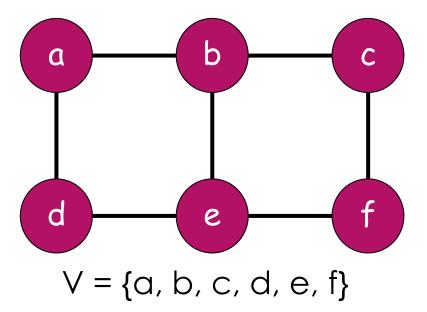


Linear Data Structures: Queue...

- Priority queues
 - ► Select item of highest priority among dynamically changing candidates. E.g., schedule job in a shared computer
 - ▶ Principal operations:
 - Find largest, delete largest, add new element
 - ► Add/delete must result in priority queue
 - Array or Sorted array based implementation is inefficient
 - "Heap" is better (We shall discuss in Transform and Conquer approach)

Graph

- ► A graph, G = < V, E > is defined by a pair of sets:
 - ▶ V is called <u>vertices</u> and E is called <u>edges</u>



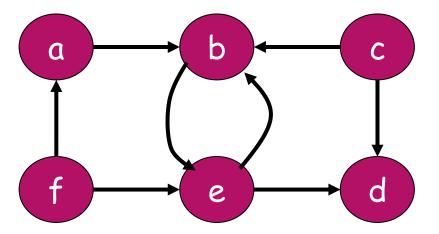
 $E = \{ (a, b), (b, c), (c, f), (f, c), (e, d), (d, a), (b, e) \}$

Graph

- Undirected graphs and Directed Graphs (Digraphs)
- ▶ We usually will not allow graphs to have loops

▶ What is the **maximum number of edges** in an undirected graph with | ∨ |

vertices?

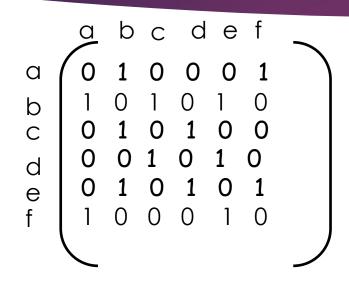


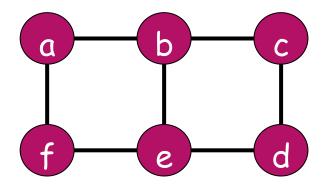
Directed graph

Representing Graphs

- Adjacency matrix
 - N × N boolean matrix
 - ► A[i, j] = 1 if there is an **edge** from i-th vertex to j-th vetex
 - ▶ Adjacency matrix of an undirected graph is symmetric.
- Adjacency list
 - A collection of linked lists, one for each vertex, that contain all neighbors of a vertex

Representing Graphs

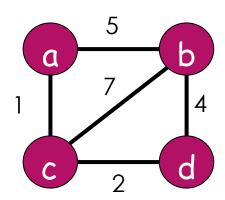




$$\begin{array}{c|cccc} a & \longrightarrow & b & \longrightarrow & f \\ \hline b & \longrightarrow & a & \longrightarrow & c & \longrightarrow & e \\ \hline c & \longrightarrow & b & \longrightarrow & d \\ \hline d & \longrightarrow & c & \longrightarrow & e \\ \hline e & \longrightarrow & b & \longrightarrow & d & \longrightarrow & f \\ \hline f & \longrightarrow & a & \longrightarrow & e \\ \end{array}$$

Weighted Graphs

▶ Edges have numbers associated with them, e.g., distance between two cities



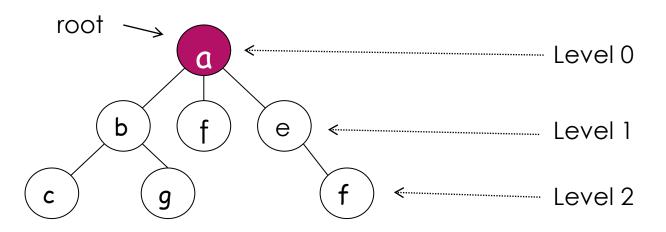
a
$$\longrightarrow$$
 b, 5 \longrightarrow c, 1
b \longrightarrow a, 5 \longrightarrow c, 7 \longrightarrow d, 4
c \longrightarrow a, 1 \longrightarrow b, 7 \longrightarrow d, 2
d \longrightarrow b, 4 \longrightarrow c, 2

Tree

- ▶ A tree is a connected acyclic graph. |E| = |V|-1
- Forest: has no cycle but may be disconnected
- ▶ Between every two vertices there is exactly one simple path.
- Any vertex can be regarded as the root,
- and then we have a rooted tree.

Tree...

► Ancestors: For vertex v, all the vertices on the simple path from root to v are called v's ancestors.



Tree...

- Descendants: All vertices for which v is an ancestor are descendants of v.
- Parent, child, sibling:
 - ▶ If (u, v) is the last edge of the simple path from root to v, then u is parent of v and v is a child of u.
 - Vertices having same parents are siblings.
- ▶ Leaves: A vertex without children is a leaf.
- ▶ **Subtree:** v with all its descendants is the subtree rooted at v.
- ▶ **Depth of vertex:** Length of the simple path from root to v is v's depth.
- ▶ **Height of tree:** The length of the longest simple path from root to leaf.

Ordered Tree

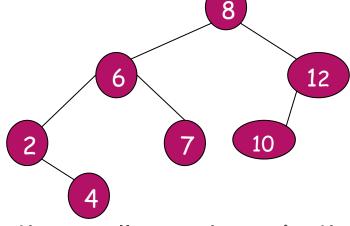
An ordered tree is a rooted tree in which all children of each vertex are ordered.

▶ Binary tree:

- An ordered tree, each vertex has at most two children and each children is designated as either left child or right child.
- $|\log_2 n| \le h \le n-1$, here n is the number of
- nodes in the tree and h is tree's height

Binary Search Tree:

- ► Each vertex is assigned a number
- ► A number assigned to a parental vertex is larger than all numbers in the left subtree and smaller than all numbers in the right subtree.



What we discussed about

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Thank You

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