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|-----------------------|---------|
| Equipment Description | CubeSat |
| Ixys Part Number:     | 118955  |

|               |                        |                 |                         |
|---------------|------------------------|-----------------|-------------------------|
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## 1. INTRODUCTION

### 1.1. GENERAL NOTES

This document outlines and defines the interfaces of the Ixys CubeSat.

### 1.2. PURPOSE AND SCOPE

The purpose of this document is to give instructions on how to use and interface with the CubeSat supplied by Ixys AS.

### 1.3. ABBREVIATIONS

| Abbreviation | Description                                 |
|--------------|---|
| <b>EPC</b>   | Electrical Power Control                    |
| <b>IMU</b>   | Inertial Measurement Unit                   |
| <b>I2C</b>   | Inter-Integrated Circuit                    |
| <b>JTAG</b>  | Joint Test Action Group                     |
| <b>NC</b>    | Not Connected                               |
| <b>PC</b>    | Personal Computer                           |
| <b>PCB</b>   | Printed Circuit Board                       |
| <b>SPI</b>   | Serial Peripheral Interface                 |
| <b>SWD</b>   | Serial Wire Debug                           |
| <b>UART</b>  | Universal Asynchronous Receiver-Transmitter |
| <b>UHF</b>   | Ultra-High Frequency                        |
| <b>USB</b>   | Universal Serial Bus                        |
| <b>6DOF</b>  | 6° of freedom                               |
| <b>9DOF</b>  | 9° of freedom                               |

### 1.4. SUPPLIER CONTACT INFORMATION

Ixys AS  
 Langmyra 11  
 N-4344 Bryne  
 Norway

+47 51 42 22 22

[post@ixys.no](mailto:post@ixys.no)

[www.ixys.no](http://www.ixys.no)

## 2. IXYS CUBESAT

The Ixys CubeSat is a standard 1U size satellite with physical space and electrical interfaces to allow implementing different types of sensor payloads.

The CubeSat contains a stack of an Electrical Power Control PCB, a Communication PCB, and a Turnstile Antenna Feed PCB. The PCBs use the PC-104 mechanical form factor, with M3 size fastening equipment.

The following section 3 describes the PCBs in more detail, section 4 describes firmware functionality and section 5 describes the payload communication interface.

| Designator | PART NUMBER | PCB                      |
|------------|-------------|--------------------------|
| -A1        | 119519      | Electrical Power Control |
| -A2        | 119521      | Communication            |
| -A3        | 119599      | Turnstile Antenna Feed   |

*Table 2-1 List of included PCBs*

### 3. HARDWARE DESCRIPTION

#### 3.1. ELECTRICAL POWER CONTROL PCB

The EPC PCB contains the following components:

- Power supply components (converting battery voltage to 5V and 3.3V)
- Microcontroller (STM32F205)
- Combined 3-axis accelerometer and gyroscope (ISM42670P)
- 3-axis magnetometer (MMC5983)
- Temperature sensor (TC74A0)
- Payload interface circuitry, supporting UART, CAN, SPI and I2C

The EPC PCB has a Micro-USB connector to allow configuration and programming, as well as an SWD header to allow microcontroller debugging and flashing.

SPI, UART and I2C payload interfaces are available both in the stack connector ST1 and connectors J7, J8 and J9, while CAN is only available in ST1. The following figure shows the different electrical interfaces available for payload communication.

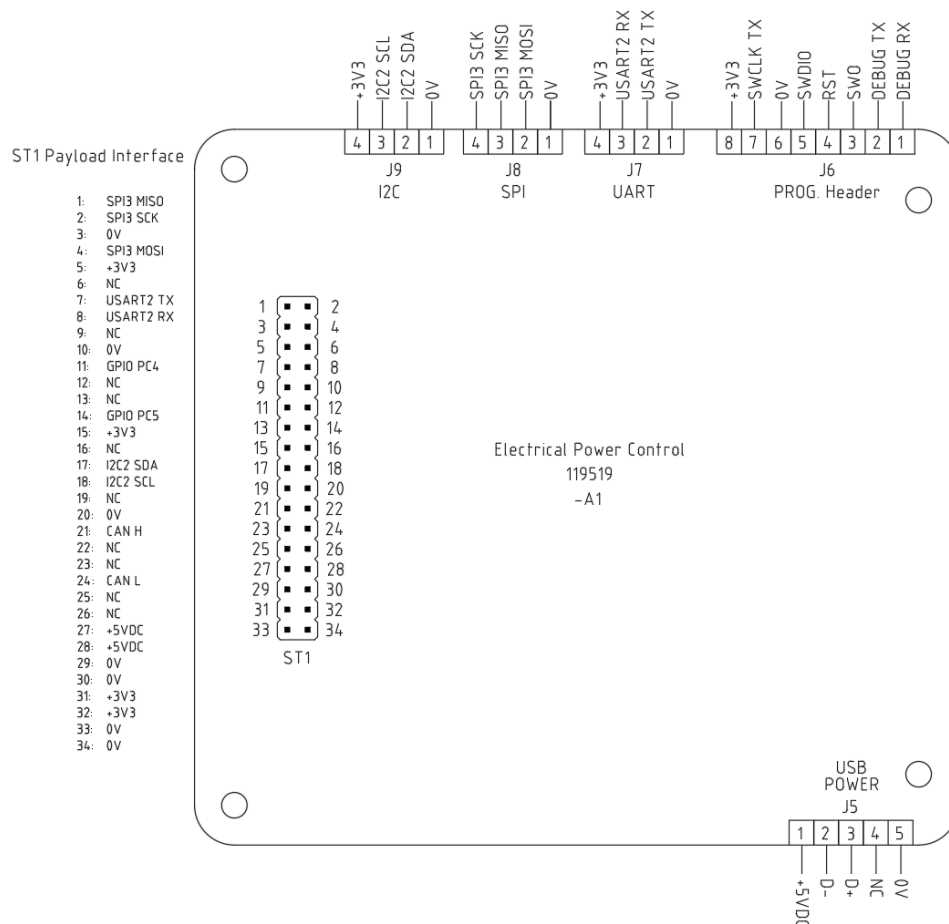


Figure 1 Electrical interfaces available for payload on EPC PCB

### 3.1.1. ELECTRICAL CONNECTORS

| Connector             | Pinout  | Note   |
|-----------------------|---|--|
| ST1 (Stack connector) | Pin 1: SPI MISO<br>Pin 2: SPI SCK<br>Pin 3: 0V<br>Pin 4: SPI MOSI<br>Pin 5: +3.3V<br>Pin 6: NC<br>Pin 7: UART TX<br>Pin 8: UART RX<br>Pin 9: NC<br>Pin 10: 0V<br>Pin 11: GPIO PC4<br>Pin 12: NC<br>Pin 13: NC<br>Pin 14: GPIO PC5<br>Pin 15: +3.3V<br>Pin 16: NC<br>Pin 17: SDA<br>Pin 18: SCL<br>Pin 19: NC<br>Pin 20: 0V<br>Pin 21: CAN High<br>Pin 22: NC<br>Pin 23: NC<br>Pin 24: CAN Low<br>Pin 25: NC<br>Pin 26: NC<br>Pin 27: +5V<br>Pin 28: +5V<br>Pin 29: 0 V<br>Pin 30: 0 V<br>Pin 31: +3.3V<br>Pin 32: +3.3V<br>Pin 33: 0 V<br>Pin 34: 0 V | 120 $\Omega$ CAN bus termination on PCB.<br>UART, SPI, I2C pins are in parallel to equivalent pins on J7/J8/J9 |
| J5 (Micro USB)        | Pin 1: +5V<br>Pin 2: Digital –<br>Pin 3: Digital +<br>Pin 4: NC<br>Pin 5: 0VDC  |  |
| J6 (SWD)              | Pin 1: Debug RX<br>Pin 2: Debug TX<br>Pin 3: SWO<br>Pin 4: RST<br>Pin 5: SWDIO<br>Pin 6: 0V<br>Pin 7: SWCLK TX<br>Pin 8: +3.3V  |  |
| J7 (UART)             | Pin 1: 0V<br>Pin 2: TX<br>Pin 3: RX<br>Pin 4: +3.3V   | In parallel to equivalent pins on ST1  |
| J8 (SPI)              | Pin 1: 0V<br>Pin 2: MOSI<br>Pin 3: MISO<br>Pin 4: SCK   | In parallel to equivalent pins on ST1  |
| J9 (I2C)              | Pin 1: 0V<br>Pin 2: SDA<br>Pin 3: SCL<br>Pin 4: +3.3V   | In parallel to equivalent pins on ST1  |

Table 3-1 List of connectors and interfaces

### 3.1.2. POWER

The CubeSat is powered by 3pcs. 18650 Li-Ion batteries wired in parallel. The battery voltage is boosted to +5V, which is then stepped down to 3.3V. The batteries can be charged through the J5 Micro USB connector. The satellite can also be powered directly through this interface.

The PCB contains two separate power supplies, with one powering the satellite itself, and the other being available to the payload through ST1 and J7/J8/J9. The power supply limits are given in the table below.

| Voltage | Fuse  | Power   |
|---------|-------|---------|
| +5V     | 2A    | < 10W   |
| +3V3    | 500mA | < 1.65W |

Table 3-2 Payload power supply specification

The ST2 stack connector must not be used by the payload.

### 3.2. CUBESAT COMMUNICATION PCB

CubeSat Communication PCB uses a Texas Instruments CC1120 radio transceiver together with a Guerilla GRF5540 power amplifier. Combined, these gives the satellite the ability to send messages in the UHF range (433 MHz) to the Ixys Ground Station.

| Frequency | Signal strength | Power | Bit Rate |
|-----------|-----------------|-------|----------|
| 433MHz    | +31dBm          | ~1W   | 1.2 kbps |

Table 3-3 Radio Specification

The EPC PCB controls the radio over an internal SPI bus.

### 3.3. CUBESAT TURNSTILE ANTENNA FEED PCB

The antenna PCB provides a 90° phase shift between four individual  $\frac{1}{2} - \lambda$  antennas using different RF couplers, providing a circular polarized antenna solution. Matched to 50  $\Omega$  impedance.

## 4. FIRMWARE

The firmware of the EPC PCB has the following functionality:

- Reads all on-boards sensors.
- Controls the radio and communication.
- Provides a configuration interface through USB.

The firmware will toggle LED4 on the EPC PCB continuously while running, as a heartbeat indicator, showing that it is running.

### 4.1. SENSOR DATA

The EPC PCB integrates the following sensors:

- ICM42670 3-axis combined accelerometer and gyroscope
- MMC5983MA 3-axis magnetometer
- TC74A0 temperature sensor

All sensors are read periodically over an internal I2C bus.

### 4.2. RADIO COMMUNICATION

Every 5 s, the main microcontroller will build a message to be sent over the radio to the ground station, with following contents:

- Temperature
- 3-axis acceleration
- 3-axis angular acceleration
- 3-axis magnetic field
- Any data received through the payload interface (see section 5)

### 4.3. CONFIGURATION

When the Micro-USB connector J5 is connected to a computer, it will appear as a serial port. Opening this serial port in a terminal emulator (for instance PuTTY or similar) allows configuration and testing of various aspects of the CubeSat.

Note: This is intended for internal Ixys use.

### 4.4. PROGRAMMING

If the S2 switch is held while the EPC PCB is powered-on, the microcontroller will boot in USB DFU mode, and hence be programmable over USB, for instance by using STM32CubeProgrammer available from [www.st.com](http://www.st.com).

Alternatively, the microcontroller can be programmed directly with any SWD compatible debug probe (for instance an ST-Link or a Segger J-Link) through the debug connector J5.

Any firmware updates will be provided by Ixys.



## 5. PAYLOAD COMMUNICATION INTERFACE

Any data received on any of the Payload Communication Interfaces will be included in the radio messages sent from the CubeSat.

Note: The hardware has components for multiple different interfaces, but in the current firmware version only UART is implemented and used.

### 5.1. UART

The EPC PCB will include any data received over UART in its radio messages. Data can be textual or binary, as desired by the payload implementer.

There is currently no acknowledgement of messages received on the UART interface. Max message length is yet to be determined.

The communication parameters for the UART interface are given in the table below.

|              |      |
|--------------|------|
| Baud rate    | 9600 |
| Data bits    | 8    |
| Parity       | None |
| Stop bits    | 1    |
| Flow control | None |

*Table 5-1 Payload UART interface parameters*

### 5.2. SPI

Not implemented in current firmware.

### 5.3. I2C

Not implemented in current firmware.

### 5.4. CAN

Not implemented in current firmware.