

# Back Propagation report

icf

October 2017

## 1 Back Propagation in CPMC-Lab

The problem will be solved in five steps:

- 1) Pre-analysis
- 2) Matlab Program Modification
- 3) Input
- 4) Output
- 5) Discussion

Notice:

Calculation used the running parameters below if no special mention:

deltat=0.01;  
N\_wlk=100;  
N\_blksteps=300;  
N\_eqblk=3;  
N\_blk=10;  
itv\_modsvd=5;  
itv\_pc=10;  
itv\_Em=50;

### 1.1 Pre-analysis

1. Remember all the walkers at the detect point and the  $x$  (Auxiliary field) from this point to the next detect point .
2. Adjust the remembered data with popcotrol.
3. At the next detect point, using back propagation of  $|\phi_T\rangle$  along  $x_i$  for each walker  $i$ .
4. Use the remembered data and Back Propagation Formula to calculate average values of operators in Groundstate.

System	(kx,ky)	$\langle K \rangle$	$\langle V \rangle$	$\langle K \rangle_{mixed}$	$\langle V \rangle_{mixed}$
Data		$\langle K \rangle_{bp}$	$\langle V \rangle_{bp}$		
2*4	(+0.0819,-0.6052)	-13.7778	1.65680	-14.3892	2.2609
2.1.mat		-13.7413	1.6431		
3*4	(+0.02,0.04)	-15.2849	1.29311	-15.9954	2.0002
2.2.mat		-15.2905	1.3176		
4*4	(0,0)	-22.5219	2.94100	-24	4.4205
2.3.mat		-22.5744	3.0185		

Table 1:  $\langle V \rangle_{mixed}$ ,  $\langle K \rangle_{mixed}$  are calculated mixed results of Kinetic and Potential Energy,  $\langle V \rangle$ ,  $\langle K \rangle$  are Ground State Kinetic and Potential Energy and  $\langle V \rangle_{bp}$ ,  $\langle K \rangle_{bp}$  are back propagation Ground State Kinetic and Potential Energy.

## 1.2 Matlab Program Modification

batchsample\_U\_BP.m;  
 CPMC\_Lab\_BP.m;  
 measure\_BP.m;  
 pop\_cntrl\_BP.m;  
 stblz\_BP.m;  
 stepwtk\_AP.m;  
 stepwtk\_BP.m;  
 V\_AP.m;  
 V\_BP.m;

## 1.3 Input/Output

Table 1;  
 Figure 1; 2.4.mat;

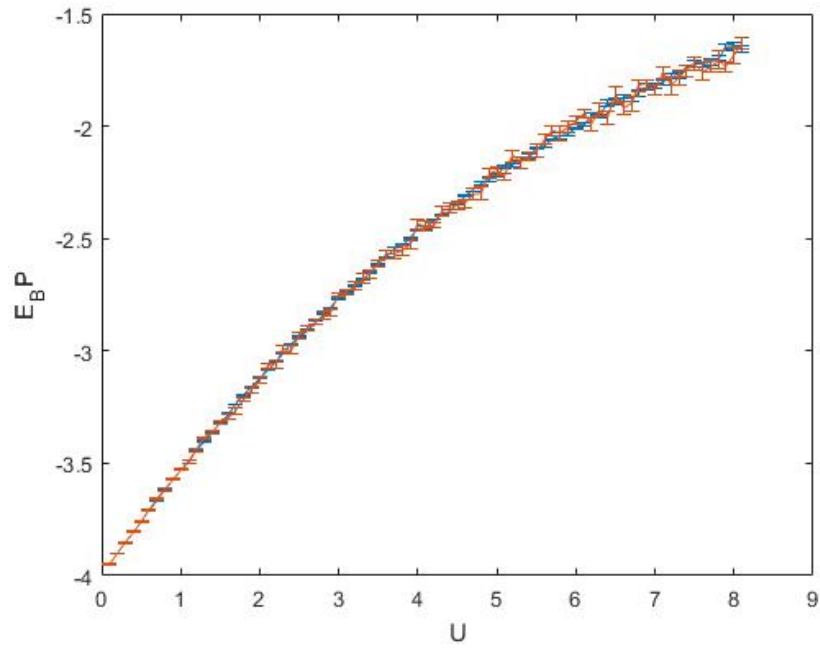


Figure 1: One of the curve is  $\langle H \rangle_{mixed}$  vs.  $U$  and one of the curve is  $\langle H \rangle_{bp}$  vs.  $U$ .