Final Report: Brain Dataset

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Overview

- ① Dataset
- Methodology
- Results
- Pitfalls

Dataset

Experiment recording human grasp and lift tasks¹

- 12 participants, 9 series recorded each
- EEG: 32 electrodes recorded at 5kHz
- EMG: 5 signals at 4kHz
- kinetic: 36 signals at 500Hz
- objects to grasp with different surface friction/weights (165g 660g)
- preprocessing: trials provided in windowed format (event timing relative to window)

 $^{^{1}}$ Data source: Luciw, M. D., Jarocka, E. & Edin, B. B. FigShare http://dx.doi.org/10.6084/m9.figshare.988376 (2014). 4

Experiment

Single trial procedure

- start command signaled visually by LED
- participant moves hand to object
- grasp object
- move object to target position
- hold position
- LED signal, to move object back to initial position
- hand release object
- move hand back to resting position

Experiment



t-SNE

- expectation
- result

General developement

- Theano (python)
- climin library
- breze library

Data preparation

- Input normalization to -1/1 range (tanh activation optimization)
- imagine one lifting trial as a single learning sample
 - recordings have different length, therefore equalize it!
 - ullet zero padding o learning in danger of being misguided
 - ullet tail cut o targets fall of, fails to learn sometimes
- separation into sets of 300 data point records length improves learning.... Why did Smagt tell us to do that??)
- Subsampling (10Hz) of EMG data
- Data set split: train/valid/test $\rightarrow 0.8/0.1/0.1$

Recurrent Neural Network

- ullet assuming predictability in human planning o history matters
- Network design:
 - 100 neurons
 - 1 hidden layer
 - tanh activation function
 - 50 samples per batch
 - optimizer: Adadelta
- parameter weight initialization by uniform normal distribution
- spectral radius
- Important weights: some samples are more important than others
- Bernoulli cross entropy loss

Learning Targets

- one dim multi class vector vs. mult dim one-hot-encoding
- Selection of available events
 - LEDOn/LEDOff: participant signal
 - 2 tHandStart/tHandStop: hand moving
 - trial_DurReach: time needed to move hand to object
 - tLiftOff: lift object
- Targets defined over (multiple) intervals in between events
 - move hand to target
 - 2 lift object
 - 4 hold object phase
 - replace object
- Data shape
 - Input: [time slice, features, sensors] \rightarrow [300 x 2428 x 5/32]
 - Target: [time slice, features, targets] \rightarrow [300 x 1320 x 1]

Results (1): t-SNE

- Figure of t-SNE of EEG data → Seperability of trials
- Possible to separate with standard NN
- ullet Figure of t-SNE of EMG data o As expected

Results (2): RNN

- Overview of the targets
- Hand move to target works good.
- Touch phase target also quite ok.
- hand move back target also (partially) sucessful
- Comparison: Training with data of one person vs. data of more participants
- etc.

Pitfalls

- Prediction do not fit to the target borders exactly
- No working early stopping criterion (so far)
- Targets within the lift phase cannot be predicted properly
- etc.

Blocks of Highlighted Text

Block 1

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Multiple Columns

Heading

- Statement
- 2 Explanation
- Second Example
 Second Example

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Table

Treatments	Response 1	Response 2
Treatment 1	0.0003262	0.562
Treatment 2	0.0015681	0.910
Treatment 3	0.0009271	0.296

Table: Table caption

Theorem

Theorem (Mass-energy equivalence)

$$E = mc^2$$

Verbatim

Example (Theorem Slide Code)

```
\begin{frame}
\frametitle{Theorem}
\begin{theorem}[Mass--energy equivalence]
$E = mc^2$
\end{theorem}
\end{frame}
```

Figure

Uncomment the code on this slide to include your own image from the same directory as the template .TeX file.

Citation

An example of the \cite command to cite within the presentation:

This statement requires citation [Smith, 2012].

References



John Smith (2012)

Title of the publication

Journal Name 12(3), 45 - 678.

The End