

# SAT/SMT solvers

## 11. Binary Decision Diagrams

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# Binary Decision Trees

A binary decision tree is a rooted, directed tree with two types of vertices, terminal vertices and nonterminal vertices.

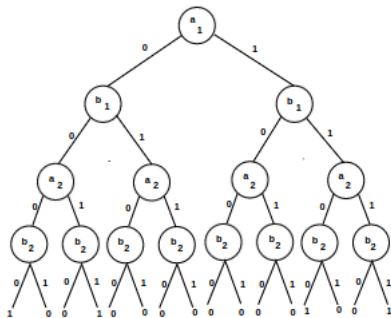
Each nonterminal vertex  $v$  is labeled by a variable  $var(v)$  and has two successors:

- $low(v)$  corresponding to the case where the variable  $v$  is assigned 0
- $high(v)$  corresponding to the case where the variable  $v$  is assigned 1

Each terminal vertex  $v$  is labeled by  $value(v)$  which is either 0 or 1

# Binary Decision Trees

$$f(a_1, a_2, b_1, b_2) = (a_1 \iff b_1) \wedge (a_2 \iff b_2)$$



There is usually a lot of redundancy in such trees

There are eight subtrees with roots labeled by  $b_2$ , but only three are distinct

# Binary Decision Diagrams

- Binary decision diagram is a rooted, directed acyclic graph with two types of vertices, terminal vertices and nonterminal vertices
- Each nonterminal vertex  $v$  is labeled by a variable  $var(v)$  and has two successors,  $low(v)$  and  $high(v)$
- Each terminal vertex is labeled by either 0 or 1

# Example

$$f = x_1x_2 + x_4$$
$$(x_1 \wedge x_2 \vee x_4)$$

# Odd parity function

$$x_1 x_2 x_3 x_4$$

$\neg, \vee, \wedge$



# Canonical Form Property

- Such a representation must guarantee that two boolean functions are logically equivalent if and only if they have isomorphic representations
- This simplifies tasks like checking equivalence of two formulas and deciding if a given formula is satisfiable or not

Two binary decision diagrams are isomorphic if there exists a bijection  $h$  between the graphs such that:

- terminals are mapped to terminals and nonterminals are mapped to nonterminals
- for every terminal vertex  $v$ ,  $value(v) = value(h(v))$
- for every nonterminal vertex  $v$ :
  - $var(v) = var(h(v))$
  - $h(low(v)) = low(h(v))$
  - $h(high(v)) = high(h(v))$

# Canonical Form Property

To obtain a canonical representation for boolean functions by placing two restrictions on binary decision diagrams:

- The variables should appear in the same order along each path from the root to a terminal
- There should be no isomorphic subtrees or redundant vertices in the diagram

The first requirement is easy to achieve:

- Impose total ordering  $<$  on the variables in the formula
- Require that if vertex  $u$  has a nonterminal successor  $v$ , then  $var(u) < var(v)$

# Canonical Form Property

The second requirement is achieved by repeatedly applying three transformation rules that do not alter the function represented by the diagram:

- Remove duplicate terminals: Eliminate all but one terminal vertex with a given label and redirect all arcs to the eliminated vertices to the remaining one
- Remove duplicate nonterminals: If nonterminals  $u$  and  $v$  have  $var(u) = var(v)$ ,  $low(u) = low(v)$  and  $high(u) = high(v)$ , then eliminate one of the two vertices and redirect all incoming arcs to the other vertex
- Remove redundant tests: If nonterminal vertex  $v$  has  $low(v) = high(v)$ , then eliminate  $v$  and redirect all incoming arcs to  $low(v)$

The term Ordered Binary Decision Diagram (OBDD) will be used to refer to the graph obtained in this manner

# Example

# Ordered Binary Decision Diagrams

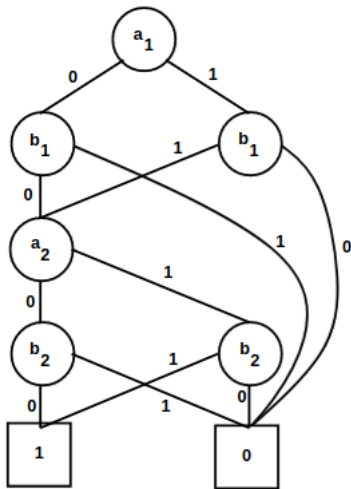
- The canonical form may be obtained by applying the transformation rules until the size of the diagram can no longer be reduced
- It was shown how this can be done by a procedure called Reduce in linear time

If OBDDs are used as a canonical form for boolean functions, then

- checking equivalence is reduced to checking isomorphism between OBDDs
- satisfiability can be determined by checking equivalence with the trivial OBDD that consists of only one terminal labeled by 0

# OBDD for Comparator Example

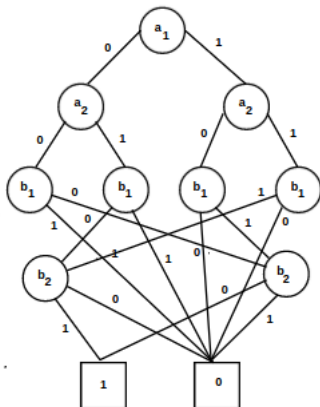
$$a_1 < b_1 < a_2 < b_2$$



The number of vertices will be  $3n + 2$

# OBDD for Comparator Example

$$a_1 < a_2 < b_1 < b_2$$



The number of vertices will be  $3 * 2^n - 1$

How to get OBDD for  $f * g$  (if we know OBDDs for  $f$  and  $g$ )?

The key idea for efficient implementation of these operations is the Shannon expansion

$$f = \neg x \wedge f|_{x=0} \vee x \wedge f|_{x=1}$$

Let  $*$  be an arbitrary two argument logical operation, and let  $f$  and  $f'$  be two boolean functions

To simplify the explanation of the algorithm we introduce the following notation:

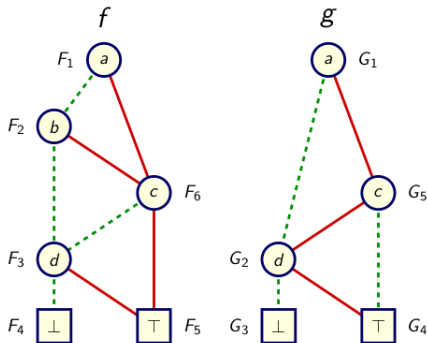
- $v$  and  $v'$  are the roots of the OBDDs for  $f$  and  $f'$
- $x = \text{var}(v)$  and  $x' = \text{var}(v')$



# Logical Operations

- If  $v$  and  $v'$  are both terminal vertices, then
$$f * f' = \text{value}(v) * \text{value}(v')$$
- If  $x = x'$ , then we use the Shannon expansion
$$f * f' = \neg x \wedge (f|_{x=0} * f'|_{x=0}) \vee x \wedge (f|_{x=1} * f'|_{x=1})$$
- If  $x < x'$ , then  $f'|_{x=0} = f'|_{x=1} = f'$  since  $f'$  does not depend on  $x$ . In this case the Shannon Expansion simplifies to
$$f * f' = \neg x \wedge (f|_{x=0}) \vee x \wedge (f|_{x=1})$$
- If  $x > x'$  - in the previous manner

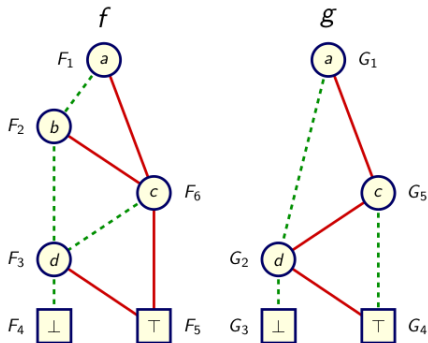
# Logical Operations



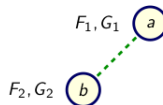
Recursive Calls



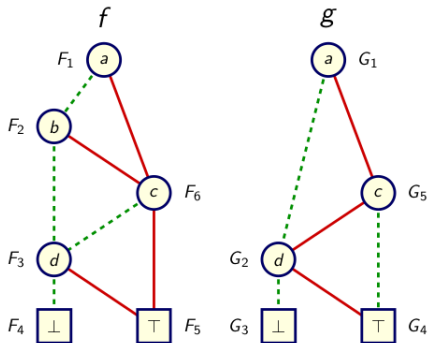
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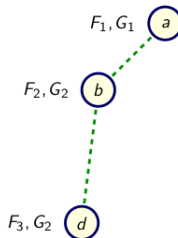
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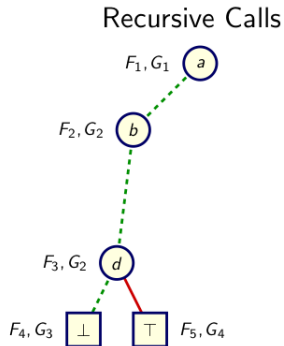
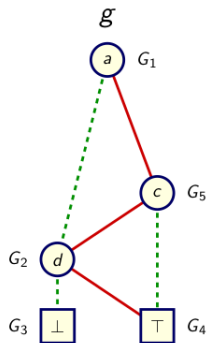
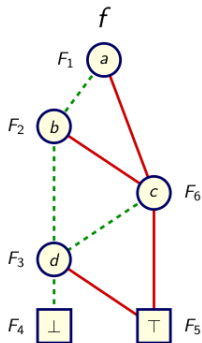
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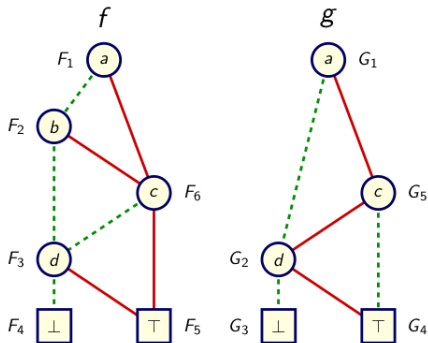
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# Logical Operations



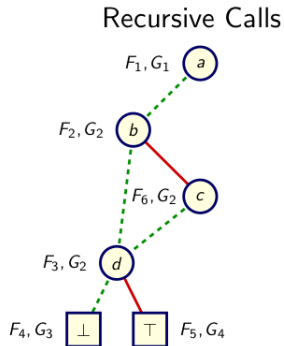
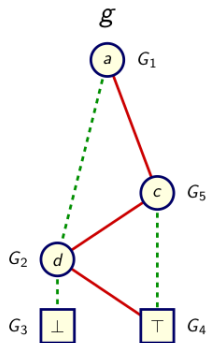
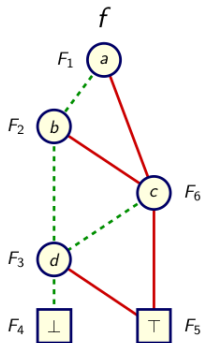
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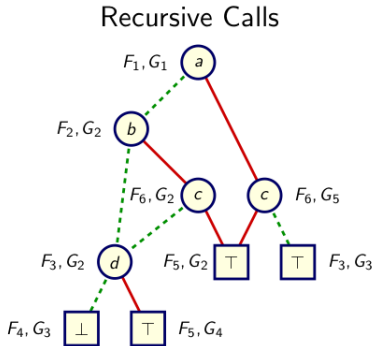
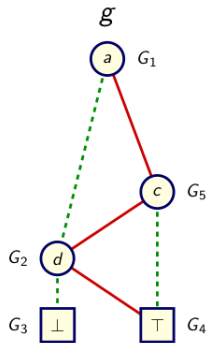
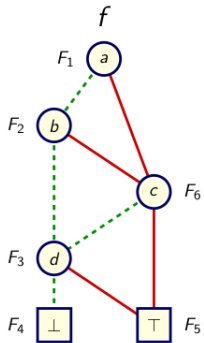
Recursive Calls



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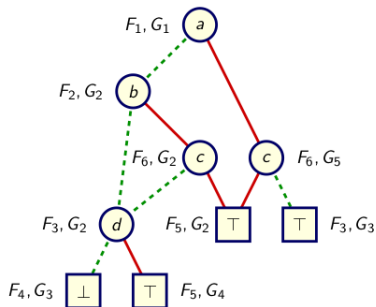
# Logical Operations





# Logical Operations

Recursive Calls



Reduced Result

