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a_rd_en = control_signals[0];
a_wr_en = control_signals[1];
a_shift = control_signals[2];
a_bus_out_en = control_signals[3];

b_rd_en = control_signals[4];
b_wr_en = control_signals[5];

alu_sub_en = control_signals[6];
alu_status_out_en = control_signals[7];
alu_bus_out_en = control_signals[8];

ic_rd_en = control_signals[9];
ic_wr_en = control_signals[10];
ic_count_dir = control_signals[11];
ic_w_r_en = control_signals[12];
ic_w_r_en = control_signals[13];

mar_mux_sel = control_signals[14];
mar_w_r_en = control_signals[15];

mem_rd_en = control_signals[17];
mem_wr_en = control_signals[18];
mem_addr_valid = 1;

count_wr_en = control_signals[19];
count_rd_en = control_signals[20];
count_dir = control_signals[21];
count = control_signals[22];

mem_bus_out_en = control_signals[23];

main_reset = control_signals[24];
ic_sel = control_signals[25];
i_2_rd_en = control_signals[26];
i_2_wr_en = control_signals[27];
current_access = control_signals[28];
address_word = control_signals[29];
data_word = control_signals[30];
mem_sel = control_signals[31];

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