

Hidden Markov Models presentation

# Electricity Load Forecasting

using Particle Filters

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# Summary

## Context

## Method

## Results

## Conclusion

Context

# Context / Data

Application of Sequential Monte Carlo methods & more specifically Particle Filters to Electricity load forecasting for EDF.

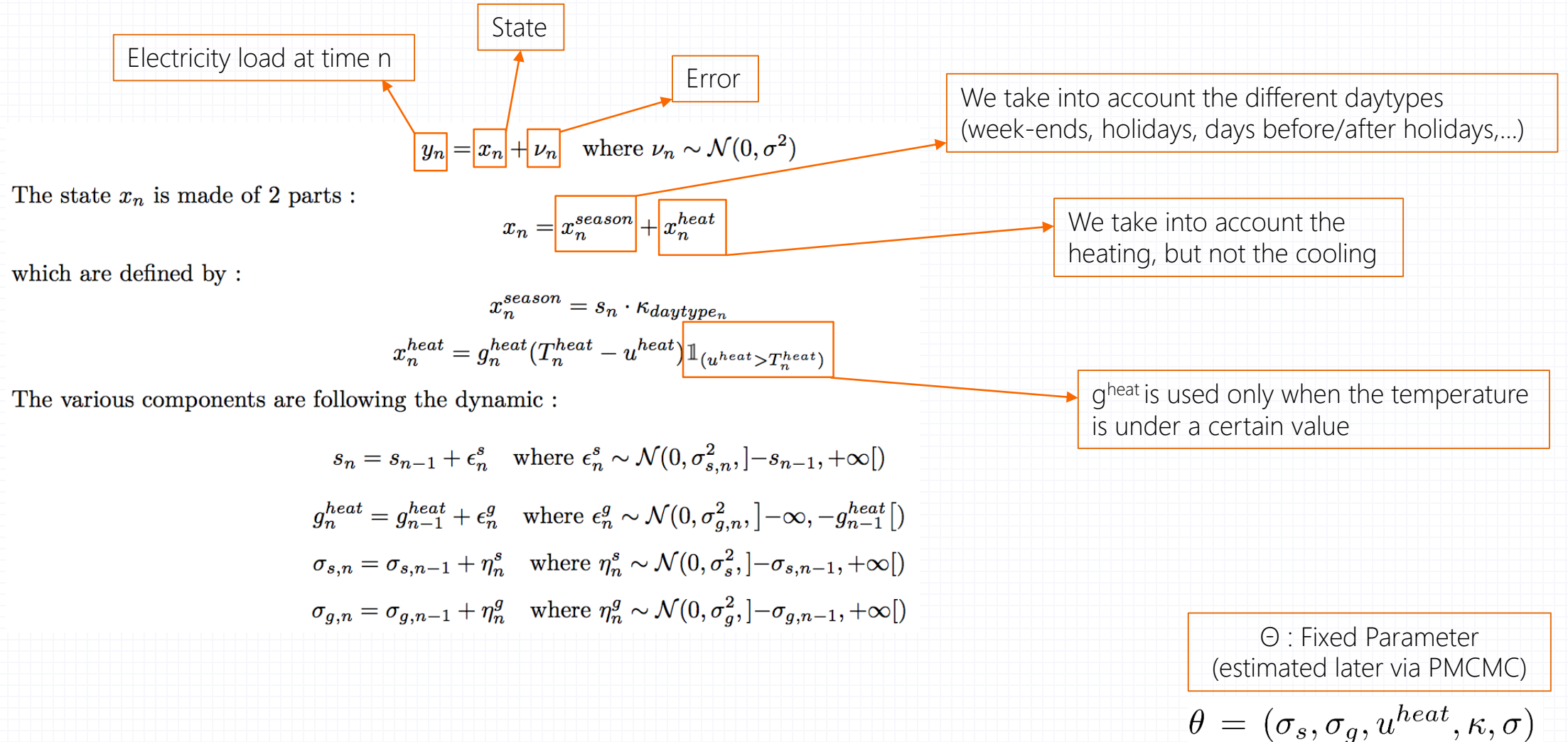


Adding a new observation does not require the model to be entirely re-estimated.(vs. traditional MCMC methods such as Gibbs sampling).

Electricity Consumption data every 30min in Metropolitan France (ex. Corsica) over the 2011-2015 period from RTE  
Average Temperature of weather stations, every 3h from Météo France (while the article uses EDF Internal Forecast Model)



# Model (for a chosen half-hour)



# Goal : Forecasting

**Input :**

Daily Temperature for a specific half-hour  
*(several Forecasting models are available)*

**Ouput:**

Electricity Load Forecast for a specific half-hour  
Time Horizon: **1 to 5 days ahead.**

- We train a **different** model for **each half hour** of the day. Here, we chose to work on 3:00PM time series.
- Therefore we cannot use the previous half-hour electricity load to predict the next one.

Method

# Particle Filter algorithm

**Algorithm 3.10** (Particle filter used for our application).

**At time  $n = 0$**

1. Sample  $\hat{X}_0^j \sim \mu(x_0)$ .
2. Compute  $\tilde{w}_0^j = g_0(y_0|X_0^j)$  and set  $\hat{w}_0^j \leftarrow \frac{\tilde{w}_0^j}{\sum_{k=1}^M \tilde{w}_0^k}$ .
  - if  $\widehat{\text{ESS}}(0) < 0.001M$ , set  $X_0^j \leftarrow \hat{X}_0^j$  and  $w_0^j \leftarrow 1/M$ .
  - if  $0.001M \leq \widehat{\text{ESS}}(0) < 0.5M$ , use residual-multinomial resample (see Algorithm 3.5) and regularisation move (see Algorithm 3.6) steps to set  $X_0^j$  and  $w_0^j$ .
  - if  $0.5M \leq \widehat{\text{ESS}}(0)$ , set  $X_0^j \leftarrow \hat{X}_0^j$  and  $w_0^j \leftarrow \hat{w}_0^j$ .

Initialization step: the algorithm is very sensitive to the initial value of the particles

**At time  $n \geq 1$**

1. Sample  $\hat{X}_n^j \sim f_n(x_n|X_{n-1}^j)$ .
2. Compute  $\tilde{w}_n^j = w_{n-1}^j g_n(y_n|X_n^j)$  and set  $\hat{w}_n^j \leftarrow \frac{\tilde{w}_n^j}{\sum_{k=1}^M \tilde{w}_n^k}$ .
  - if  $\widehat{\text{ESS}}(n) < 0.001M$ , set  $X_n^j \leftarrow \hat{X}_n^j$  and  $w_n^j \leftarrow w_{n-1}^j$ .
  - if  $0.001M \leq \widehat{\text{ESS}}(n) < 0.5M$ , use residual-multinomial resample (see Algorithm 3.5) and regularisation move (see Algorithm 3.6) steps to set  $X_n^j$  and  $w_n^j$ .
  - if  $0.5M \leq \widehat{\text{ESS}}(n)$ , set  $X_n^j \leftarrow \hat{X}_n^j$  and  $w_n^j \leftarrow \hat{w}_n^j$ .

Removal of outliers

Multinomial resampling instead

Non-systematic resampling



# How to initialize the Particle Filter ?

Basic idea



Solution



Results

With arbitrary values

Problem in our model: Hard to find an appropriate order of magnitude for all components, especially the variances, due to complex hierarchy

Gibbs sampling

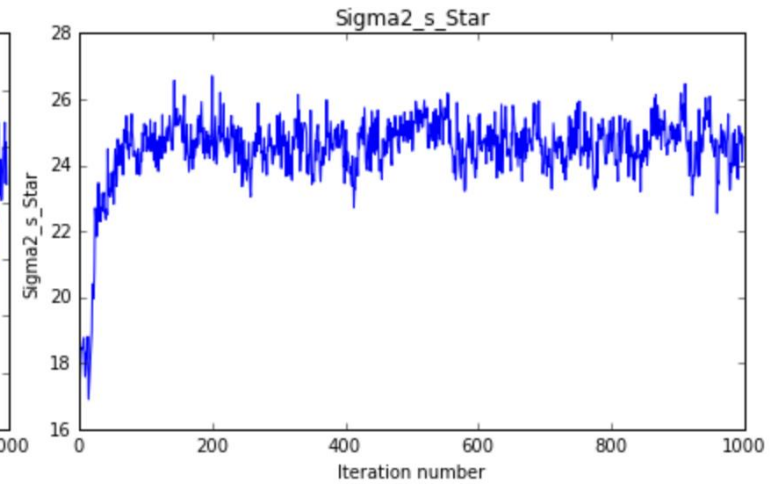
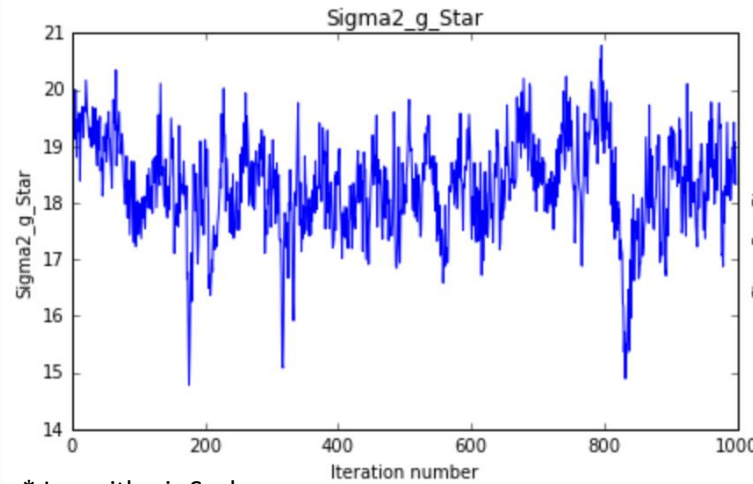
Idea: Simulate from the smoothed distribution until a date  $n_0 - 1$  using a Gibbs sampler and use the last simulated value for date  $n_0 - 1$  to initialize the Particle Filter

Fast convergence to a right order of magnitude

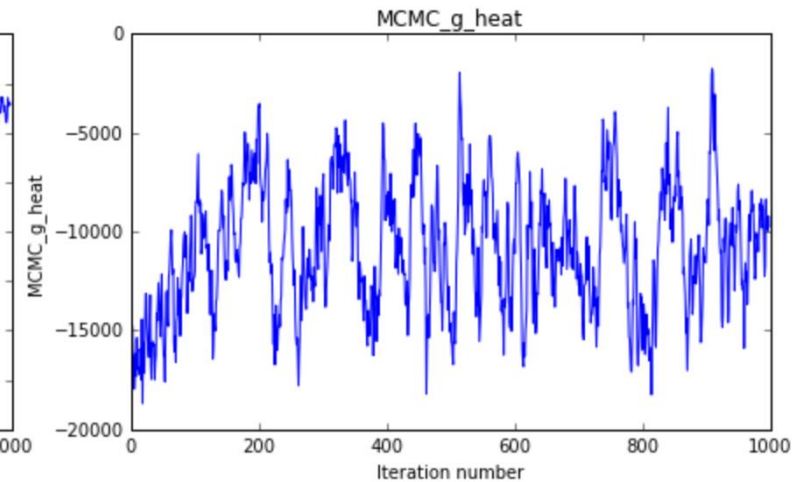
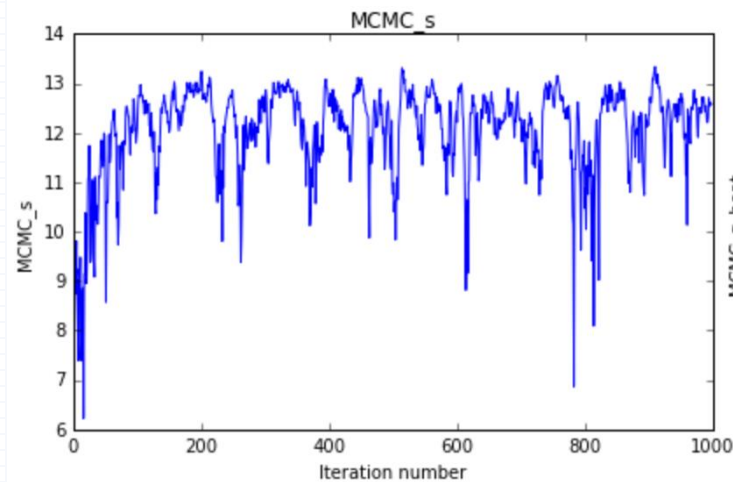
14 days during a cold period (2 weeks in January), where the temperatures are below the  $u^{\text{heat}}$  threshold, are enough to get a good initialization and are computationally affordable!

# Gibbs Convergence

1 000 iterations  
Results on the last day values ( $n_0 - 1$ )



\* Logarithmic Scale



# Particle Filter application

## 1. Parameter Estimation



The PF provides a **likelihood estimation** which can be reused in a Metropolis-Hastings algorithm in order to estimate the posterior distribution of the parameters (Marginal PMCMC algorithm)

## 2. Forecast



The PF provides predictions by simulating the particles of the future dates:

$$\hat{y}_{n+\tau,i} = \mathbb{E}[x_{n+\tau}|y_{0:n,i}].$$

# Parameter Estimation using PMCMC

## Marginal PMCMC

From current point  $\theta_m$  (and current PF estimate  $L_T^N(\theta_m)$ ):

- 1 Sample  $\theta_\star \sim H(\theta_m, d\theta_\star)$
- 2 Run a PF so as to obtain  $L_T^N(\theta_\star)$ , an unbiased estimate of  $L_T(\theta_\star) = p(y_{0:T}|\theta_\star)$ .
- 3 With probability  $1 \wedge r$ , set  $\theta_{m+1} = \theta_\star$ , otherwise  $\theta_{m+1} = \theta_m$  with

$$r = \frac{p(\theta_\star)L_T^N(\theta_\star)h(\theta_m|\theta_\star)}{p(\theta_m)L_T^N(\theta_m)h(\theta_\star|\theta_m)}$$

Goal: Estimate the parameter  $\theta = (\sigma_s, \sigma_g, u^{heat}, \kappa, \sigma)$

# Parameter Estimation using PMCMC - Difficulties

## Difficulty 1: Proposal Choice for $\theta = (\sigma_s, \sigma_g, u^{heat}, \kappa, \sigma)$

Gaussian Random Walk ?

- Truncated Normal distribution for the 3 variance parameters => Non-symmetric proposal
- Kappa is a vector which sum must be 1 => no random walk can be used

## Difficulty 2: $\kappa$ estimation and proposal

Independent uniform Dirichlet proposal ?

- In practice, we tested this method and it led to a acceptance ratio close to 0
- So we fixed  $\kappa$  to  $(1/8, \dots, 1/8)$  where 8 was our number of daytypes => **Strong hypothesis**: we assumed there was no difference between daytypes

## Difficulty 3: Tuning the hyperparameters

Try many different values ?

- Computational intensive algorithm : 16 hours to run 300 Metropolis iterations => we have to allow a large variance in order to explore a large range of values in a small amount of iterations

# Results

# Result of the PMMH Algorithm (1/2)

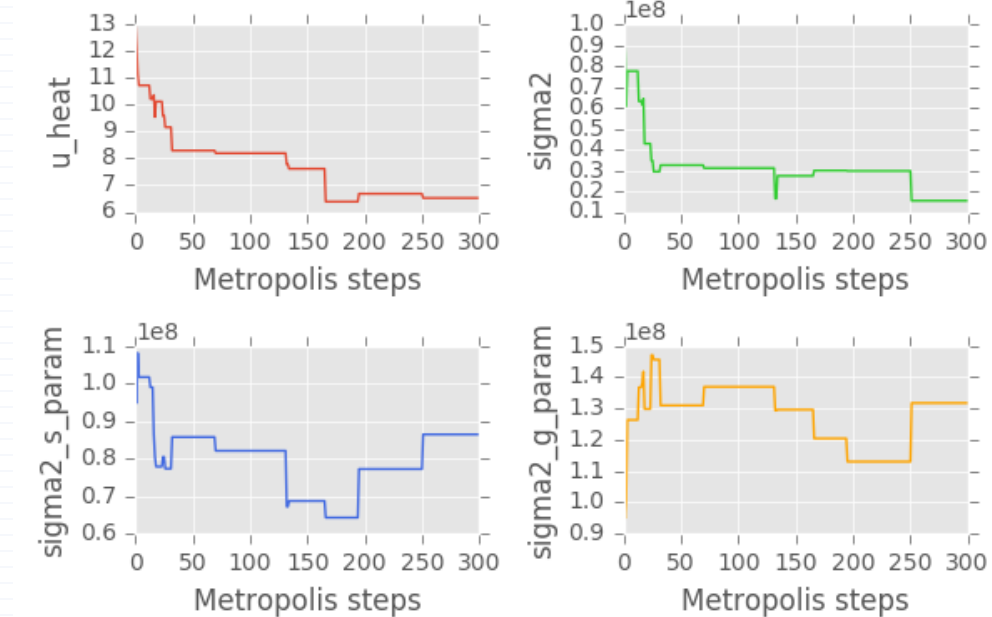
*PMMH Result (with a burn out of 30 iterations)*

	Acceptance rate	$u^{heat}$	$\sigma^2$	$\sigma_s^2$	$\sigma_g^2$
PMMH	5.35 %	7.3	27E+06	79E+06	127E+06

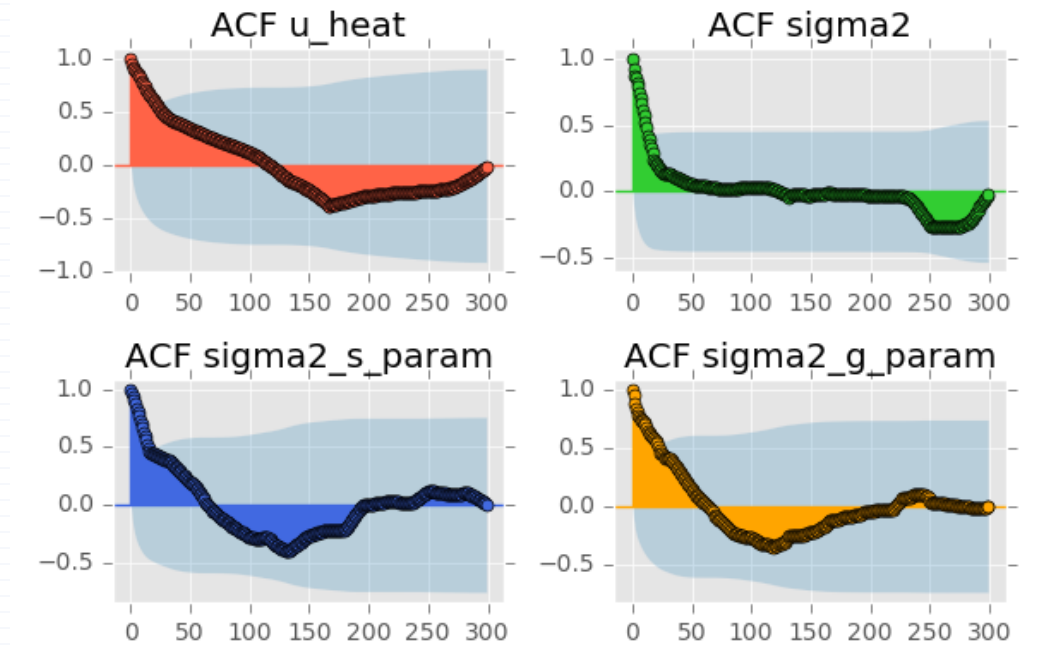
- This result has been computed using a PMMH algorithm with 300 iterations
- We observed similar results in previous versions of PMMH
- The value of  $u^{heat}$  is lower than expected (around 14 C° in the article)
- The acceptance rate is low because the model is very sensitive to the parameters → for some parameters the likelihood can be  $-\infty$ !

# Result of the PMMH Algorithm (2/2)

*Convergence of the PMMH*



Evolution of the parameters



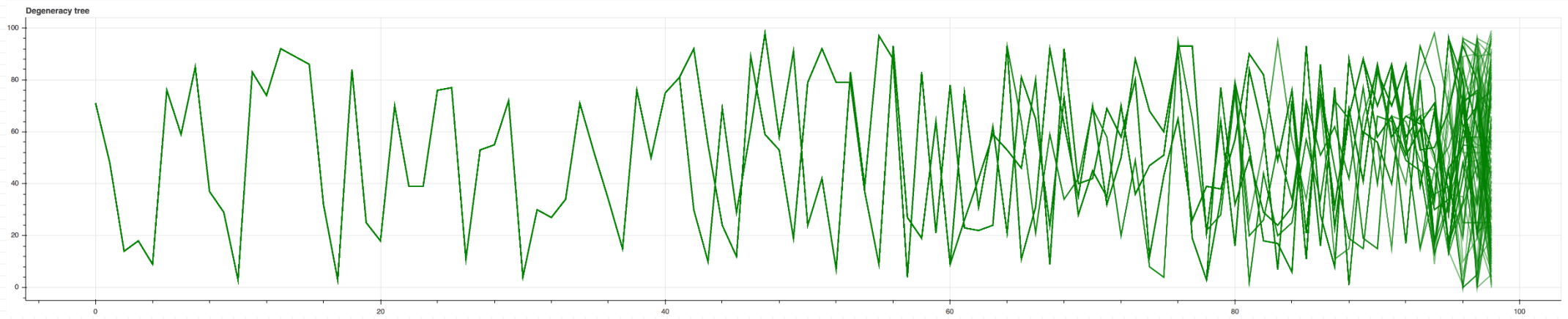
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# Degeneracy in the Particle Filter

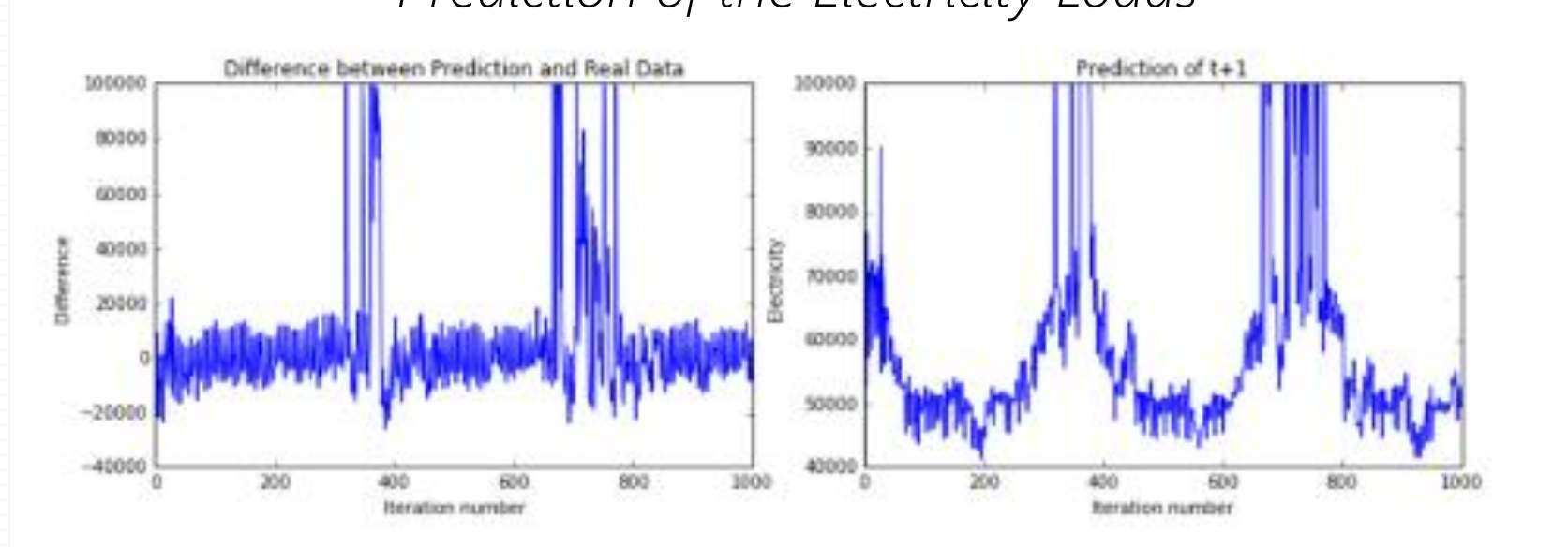
- A particle can move too far from the real value → after some iterations almost all particles are too far from the real value : the model is **degenerate**
- When the model is too degenerate, we resample the particle → we can observe the genealogy of the particles.

*Genealogy of the particles*



# Forecast Result (1/2)

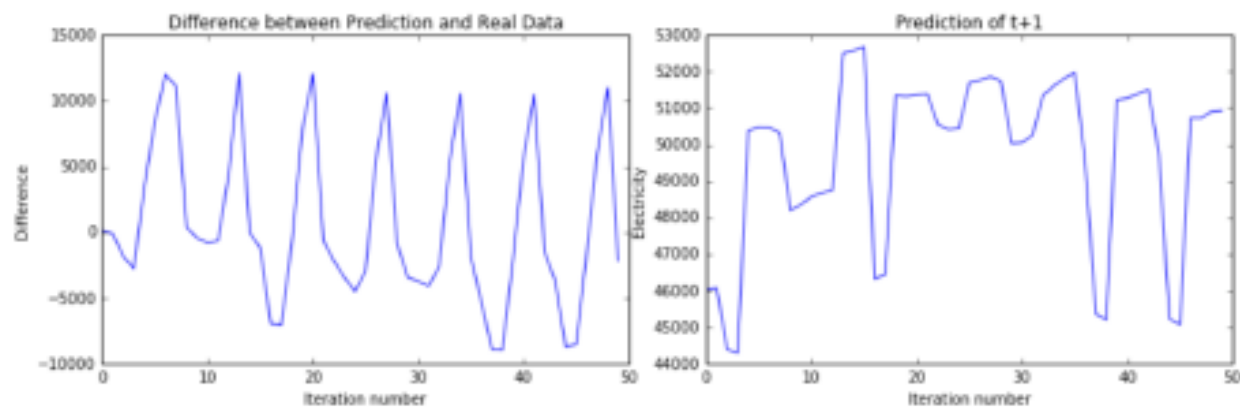
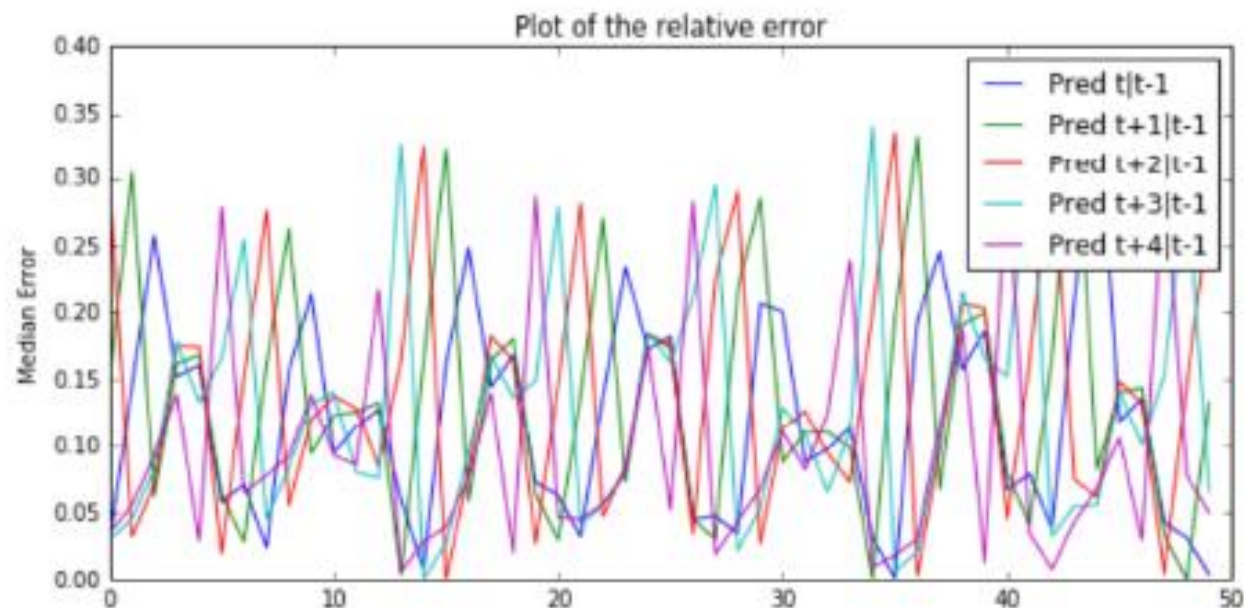
## *Prediction of the Electricity Loads*



- We can observe an annual seasonality
- We have big outliers during winter, when the temperature drops below  $u^{\text{heat}}$
- The MAPE is around 10% without these outliers (20% with).

# Forecast Result (2/2)

*Forecasting during 50 days*



# Conclusion

# Practical Issues

- All the parameters have very strong links together, and results are based on random simulation
  - it is difficult to explain why we sometimes generate extreme values
- The different calculus can provide very big result (displayed as Inf in Python) or very close to zero (displayed as zero) → we had to use logarithmic transformations
- The different algorithms take a lot of times to run :
  - ✓ Around 10 minutes for a PF with 1000 particles and 1000 iterations
  - ✓ 16 hours for the PMMH with 300 iterations

# Further Improvements

- Increase the length of the different algorithms / the number of particles for a better accuracy
- Build a model for every half-hour → we only forecast the electricity load at 3:00pm
- Compare our model with other models (like SARIMA, Kalman Filters, Rule-Based Modelling (Dordonnat & al, 2008)...).

# Conclusion