

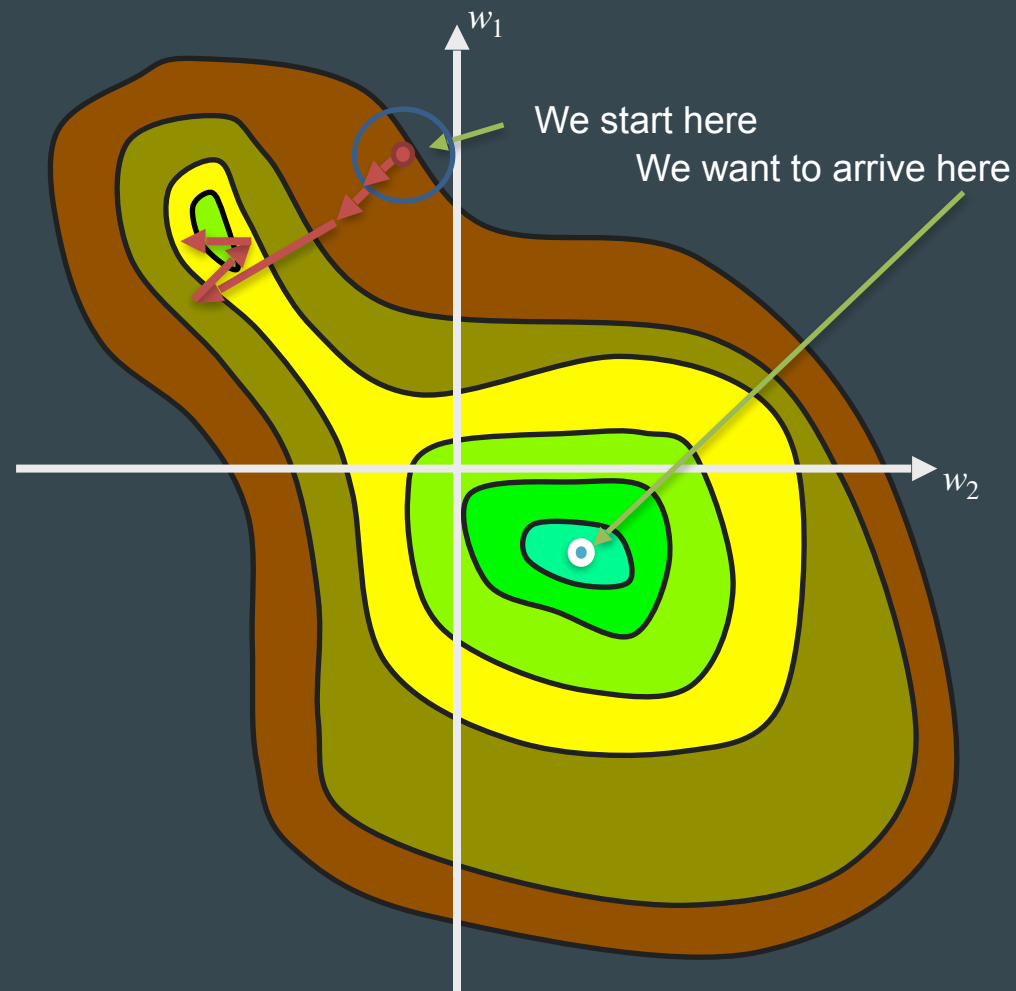
Part 4: Optimisers

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Mikhail Romanov

Gradient Descent

Gradient Descent



$$\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_p \end{bmatrix} \quad \nabla_{\mathbf{w}} L = \begin{bmatrix} \frac{\partial L}{\partial w_0} \\ \frac{\partial L}{\partial w_1} \\ \vdots \\ \frac{\partial L}{\partial w_p} \end{bmatrix}$$

$$\mathbf{w}^{t+1} = \mathbf{w}^t - \alpha \nabla_{\mathbf{w}} L_{total}^t$$

$$L_{total}^{t=0} = \frac{1}{S} \sum_{s=1}^S L(Net_{\mathbf{w}^t=0}(x_s), y_s)$$

Stochastic Gradient Descent



$$\nabla L = \nabla(L_1 + L_2 + \dots + L_S) = \nabla L_1 + \nabla L_2 + \dots + \nabla L_S$$

$$L_{total}^{t=0} = \overset{1}{L_5} + \overset{2}{L_3} + \overset{3}{L_9} + \dots + \overset{S}{L_5}$$

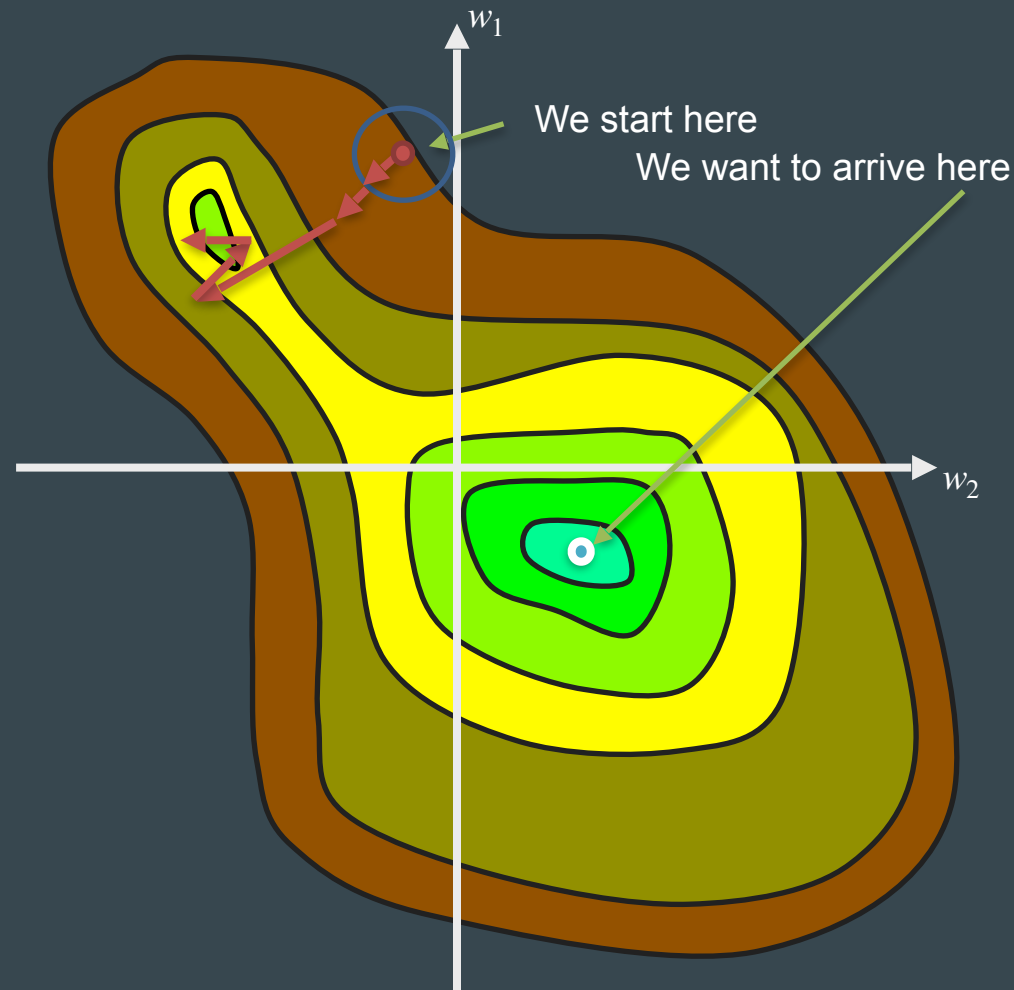
$$\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_p \end{bmatrix} \quad \nabla_{\mathbf{w}} L = \begin{bmatrix} \frac{\partial L}{\partial w_0} \\ \frac{\partial L}{\partial w_1} \\ \vdots \\ \frac{\partial L}{\partial w_p} \end{bmatrix}$$

$$\mathbf{w}^{t=1} = \mathbf{w}^{t=0} - \alpha \nabla_{\mathbf{w}} L_1^{t=0}$$

Gradient is calculated for one sample

$$\mathbf{w}^{t=1} = \mathbf{w}^{t=0} - \alpha \nabla L_1 - \alpha \nabla L_2 - \dots - \alpha \nabla L_S \approx \mathbf{w} - \alpha \nabla L$$

Stochastic Gradient Descent



$$L_{total} = \boxed{L_5 + L_3}^{b_1} + \boxed{L_9 + \dots}^{b_2} + \boxed{L_5}^{b_N}$$

$$\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_p \end{bmatrix} \quad \nabla_{\mathbf{w}} L = \begin{bmatrix} \frac{\partial L}{\partial w_0} \\ \frac{\partial L}{\partial w_1} \\ \vdots \\ \frac{\partial L}{\partial w_p} \end{bmatrix}$$

$$\mathbf{w}^{t=1} = \mathbf{w}^{t=0} - \alpha \nabla_{\mathbf{w}} L_{b_1}^{t=0}$$

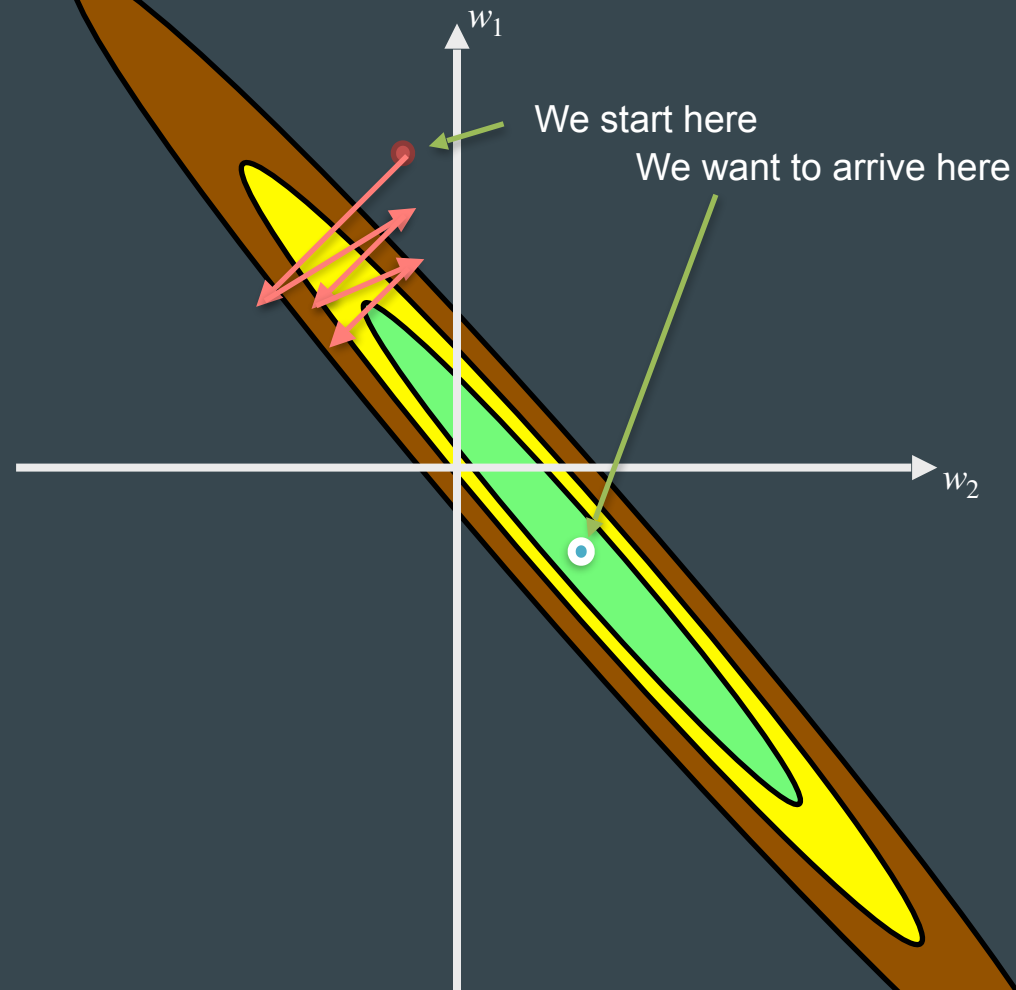
$$\mathbf{w}^{t=2} = \mathbf{w}^{t=1} - \alpha \nabla_{\mathbf{w}} L_{b_2}^{t=1}$$

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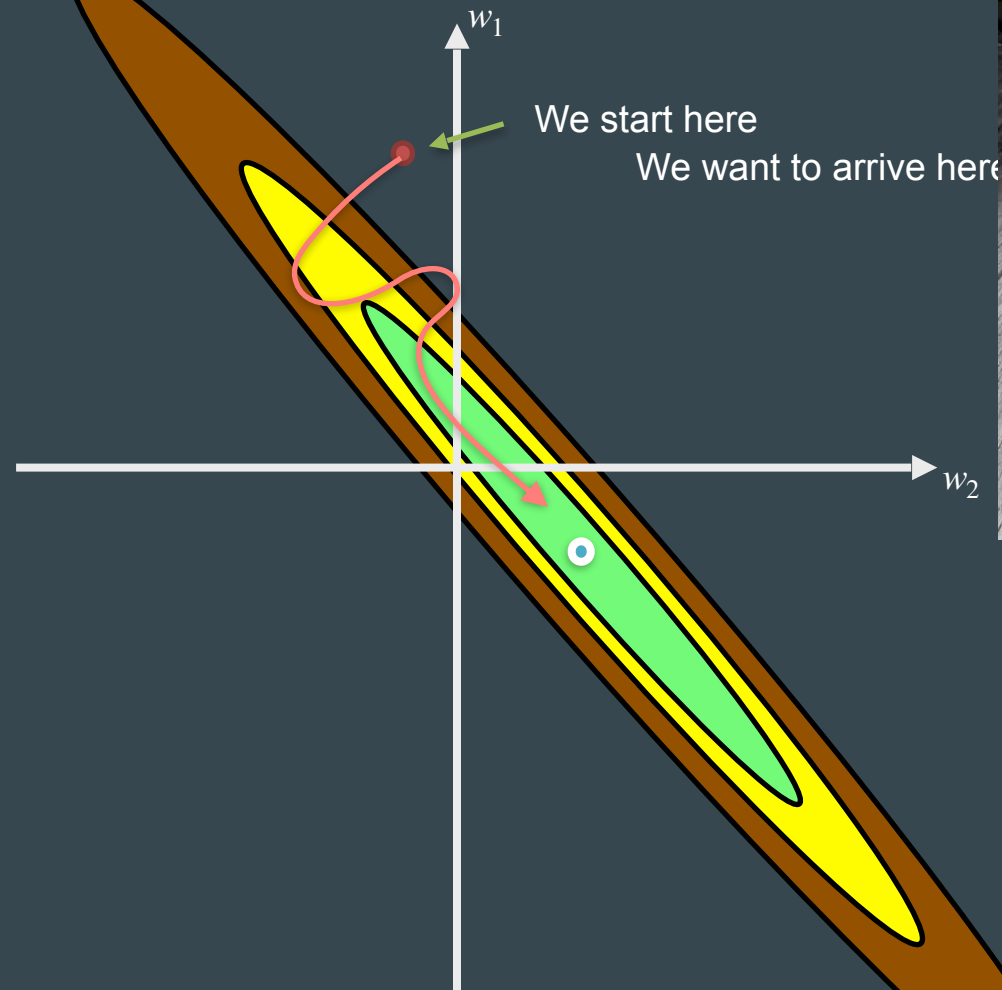
$$\mathbf{w}^{t+1} = \mathbf{w}^t - \alpha \nabla_{\mathbf{w}} L_{b_t}^t$$

Gradient is
calculated
for one
Batch

Possible Problems

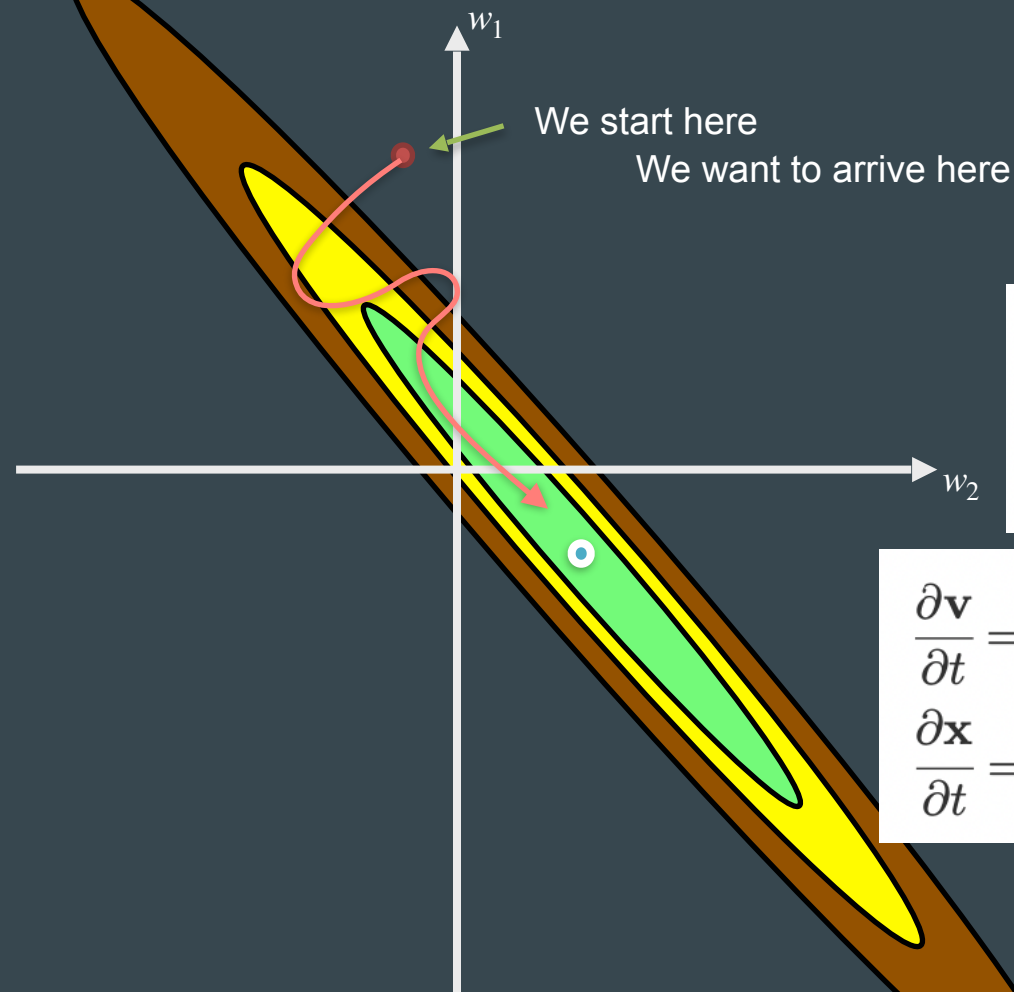


Momentum



$$\begin{cases} \frac{\partial \mathbf{v}}{\partial t} = \frac{1}{m} (\mathbf{F} + \mathbf{F}_{\text{tp}}) \\ \frac{\partial \mathbf{x}}{\partial t} = \mathbf{v} \end{cases}$$

Momentum



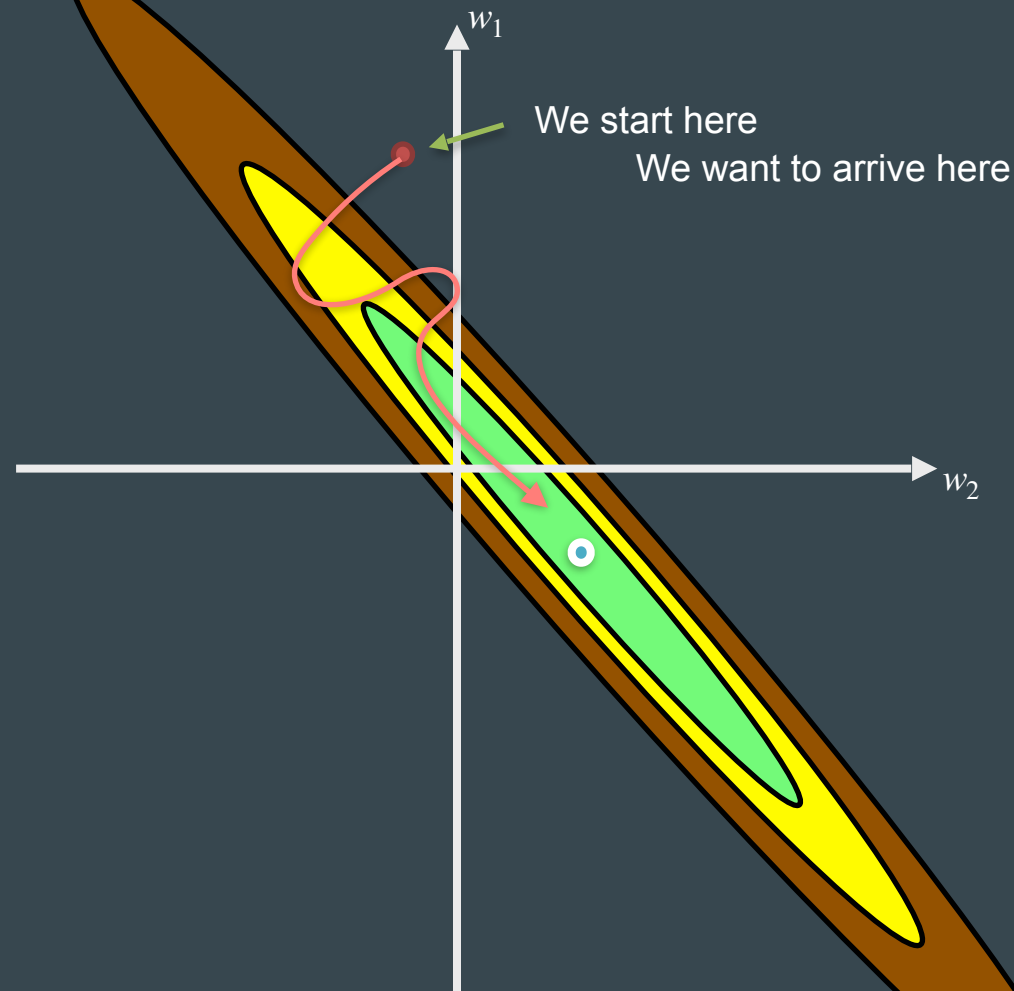
$$\begin{cases} \frac{\partial \mathbf{v}}{\partial t} = \frac{1}{m} (\mathbf{F} + \mathbf{F}_{\text{tp}}) \\ \frac{\partial \mathbf{x}}{\partial t} = \mathbf{v} \end{cases}$$

$$\begin{cases} \frac{\partial \mathbf{v}}{\partial t} = \frac{1}{m} (\mathbf{F} + \mathbf{F}_{\text{tp}}) = -\frac{1}{m} \nabla L - \frac{1}{m} \gamma \mathbf{v} \\ \frac{\partial \mathbf{x}}{\partial t} = \mathbf{v} \end{cases}$$

$$\begin{aligned} \frac{\partial \mathbf{v}}{\partial t} &= \frac{\mathbf{v}^{t+1} - \mathbf{v}^t}{\Delta t} \\ \frac{\partial \mathbf{x}}{\partial t} &= \frac{\mathbf{x}^{t+1} - \mathbf{x}^t}{\Delta t} \end{aligned}$$

$$\begin{cases} \mathbf{v}^{t+1} = -\alpha \nabla L(\mathbf{w}^t) - \beta \mathbf{v}^t \\ \mathbf{w}^{t+1} = \mathbf{w}^t + \mathbf{v}^t \end{cases}$$

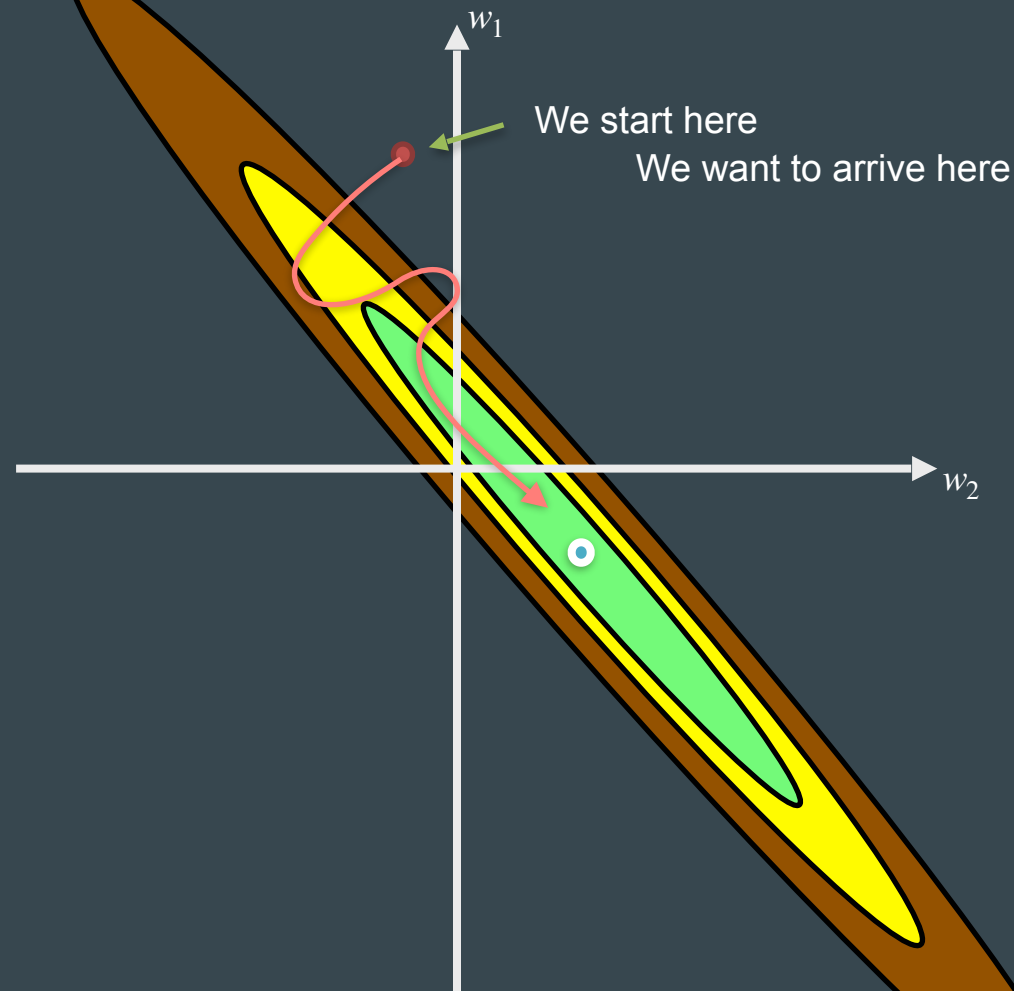
Momentum



$$\begin{cases} \frac{\partial \mathbf{v}}{\partial t} = \frac{1}{m} (\mathbf{F} + \mathbf{F}_{\text{tp}}) = -\frac{1}{m} \nabla L - \frac{1}{m} \gamma \mathbf{v} \\ \frac{\partial \mathbf{x}}{\partial t} = \mathbf{v} \end{cases}$$

$$\begin{cases} \mathbf{v}^{t+1} = -\alpha \nabla L(\mathbf{w}^t + \mathbf{v}^t) - \beta \mathbf{v}^t \\ \mathbf{w}^{t+1} = \mathbf{w}^t + \mathbf{v}^{t+1} \end{cases}$$

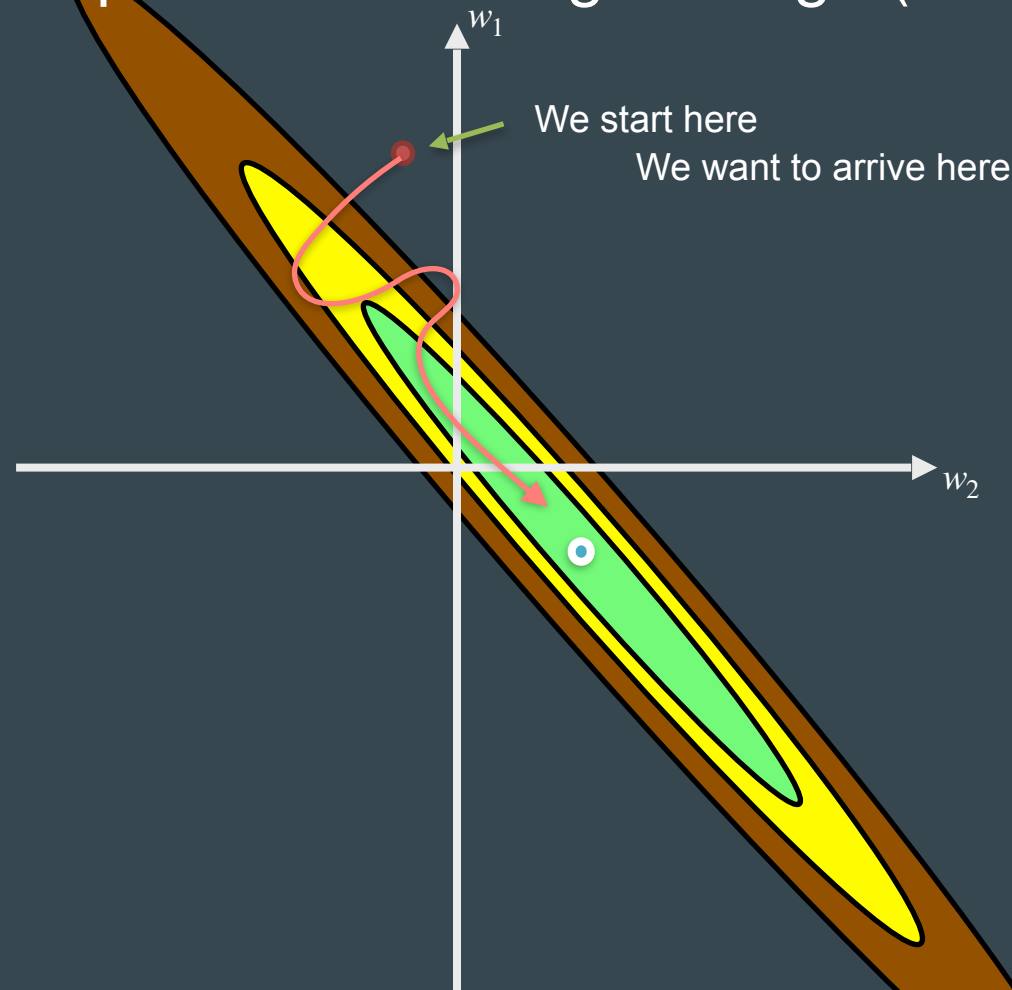
Momentum



$$\mathbf{w}^{t+1} = \mathbf{w}^t - \alpha EM A_{\beta}^t(\nabla L)$$

$$EM A_{\beta}^t(\nabla L) = (1 - \beta) \nabla L^t + \beta EM A_{\beta}^{t-1}(\nabla L)$$

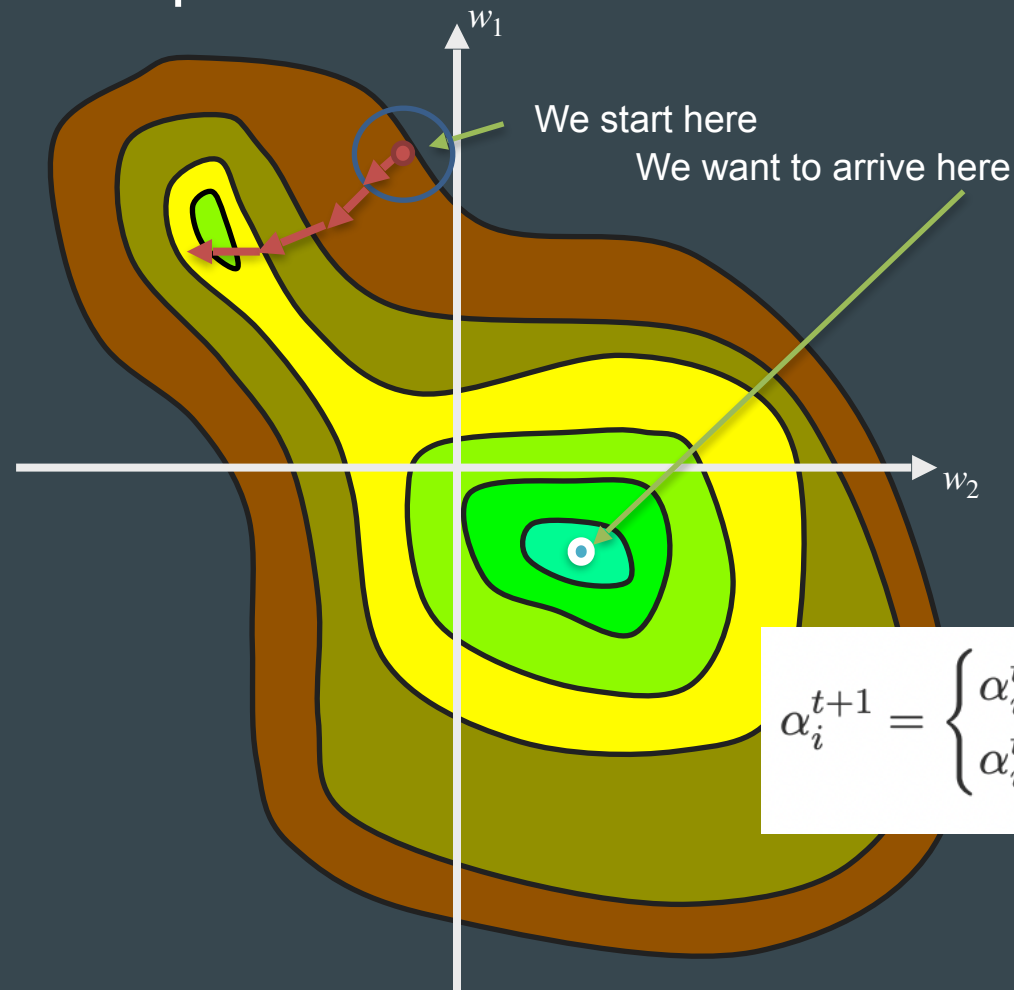
Exponential Moving Average (EMA)



$$\mathbf{w}^{t+1} = \mathbf{w}^t - \alpha EMA_{\beta}^t(\nabla L)$$

$$EMA_{\beta}^t(\nabla L) = (1 - \beta) \nabla L^t + \beta EMA_{\beta}^{t-1}(\nabla L)$$

RProp

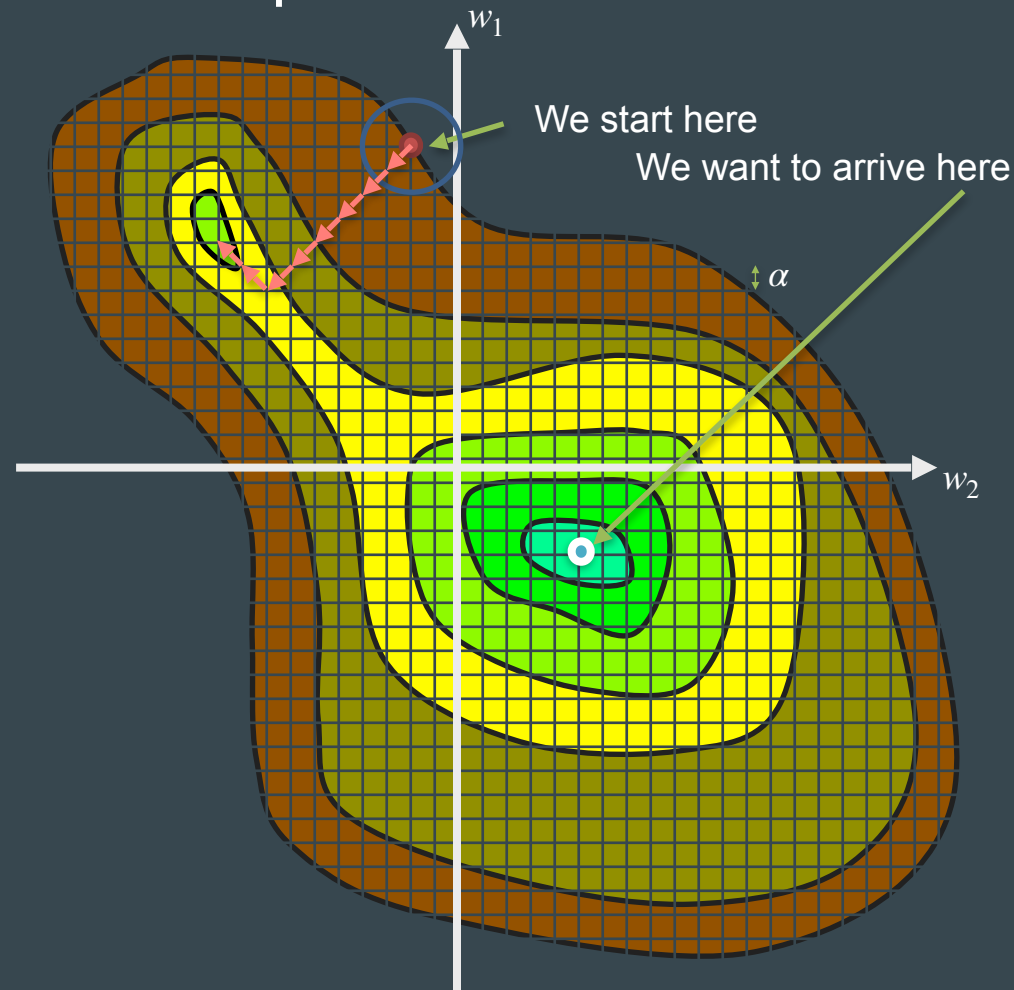


- SGD has equal learning rates for all the parameters
- What if we make individual LR's?
- We will only take into account signs of gradients
- We will initialise all the LR's with equal values
- And then we will adjust them

$$\mathbf{w}_i^t = \mathbf{w}_i^{t-1} - \alpha_i^t \cdot \text{sign}(\nabla_i L(\mathbf{w}^{t-1}))$$

$$\alpha_i^{t+1} = \begin{cases} \alpha_i^t \cdot 1.2 & \text{if } \text{sign}(\nabla_i L(\mathbf{w}^t) \cdot \nabla_i L(\mathbf{w}^{t-1})) > 0 \\ \alpha_i^t \cdot 0.6 & \text{if } \text{sign}(\nabla_i L(\mathbf{w}^t) \cdot \nabla_i L(\mathbf{w}^{t-1})) \leq 0 \end{cases}$$

RMSProp



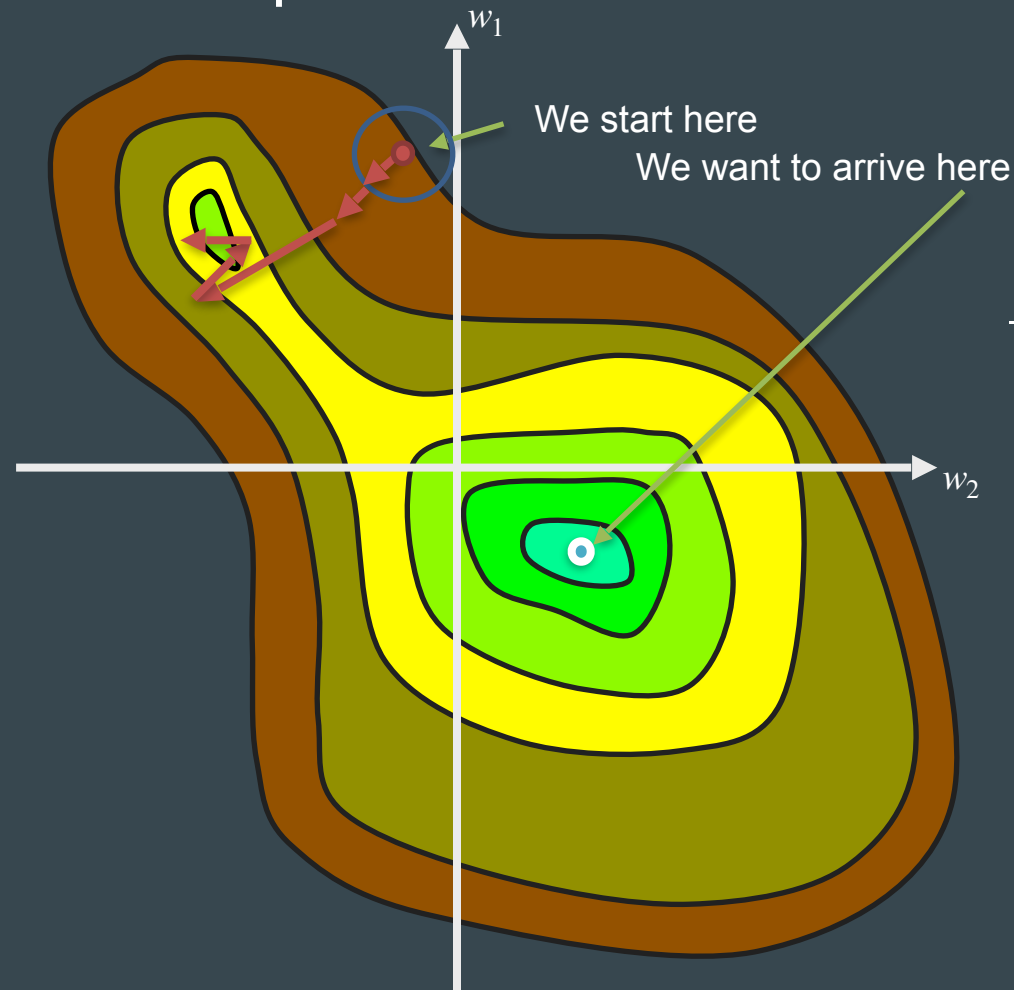
- RMSProp == RProp, no LR adjusting
- Equal step lengths for all parameters and gradients
- Like grid search

$$\mathbf{w}^{t+1} = \mathbf{w}^t - \alpha \frac{\nabla L}{\nabla L}$$

$$\frac{\nabla(L_1 + L_2)}{\nabla(L_1 + L_2)} \neq \frac{\nabla L_1}{\nabla L_1} + \frac{\nabla L_2}{\nabla L_2}$$

$$\frac{\nabla(L_1 + L_2)}{\nabla(L_1 + L_2)} = \frac{\nabla L_1}{\nabla(L_1 + L_2)} + \frac{\nabla L_2}{\nabla(L_1 + L_2)}$$

RMSProp



$$\nabla L = \nabla L_1 + \nabla L_2 + \dots + \nabla L_S$$

$$\frac{\nabla L}{\nabla L} \neq \frac{\nabla L_1}{\nabla L_1} + \frac{\nabla L_2}{\nabla L_2} + \dots + \frac{\nabla L_S}{\nabla L_S}$$

$$\frac{\nabla L}{\nabla L} = \frac{\nabla(L_1 + L_2 + \dots + L_S)}{\nabla L} =$$

$$\frac{\nabla(L_1 + L_2 + \dots + L_S)}{\sqrt{\nabla L^2}} =$$

$$\frac{\nabla L_1}{\sqrt{\nabla L^2}} + \frac{\nabla L_2}{\sqrt{\nabla L^2}} + \dots + \frac{\nabla L_S}{\sqrt{\nabla L^2}}$$

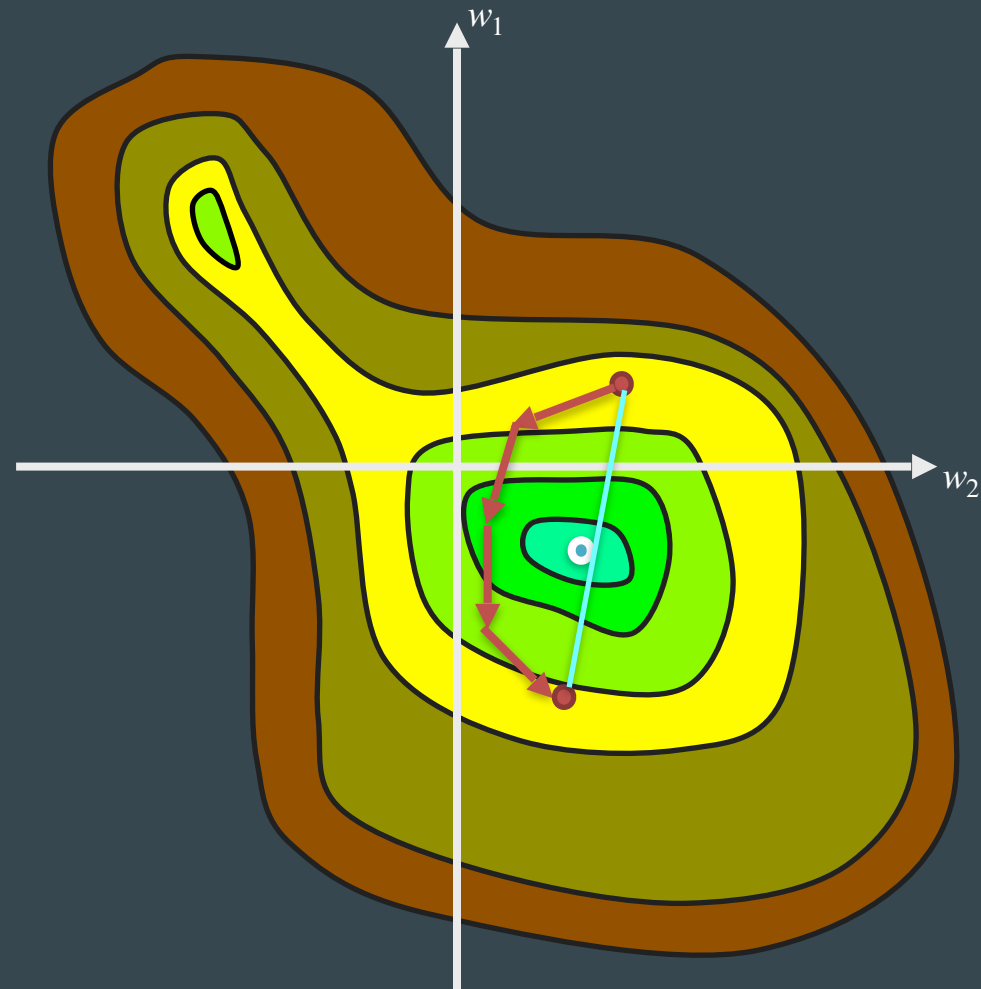
$$\mathbf{w}^{t+1} = \mathbf{w}^t - \alpha \frac{\nabla L}{\sqrt{EMA_{\beta_2}^t \nabla L^2} + \varepsilon}$$

Adam



$$\mathbf{w}^{t+1} = \mathbf{w}^t - \alpha \frac{EMA_{\beta_1}^t \nabla L}{\sqrt{EMA_{\beta_2}^t \nabla L^2 + \epsilon}}$$

Look Ahead



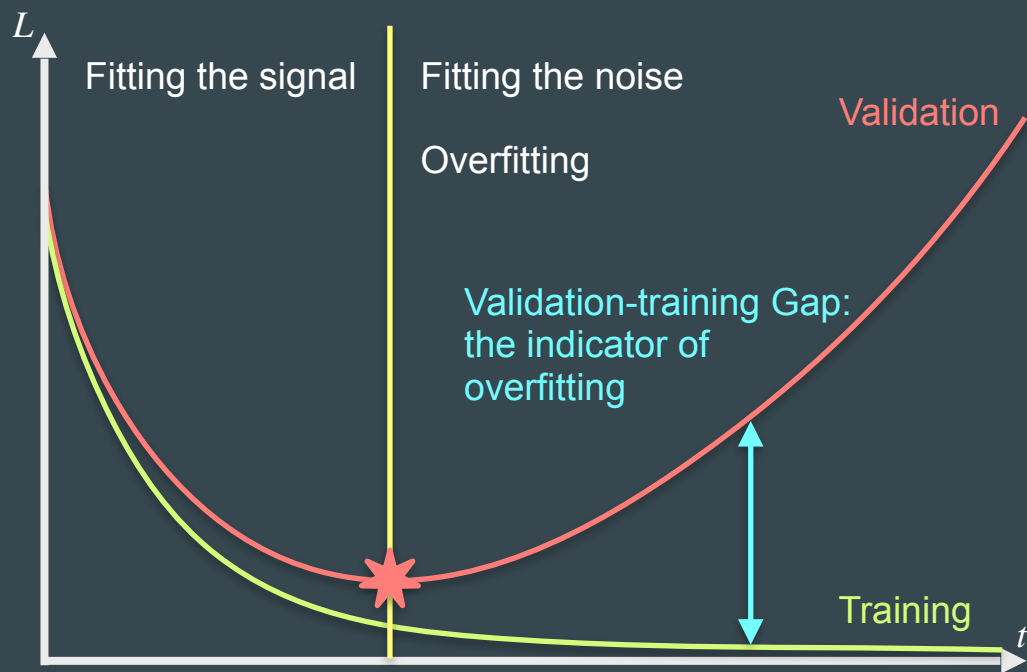
$$\mathbf{w}_{end}^* = (1 - \gamma)\mathbf{w}_{start} + \gamma\mathbf{w}_{end}$$

Two ways:

- γ is constant
- γ is adjusted on-the-fly

Scheduling

Training procedure: how the process goes



The main objective is not to make a zero Train-Valid Gap!

It is to get the best loss/metric value for validation

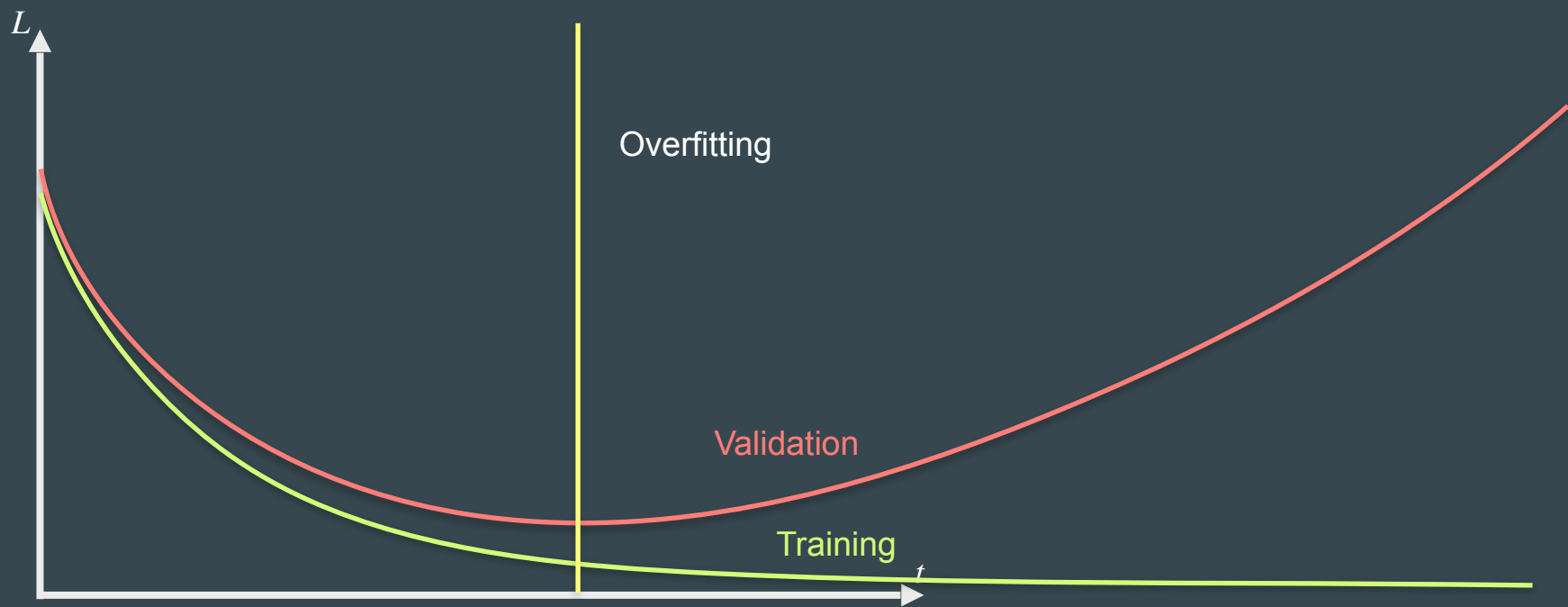
But the Gap is a compass:

- No gap = underfitting
- Big gap = overfitting

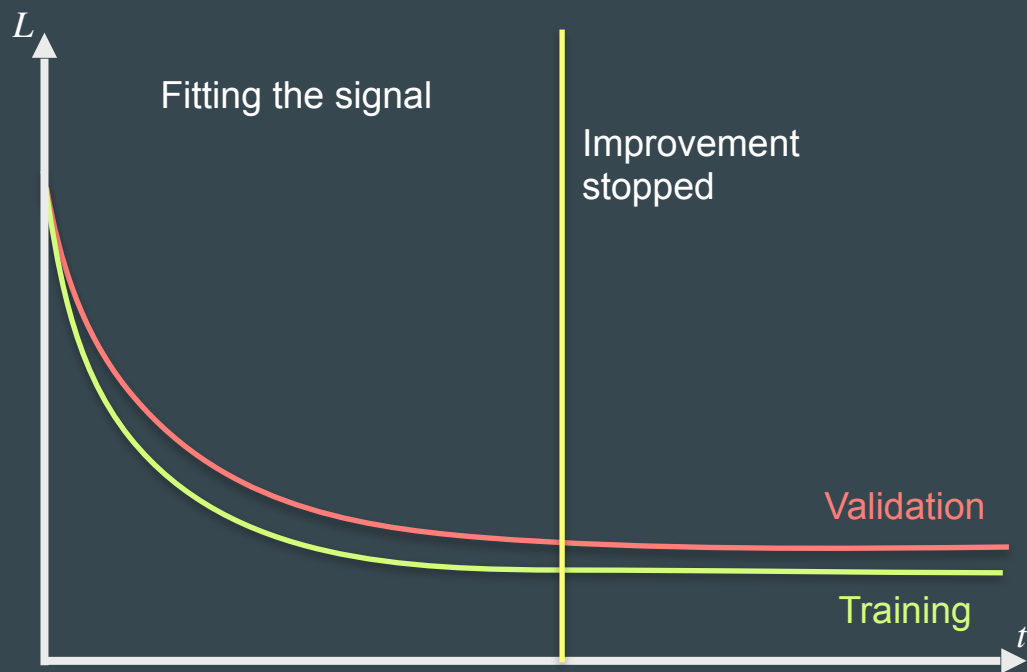
Q: How to stop at the best point?

A: We can save best model and last model

What if we reduce LR?



What if we increase LR?



Q: What's going on?
A: The solution jumps

Q: What's going on?
A: The solution jumps

What if we increase LR?

$$\alpha_t = \frac{\alpha_0}{t}$$

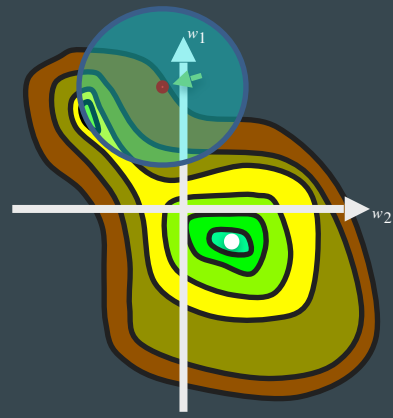
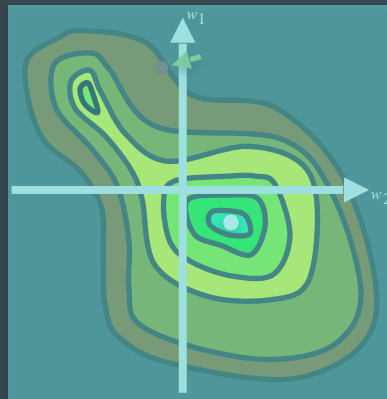
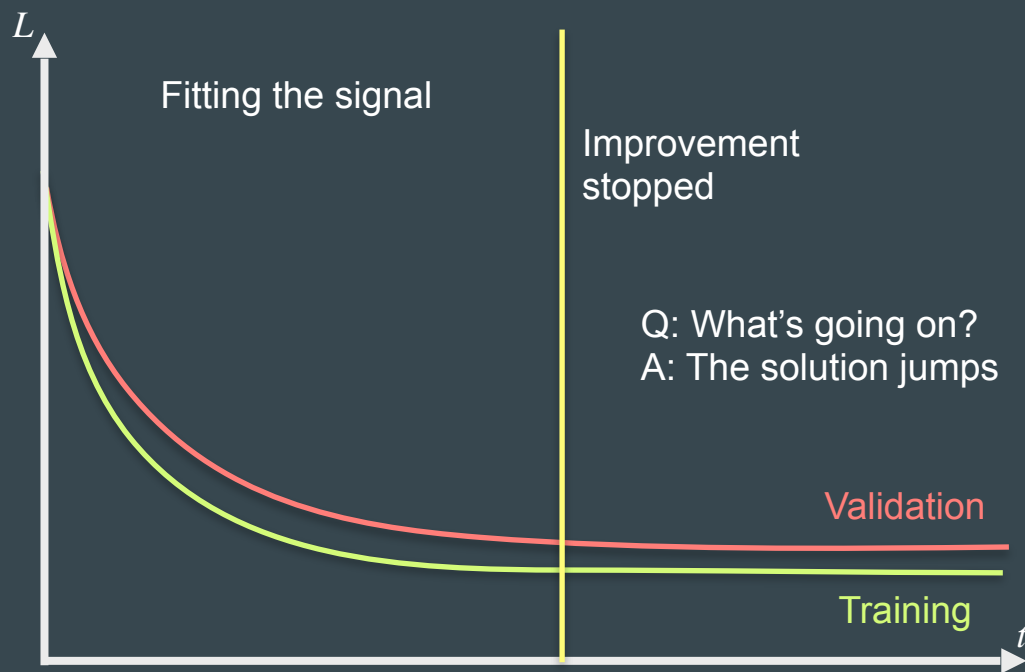
$$\alpha_t = \frac{\alpha_0}{t^2}$$

$$\alpha_t = \frac{\alpha_0}{2^t}$$

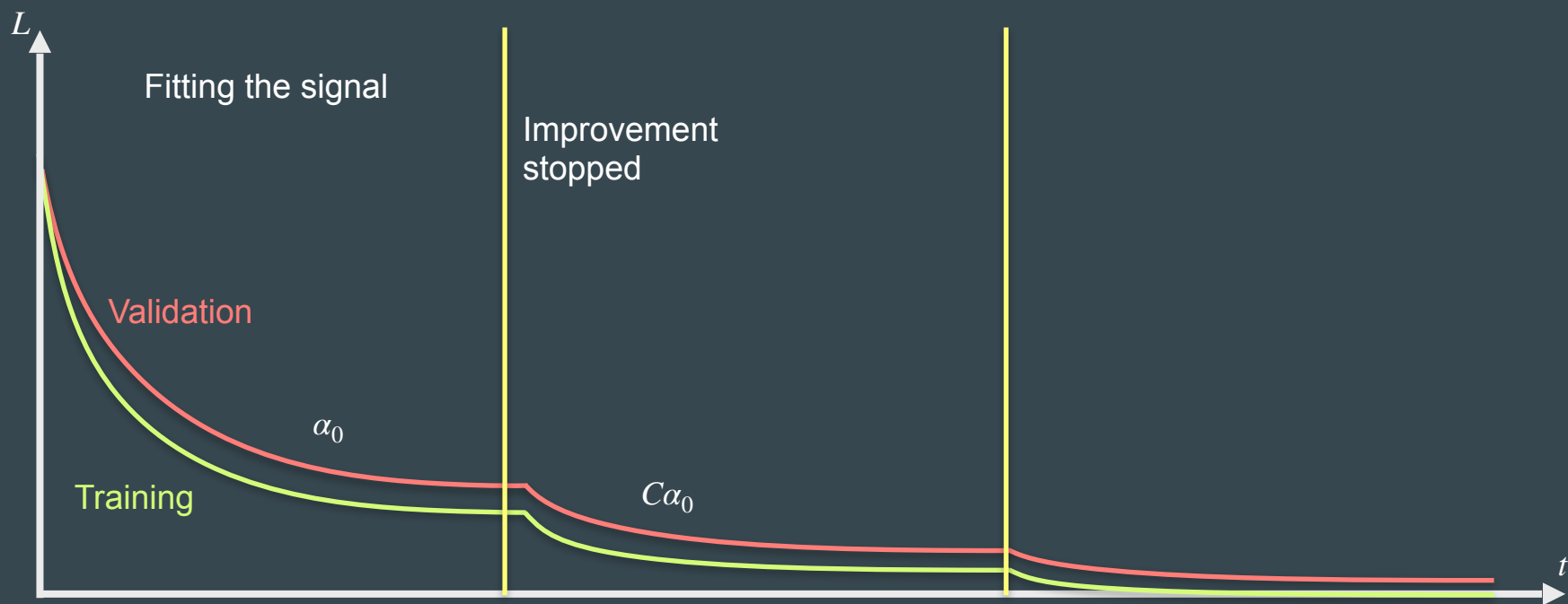
$$\sum_{t=1}^{\infty} \alpha_t = \infty$$

$$\sum_{t=1}^{\infty} \alpha_t = C$$

$$\sum_{t=1}^{\infty} \alpha_t = C$$



ReduceLR On Plateau



Summary

- Gradient Descent:
 - GD
 - SGD
 - SGD with momentum
- RMSprop
 - GD with equal steps
 - With momentum: Adam
- Look Ahead
- Scheduling
 - ReduceLROnPlateau