

2: Matrices and Operations

Mikhail Romanov

Matrix

Matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1N} \\ a_{21} & a_{22} & \dots & a_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1} & a_{M2} & \dots & a_{MN} \end{bmatrix}$$

Table of elements

$$A = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \dots & \mathbf{a}_N \end{bmatrix}$$

Or list of column-vectors

$$A = \begin{bmatrix} - & \mathbf{a}_1 & - \\ - & \mathbf{a}_2 & - \\ & \vdots & \\ - & \mathbf{a}_M & - \end{bmatrix}$$

Or list of row-vectors

$$A = [a_{kl}]$$

Elements indexed by:

- * row index k
- * Column index l

$$A \in \mathbb{R}^{N \times M}$$

A contains $N \times M$
 \mathbb{R} (real numbers)

Matrix Operations

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1N} \\ a_{21} & a_{22} & \dots & a_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1} & a_{M2} & \dots & a_{MN} \end{bmatrix}$$

$$B = \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1N} \\ b_{21} & b_{22} & \dots & b_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ b_{M1} & b_{M2} & \dots & b_{MN} \end{bmatrix}$$

Sin*:

$$\sin A = \begin{bmatrix} \sin a_{11} & \sin a_{12} & \dots & \sin a_{1N} \\ \sin a_{21} & \sin a_{22} & \dots & \sin a_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \sin a_{M1} & \sin a_{M2} & \dots & \sin a_{MN} \end{bmatrix}$$

Root*:

$$\sqrt{A} = \begin{bmatrix} \sqrt{a_{11}} & \sqrt{a_{12}} & \dots & \sqrt{a_{1N}} \\ \sqrt{a_{21}} & \sqrt{a_{22}} & \dots & \sqrt{a_{2N}} \\ \vdots & \vdots & \ddots & \vdots \\ \sqrt{a_{M1}} & \sqrt{a_{M2}} & \dots & \sqrt{a_{MN}} \end{bmatrix}$$

And many others

Sum:

$$A + B = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1N} + b_{1N} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2N} + b_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1} + b_{M1} & a_{M2} + b_{M2} & \dots & a_{MN} + b_{MN} \end{bmatrix}$$

Difference:

$$A - B = \begin{bmatrix} a_{11} - b_{11} & a_{12} - b_{12} & \dots & a_{1N} - b_{1N} \\ a_{21} - b_{21} & a_{22} - b_{22} & \dots & a_{2N} - b_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1} - b_{M1} & a_{M2} - b_{M2} & \dots & a_{MN} - b_{MN} \end{bmatrix}$$

Product*:

$$A \cdot B = \begin{bmatrix} a_{11}b_{11} & a_{12}b_{12} & \dots & a_{1N}b_{1N} \\ a_{21}b_{21} & a_{22}b_{22} & \dots & a_{2N}b_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1}b_{M1} & a_{M2}b_{M2} & \dots & a_{MN}b_{MN} \end{bmatrix}$$

Division*:

$$A \div B = \begin{bmatrix} a_{11} \div b_{11} & a_{12} \div b_{12} & \dots & a_{1N} \div b_{1N} \\ a_{21} \div b_{21} & a_{22} \div b_{22} & \dots & a_{2N} \div b_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1} \div b_{M1} & a_{M2} \div b_{M2} & \dots & a_{MN} \div b_{MN} \end{bmatrix}$$

* Non-orthodox operations. Use with caution! Some mathematicians get insulted.

Matrix Transposal

$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1N} \\ a_{21} & a_{22} & \dots & a_{2N} \\ \vdots & \vdots & & \vdots \\ a_{M1} & a_{M2} & \dots & a_{MN} \end{bmatrix}$

Transposition operation

$$A^T = \begin{bmatrix} a_{11} & a_{21} & \dots & a_{N1} \\ a_{12} & a_{22} & \dots & a_{N2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1M} & a_{2M} & \dots & a_{NM} \end{bmatrix}$$

$$A = [a_{kl}]$$

$$A^T = [a_{lk}]$$

Matrix Product

$$AB = \begin{bmatrix} - & \mathbf{a}_1 & - \\ - & \mathbf{a}_2 & - \\ & \vdots & \\ - & \mathbf{a}_N & - \end{bmatrix} \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 & \dots & \mathbf{b}_M \end{bmatrix} = \begin{bmatrix} \langle \mathbf{a}_1, \mathbf{b}_1 \rangle & \langle \mathbf{a}_1, \mathbf{b}_2 \rangle & \dots & \langle \mathbf{a}_1, \mathbf{b}_M \rangle \\ \langle \mathbf{a}_2, \mathbf{b}_1 \rangle & \langle \mathbf{a}_2, \mathbf{b}_2 \rangle & \dots & \langle \mathbf{a}_2, \mathbf{b}_M \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \mathbf{a}_N, \mathbf{b}_1 \rangle & \langle \mathbf{a}_N, \mathbf{b}_2 \rangle & \dots & \langle \mathbf{a}_N, \mathbf{b}_M \rangle \end{bmatrix}$$

$$A \propto N \times K$$

$$B \propto K \times M$$

$$A\mathbf{x} = \begin{bmatrix} - & \mathbf{a}_1 & - \\ - & \mathbf{a}_2 & - \\ & \vdots & \\ - & \mathbf{a}_N & - \end{bmatrix} \begin{bmatrix} \mathbf{x} \end{bmatrix} = \begin{bmatrix} \langle \mathbf{a}_1, \mathbf{x} \rangle \\ \langle \mathbf{a}_2, \mathbf{x} \rangle \\ \vdots \\ \langle \mathbf{a}_N, \mathbf{x} \rangle \end{bmatrix} = \mathbf{y}$$

$$A \propto M \times N$$

$$\mathbf{x} \in \mathbb{R}^N$$

$$\mathbf{y} \in \mathbb{R}^M$$

Matrix A transforms \mathbf{x} to \mathbf{y} :

$$\mathbf{x} \rightarrow A \rightarrow \mathbf{y}$$

Several multiplications:

$$ABC\mathbf{x} : \mathbf{x} \rightarrow C \rightarrow B \rightarrow A \rightarrow \mathbf{y}$$

Properties

Matrix-vector product is linear:

$$A(\mathbf{x} + \mathbf{y}) = A\mathbf{x} + A\mathbf{y}$$

$$(A + B)\mathbf{x} = A\mathbf{x} + B\mathbf{x}$$

Comes from linearity of
 $\langle \mathbf{a} + \mathbf{b}, \mathbf{y} \rangle = \langle \mathbf{a}, \mathbf{y} \rangle + \langle \mathbf{b}, \mathbf{y} \rangle$

Matrices in product do not commute:

$$AB \neq BA$$

Result does not depend on the order

$$ABC = (AB)C = A(BC)$$

$$ABC = \sum_{m=1}^M a_{nm} \left(\sum_{k=1}^K b_{mk} c_{kl} \right) = \sum_{k=1}^K \left(\sum_{m=1}^M a_{nm} b_{mk} \right) c_{kl}$$

Identity Matrix

$\mathbf{x} \rightarrow A? \rightarrow \mathbf{x}$ Which matrix works like that?

That is what we want

$$A\mathbf{x} = \begin{bmatrix} - & \mathbf{a}_1 & - \\ - & \mathbf{a}_2 & - \\ & \vdots & \\ - & \mathbf{a}_N & - \end{bmatrix} \begin{bmatrix} \mathbf{x} \end{bmatrix} = \begin{bmatrix} \langle \mathbf{a}_1, \mathbf{x} \rangle \\ \langle \mathbf{a}_2, \mathbf{x} \rangle \\ \vdots \\ \langle \mathbf{a}_N, \mathbf{x} \rangle \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} = I$$

Identity matrix

$$IA = A$$

$$AI = A$$

Inverse Matrix

Inverse matrix of A

A^{-1}

$\mathbf{x} \rightarrow A \rightarrow \mathbf{y} \rightarrow A^{-1} \rightarrow \mathbf{x}$

It reverts the result of original matrix

$\mathbf{x} = A^{-1}(A\mathbf{x})$

$A^{-1}A = I$

\mathbf{x} goes to A and the result then to A^{-1}

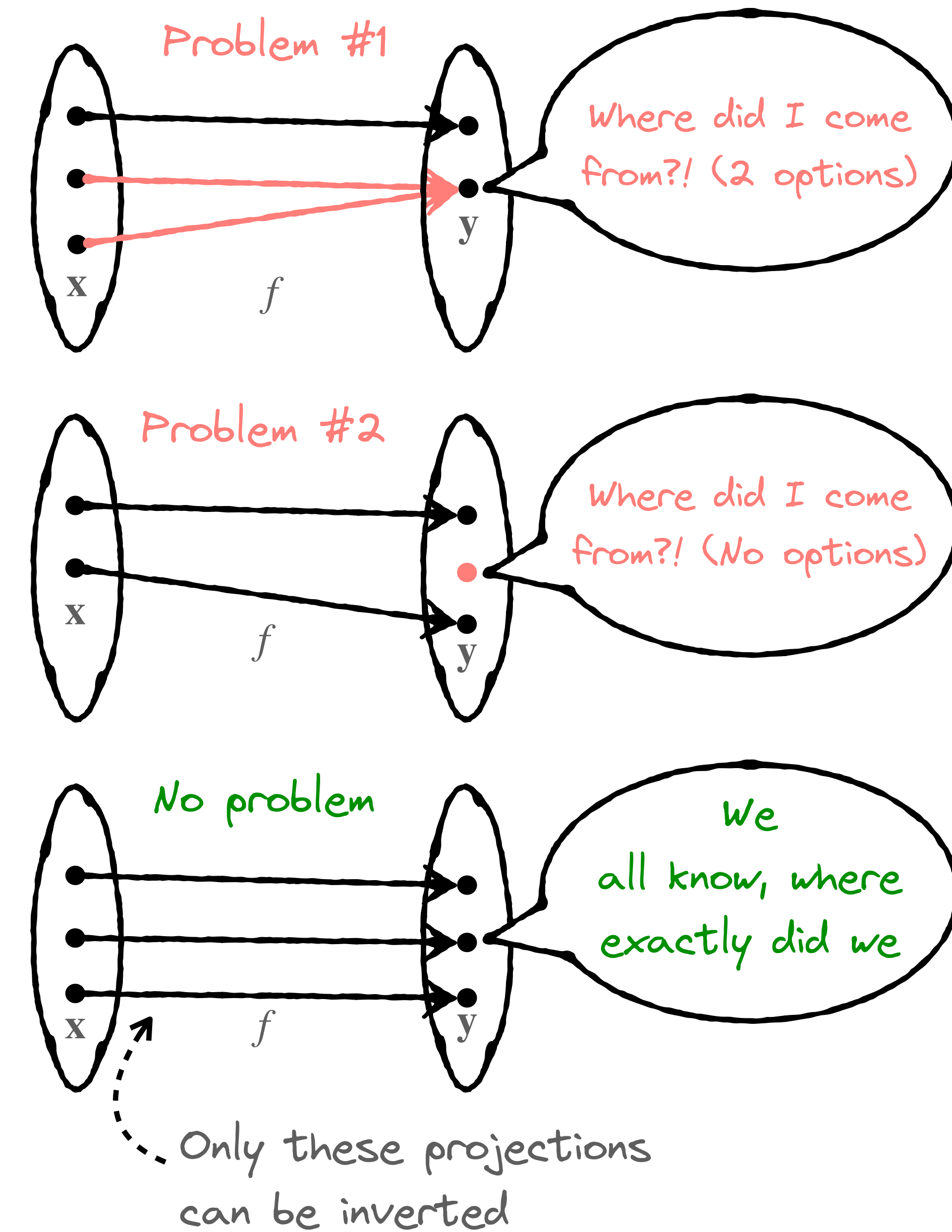
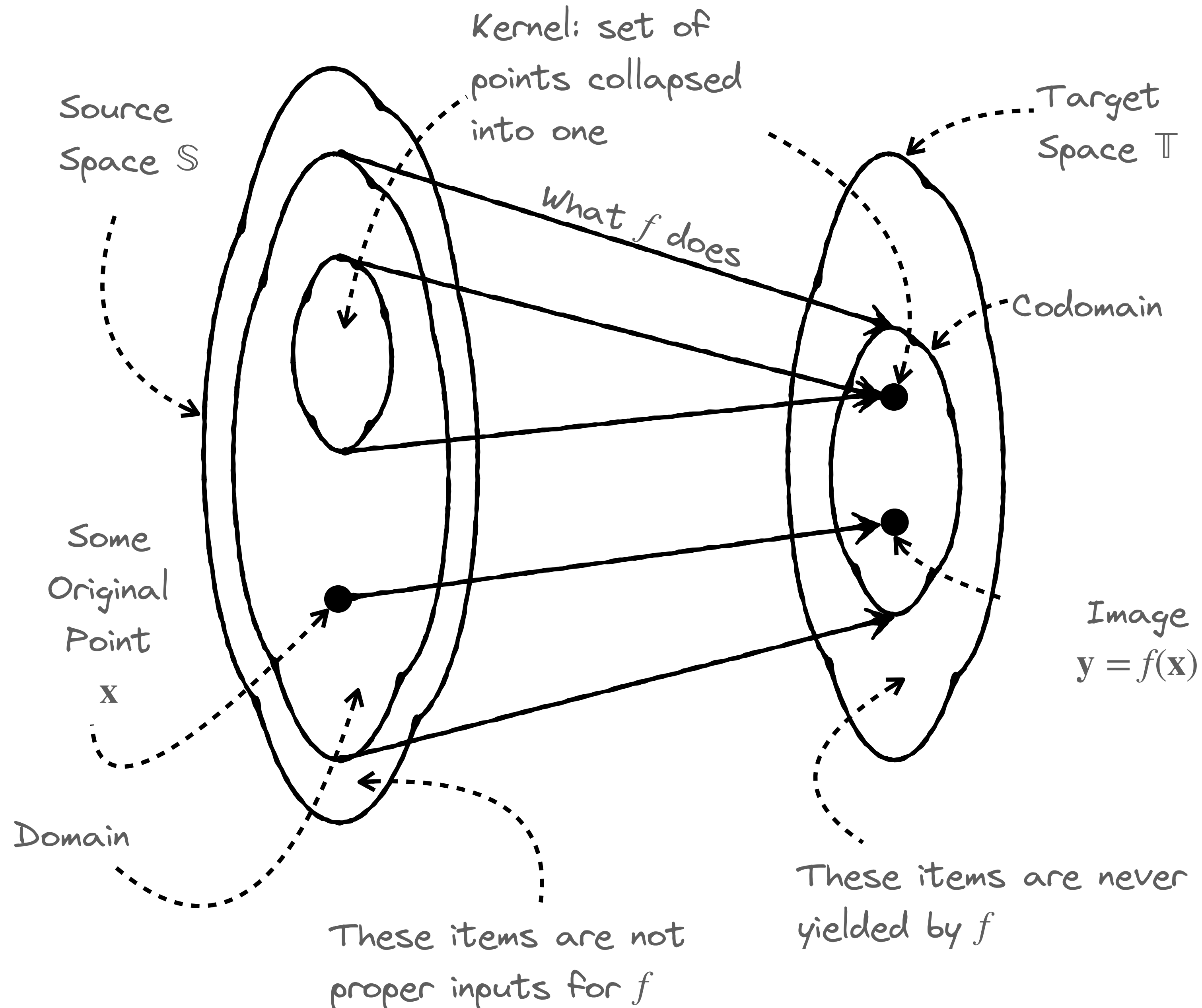
$A^{-1}\mathbf{x} = A^{-1} \underbrace{AA^{-1}} \mathbf{x}$

$AA^{-1} = I$

Take A^{-1} (because we can) And feed it to A and then to A^{-1}

Functions as Transforms

How projections work

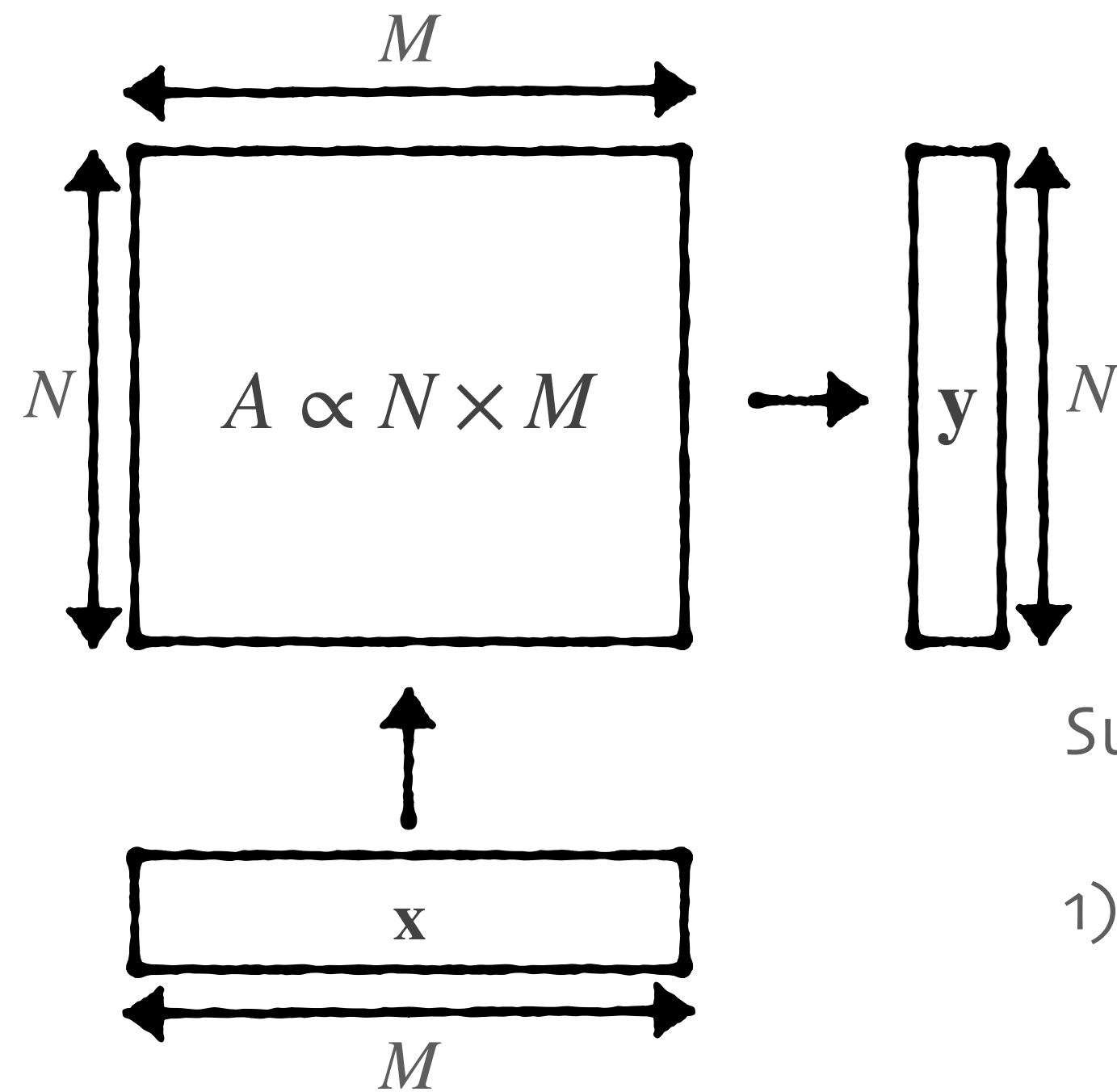


What's the point?

The point is: NOT ALL THE MATRICES HAVE INVERSE!

Matrix A has A^{-1} if it works like case #3!

Otherwise — NO INVERSE (as we cannot resolve the conflicts)



Suppose $A \propto N \times M$

1) If $M \neq N$

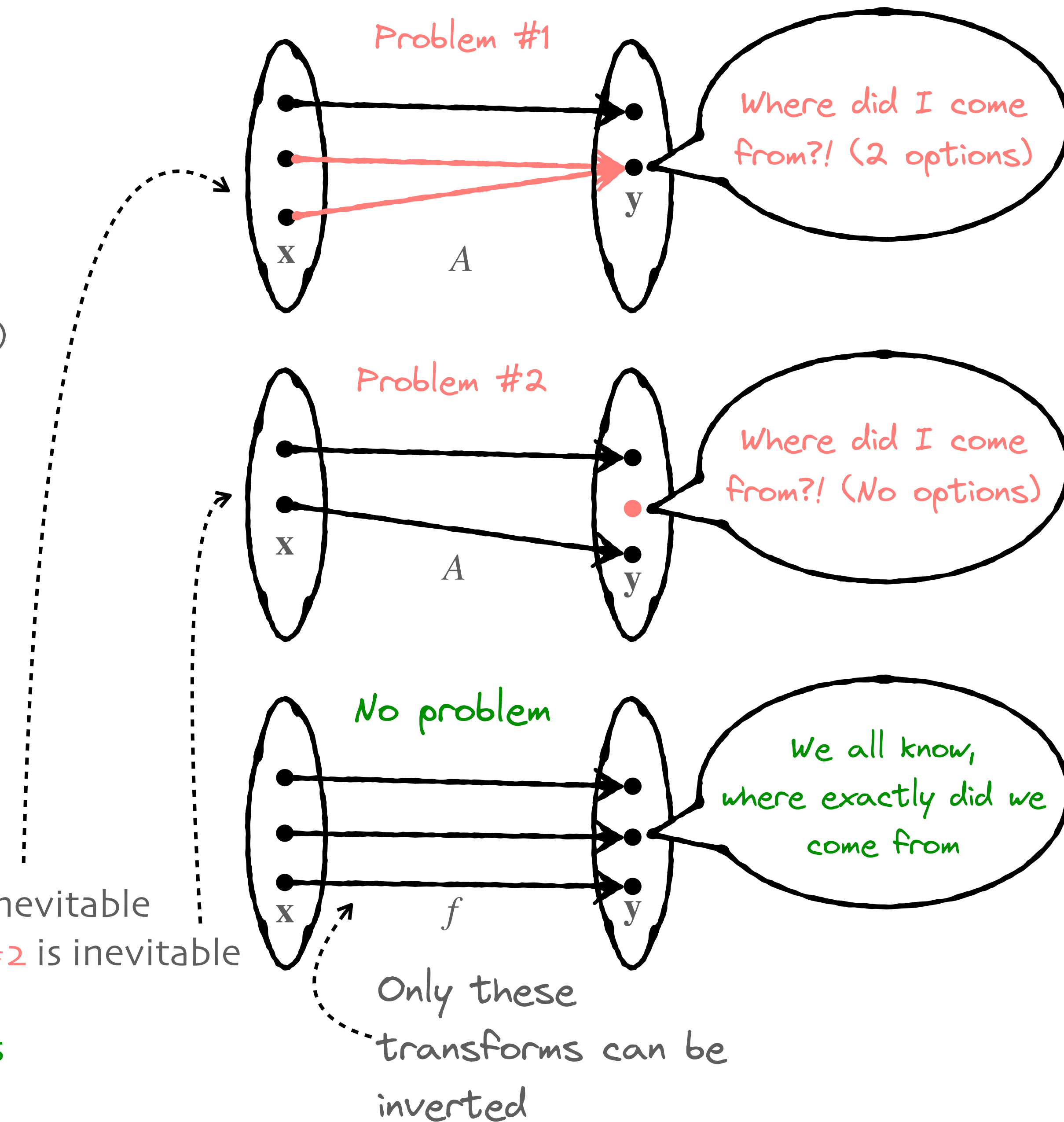
1) If $M > N$, **problem #1** is inevitable

2) If $M < N$, now **problem #2** is inevitable

2) Only when $M = N$, A^{-1} exists

3) But **not always!!**

Not always ... :(



Takeaways

✧ Matrix as table of numbers

✧ Table of values

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1N} \\ a_{21} & a_{22} & \dots & a_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1} & a_{M2} & \dots & a_{MN} \end{bmatrix}$$

$$A = [a_{kl}]$$

$$A \in \mathbb{R}^{N \times M}$$

✧ List of column vectors

$$A = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \dots & \mathbf{a}_N \end{bmatrix}$$

✧ List of row vectors

$$A = \begin{bmatrix} - & \mathbf{a}_1 & - \\ - & \mathbf{a}_2 & - \\ & \vdots & \\ - & \mathbf{a}_M & - \end{bmatrix}$$

✧ Elementwise operations

✧ Unary

$$f(A) = \begin{bmatrix} f(a_{11}) & \dots & f(a_{1N}) \\ \vdots & \ddots & \vdots \\ f(a_{M1}) & \dots & f(a_{MN}) \end{bmatrix}$$

✧ Binary

$$A \odot B = \begin{bmatrix} a_{11} \odot b_{11} & \dots & a_{1N} \odot b_{1N} \\ \vdots & \ddots & \vdots \\ a_{M1} \odot b_{M1} & \dots & a_{MN} \odot b_{MN} \end{bmatrix}$$

✧ Matrix Transposition

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1N} \\ a_{21} & a_{22} & \dots & a_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1} & a_{M2} & \dots & a_{MN} \end{bmatrix}$$

Transposition operation

✧ Matrix product

$$AB = \begin{bmatrix} - & \mathbf{a}_1 & - \\ - & \mathbf{a}_2 & - \\ & \vdots & \\ - & \mathbf{a}_N & - \end{bmatrix} \begin{bmatrix} | & | & \dots & | \\ \mathbf{b}_1 & \mathbf{b}_2 & \dots & \mathbf{b}_M \\ | & | & \dots & | \end{bmatrix} = \begin{bmatrix} \langle \mathbf{a}_1, \mathbf{b}_1 \rangle & \langle \mathbf{a}_1, \mathbf{b}_2 \rangle & \dots & \langle \mathbf{a}_1, \mathbf{b}_M \rangle \\ \langle \mathbf{a}_2, \mathbf{b}_1 \rangle & \langle \mathbf{a}_2, \mathbf{b}_2 \rangle & \dots & \langle \mathbf{a}_2, \mathbf{b}_M \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \mathbf{a}_N, \mathbf{b}_1 \rangle & \langle \mathbf{a}_N, \mathbf{b}_2 \rangle & \dots & \langle \mathbf{a}_N, \mathbf{b}_M \rangle \end{bmatrix}$$

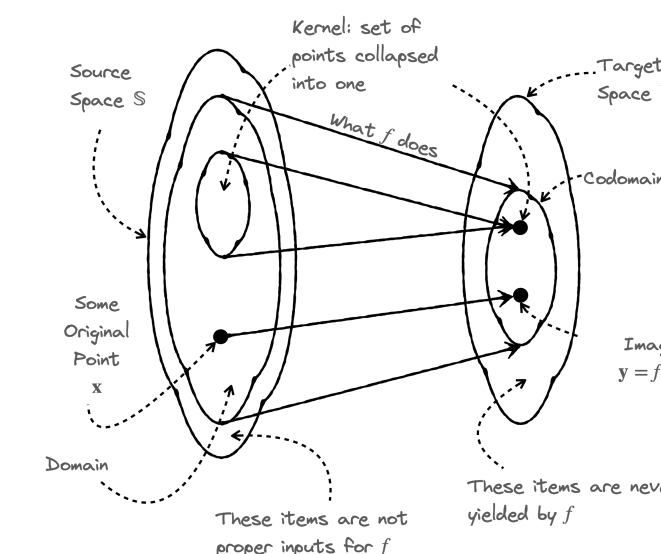
✧ Identity matrix

$$I = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

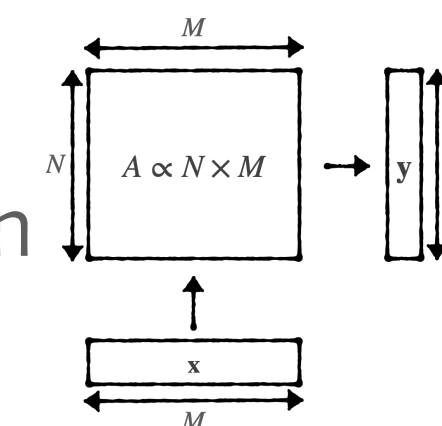
✧ Inverse Matrix

$$A^{-1}A = AA^{-1} = I$$

✧ Transforms



✧ Matrix as transform



✧ Invertible Transforms

