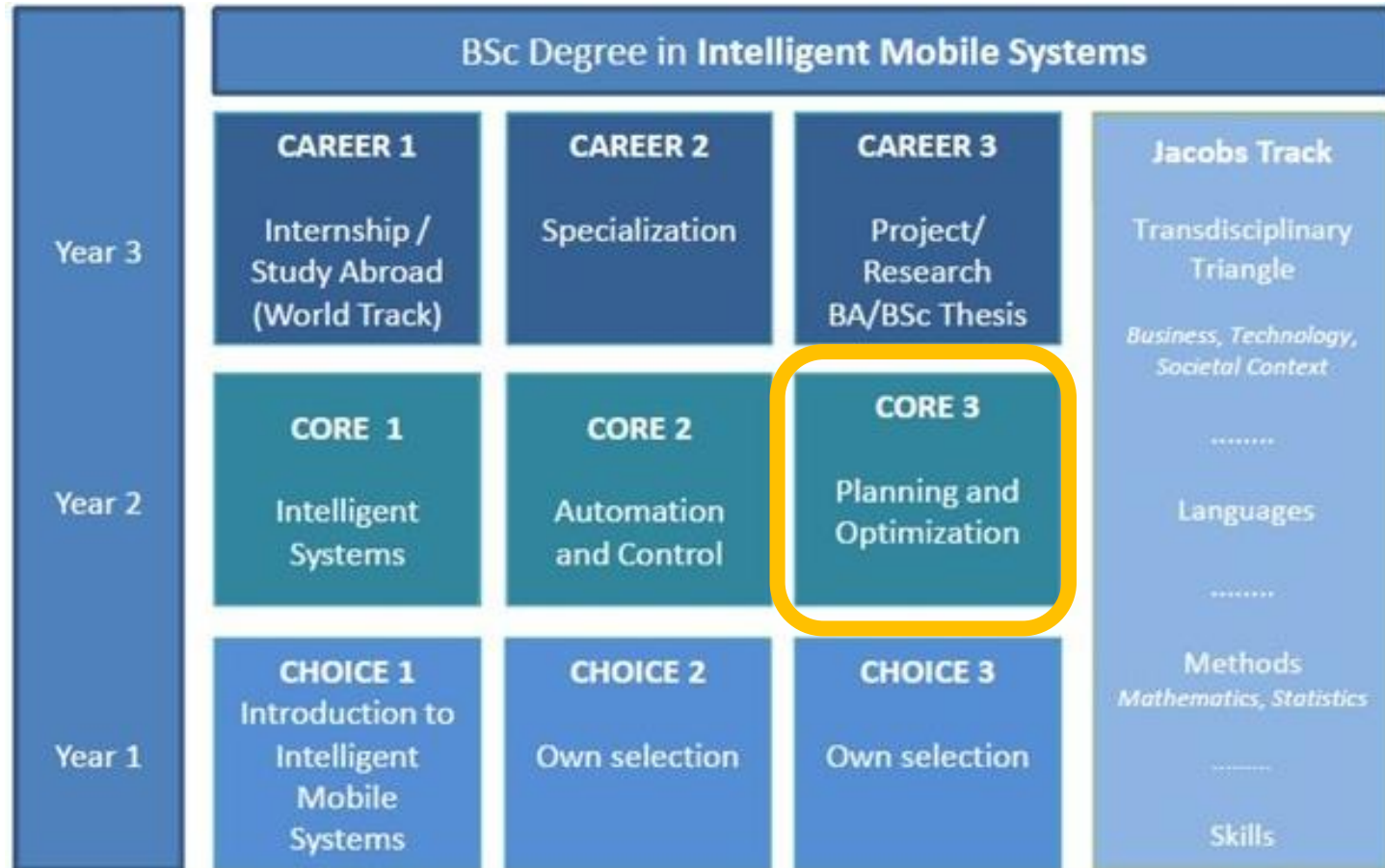


# Artificial Intelligence

**Andreas Birk**  
Jacobs University

# AI @ Jacobs



part of **Intelligent Mobile Systems (IMS)**

# AI @ Jacobs

Year 2 - CORE						45
<i>Take all three modules <u>or</u> replace one with a CORE module from a different study program. <sup>2</sup></i>						
CO22-IntelSys	Module: Intelligent Systems		me			15
CO22-320671	Computer Vision	Lecture	m	3		5
CO22-320311	Robotics	Lecture	m	4		5
CO22-320372	Machine Learning	Lecture	m	4		5
CO23-AutoControl	Module: Automation and Control		me			15
CO23-320301	Control Systems	Lecture	m	3		5
CO26-300312	Embedded Systems Lab	Lab	m	3		5
CO23-320203	Automation	Lecture	m	4		5
CO24-PlanOpt	Module: Planning and Optimization		me			15
CO29-080202	Operations Research	Lecture	m	3		5
CO24-300491	Optimization	Lecture	m	4		5
CO24-320521	Artificial Intelligence	Lecture	m	3		5

note:

Machine Learning (a.o. Artificial Neural Networks, ANN) is covered in an other lecture (Intelligent Systems module)

# Scope of the Lecture

a bit of an ***autonomous systems*** perspective  
(often also denoted as *intelligent autonomous systems*)

- autonomy
  - data-structures & algorithms
  - for acting in “intelligent” ways
- system
  - system integration
  - software architectures

What is „intelligence“?  
Or „autonomy“?

# Background

- meaning of “**intelligence**” has severely changed in the course of history
  - The Roman politician **Marcus Tullius Cicero** (106 - 43 B.C.) forming the noun “*intelligentia*”
  - from a divine property to a marketing label
- the same applies to “**autonomy**”
  - from powercord-free to human property
  - less awareness of the wide range of meanings

# Notions of Autonomy

- a philosophical approach
  - auto = self + nomos = law, rule (Greek)
  - self + decisions => alive + cognition ?!?!
- a technical approach
  - not directly defining/explaining autonomy, but **autonomous systems**
  - computerized systems capable of “intelligent” /“adaptive” performance in “complex” environments/tasks

# Related Terms

- Cognitive Systems
  - was a large EU funding scheme
  - typically more related to Neuro/Cognitive Science
- Cyber Physical Systems
  - started as US funding “brand”
  - more related to Internet of Things (IoT) & Industry 4.0

note:

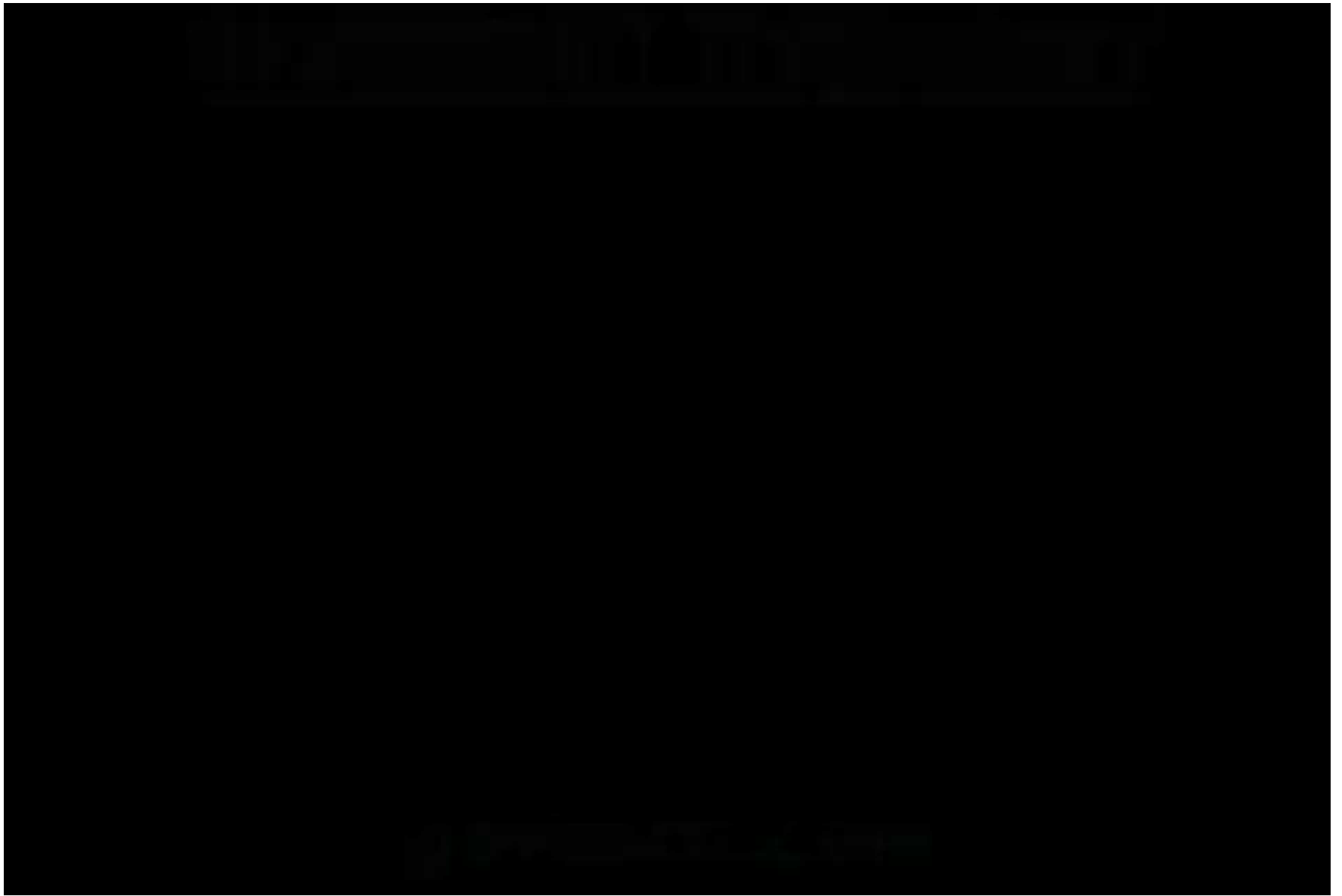
buzzwords with fuzzy boundaries  
and not “scientific” terms



# Machine Intelligence



Deep Blue (1997)  
machine beats human at chess



DARPA Urban challenge (2007)  
autonomous driving in urban scenario

# Machine Intelligence



DARPA Robotic Challenge (2015)  
(semi)autonomous search and rescue scenario

# Machine Intelligence

“intelligence”: we are subjective observers

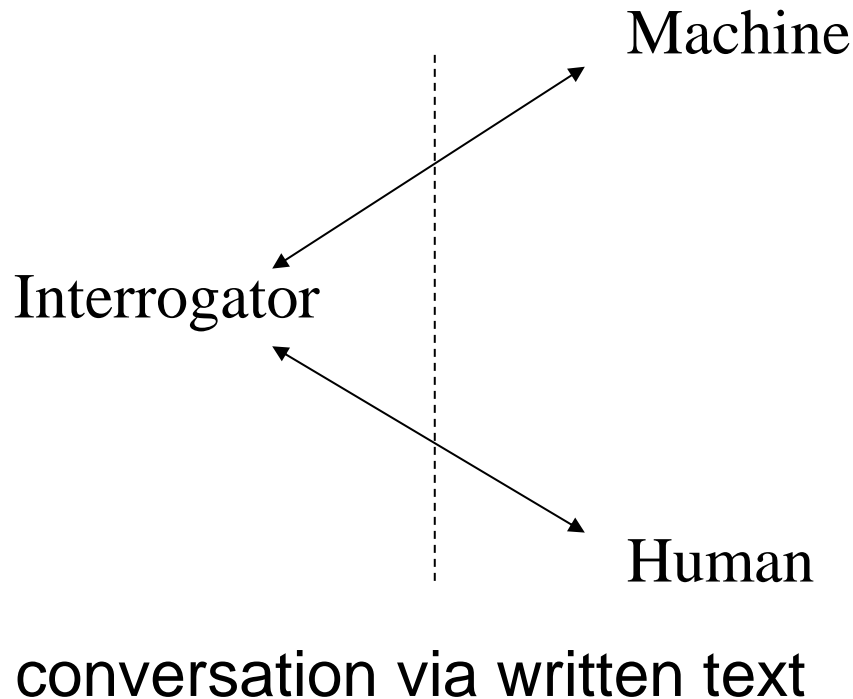
- as how hard do we perceive the problem?
- are adaptive/creative solutions needed?
- how human like is the performance?
- how fast and robust is the system?

# Turing Test (Alan Turing, 1950)

*I propose to consider the question, "Can machines think?" This should begin with definitions of the meaning of the terms "machine" and "think." ... [But] [i]nstead of attempting such a definition I shall replace the question by another, which is closely related to it and is expressed in relatively unambiguous words.*

*The new form of the problem can be described in terms of a game which we call the 'imitation game.'*

# The Imitation Game



*“I believe that in about fifty years’ time it will be possible to program computers, with a storage capacity of about  $10^9$ , to make them play the imitation game so well that an average interrogator will not have more than 70 per cent chance of making the right identification after 5 minutes of questioning”*

-Alan Turing (1950)

# Cheap Trick(s) Solution: Eliza

psychotherapist Joseph Weizenbaum  
programmed in 1966

- keywords and pre-canned responses
  - “Perhaps I could learn to get along with my mother”
  - “Can you tell me more about your family?”
- Parroting
  - “My boyfriend made me come here”
  - “Your boyfriend made you come here?”
- Highly general questions
  - “In what way?”
  - “Can you give a specific example?”

e.g.: <http://www.masswerk.at/elizabot/>

# Machine Intelligence

some persistent topics for “intelligence”

- perceiving and representing “the world”
- reasoning about “the world”
- acting in “the world”
- in some “optimal” way

with “the world” e.g. being

- an abstract game like chess
- a physical environment



# Intelligence as “Optimal” Performance in “the World”

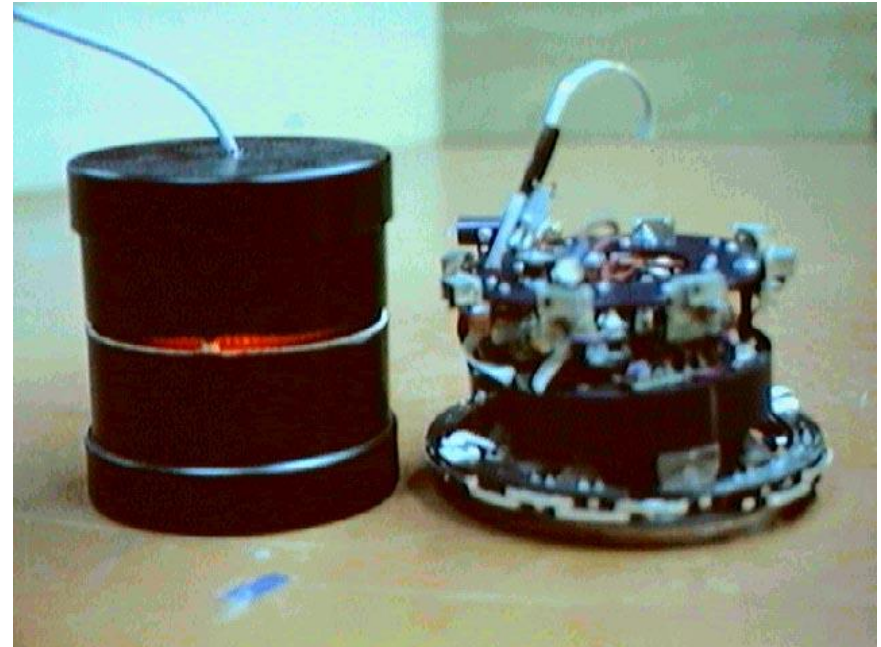
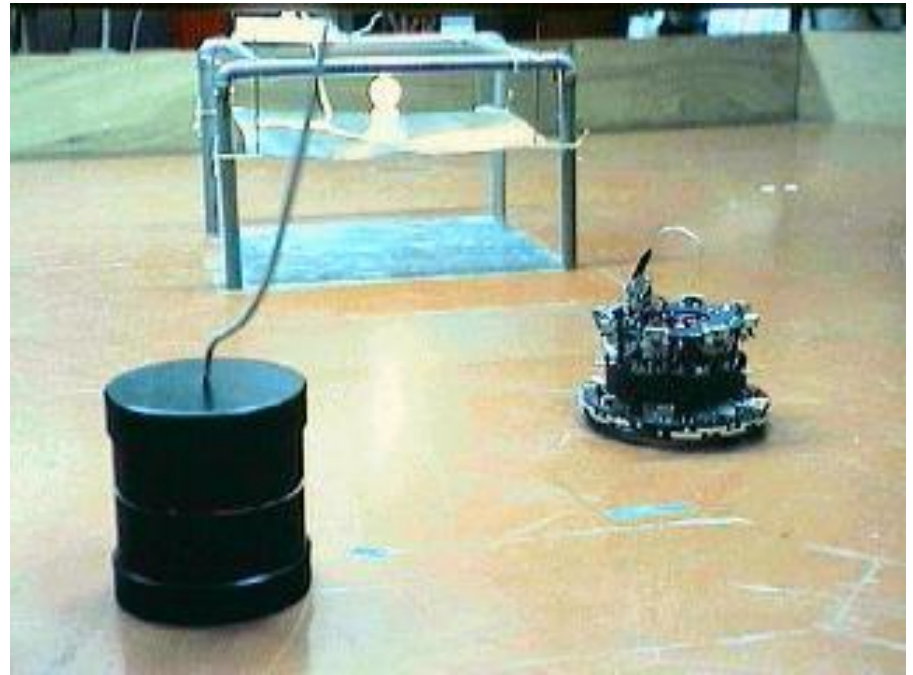
- the role of choice
  - caring about resources [Ross Ashby 52]
  - energy and basic cycles [David McFarland 97]
- systems perspective
  - manipulation and mobility
  - “thinking” (perceive, model, reason)
  - to get and manage resources

# E.g., Robot “Ecosystem”

## basic set-up

[Steels, McFarland 1994]

- “simple” mobile robots
- charging-station
- competitors
  - boxes housing lamps
  - working task



# AI: Two Worlds in One

bad cliché:

- science = understanding things
- engineering = making things work

but it pays to

**understand while/by making things work**

# Two Worlds in One

## **basic research**

- constructive understanding of intelligence
- inseparable aspects of
  - body
  - mind
  - society

## **application-oriented R&D**

### technical devices

- with elaborate I/O (incl. sensor/motor interfaces)
- freed from explicit and permanent human supervision
- being networked

# Scientific roots & relations

# Artificial Intelligence

- changes in emphasis over time
  - symbolic (reasoning) / sub-symbolic (neural nets)
  - “nouvelle” AI: situated, embodied, reactive behavior  
*(more about this soon)*
- always strong ties to robotics
  - Stanford AI Lab (SAIL), robot-arm in ‘68
  - Stanford Research Institute (SRI), mobile robot **Shakey** from ‘66 on
    - cameras, optical range sensors, bumpers
    - radio-linked to a DEC PDP-11, vision & planning
    - over-ambitious goal to get an industrial device

# Robotics

two roots: **science fiction & technical reality**

SF

- Karel Capek (Czech) 1921: “robota”
  - satirical play “Rossum’s Universal Robots(RUR)”
  - robots as superhuman slave workers
- Isaac Asimov, 50s SF-novels: robotics
  - the **three laws of robotics** require high cognitive capabilities of the robots

# Robotics (2)

technological reality:

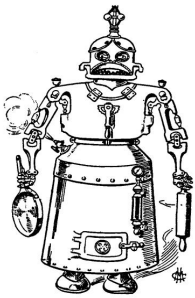
- Robotics Industries Association (RIA)
  - re-programmable multi-functional manipulator
- Robot-arms
  - Unimation (Universal Automation) founded in '58
  - by Joseph Engelberger; technology George Devol
  - first five axis, hydraulic manipulator
- used in production
  - repetitious tasks
  - precision and strength

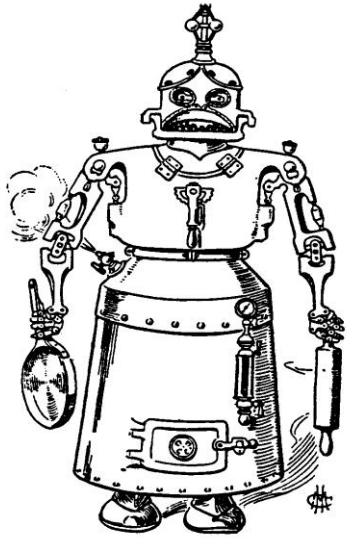


# Robotics (3)

## two notions of a robot

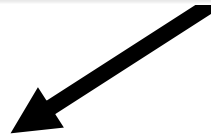
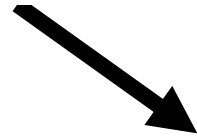
- SF: highly intelligent superhuman
  - industry: dumb, inelegant robot-arm
- are breaking apart and coming closer  
(a.o., due to progresses in AI)





## AI & Robots

*science fiction*  
and  
*reality*  
are getting closer



can you list some AI capabilities needed here?

# Organizational Matters

course page:

**<http://robotics.jacobs-university.de/TMP/AI19/>**

pre-requisites

- CS choice module (strongly recommended)
- IMS choice module (or being CS 3<sup>rd</sup> year)

grading

- final (55%) 04. Dec. 2019
- midterm (45%) 04. Nov. 2019 (tentative)
- **homework (not graded)** exam prep, **discussed in class**

# Organizational Matters

**There is**

- **a strong correlation**
- **between class attendance**
- **and the course grade!!!**

**Past experience showed:**

**You need to attend all classes of this course to pass it!!!**

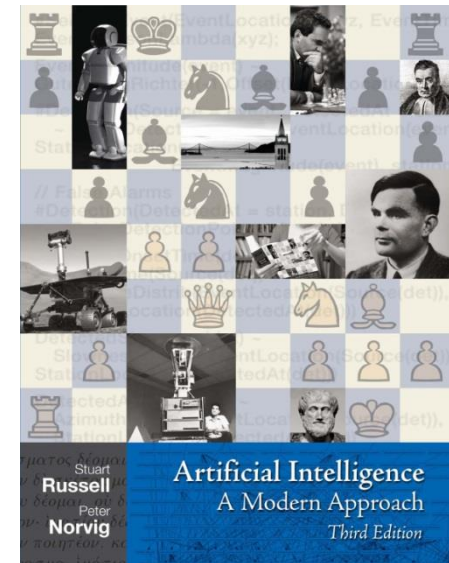
# Content

- “flavors” of AI
  - Goofai vs Nouvelle AI, agent architectures
- behavior-oriented AI
  - behavior programming, scheduling, hierarchies
- problem solving as search
  - simple search, informed search
- domain specific application: path-planning
  - representation, algorithms
- logic
  - propositional logic, first order logic, planning
- imprecision and uncertainty
  - fuzzy logic

# Textbook(s)

Stuart Russell and Peter Norvig

## **Artificial Intelligence: A Modern Approach**



Jean-Claude Latombe  
**Robot Motion Planning**