# TITLE OF PRESENTATION

This is a more detailed subtitle

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# TITLE OF SLIDE

Example text within slide.<sup>1</sup>

estimate of optimal discounted value

$$\underbrace{V(s)}_{\text{state value}} \leftarrow \max_{a} \underbrace{\left(\underbrace{R(s,a)}_{\text{reward}} + \underbrace{\gamma V(s')}_{\text{of next state}}\right)}_{\text{reward discounted value}}$$

<sup>&</sup>lt;sup>1</sup>Mykel J. Kochenderfer and Tim A. Wheeler. *Algorithms for Optimization*. MIT Press, 2019.

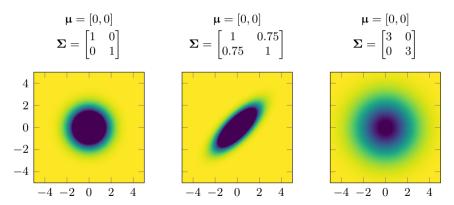
#### JULIA CONSOLE

```
Example Julia code executing at LaTeX compilation time.
julia> using LinearAlgebra

julia> A = Matrix{Int}(I, 3, 3)
3×3 Array{Int64,2}:
    1    0    0
    0    1    0
    0    0    1
```

# PLOTTING

Plot using PGFPlots.jl<sup>2</sup> directly in the TeX file.



<sup>2</sup>https://github.com/JuliaTeX/PGFPlots.jl

# EXAMPLE: BULLET POINTS

- Bullet point
  - Sub-bullet point
- Bullet point
- Bullet point

# REFERENCES

Kochenderfer, Mykel J. and Tim A. Wheeler. Algorithms for Optimization. MIT Press, 2019.