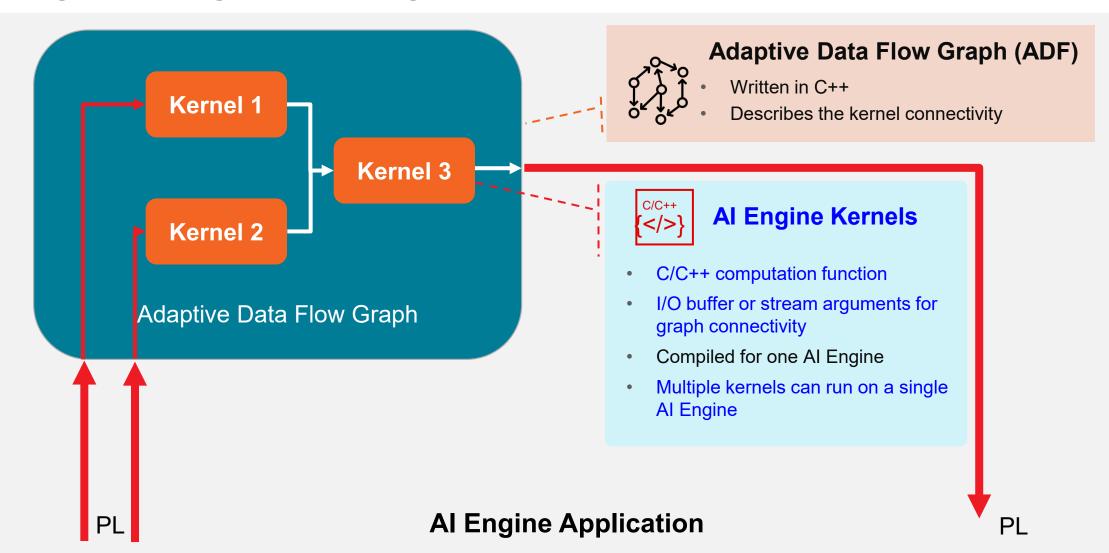
## Al Engine Programming: Kernels and Graphs

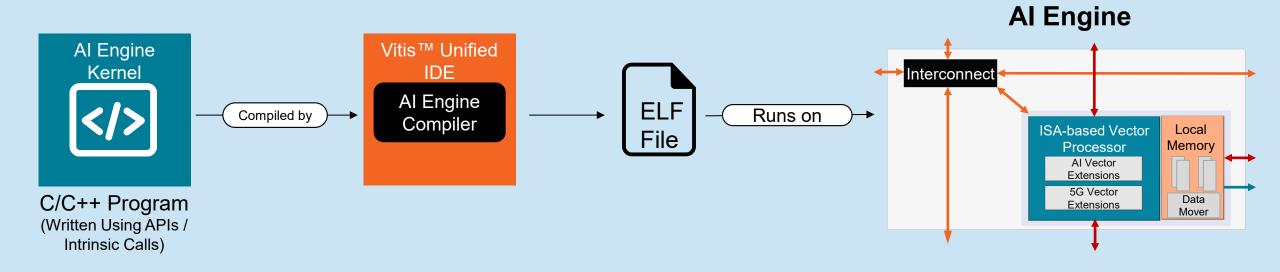
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## **Programming the Al Engine**



#### **Al Engine Kernel Programming**



#### Recommended:

- Use AI Engine APIs for your designs
- Usage of intrinsics must only be considered for situations where performance is required (not covered by AI Engine APIs)



## **Programming the Al Engine Kernel**

Al Engines are an array of VLIW processors with SIMD vector units

Programming the AI Engine array requires understanding of:



Algorithm to be implemented



Capabilities of the Al Engines



Overall data flow between individual functional units

Al Engine array supports three levels of parallelism:

#### SIMD

Multiple elements to be computed in parallel

#### **Instruction-level Parallelism**

Multiple instructions to be executed in a single clock cycle

#### Multicore

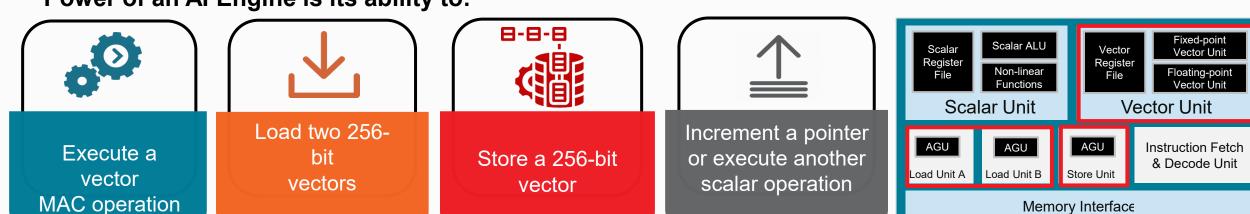
Multiple Al Engines can execute in parallel



## **Programming the Al Engine Kernel**



#### Power of an Al Engine is its ability to:





Al Engine compiler does not perform any auto or pragma-based vectorization



## Al Engine APIs (Based on C++)

Al Engine API – A portable programming interface for Al Engine kernel programming

#### Al Engine API interface:

Targets current and future Al Engine architectures

Provides
parameterizable data
types that enable
generic programming

Implements the most common operations in a uniform way

Easier programming interface as compared to using intrinsic functions

Al Engine APIs are implemented as a C++ header-only library that is translated into optimized intrinsic functions

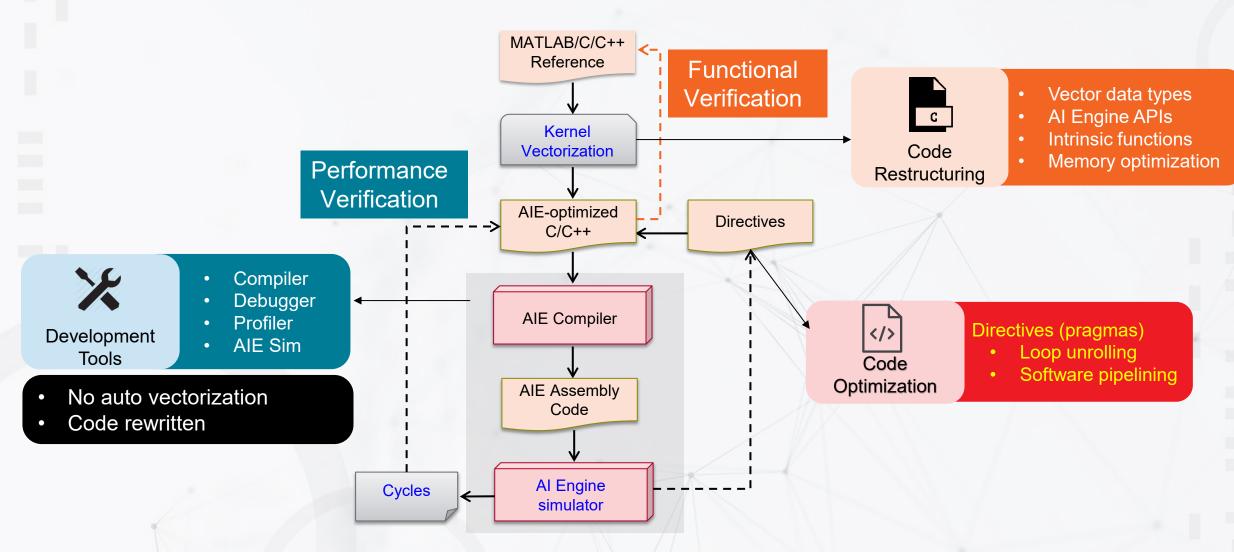
```
#include "aie_api/aie.hpp"
#include "aie_api/aie_adf.hpp"
```



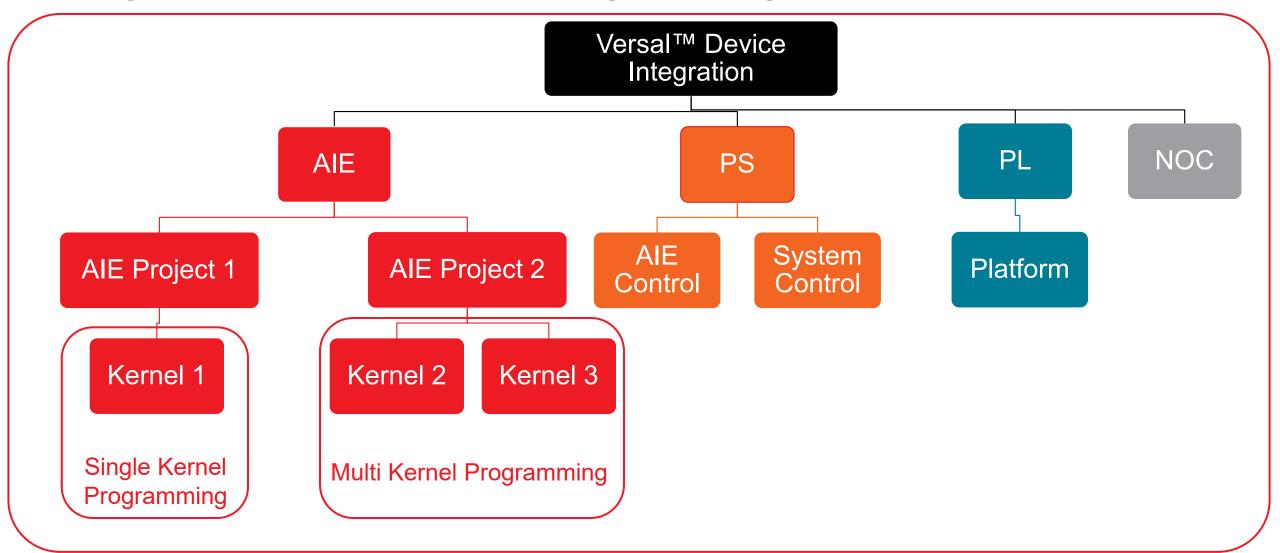
For more details: AI Engine API User Guide (UG1529)

For advanced users that need programming with intrinsics: AI Engine Intrinsics User Guide (UG1078)

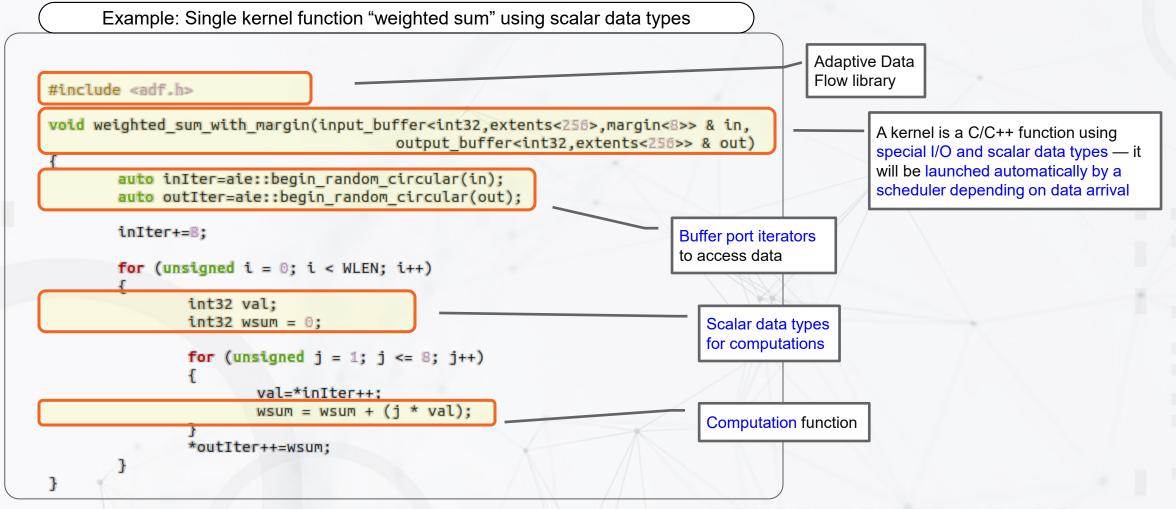
## **Al Engine Programming Flow**



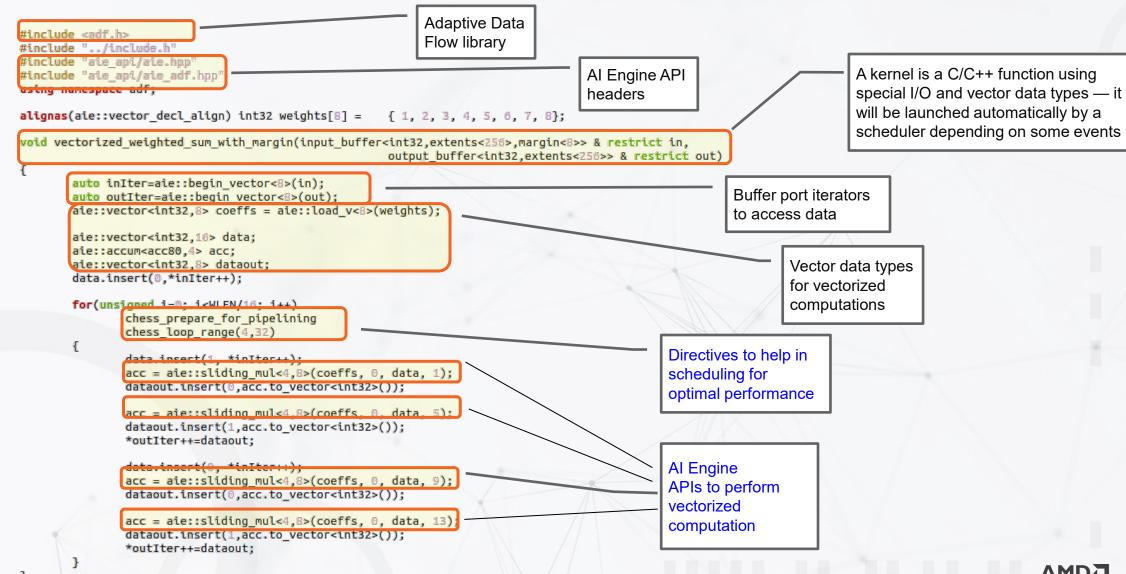
#### Single and Multiple Kernel Programming



## **Kernel Function Program**



## Kernel Function: Code Restructuring and Directives



## **Example: Scalar and Vector Programming**

#### **Scalar Programming Vector Programming** void vect mul(input buffer<int32>& restrict data1, void scalar mul(input buffer<int32>& restrict data1, input buffer<int32>& restrict data2, input buffer<int32>& restrict data2, output buffer<int32>& restrict out) output buffer<int32>& restrict out) auto inIter1=aie::begin vector<8>(data1); auto inIter1=aie::begin(data1); auto inIter2=aie::begin vector<8>(data2); auto inIter2=aie::begin(data2); auto outIter=aie::begin vector<8>(out); auto outIter=aie::begin(out); for(int i=0;i<NUM SAM/8;i++)</pre> for(int i=0;i<512;i++) chess prepare for pipelining int32 a=\*inIter1++; auto va=\*inIter1++; int32 b=\*inIter2++; auto vb=\*inIter2++; int32 c=a\*b; auto vt=aie::mul(va,vb); \*outIter++=c; \*outIter++=vt.to vector<int32>(0);



Cycles: 1055



Cycles: 99



Performance: 10x speed up, 8x throughput (int 32 multiplication)

**Example:** X and  $Z \rightarrow 32$ -bit input vectors

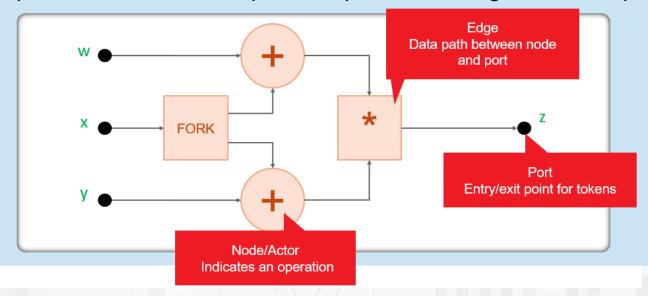
No. of GMACs @ 1 GHz (8 MACs \* 1 GHz clock frequency) = 8 GMAC operations/second



#### **Adaptive Data Flow Graph**

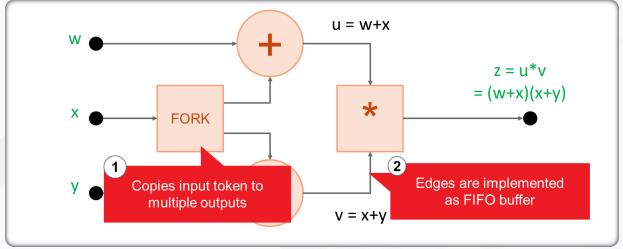
- Written in C++
- Can be compiled and executed using the AI Engine compiler
- Consists of nodes and edges:
  - Nodes [ ] represent compute kernel functions
  - Edges [ \* ] represent data connections
- It is a modified Kahn process network with the Al Engine kernels operating in parallel

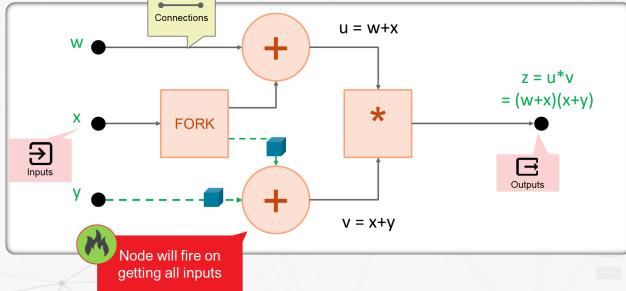
#### A representation of how inputs are processed to generate outputs



## **Adaptive Data Flow Graph**

#### Indicates processing sequence, parallelism, and data dependence

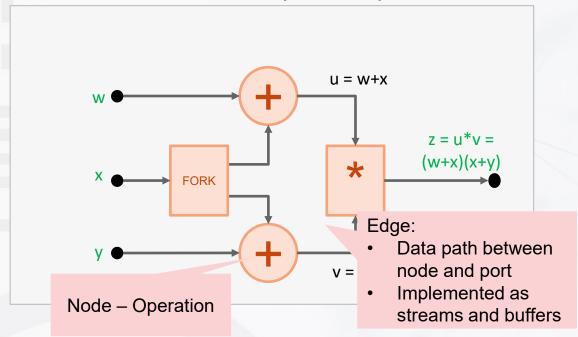






## Adaptive Data Flow Programming for Al Engine

Data Flow Graph Example

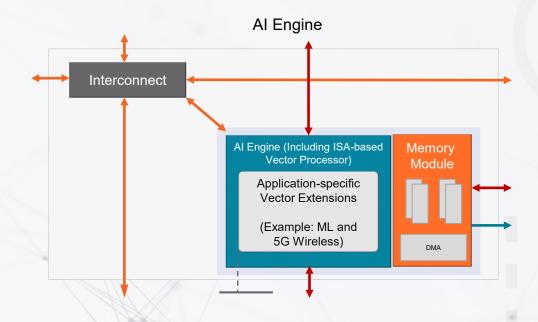


#### **Data Flow Graph**

- Determines execution schedule
- No "instruction pointer" to fire the Al Engines

#### **Algorithm:**

Program – series of sequential operations



#### Al Engine

- Implements nodes/kernels
- Operations with multiple operators
- Can have multiple kernels
- Limitation: instruction memory 16 KB
- 10s to 100s of Al Engines
  - Al Engines either computing or waiting for data

together we advance\_

## Describing a Single Kernel Environment in Graph

```
#include "aie kernel.h"
                                                             Adaptive Data
#include "include.h"
#include <adf.h>
                                                             Flow library
using namespace adf;
                                                                             Al Engine application
class FirstGraph : public adf::graph
                                                                             described as a graph:
                                                                             Class declaration
private:
  adf::kernel k;
                                               Single kernel declaration
public:
  adf::input plio pl in;
  adf::output plio pl out:
                                                                      I/Os of the graph
  FirstGraph()
    pl_in = adf::input_plio::create("PLIO_In", plio_32_bits, INPUT_FILE, 250.0);
    pl out = adf::output plio::create("PLIO Out", plio 32 bits, OUTPUT FILE, 250.0);
    k = adf::kernel::create(vectorized weighted sum with margin);
    adf::connect< >(pl_in.out[0], k.in[0]);
    adf::connect< >(k.out[0], pl out.in[0]);
    adf::source(k) = "aie kernel/weighted sum.cc";
    adf::runtime<ratio>(k) = 0.9;
```

Creation of a virtual platform:

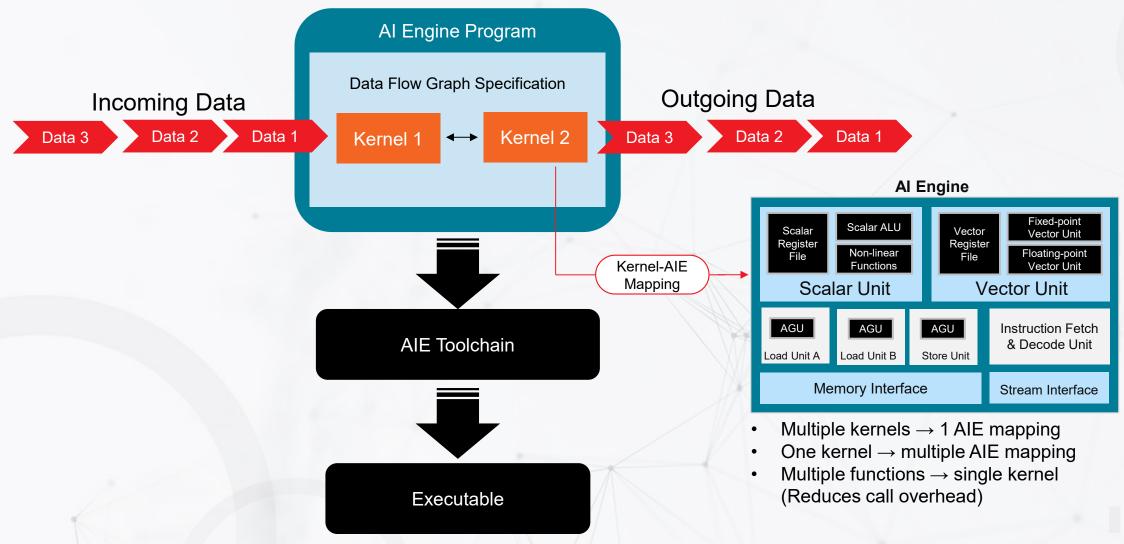
- Input test vector file
- Output vector file
- Connection of the graph

The constructor of the graph describes all the connections and some other parameters

For single kernel programming this section is very simple

**}**;

## **Multiple Kernel Programming**



## **Data Flow Graph for Multiple Kernels**

Derived from adf::graph

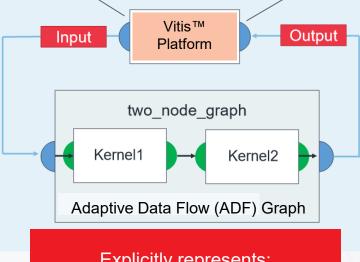
Loaded once on reset or loaded dynamically

Edges will be replaced by streams and buffer

Use blocking read and non-blocking write

Model extensions for synchronized data, double buffers, etc.

Schedule, interleave, parallelize the processes in any order C/C++ kernels OpenCL™ kernels RTL kernels Target platform using Vitis compiler I/O can connect to:



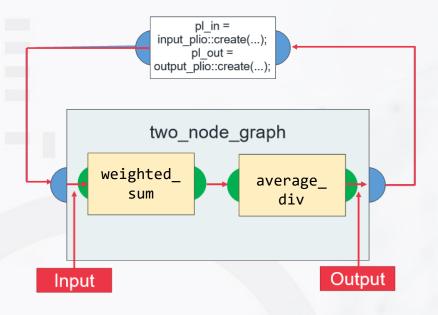
#### Explicitly represents:

- Compute block
- Data flow

Only risk: Deadlock due to blocking read/write



#### **Graph Code for Multiple Kernels**



Define application graph class in header file

Add Adaptive Data Flow (ADF) library and include the kernel function prototypes

Define graph class
Use objects defined in the adf
name space

Declare the top-level ports to the graph class

Declare the kernels

```
#include <adf.h>
#include "kernels.h"
using namespace adf;
class simpleGraph : public
       adf::graph {
      public:
// Declare external ports
     input plio in;
     output plio out;
  Declare kernels
     adf::kernel k1;
     adf::kernel k2;
```

## Kernel Instantiation and Connections in graph.h

#### Kernels:

Ordinary C/C++
functions

- Return void
- Use special data types

#### kernel::create

To instantiate the first and second C++ kernel objects

#### **Example: Two-node application implemented on Al Engines**

```
class simpleGraph
                    public adf graph {
public
  input plio in;
  output plio out;
  // Declare kernels
        adf::kernel k1;
        adf::kernel k2;
 simpleGraph() {
   // Bind a function to each of the declared kernels
       = adf::kernel::create(weighted sum);
      = adf::kernel::create(average div);
 // create nets to connect kernels and IO ports
     adf::connect<> net0 (pl in.out[0], k1.in[0]);
     adf::connect<>net1 (k1.out[0], k2.in[0]);
     adf::connect<>net2 (k2.out[0], pl out.in[0]);
```

## Create connection between ports and kernels



Connectivity information added in a data flow graph

Ports are referred to by indices



#### **Runtime Ratio Constraint**

Al Engine Utilization Attribute

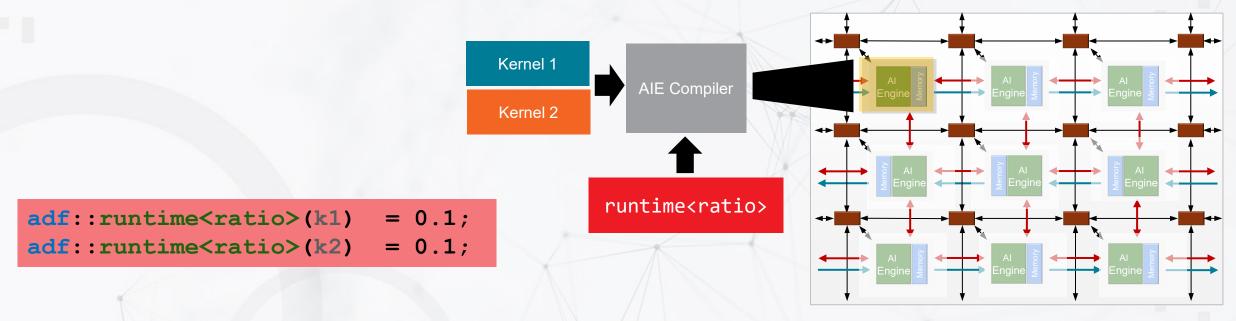
Cycle budget for an application is typically fixed

Ratio of the kernel runtime compared to cycle budget (between 0 and 1)

Cycle budget and function runtime can be affected when changing frame size

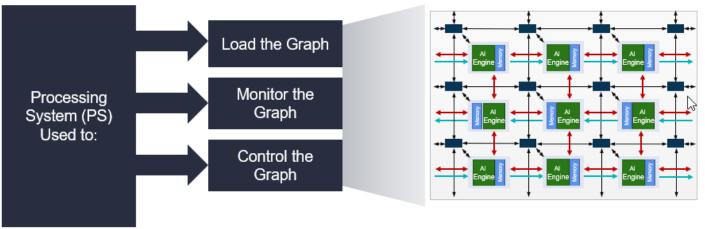
Sets specific AI Engine usage for a kernel

Ratio of the number of cycles taken by one invocation





**Graph Control API** 



Graph base class provides a number of API methods

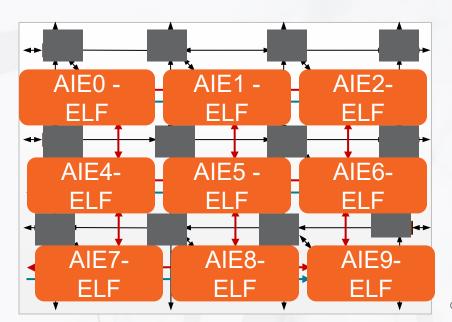
Control initialization and execution of the graph

```
simpleGraph mygraph;
int main(void) {
 mygraph.init();
 mygraph.run(1);
 mygraph.end();
  return 0;
```

```
class simpleGraph : public adf::graph {
      public:
       // Declare external ports
      input plio in;
      output plio out;
      // Declare kernels
      adf::kernel k1;
      adf::kernel k2;
```

#### **Graph Control API**

```
simpleGraph mygraph;
int main(void) {
   mygraph.init();
   mygraph.run(1);
   mygraph.end();
   return 0;
}
```



Initialize the Al Engines

init() method loads the graph to the Al Engine
array at pre-specified Al Engine tiles

- Loads ELF binaries for each Al Engine
- Configures the stream switches for routing
- Configures the DMAs for I/O
- Leaves the processors in a disabled state

Run the AIE Programs

run() method starts the graph execution by enabling the processors

End AIE Programs end() method waits until all the processors reach the end of their respective (local) main execution

Disables the graph execution



## **Graph Control API: Iterative Control**

#### **API** wait()

Calling *run* back-to-back without an intervening *wait* to finish that run can have an unpredictable effect

 run() API modifies the loop bounds of the active processors of the graph

If there is not enough data for the input, the simulation will hang

#### Specify #iterations in the main program

```
X
```

- Used to wait for the first run to finish before starting the second run
- Has the same blocking effect as end
- Allows re-running the graph again without having to re-initialize it



## **Graph Control API: Timed Control**

**Timed execution model** is suitable for testing multi-rate graphs

There are variants of the wait() and end() APIs specifying a cycle timeout

This is the number of AI Engine cycles before disabling the processors and returning

**Blocking condition** does not depend on any graph termination event

Graph can be in an arbitrary state

#### Specify #cycles in the main program

## Describing a Multiple Kernel Environment in a Graph

```
Step 1: Add the Adaptive Data Flow (ADF) library and
#include <adf.h>
using namespace adf:
                                                                              include the kernel function prototypes
class simpleGraph : public adf::graph
                                                                              Step 2: Define your graph class
private:
       adf::kernel k1:
       adf::kernel k2:
public:
                                                                              Step 3: Declare the top-level ports
       input plio pl in;
       output plio pl out;
simpleGraph()
                                                                              Step 4: Specify the input & output files to the I/O ports
   pl_in = input_plio::create("PLIO_InO", plio_32_bits, INPUT_FILE, );
  pl out = output plio::create("PLIO Outo", plio 32 bits, OUTPUT FILE, );
                                                                              Step 5: Declare the kernels
       k1 = kernel::create(weighted sum with margin);
       k2 = kernel::create(average div);
                                                                              Step 6: Connect the ports for the kernels k1 and k2
       adf::connect <> net0 (pl in.out[0], k1.in[0]);
       adf::connect <> net1 (k1.out[0], k2.in[0]);
       adf::connect <> net2 (k2.out[0], pl_out.in[0]);
                                                                              Step 7: Attach the source to the kernels
       adf::source(k1) = "kernels/weighted sum.cc";
       adf::source(k2) = "kernels/average_div.cc";
                                                                              Step 8: Sets the Al Engine utilization
       runtime<ratio>(k1) = 0.1:
       runtime<ratio>(k2) = 0.1;
```

#### **Test Bench Description**

A graph object **mygraph** is declared using a pre-defined graph class called **simpleGraph** 

In the main application, this graph object is:

- Initialized
- Run
- Terminated

```
init run end

Load the Execute End the graph graph
```

```
project.cpp
  #include "kernels.h"
  #include "graph.h"
2 simpleGraph mygraph;
  int main(void) {
    mygraph.init();
    mygraph.run();
    mygraph.end();
    return 0;
```

#### **Recommended Project Directory Structure**

- All the ADF graphs must be located in a header file
- Multiple ADF graph definitions can be included in the same header file
- Class header file should be included in the main application
- · All headers must be self-contained
  - Include all the other necessary header files

 There should be no dependencies in the order that the header files are to be included

#### Resources

• Overview • Al Engine Kernel and Graph Programming Guide (UG1079) • Reader • AMD Technical Information Portal

# AMDI