

رقم الماتري

1	2	3	3	3	Δ	4	4
2	2	2	Σ	4	4	√	√
2	2	3	Σ	Δ	√	√	4
2	3	3	3	4	√	4	4
3	Σ	Δ	4	Δ	Σ	Σ	Δ
2	3	Δ	Δ	Σ	Σ	Σ	Δ
2	Σ	Σ	Σ	Σ	2	3	Σ
3	Σ	Σ	3	3	2	1	Σ

$$S = L - 1 - r$$

$$L = \Lambda \Rightarrow S = V - r \Rightarrow \text{digital negative (a)}$$

4	Δ	Σ	Σ	Σ	2	1	1
Δ	Δ	Δ	2	1	1	0	0
Δ	Δ	Σ	2	2	0	0	1
Δ	Σ	Σ	Σ	1	0	1	1
Σ	2	2	1	2	3	3	2
Δ	Σ	2	2	3	3	3	2
Δ	3	3	3	3	Δ	Σ	3
Σ	3	3	Σ	Σ	Δ	4	3

⇒ digital negative image

$$1 = 001 \quad 4 = 100 \quad 7 = 111$$

$$2 = 010 \quad 5 = 101$$

$$3 = 011 \quad 6 = 110$$

first bit plane ⇒
(bit plane 0)

1	0	1	1	1	1	0	0
0	0	0	0	0	0	1	1
0	0	1	0	1	1	1	0
0	1	1	1	0	1	0	0
1	0	1	0	1	0	0	1
0	1	1	1	0	0	0	1
0	0	0	0	0	0	1	0
1	0	0	1	1	0	1	0

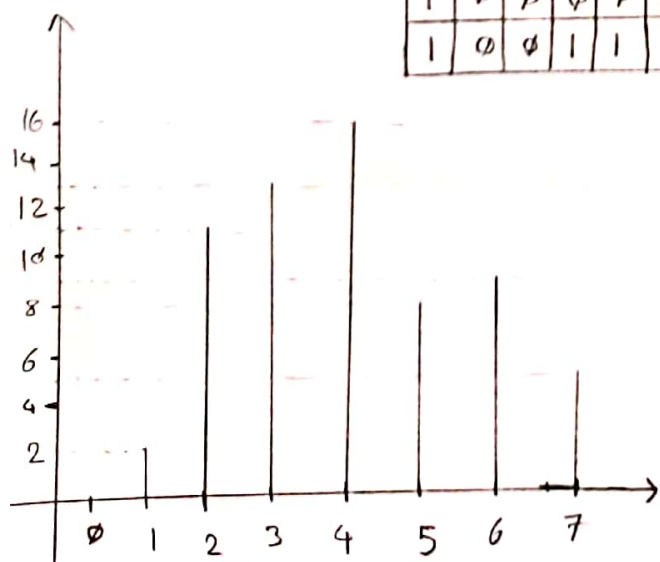
bit planes (b)

second bit plane
(bit plane 1) ⇒

0	1	1	1	1	0	1	1
1	1	1	0	1	1	1	1
1	1	1	0	0	1	1	1
1	1	1	1	1	1	1	1
1	0	0	1	0	0	0	0
1	1	0	0	0	0	0	0
1	0	0	0	0	1	1	0
1	0	0	1	1	1	0	0

third bit plane (bit plane 2)

0	0	0	0	0	1	1	1
0	0	0	1	1	1	1	1
0	0	0	1	1	1	1	1
0	0	0	0	1	1	1	1
0	1	1	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	1	1	1	0	0	1
0	1	1	0	0	0	0	1

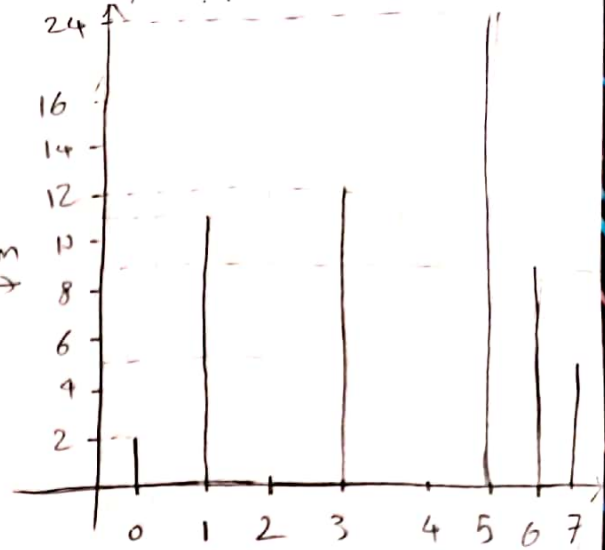


histogram (c)

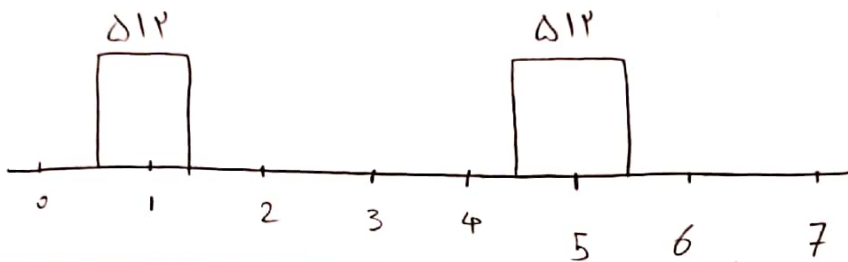
0	1	3	3	3	5	4	4
1	1	1	5	4	4	7	7
1	1	3	5	5	7	7	4
1	3	3	3	4	7	4	4
3	5	5	4	5	5	5	5
1	3	5	5	5	5	5	5
1	5	5	5	5	1	3	5
3	5	5	3	3	1	0	5

تسوية
equalize
شدة

histogram



تسوية
شدة



تسوية 19

equalize

Pixel	0	1	2	3	4	5	6	7
No of Pixel	0	12	0	0	0	12	0	0
$\sum_{j=0}^n n_j$	0	12	12	12	12	24	24	24
$\frac{\sum_{j=0}^n n_j}{n}$	0	$\frac{12}{24} = \frac{1}{2}$	$\frac{1}{2}$	$\frac{1}{2}$	$\frac{1}{2}$	1	1	1
s_k	0	Σ	Σ	Σ	Σ	√	√	√

تسوية شدة
بقيمة 0

$$S = T(r_k)$$

Pixel Value	mapping value	z_k	$G(z_k)$
0	0	0	0
1	0	1	4
2	1	2	4
3	3	3	4
4	5	4	4
5	5	5	7
6	6	6	7
7	7	7	7

$$T(r_k) = G(z_k)$$

$$z_k = G^{-1}(T(r_k))$$

$$G(z_k) = s_k \geq 0$$

$$Pr = \frac{e^r - 1}{e - 2} \quad r \in [0, 1] \rightarrow \text{histogram of image}$$

h =

$$T(r) = \int_{w=0}^1 Pr(w) dw = \int_{w=0}^1 \frac{e^w - 1}{e - 2} dw = \frac{1}{e - 2} \left(\int_{w=0}^1 e^w - 1 dw \right) =$$

$$\frac{1}{e - 2} \left(\underbrace{\int_0^1 e^w}_{e^w|_0^1} - \underbrace{\int_0^1 1}_{1} dw \right) = \frac{1}{e - 2} (e - 1 - 1) = \boxed{1}$$

cdf تابع میانی احتمال را - می توان
تبدیل gray-level در تقریباً
اینکه در آن اغلب در یک مقیاس
تابع میانی احتمال برای تغییر transform
شده برای 1 صاف یعنی توزیع
تلفافه را دارد.

$$Ps(s) ds = Pr(r) dr$$

$$\frac{ds}{dr} = \frac{dT(r)}{dr} = d \left(\int_0^r Pr(w) dw \right) = Pr(r)$$

$$Ps(s) = Pr(r) \times \frac{dr}{ds} = Pr(r) \times \frac{1}{Pr(r)} = 1$$

تصنيف المسائل : س٢

a)

-1	-1	-1
-1	8	-1
-1	-1	-1

-12	12	12	-12	-12	11	11	11
-11	11	11	-11	-11	12	12	12
-11	11	11	11	11	1	1	11
-12	12	12	12	12	11	11	-12
-10	10	10	10	10	1	1	10
11	11	11	11	11	9	9	11
12	12	12	12	12	1	1	12
12	12	12	12	12	11	11	12

=>

0	V	V	0	0	V	Δ	V
0	V	0	0	0	1	V	Δ
0	V	0	V	V	1	0	V
0	V	0	0	0	V	0	0
0	0	V	0	V	1	V	0
V	0	V	0	V	0	4	0
V	0	V	0	V	1	0	V
V	V	0	0	0	V	0	V

0	V	V	0	0	1	1	1
0	V	0	0	0	1	V	1
0	V	1	1	1	1	1	1
0	V	0	0	0	V	0	0
0	0	V	0	1	1	1	0
1	0	V	0	1	1	1	0
V	0	V	0	1	1	1	1
1	1	0	0	0	V	0	V

b)

-1	0	1
-1	0	1
-1	0	1

=>

12	V	-12	-V	4	10	0	-10
11	11	-11	-V	4	10	0	-11
11	11	-11	0	10	V	-V	-10
12	10	-11	-12	10	0	-10	-4
V	11	-V	-11	11	0	-11	-4
0	11	0	-11	9	0	-4	-9
1	1	-1	-11	11	0	-11	-4
1	-1	-1	-12	10	0	0	-1

=>

V	V	0	0	4	V	0	0
V	V	0	0	4	V	0	0
V	1	0	0	V	V	0	0
V	V	0	0	V	0	0	0
V	V	0	0	V	0	0	0
0	V	0	0	V	0	0	0
1	1	0	0	V	0	0	0
1	0	0	0	V	0	0	0

c)

-1	-1	0
-1	0	1
0	1	1

=>

12	12	-V	-V	4	11	10	0
12	11	-12	-1	9	10	0	-10
12	11	-11	0	V	1	-10	-11
V	0	-10	-1	V	0	-10	-4
1	V	0	-1	9	-1	-V	-1
V	11	0	-11	4	0	-1	-1
1	0	-V	-11	V	1	1	1
-12	-10	-10	-V	12	-4	-4	-4

=>

V	V	0	0	4	V	V	0
V	1	0	0	V	V	0	0
V	1	0	0	V	1	0	0
V	0	0	0	V	0	0	0
1	V	0	0	V	0	0	0
V	V	0	0	4	0	0	0
1	0	0	0	V	1	1	1
0	0	0	0	12	0	0	0

d)

0	-1	0
-1	1	-1
0	-1	0

=>

-V	12	11	V	-1	4	-1	4
-V	12	-11	-1	-4	-1	11	-1
-V	11	1	4	4	-1	-1	4
-V	11	-11	-1	-11	11	-11	-1
-1	-12	11	-10	4	-12	4	-1
Δ	-10	12	-10	1	0	1	-4
11	-11	11	-10	4	-12	1	1
1	9	-10	0	-10	11	-11	11

=>

0	V	V	0	0	4	0	4
0	V	0	0	0	0	V	0
0	V	1	4	4	0	0	4
0	V	0	0	0	V	0	0
0	0	V	0	4	0	4	0
Δ	0	V	0	1	0	1	0
V	0	V	0	4	0	1	1
1	V	0	0	0	V	0	V

c)

1	1	1
1	1	1
1	1	1

=>

12	21	11	V	4	14	22	14
21	17	22	14	10	20	21	22
21	22	22	9	19	24	29	14
12	22	22	19	22	20	22	9
10	22	21	20	19	20	19	4
10	21	21	20	18	22	21	12
14	20	14	20	19	20	29	14
12	20	10	10	12	14	22	12

=>

V	V	V	V	V	V	V	V
V	V	V	V	V	V	V	V
V	V	V	V	V	V	V	V
V	V	V	V	V	V	V	V
V	V	V	V	V	V	V	V
V	V	V	V	V	V	V	V
V	V	V	V	V	V	V	V
V	V	V	V	V	V	V	V

0	V	V	0	0	2	2	2
0	V	0	0	0	2	V	2
0	V	2	2	2	2	2	2
0	V	0	0	0	V	0	0
0	0	V	0	2	2	2	0
2	0	V	0	2	2	2	0
V	0	V	0	2	2	2	2
2	2	0	0	0	V	0	V

-1	-1	-1
2	2	2
-1	-1	-1

=>

V	21	21	12	2	2	2	2
0	-10	-2	-14	-4	0	8	8
0	4	12	18	8	1	-2	2
V	-2	-4	-19	-1	-2	-1	-9
-10	-2	0	10	-1	2	-1	2
-1	-1	0	0	0	0	-2	-10
2	12	2	10	-1	2	-2	2
2	-2	-1	-10	8	2	19	8

=>

V	V	V	V	2	2	2	2
0	0	0	0	0	2	V	V
0	4	V	V	V	1	0	2
V	0	0	0	0	0	0	0
0	0	0	V	0	2	0	2
0	0	0	0	0	0	0	0
2	V	2	V	0	2	0	2
2	0	0	0	V	2	V	V

f)

0	-1	-1
1	0	-1
1	1	0

=>

-V	0	12	V	-2	0	10	12
-12	-2	12	4	0	-V	0	10
-12	-2	11	0	-2	-2	-2	0
-12	-10	8	1	-10	0	V	0
-2	-11	V	11	-V	-1	9	4
V	-2	0	8	-4	0	4	9
0	-1	-2	1	-9	1	2	10
-10	-2	-2	-2	-12	-4	-4	-2

=>

0	0	V	V	0	0	V	V
0	0	V	4	0	0	0	V
0	0	V	0	0	0	0	0
0	0	V	1	0	0	V	0
0	0	V	V	0	0	V	4
V	0	0	V	0	0	4	V
0	0	0	1	0	1	2	V
0	0	0	0	0	0	0	0

g)

-1	2	-1
-1	2	-1
-1	2	-1

h)

-12	21	0	-V	-4	2	8	2
-21	22	-2	-V	-4	2	8	2
-21	22	-18	0	-10	12	1	2
-2	18	2	-10	-2	12	-2	0
-1	-2	21	-20	-1	12	-1	-4
20	-21	22	-20	9	0	4	-2
22	-21	20	-20	-1	12	-11	12
14	-11	11	-10	-2	12	-12	14

=>

0	V	0	0	0	2	V	2
0	V	0	0	0	2	V	2
0	V	0	0	0	V	1	2
0	V	2	0	0	V	0	0
0	0	V	0	0	V	0	0
V	0	V	0	V	0	4	0
V	0	V	0	0	V	0	V
V	0	V	0	0	V	0	V

0	V	V	0	0	3	3	3
0	V	0	0	0	3	V	3
0	V	3	3	3	3	3	3
0	V	0	0	0	V	0	0
0	0	V	0	3	3	3	0
3	0	V	0	3	3	3	0
V	0	V	0	3	3	3	3
3	3	0	0	0	V	0	V

تقدیر اصلی

x_1	x_2	x_3
x_4	x_5	x_6
x_7	x_8	x_9

\Rightarrow

$$P = Vx_4 + Vx_9$$

$$P = Vx_4 + Vx_8 + Vx_5$$

$$P = Vx_2 + Vx_7 + Vx_5 \Rightarrow x_2 = \frac{1}{V} \cdot \frac{P}{V} \Rightarrow Vx_7 + Vx_5 = 1$$

$$V(x_7 + x_5) = 1 \Rightarrow$$

$$x_7 + x_5 = \frac{1}{V}$$

$$1 = Vx_2 \Rightarrow \boxed{x_2 = \frac{1}{V}}$$

$$1 = 3x_4 + 3x_9$$

$$(*) P = 3x_5 + 3x_8 + 3x_4 + Vx_9$$

$$P = 3x_2 + 3x_5 + 3x_4 + 3x_7 + Vx_8 + 3x_9$$

$$\Rightarrow 3x_4 + 3x_9 = 1$$

$$3x_2 + 3x_5 + 3x_7 + Vx_8 = 1 \rightarrow x_2 = \frac{1}{V} \Rightarrow$$

$$3x_5 + 3x_7 + Vx_8 = \frac{2}{V} \Rightarrow 3(x_5 + x_7) + Vx_8 = \frac{2}{V}$$

$$\frac{3}{V} + Vx_8 = \frac{2}{V} \Rightarrow Vx_8 = \frac{1}{V} \Rightarrow$$

$$\Rightarrow \boxed{x_8 = \frac{1}{V^2}}$$

$$P = Vx_4 + V \cdot \frac{1}{V^2} + Vx_5 \Rightarrow$$

$$P - \frac{1}{V} = V(x_4 + x_5) = \frac{3}{V} \Rightarrow x_4 + x_5 = \frac{3}{V}$$

$$3(x_5 + x_4) + 3 \cdot \frac{1}{V^2} + Vx_9 = P \Rightarrow \frac{3}{V} + \frac{3}{V^2} + Vx_9 = P \Rightarrow Vx_9 = P - \frac{3}{V} - \frac{3}{V^2} = \frac{5P}{V^2}$$

$$P = V(x_4 + x_9) \Rightarrow x_4 + \frac{1}{V^2} = \frac{P}{V} \Rightarrow$$

$$\boxed{x_9 = \frac{1}{V^2}}$$

$$x_4 = \frac{12}{V^2} - \frac{1}{V^2} = \frac{11}{V^2} \Rightarrow \boxed{x_4 = \frac{11}{V^2}}$$

$$x_5 + x_4 = \frac{3}{V} \Rightarrow \boxed{x_5 = \frac{3}{V} - \frac{11}{V^2}}$$

$$x_5 + x_7 = \frac{1}{V} \Rightarrow \boxed{x_7 = 0}$$

$$V u_1 + V u_2 + V u_3 = 1 \rightarrow u_1 = \frac{4}{29} \Rightarrow V u_1 + V \left(\frac{12}{29} \right) = 1 \Rightarrow$$

$$u_2 = \frac{1}{29} \quad V u_3 = 0 \Rightarrow \boxed{u_3 = 0}$$

$$1'' u_1 + 1'' u_2 + 1'' u_3 = 1 \Rightarrow 1'' (u_1 + u_2) = 1 \Rightarrow u_1 + u_2 = \frac{1}{1''}$$

$$1'' u_1 + 1'' u_2 + 1'' u_3 = 1 \Rightarrow \frac{29}{29} - \frac{12}{29} = 1'' u_1 \Rightarrow$$

$$\frac{17}{29} = 1'' u_1 \Rightarrow \boxed{u_1 = \frac{17}{3 \times 29}}$$

$$u_2 = \frac{1}{1''} - \frac{17}{3 \times 29} = \frac{12}{3 \times 29} \Rightarrow \boxed{u_2 = \frac{1}{29}}$$

نوعی از *deconvolution* را به این صورت انجام می‌دهیم که یک فیلتر با معادله محمول در نظر می‌گیریم و با آن به فیلتر معکوس اصلی در جواب گای بازنویسی یک معادله بر اساس محمول به دست می‌آوریم. با به دست آوردن این معادله ها و حل کردن آن‌ها می‌توانیم به معادله فیلتر درست بپردازیم. تمام معادله‌های که بالای نوشته شده از محاسبه بازنویسی به دست آمده است.

1	Σ	π	1	1	ρ	π	ρ
ρ	Σ	π	1	1	π	π	π
ρ	Σ	π	ρ	ρ	π	π	ρ
1	π	π	1	ρ	π	ρ	1
1	ρ	π	ρ	ρ	π	ρ	1
ρ	π	Σ	π	ρ	π	ρ	1
π	π	π	ρ	ρ	π	π	ρ
ρ	ρ	1	1	1	π	π	ρ

u_1	u_2	u_3
u_4	u_5	u_6
u_7	u_8	u_9

$$V u_1 + V u_9 = 1 \Rightarrow u_1 + u_9 = \frac{1}{V}$$

$$V(u_2 + u_4 + u_6) = 1 \Rightarrow V u_2 = 1 \Rightarrow \boxed{u_2 = \frac{1}{V}}$$

$$\frac{1}{V} V u_2 + V u_4 = 1 \Rightarrow \boxed{u_4 = 0} \Rightarrow \boxed{u_6 = \frac{1}{V}}$$

$$V u_2 + \pi u_5 + \pi u_6 = 1$$

$$\pi u_2 + V u_5 + \pi u_6 + \pi u_9 = 1 \Rightarrow \pi u_2 + V \times \frac{1}{V} + 0 + \frac{\pi}{V} = 1 \Rightarrow$$

$$\pi u_5 + V u_6 = 1$$

$$\frac{1}{V} V u_5 + \pi u_6 = 1 \Rightarrow \boxed{u_5 = 0} \Rightarrow \pi u_6 = 1 \Rightarrow \boxed{u_6 = \frac{1}{\pi}}$$

$$V u_1 + \pi u_2 = 1 \Rightarrow V u_1 = \frac{\Sigma}{V} \Rightarrow \boxed{u_1 = \frac{\Sigma}{29}}$$

$$\pi u_2 + V u_6 = 1 \Rightarrow \pi u_2 - \frac{\Sigma \Sigma}{9} = 1 \Rightarrow \pi u_2 = \frac{11 + \Sigma \Sigma}{9} = \frac{4 \rho}{9} \Rightarrow \boxed{u_2 = \frac{4 \rho}{11}}$$

$$\pi u_2 = 1 - \frac{1}{V} - \frac{1 \Sigma}{\pi}$$

$$\pi u_2 = \frac{4 \rho - 9 - 9 \pi}{\pi}$$

$$\pi u_2 = -\frac{\Sigma \Sigma}{\pi} \Rightarrow$$

$$\boxed{u_2 = -\frac{\Sigma \Sigma}{4 \rho}}$$

0	0	0	0	0	0	0	0
0	Σ	Δ	0	0	0	0	0
0	0	0	0	0	0	V	V
V	V	γ	γ	μ	0	μ	γ
1	Σ	0	0	0	γ	0	0
0	0	0	0	0	0	0	0
0	1	V	V	γ	0	0	0
V	V	V	V	V	V	V	V

q_1	q_2	q_3
q_4	q_5	q_6
q_7	q_8	q_9

$$Vq + Vq_4 + Vq_\mu = 0 \Rightarrow \underbrace{q_\mu + q_\gamma + q_9}_{=1} = 0 \Rightarrow \boxed{q_9 = -1}$$

$$\mu q_\Lambda + Vq_\mu = 1$$

$$Vq_\mu + Vq_\gamma = V \Rightarrow q_\mu + q_\gamma = 1$$

$$Vq_\gamma + Vq_\Delta + Vq_\Lambda + Vq_\mu + \mu q_9 = \Sigma$$

$$Vq_1 + Vq_\Sigma + Vq_V + Vq_\gamma + \mu q_\Lambda + \mu q_9 = \Delta \rightarrow V(q_1 + q_\gamma + q_V) + \mu q_\Lambda = \Delta$$

$$Vq_\Sigma = 0 \Rightarrow \boxed{q_\Sigma = 0}$$

$$\mu(q_\Sigma + q_\Delta + q_4) = 0 \Rightarrow q_\Delta + q_4 = 0$$

$$\mu q_\Lambda = -4 \Rightarrow$$

$$\boxed{q_\Lambda = -1}$$

$$\mu q_1 + \mu q_\gamma + \mu q_V = 4 \Rightarrow q_1 + q_\gamma + q_V = \mu$$

$$\mu(q_1 + q_\gamma + q_\mu) + Vq_\Sigma + \mu(q_V + q_\Lambda) = \mu \Rightarrow \mu(q_1 + q_\gamma + q_\mu + q_V) = 9$$

$$\mu(q_1 + q_\gamma + q_\mu) + Vq_\Delta + \mu(q_V + q_\Lambda + q_9) = 0 \Rightarrow \mu(q_1 + q_\gamma + q_\mu + q_V) + Vq_\Delta = 9$$

$$\boxed{q_\Delta = 0}$$

$$\boxed{q_\mu = 1} \Leftrightarrow \boxed{q_4 = 0}$$

$$Vq_\gamma + 0 - 1\Sigma + V - \mu = \Sigma \Rightarrow$$

$$Vq_\gamma = 1\Sigma \Rightarrow \boxed{q_\gamma = \mu}$$

$$\mu q_V + Vq_\gamma + Vq_4 + Vq_9 = \Sigma \Rightarrow \mu q_V = -\mu \Rightarrow \boxed{q_V = -1} \Rightarrow$$

$$q_1 + q_\gamma + q_V = \mu \Rightarrow \boxed{q_1 = 1}$$

1	μ	1
0	0	0
-1	$-\mu$	-1

V	V	V	V	W	Y	V	Y
V	V	V	0	W	V	V	Y
V	V	V	V	V	V	V	Y
V	V	V	0	V	V	V	0
0	V	V	V	Y	V	Y	W
W	V	V	V	Y	V	Y	W
V	V	V	V	Y	V	V	Y
Y	Y	W	0	V	V	V	Y

x_1	x_2	x_3
x_2	x_3	x_4
x_4	x_1	x_4

\Rightarrow

$$Vx_4 + Vx_4 = V \Rightarrow x_4 + x_4 = 1$$

$$Vx_3 + Vx_4 + Vx_4 = V \Rightarrow V(x_3 + x_4 + x_4) = V \Rightarrow$$

$$x_3 = 0$$

$$Vx_3 + Wx_1 = 0 \Rightarrow$$

$$x_1 = 0$$

$$Wx_3 + Vx_1 = W \Rightarrow$$

$$x_3 = 1$$

$$Vx_3 + Wx_2 + Wx_1 = V \Rightarrow Wx_2 = 0 \Rightarrow$$

$$x_2 = 0$$

$$Vx_2 + Wx_3 + Wx_4 = Y \Rightarrow Wx_4 = W \Rightarrow$$

$$x_4 = 1$$

$$x_4 + x_4 = 1 \Rightarrow$$

$$x_4 = 0$$

$$Vx_1 + Vx_2 + Wx_3 + Wx_4 = Y \Rightarrow Vx_1 + Wx_3 = W$$

$$Wx_3 + Vx_2 = W \Rightarrow x_3 = 1 \rightarrow Vx_1 = 0 \Rightarrow$$

$$x_1 = 0$$

$$Wx_1 + Wx_3 + Wx_4 + Wx_1 = W \Rightarrow$$

$$x_4 = 0$$

0	0	0
1	1	1
0	0	0

\Rightarrow ماتريك الحل

0	Δ	γ	0	0	γ	γ	γ
0	V	γ	1	1	γ	Σ	γ
0	V	1	1	1	Σ	γ	γ
0	Δ	γ	1	γ	Σ	γ	1
1	γ	Δ	0	γ	Σ	γ	0
γ	0	V	0	γ	γ	γ	1
Σ	1	Δ	0	γ	Σ	γ	γ
γ	1	γ	0	1	γ	1	γ

$q_{\lambda 1}$	$q_{\lambda \gamma}$	$q_{\lambda \gamma}$
$q_{\lambda \Sigma}$	$q_{\lambda \Delta}$	$q_{\lambda \gamma}$
$q_{\lambda V}$	$q_{\lambda 1}$	$q_{\lambda \gamma}$

$$V q_{\lambda 4} + V q_{\lambda 9} = 0 \Rightarrow q_{\lambda 4} + q_{\lambda 9} = 0$$

$$V q_{\lambda \gamma} + V q_{\lambda 4} + V q_{\lambda 9} = 0 \Rightarrow \boxed{q_{\lambda \gamma} = 0}$$

$$V q_{\lambda \gamma} + \gamma q_{\lambda 1} = 1 \Rightarrow \boxed{q_{\lambda 1} = \frac{1}{\gamma}}$$

$$\gamma q_{\lambda \Delta} + \frac{V}{\gamma} q_{\lambda 1} = \gamma \Rightarrow \gamma q_{\lambda \Delta} = \frac{\gamma}{\gamma} - \frac{V}{\gamma} = \frac{\gamma - V}{\gamma} \Rightarrow \boxed{q_{\lambda \Delta} = \frac{\gamma - V}{\gamma}}$$

$$\gamma q_{\lambda \gamma} + \frac{1 \Sigma}{\gamma} + \gamma q_{\lambda 1} + \gamma q_{\lambda 9} = \Sigma \Rightarrow \gamma (q_{\lambda \gamma} + q_{\lambda 9}) = \Sigma - \frac{1 \Sigma}{\gamma} \Rightarrow q_{\lambda \gamma} + q_{\lambda 9} = \frac{1 \Sigma - \Sigma}{\gamma \lambda \gamma} = \frac{1 \Sigma - \Sigma}{\gamma \lambda \gamma}$$

$$V q_{\lambda \gamma} + \gamma q_{\lambda \Delta} + \gamma q_{\lambda 4} = \gamma \Rightarrow V q_{\lambda \gamma} + \gamma q_{\lambda 4} = \frac{\gamma - 1}{\gamma} \Rightarrow q_{\lambda 4} = -q_{\lambda 9} \Rightarrow$$

$$\begin{cases} V q_{\lambda \gamma} - \gamma q_{\lambda 9} = \frac{\gamma - 1}{\gamma} \\ \gamma (q_{\lambda \gamma} + q_{\lambda 9}) = \frac{1 \Sigma - \Sigma}{\gamma \lambda \gamma} \end{cases} \Rightarrow 10 q_{\lambda \gamma} = \frac{\gamma - 1}{\gamma \lambda \gamma} + \frac{\gamma - 1}{\gamma \lambda \gamma} \Rightarrow$$

$$\frac{10 \gamma}{\gamma \lambda \gamma} q_{\lambda \gamma} + q_{\lambda 9} = \frac{1 \Sigma - \Sigma}{\gamma \lambda \gamma} \Rightarrow \boxed{q_{\lambda 9} = \frac{1 \Sigma - \Sigma}{\gamma \lambda \gamma}}$$

$$\boxed{q_{\lambda \gamma} = \frac{10 \gamma - 1 \Sigma}{\gamma \lambda \gamma} = \frac{10 \gamma - 1 \Sigma}{\gamma \lambda \gamma}}$$

$$V q_{\lambda 1} + \frac{V}{\gamma} q_{\lambda \gamma} + \gamma q_{\lambda \Sigma} + \gamma q_{\lambda \Delta} = 1 \Rightarrow V q_{\lambda 1} + \gamma q_{\lambda \Sigma} = \frac{1}{\gamma}$$

$$\gamma q_{\lambda \Sigma} + V q_{\lambda \gamma} = \gamma \Rightarrow \gamma q_{\lambda \Sigma} = \gamma - V \times \frac{10 \gamma}{\gamma \lambda \gamma} \Rightarrow \frac{\Delta \Sigma - V 1 \Sigma}{\gamma \lambda \gamma} = \boxed{\frac{-1 V \Sigma}{\gamma \lambda \gamma \times \gamma}}$$

$$\gamma q_{\lambda 1} + \gamma q_{\lambda \Sigma} + \gamma q_{\lambda V} + \gamma q_{\lambda 1} = 1 \Rightarrow q_{\lambda 1} + q_{\lambda \Sigma} + q_{\lambda V} = 0 \Rightarrow \boxed{q_{\lambda V} = 0}$$

$$\gamma q_{\lambda 1} + \gamma q_{\lambda \Sigma} + \frac{\gamma}{\gamma} q_{\lambda \Delta} + \frac{V}{\gamma} q_{\lambda 1} = \gamma \Rightarrow q_{\lambda 1} + q_{\lambda \Sigma} = 0$$

$$\gamma q_{\lambda 1} + \gamma q_{\lambda \gamma} + V q_{\lambda \Delta} = \gamma \Rightarrow \gamma q_{\lambda 1} = \frac{-V \gamma \gamma}{\gamma \lambda \gamma} + \frac{\gamma \times \gamma \lambda \gamma}{\gamma \lambda \gamma} \Rightarrow \boxed{q_{\lambda 1} = \frac{1 \Sigma}{\gamma \lambda \gamma \times \gamma} - \frac{\gamma \lambda}{\gamma \lambda \gamma}}$$

1	0	0	0	1	0	0	0
Σ	0	Σ	1	1	0	0	0
Σ	0	1	0	0	0	0	0
1	0	1	Σ	1	0	1	1
1	1	0	1	0	0	0	1
0	Δ	0	Δ	0	0	0	1
0	1	0	1	0	0	1	0
0	1	0	1	1	0	1	0

$$V(n_1 + n_2) = 1 \Rightarrow n_1 + n_2 = \frac{1}{V}$$

$$V(n_1 + n_2 + n_3) = \Sigma \Rightarrow n_1 + n_2 + n_3 = \frac{\Sigma}{V} \Rightarrow$$

$$V(n_1 + n_2) = 1 \Rightarrow \boxed{n_2 = 0}$$

$$\boxed{n_1 = \frac{1}{V}}$$

$$\boxed{n_3 = \frac{1}{V}}$$

$$1 \cdot n_1 + V \cdot n_2 = 1 \Rightarrow \boxed{n_2 = 0}$$

$$V \cdot n_1 + 1 \cdot n_2 = 0 \Rightarrow$$

$$V \cdot n_1 + 1 \cdot n_2 = 1 \Rightarrow V \cdot n_1 = \frac{1}{V} - \frac{1}{V} \Rightarrow$$

$$V \cdot n_1 = \frac{1 \Delta}{V} \Rightarrow \boxed{n_1 = \frac{1 \Delta}{\Sigma 9}}$$

$$V \cdot n_1 + V \cdot n_2 + 1 \cdot (n_1 + n_2 + n_3) = 1$$

$$1 \cdot n_1 + 1 \cdot n_2 + \frac{1}{V} \cdot n_3 = 1 \Rightarrow 1 \cdot n_1 = \frac{1}{V} \Rightarrow \boxed{n_1 = \frac{1}{V}}$$

$$1 \cdot (n_1 + n_2 + \frac{1}{V}) = 1 \Rightarrow \boxed{n_2 = \frac{1}{V}}$$

$$1 \cdot (n_1 + n_2 + \frac{1}{V} + n_3) = 1 \Rightarrow \frac{1 \Delta}{\Sigma 9} + \frac{1}{V} + n_3 = \frac{1}{V} \Rightarrow$$

$$n_3 = \frac{1}{V} - \frac{1 \Delta}{\Sigma 9} = \frac{\Sigma 9 - 1 \Delta}{\Sigma 9 \times V} = \boxed{\frac{\Sigma}{\Sigma 9 \times V}}$$

$$V \cdot n_1 + V \cdot n_2 + 1 \cdot n_3 + 1 \cdot n_4 = 1$$

$$\frac{1 \Delta}{V} + 1 + 1 + 1 \cdot n_4 = 1 \Rightarrow 1 \cdot n_4 = -\frac{1 \Sigma}{V} - \frac{1 \Delta}{V} \Rightarrow \boxed{n_4 = -\frac{1 \Sigma}{V}}$$

0	✓	✓	0	0	✓	✓	✓
0	✓	0	0	0	✓	✓	✓
0	✓	Δ	✓	✓	0	✓	✓
0	✓	0	0	0	✓	0	0
0	0	✓	0	✓	0	✓	0
✓	0	✓	Δ	✓	✓	0	0
✓	0	✓	0	✓	0	✓	Δ
Δ	✓	0	0	0	✓	0	✓

q_1	q_r	q_p
q_2	q_v	q_y
q_v	q_Δ	q_q

row 1, 2, 3, 4, 5, 6, 7, 8

$$1^w q_\Delta + 1^w q_r + 1^w q_y = \Delta$$

$$1^w q_1 + 1^w q_2 + 1^w q_\Delta + 1^w q_\Delta = \Delta$$

$$1^w q_1 + 1^w q_2 + 1^w q_v + 1^w (q_r + q_\Delta + q_\Delta) = 1^w$$

$$1^w q_1 + 1^w q_2 + 1^w q_r + 1^w q_\Delta + 1^w q_v + 1^w q_y = 1^w$$

$$1^w q_1 + 1^w q_v = 0$$

$$1^w (q_r + q_\Delta + q_\Delta + q_v + q_y + q_q) = 1^w \Rightarrow q_r + q_v + q_\Delta + q_y + q_\Delta + q_q = 1^w$$

$$1^w (q_1 + q_r + q_v + q_2 + q_\Delta + q_y + q_v + q_\Delta + q_q) = 1^w \Rightarrow q_1 + q_2 + q_v = -1$$

$$1^w (q_1 + q_r + q_2 + q_\Delta + q_v + q_\Delta + q_q) = 1^w \Rightarrow q_r + q_\Delta + q_\Delta + q_q = 1^w$$

-1

$$q_v + q_y = -1$$

$$1^w (q_1 + q_2 + q_v) + 1^w q_\Delta + 1^w q_y = \Delta \Rightarrow 1^w (q_\Delta + q_y) = 1^w \Rightarrow q_\Delta + q_y = 1$$

$$1^w (q_\Delta + q_y) + 1^w q_r = \Delta \Rightarrow q_r = -1$$

$$1^w (q_1 + q_r + q_2 + q_\Delta + q_y) + 1^w (q_v + q_q) = 1^w \Rightarrow q_\Delta + q_v + q_q = 1$$

$$1^w (q_1 + q_2 + q_v) + 1^w (q_v + q_q) = 1^w \Rightarrow 1^w q_1 + q_2 + 1^w q_v + 1^w q_q = -1^w$$

$$1^w q_v + 1^w q_r + 1^w q_\Delta + 1^w q_\Delta + 1^w q_v + 1^w q_q + 1^w q_y = 1^w \Rightarrow 1^w q_v + 1^w q_r + 1^w q_y = -1^w$$

$$1^w (q_1 + q_2 + q_\Delta + q_y + q_r) + 1^w (q_v + q_q) = 1^w \Rightarrow -1^w - 1^w q_v + 1^w q_\Delta - 1^w + 1^w q_v = 1^w \Rightarrow -2 = 1^w \Rightarrow 1^w = -2$$

$$1^w q_v + 1^w q_\Delta = 1^w \Delta$$

$$1^w q_1 + 1^w q_v + 1^w q_2 + 1^w q_\Delta + 1^w q_\Delta = \Delta$$

$$1^w (-1 - q_2) + 1^w (1 - q_q) = \Delta$$

$$1^w q_2 - 1^w q_q = -1$$

V	0	0	V	Y	0	0	0
V	0	V	V	V	0	0	0
V	0	0	0	0	0	Y	0
V	0	V	V	V	0	V	V
V	V	0	V	0	0	0	Y
0	V	0	V	0	0	0	V
0	V	0	V	0	0	Y	0
0	0	V	V	V	0	V	0

x_1	x_2	x_3
x_4	x_5	x_6
x_7	x_8	x_9

$$Vx_V = V \Rightarrow \boxed{x_V = 1}$$

$$Vx_Y + Vx_Q = Y \Rightarrow x_Y + x_Q = Y$$

$$Vx_\Sigma + Vx_V = Y \Rightarrow x_\Sigma + x_V = Y \leadsto \boxed{x_\Sigma = 1}$$

$$Vx_1 + Vx_P + Vx_\Sigma + Vx_\Delta + Vx_Y + Vx_V + Vx_Q = Y$$

$$V(x_1 + x_P + x_\Sigma + x_\Delta + x_Y + x_V + x_Q) = Y$$

$$V(x_1 + x_P + x_\Delta + x_Y) + Vx_Q = -1$$

$$Vx_1 + Vx_P + Vx_Q + Vx_\Sigma + Vx_\Delta + Vx_Y + Vx_V = Y \Rightarrow Vx_1 + Vx_P + Vx_Q + Vx_\Delta + Vx_Y = -1$$

$$V(x_1 + x_\Sigma + x_V) + V(x_\Delta + x_Y) = 0 \Rightarrow Vx_1 + Vx_\Delta + Vx_Y = -1$$

$$Vx_P + Vx_\Delta + Vx_Y < 0$$

$$x_1 + x_P + x_Q + x_\Delta + x_\Lambda = -1$$

$$Vx_1 + Vx_P + Vx_\Delta + Vx_Y + V(Y - x_Y) = -1$$

$$Vx_1 + Vx_P + Vx_Q + Vx_\Delta + Vx_Y = -1 \Rightarrow -1x_1 + Vx_P + Vx_Q = Y$$

$$V(x_1 + x_\Sigma + x_V + x_\Lambda) > V \Rightarrow x_1 + x_\Lambda + Y > \frac{V}{V} \Rightarrow x_1 + x_\Lambda > \frac{1}{V}$$

$$Vx_1 + Vx_P + Vx_Q > V \Rightarrow V(x_1 + x_P) > \frac{V}{V} \Rightarrow x_1 + x_P > \frac{1}{V}$$

$$Vx_P + Vx_\Lambda > V$$

$$V(x_P + x_Y) > V \Rightarrow x_P + x_Y > 1$$

$$Vx_1 + Vx_\Sigma + Vx_V + Vx_\Lambda < 0 \Rightarrow Vx_1 + Vx_\Lambda < V \Rightarrow x_1 + x_\Lambda < \frac{V}{V}$$

$$Vx_P + Vx_Q + Vx_Y > V \Rightarrow Vx_1 + Vx_P + Vx_Q + Vx_Y > 1$$

$$Vx_1 + Vx_P > V$$

$$Vx_1 + Vx_P + Vx_\Sigma + Vx_\Delta < 0 \Rightarrow Vx_1 + Vx_P + Vx_\Delta < -1 \Rightarrow$$

$$Vx_P + Vx_\Delta + Vx_V < 0 \Rightarrow x_P + x_\Delta < \frac{V}{V}$$

$$Vx_P + Vx_\Delta + Vx_Y < 0$$