Programmazione concorrente

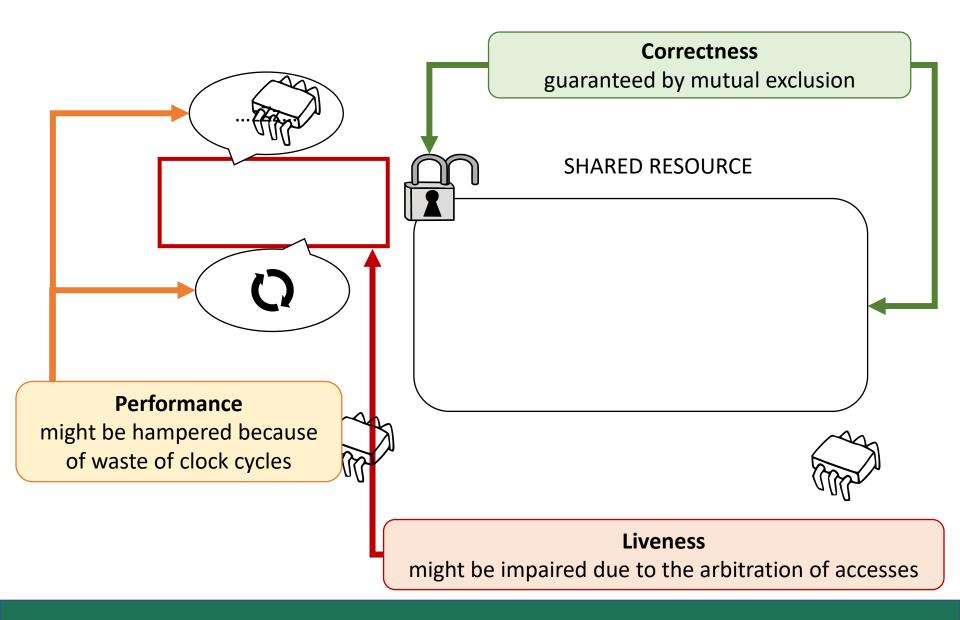
Laurea Magistrale in Ingegneria Informatica Università Tor Vergata

Docente: Romolo Marotta

Properties of Concurrent Programs

- 1. Scalability
- 2. Correctness
- 3. Progress

On concurrent programming



Properties

What do we want from parallel programs?

- Safety: nothing wrong happens (Correctness)
 - parallel versions of our programs should be correct as their sequential implementations
- Liveliness: something good happens eventually (Progress)
 - if a sequential program terminates with a given input, we want that its parallel alternative also completes with the same input

Performance

we want to exploit our parallel hardware

Properties

A bit of terminology

- Hardware
 - Processor
 - CPU
 - CPU-Core
 - Logical Core
 - Hardware thread
- Software
 - Process
 - Thread
 - Fiber
 - Task

- Programs
 - Sequential
 - Concurrent
 - Parallel
 - Distrubuted
- Memory
 - Shared
 - Distributed

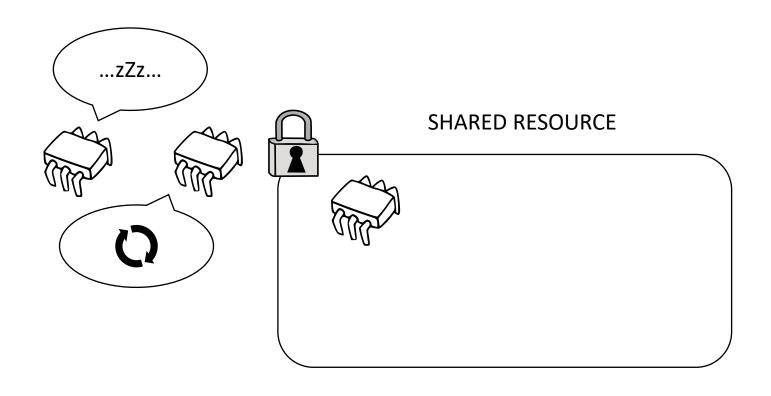
The system model

- Threads (aka processes)
- Cores (aka cpus)
- Shared memory
- Arbitrary long asynchronous delays
- Scheduler
 - A system component that decides which/when a thread runs on a given core

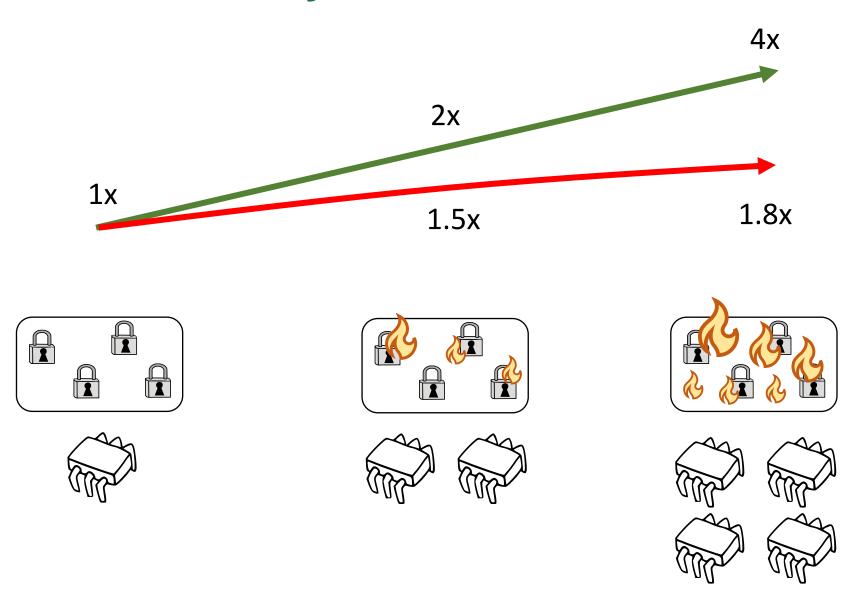
Properties

Scalability Correctness conditions Progress conditions

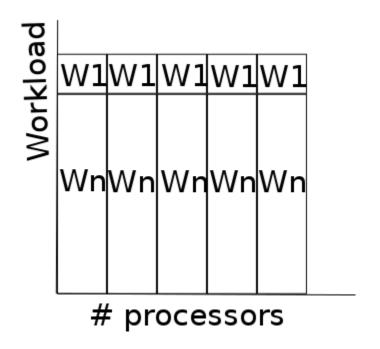
The cost of synchronization

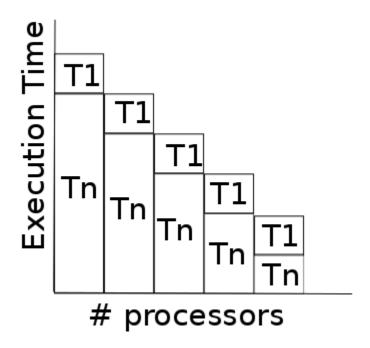


The cost of synchronization



Amdahl Law - Fixed-size Model (1967)





Amdahl Law – Fixed-size Model (1967)

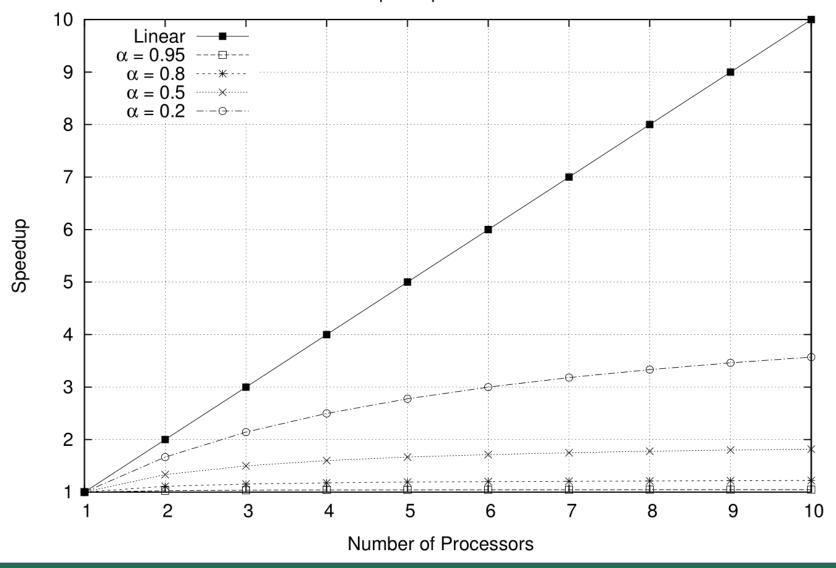
 The workload is fixed: it studies how the behavior of the same program varies when adding more computing power

$$S_{Amdahl} = \frac{T_S}{T_p} = \frac{T_S}{\alpha T_S + (1 - \alpha)\frac{T_S}{p}} = \frac{1}{\alpha + \frac{(1 - \alpha)}{p}}$$

- where:
 - $\alpha \in [0,1]$: Serial fraction of the program
 - $p \in N$: Number of processors
 - T_s: Serial execution time
 - T_p : Parallel execution time
- It can be expressed as well vs. the parallel fraction $P = 1 \alpha$

Amdahl Law - Fixed-size Model (1967)

Parallel Speedup vs. Serial Fraction



How real is this?

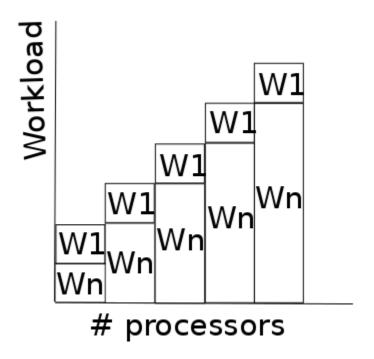
$$\lim_{p \to \infty} S_{Amdahl} = \lim_{p \to \infty} \frac{1}{\alpha + \frac{(1 - \alpha)}{p}} = \frac{1}{\alpha}$$

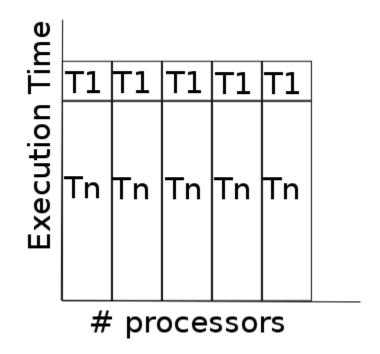
• If the sequential fraction is 20%, we have:

$$\lim_{p\to\infty} S_{Amdahl} = \frac{1}{0.2} = 5$$

Speedup 5 using infinite processors!

Fixed-time model





Gustafson Law—Fixed-time Model (1989)

 The execution time is fixed: it studies how the behavior of the <u>scaled</u> program varies when adding more computing power

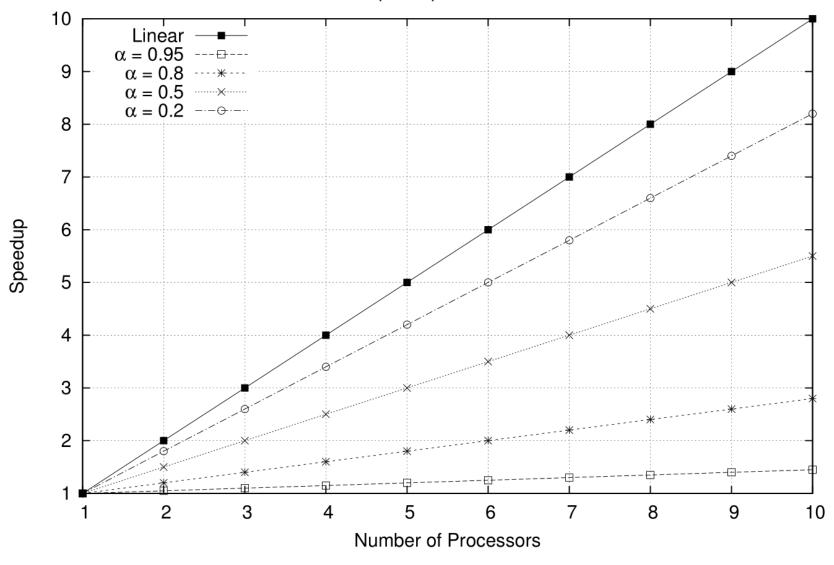
$$W' = \alpha W + (1 - \alpha)pW$$

$$S_{Gustafson} = \frac{W'}{W} = \alpha + (1 - \alpha)p$$

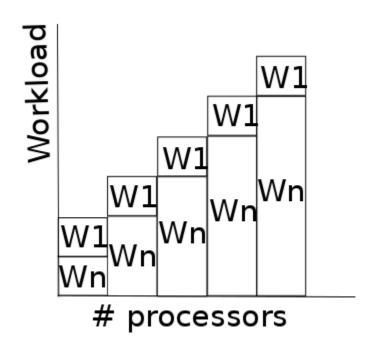
- where:
 - $\alpha \in [0,1]$: Serial fraction of the program
 - $p \in N$: Number of processors
 - W : Original workload
 - W': Scaled workload

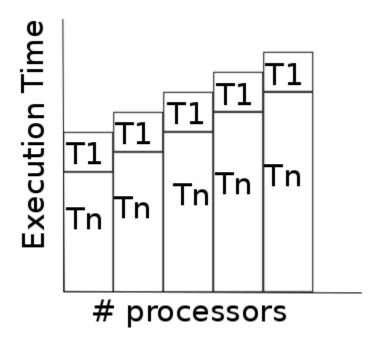
Speed-up according to Gustafson

Parallel Speedup vs. Serial Fraction



Memory-bounded model





Sun Ni Law—Memory-bounded Model (1993)

The workload is scaled, bounded by memory

$$S_{Sun-Ni} = \frac{sequential\ time\ for\ W^*}{parallel\ time\ for\ W^*}$$

$$S_{Sun-Ni} = \frac{\alpha W + (1-\alpha)G(p)W}{\alpha W + (1-\alpha)G(p)\frac{W}{p}} = \frac{\alpha + (1-\alpha)G(p)}{\alpha + (1-\alpha)\frac{G(p)}{p}}$$

- where:
 - G(p) describes the workload increase as the memory capacity increases
 - $W^* = \alpha W + (1 \alpha)G(p)W$

Speed-up according to Sun Ni

$$S_{Sun-Ni} = \frac{\alpha + (1-\alpha)G(p)}{\alpha + (1-\alpha)\frac{G(p)}{p}}$$

• If G(p) = 1

$$S_{Amdahl} = \frac{1}{\alpha + \frac{(1 - \alpha)}{p}}$$

• If G(p) = p

$$S_{Gustafson} = \alpha + (1 - \alpha)p$$

• In general, G(p) > p gives a higher scale-up

Superlinear speedup

- Can we have a Speed-up > p ? Yes!
 - Workload increases more than computing power (G(p) > p)
 - Cache effect: larger accumulated cache size. More or even all of the working set can fit into caches and the memory access time reduces dramatically
 - RAM effect: enables the dataset to move from disk into RAM drastically reducing the time required, e.g., to search it.

Scalability

Efficiency

$$E = \frac{speedup}{\#processors}$$

- Strong Scalability: If the efficiency is kept fixed while increasing the number of processes and maintain fixed the problem size
- Weak Scalability: If the efficiency is kept fixed while increasing at the same rate the problem size and the number of processes

Scalability Correctness conditions Progress conditions

Correctness in a sequential world

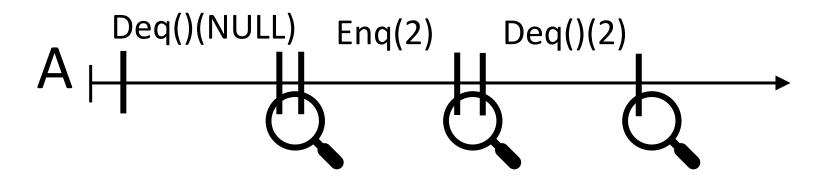
- What does it mean for a program to be correct?
- Simplification: We mask any program/algorithm behind the concept of ABSTRACT DATA TYPE
- An Abstract Data Type (ADT) defines:
 - A state
 - The domain of its values
 - Operations/methods
 - Constraints to apply operations/methods
- An ADT specification do not care about implementations
- Typically, operations and their constraints are defined via pre-conditions and post-conditions

Example: FIFO Queue ADT

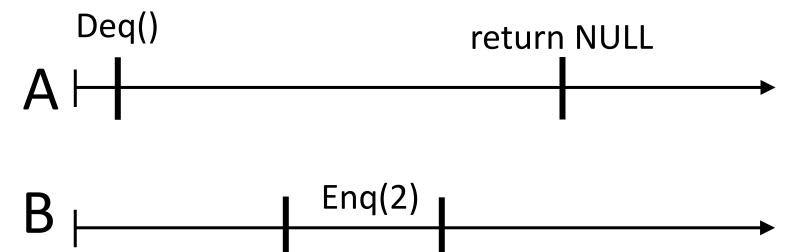
- init():
 - pre: state = NULL
 - post: state = []
- enqueue(x):
 - pre: state != NULL
 - post: state = state,x
- dequeue()(x):
 - pre: state = x,seq
 - post: state = seq
- dequeue()(NULL):
 - pre: state = []
 - post: -

Correctness in a sequential world

- When considering only sequential:
 - Methods do not overlap each other
 - The effect/result of a method can be checked by inspecting the state before/after their ending
- We totally ignore the fact that methods take time!
- We totally ignore the state during method invocations!
- Proving that a sequential implementation is correct:
 - Ensure that for all possible (sequential) executions both pre and post conditions always hold
- Focus on the correctness of an individual execution

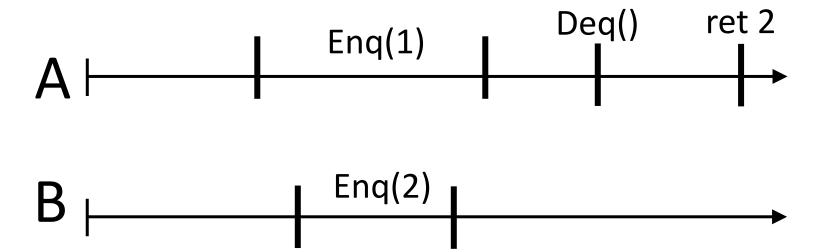


- Threads invoke methods
- Threads can experience arbitrary large delays



Is it correct?

- Threads invoke methods
- Threads can experience arbitrary large delays



• Is it correct?

- Threads invoke methods
- Threads can experience arbitrary large delays
- Methods are partially ordered intervals
- Methods could never be executed in isolation!
- We should describe any possible interleaving!
- What does it mean for a concurrent program to be correct?
 - What's exactly a concurrent FIFO queue?
 - FIFO implies a strict temporal ordering
 - Concurrency implies an ambiguous temporal ordering

Classical approach to concurrent programming

Based on blocking primitives

- Semaphores
- Locks acquiring
- Simple??

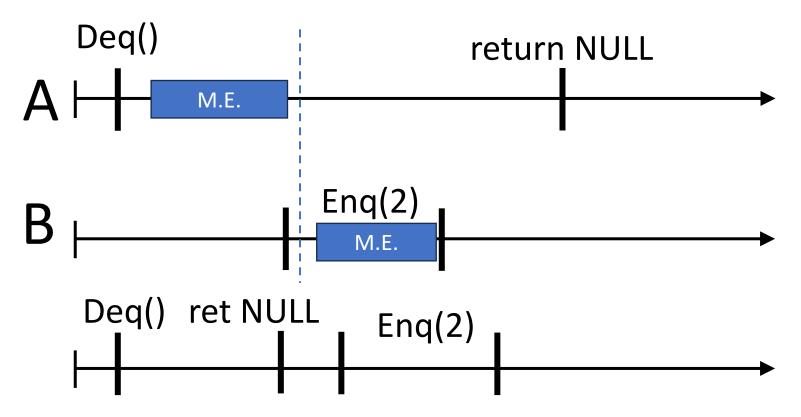
PRODUCER

```
1. Semaphore p, c = 0;
2. Buffer b;
3.
4. while(1) {
5. wait(c);
6. <Write on b>
7. signal(p);
8. }
```

CONSUMER

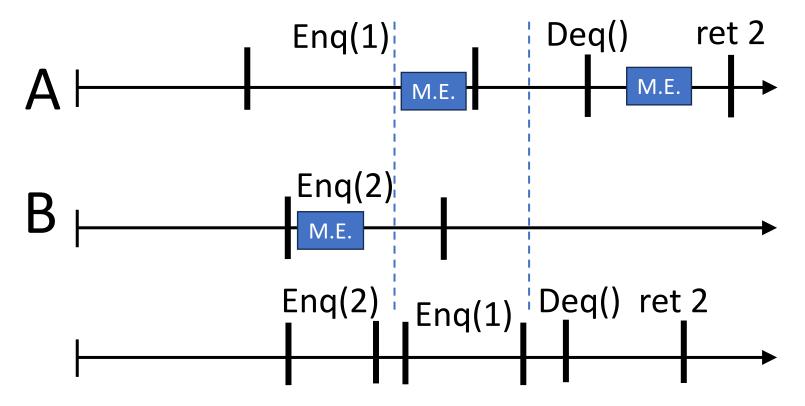
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```

- Threads invoke methods
- Threads can experience arbitrary large delays



Is it correct? Yes!

- Threads invoke methods
- Threads can experience arbitrary large delays



Is it correct? Yes!

Correctness

- Intuitively, if we rely on locks, changes happen in a non-interleaved fashion, resembling a sequential execution
- We can say a concurrent execution is correct only because we can associate it with a sequential one, which we know the functioning of
- An execution is correct if it is equivalent to a correct sequential execution

Correctness

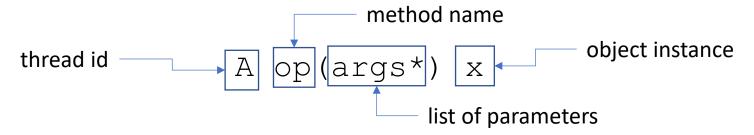
 An execution is correct if it is equivalent to a correct sequential execution

A simplified model of a concurrent system

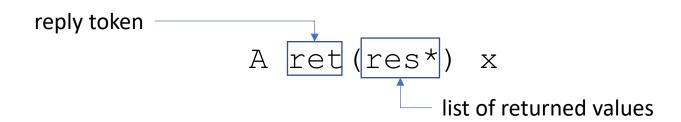
- A concurrent system is a collection of sequential threads/processes that communicate through shared data structures called objects.
- An object has a unique name and a set of primitive operations.

A simplified model of a concurrent execution

- A history is a sequence of invocations and replies generated on an object by a set of threads
- Invocation:



Reply:



A simplified model of a concurrent execution

- A sequential history is a history where all the invocations have an immediate response
- A concurrent history is a history that is not sequential

Sequential

H': A op() x A ret() x B op() x B ret() x A op() y A ret() y

Concurrent

Correctness

- An execution is correct if it is equivalent to a correct sequential execution
- ⇒ A history is correct if it is equivalent to a correct sequential history

A simplified model of a concurrent execution

 A process subhistory H|P of a history H is the subsequence of all events in H whose process names are P

```
H: A op() x
B op() x
A ret() x
A op() y
A op() y
B ret() x
A ret() y
```

Process subhistories are always sequential

Equivalence between histories

 Two histories H and H' are equivalent if for every process P, H|P=H'|P

```
H: A op() x
                    H': B op() x
                                          H|A:
   B op() x
                        B ret() x
                                         H' \mid A: A op() x
   A ret() x
                     A op() x
                                               A ret() x
   A op() y
                  A ret() x
                                               A op() y
   B ret() x
                     A op() y
                                               A ret() y
   A ret() y
                     A ret() y
                                          H|B:
                                         H'|B: B op() x
                                               B ret() x
```

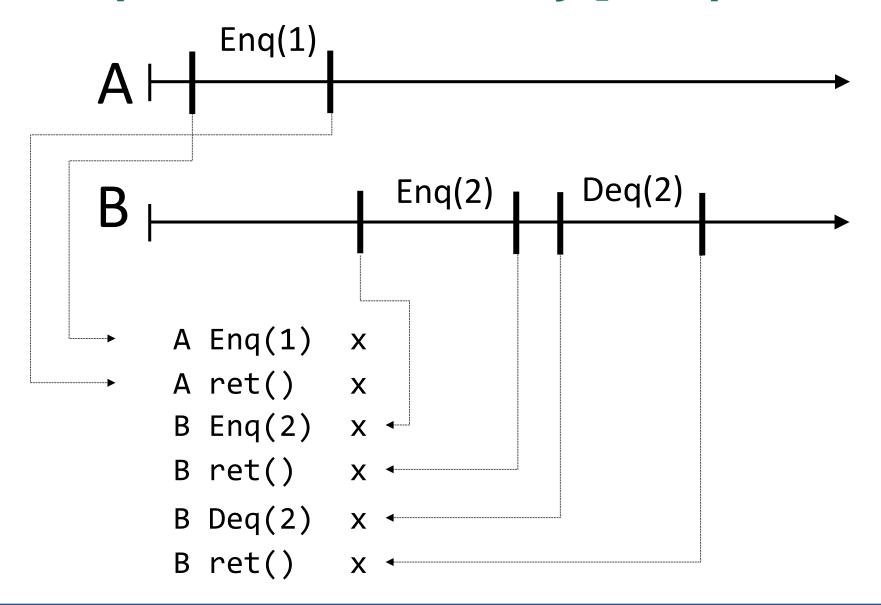
Correctness conditions

- A concurrent execution is correct if it is equivalent to a correct sequential execution
- ⇒ A history is correct if it is equivalent to a correct
 sequential history which satisfies a given correctness
 condition
- A correctness condition specifies the set of histories to be considered as reference
- ⇒In order to implement correctly a concurrent object wrt a correctness condition, we must guarantee that every possible history on our implementation satisfies the correctness condition

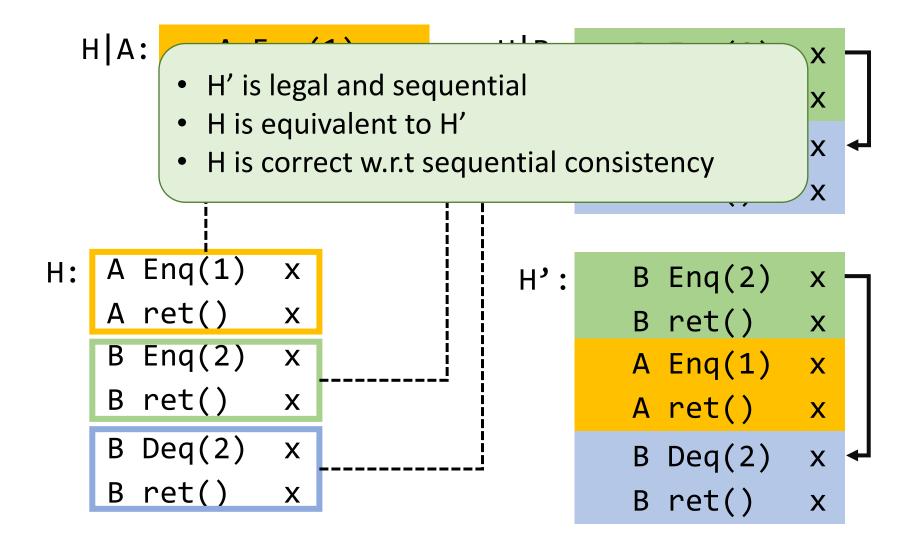
Sequential Consistency [Lamport 1970]

- A history H is sequentially consistent if
- 1. it is equivalent to a sequential history S
- 2. S is legal according to the sequential definition of the object
- ⇒ An object implementation is sequentially consistent if every history associated with its usage is sequentially consistent

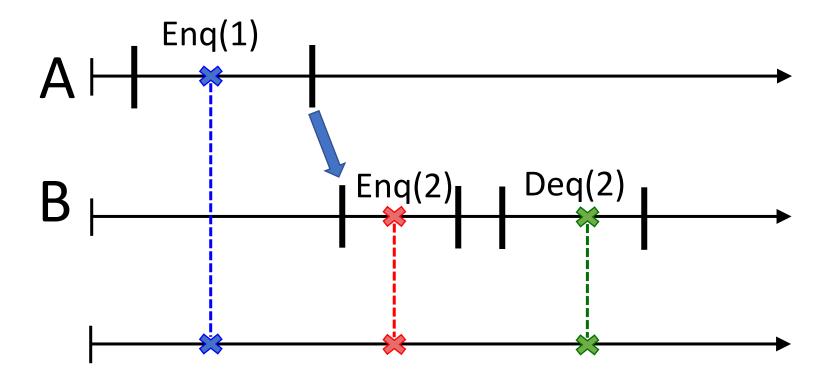
Sequential Consistency [Lamport 1970]

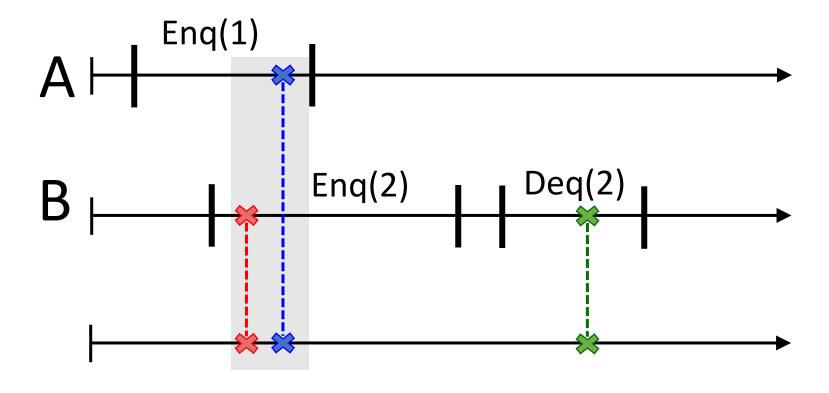


Sequential Consistency [Lamport 1970]



- A concurrent execution is linearizable if:
 - Each procedure appears to be executed in an indivisible point (*linearization point*) between its invocation and completion
 - The order among those points is correct according to the sequential definition of objects





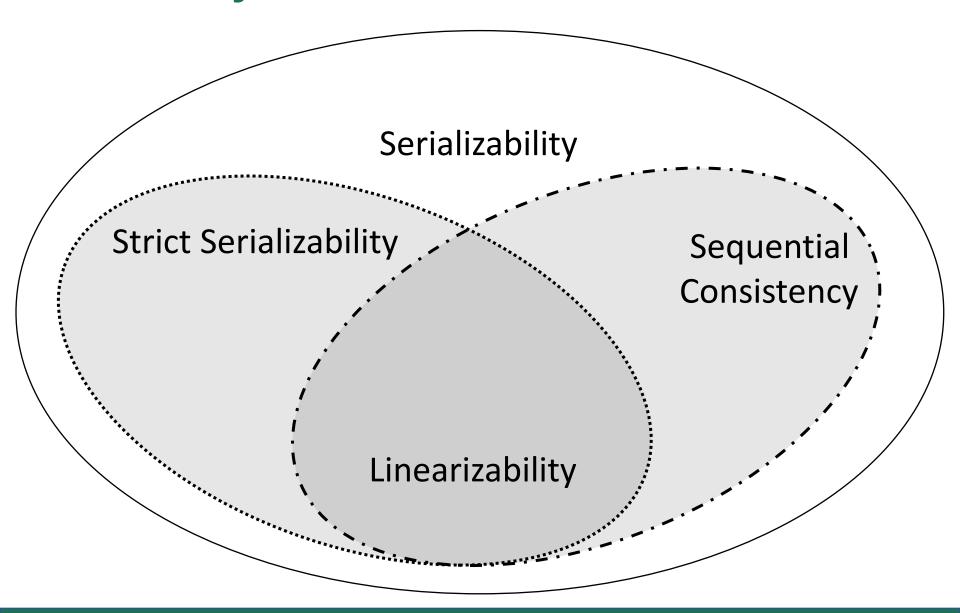
- A history H is linearizable if:
- 1. it is equivalent to sequential history S
- S is correct according to the sequential definition of objects
- 3. If a response precedes an invocation in the original history, then it must precede it in the sequential one as well
- ⇒ An object implementation is linearizable if every history associated with its usage can be linearized

- Linearizability requires:
 - Sequential Consistency
 - Real-time order
- Linearizability ⇒ Sequential Consistency
- The composition of linearizable histories is still linearizable
- Linearizability is a *local* property (closed under composition)

Quick look on transaction correctness conditions

- We can see a transaction as a set of procedures on different object that has to appear as atomic
- Serializability requires that transactions appear to execute sequentially, i.e., without interleaving.
 - A sort of sequential consistency for multi-object atomic procedures
- Strict-Serializability requires the transactions' order in the sequential history is compatible with their precedence order
 - A sort of linearizability for multi-object atomic procedures

A bird's eye view on correctness conditions



Correctness conditions (incomplete) taxonomy

	Sequential Consistency	Linearizability	Serializability	Strict Serializability
Equivalent to a sequential order			\	

Correctness conditions (incomplete) taxonomy

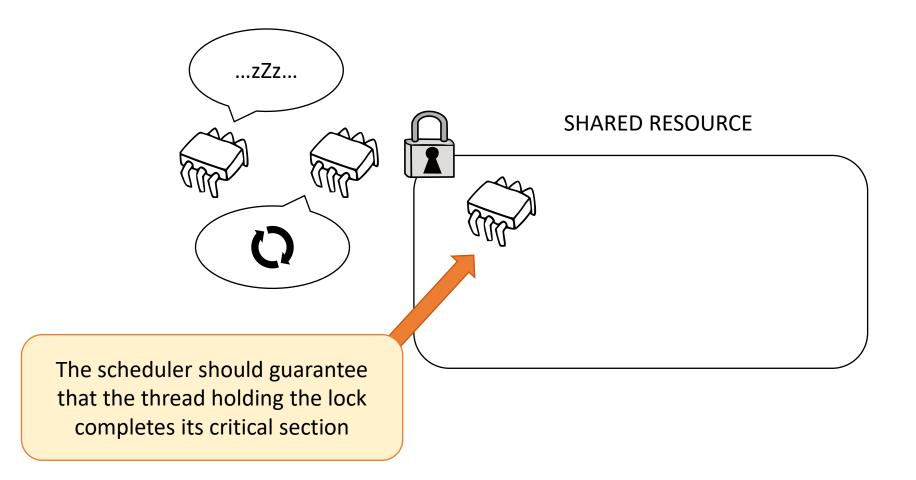
	Sequential Consistency	Linearizability	Serializability	Strict Serializability
Equivalent to a sequential order				
Respects program order in each thread				
Consistent with real-time ordering	×	✓	×	
Access multiple objects atomically	×	X		
Locality	X		X	X

Scalability Correctness conditions Progress conditions

Progress conditions

- Deadlock-freedom:
 - Some thread acquires a lock eventually
- Starvation-freedom:
 - Every thread acquires a lock eventually

Blocking synchronization



Scheduler's role

Progress conditions on multiprocessors

- Are not only about guarantees provided by a method implementation
- Are also about the scheduling support needed to provide progress

Requirement for lock-based applications

Fair histories

Every thread takes an infinite number of concrete steps

Progress conditions

Deadlock-freedom:

- Some thread acquires a lock eventually
- Some method call completes in every fair execution

Starvation-freedom:

- Every thread acquires a lock eventually
- Every method call completes in every fair execution

Lock-freedom:

Some method call completes in every execution

Wait-freedom:

Every method call completes in every execution

Obstruction-freedom:

 Every method call, which executes in isolation, completes

Progress taxonomy

	Non-blocking		Blocking
For everyone	Wait freedom	Obstruction freedom	Starvation freedom
For someone	Lock freedom		Deadlock freedom

Progress taxonomy

	Non-blocking		Blocking
For everyone	-	Thread executes in isolation	Fairness
For someone	-		Fairness

Progress taxonomy

	Independent	Depe	endent
	Non-blo	Blocking	
For everyone	Wait freedom	Obstruction freedom	Starvation freedom
For someone	Lock freedom		Deadlock freedom

- The Einsteinium of progress conditions: it does not exist in nature and (maybe) has no "commercial" value
- Clash freedom is a strictly weaker property than obstruction freedom