Programmazione concorrente

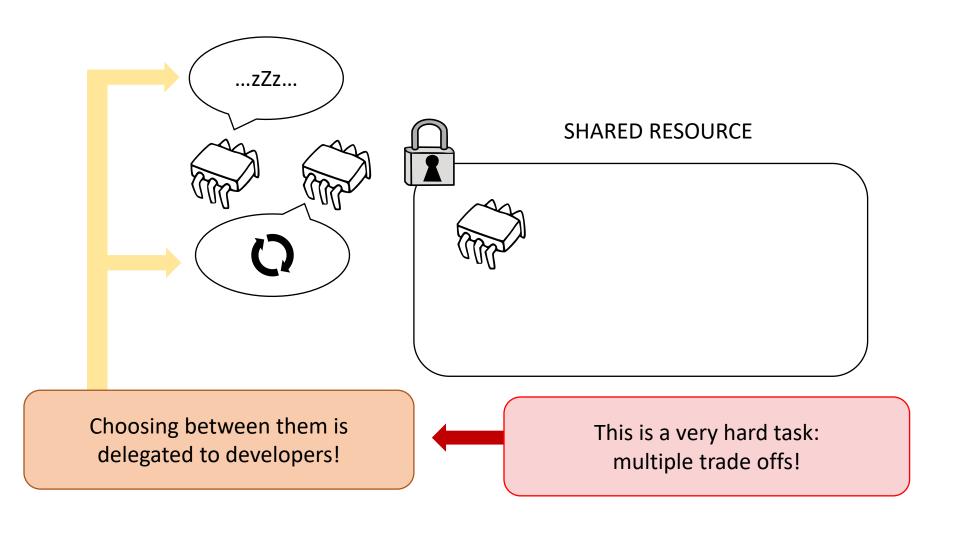
Laurea Magistrale in Ingegneria Informatica Università Tor Vergata Docente: Romolo Marotta

Docente: Romoio Marotta

Locks

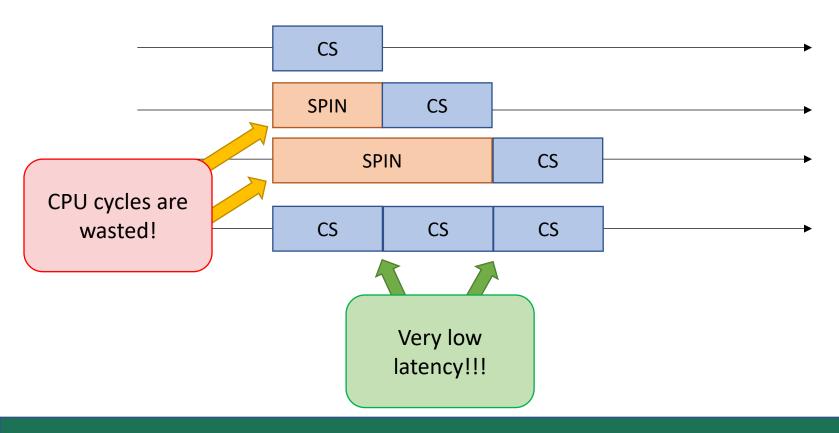
- 1. Spin locks
- 2. FIFO Spin locks
- 3. Hybrid (Spin+Sleep) locks

Blocking coordination

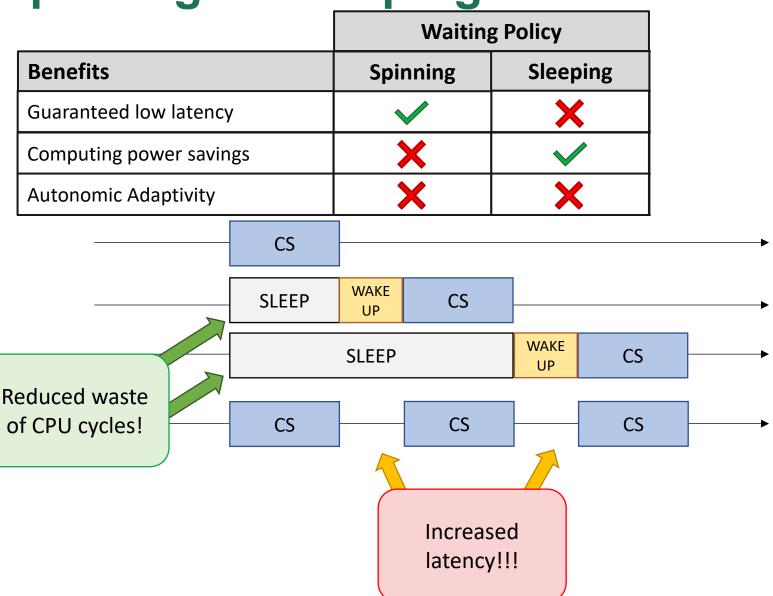


Spinning vs Sleeping

Benefits	Spinning
Guaranteed low latency	*
Computing power savings	X



Spinning vs Sleeping



Spin vs Sleep – is that all?

- Choosing the proper back off scheme is very challenging
- Even implementing a simple spin lock is not trivial
 - Trade off between low and high contented case
 - You should have heard about algorithms for Mutual Exclusion in Distributed Systems lectures
 - E.g. Dijkstra, Bakery algorithm, Peterson...
 - Those algorithm essentially implements spin locks by resorting only on read/write operations
- Here, we will focus on spin locking algorithms that exploit stronger synchronization primitives... RMW!

Test-and-set spin lock

- Test-and-set lock is the simplest spin lock
- Acquiring threads always try to set a variable via RMW

A small benchmark

- We have an array of integers
- Each thread reverse the array

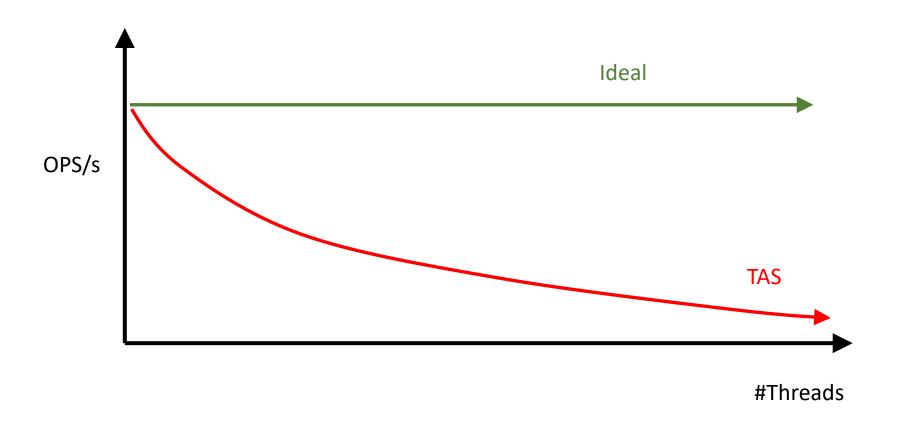


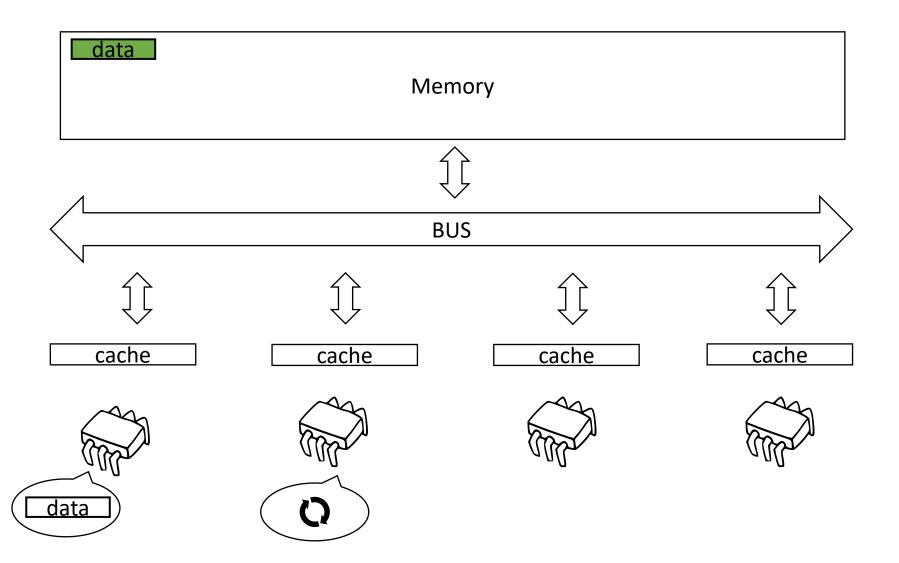
This is done within a critical section

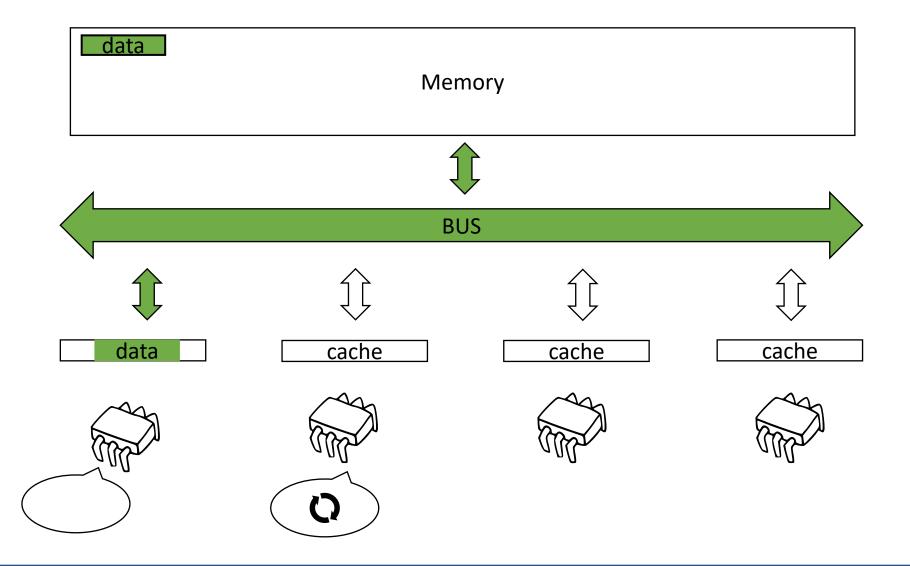
```
while(!stop){
   acquire(&lock);
   flip_array();
   release(&lock);
}
```

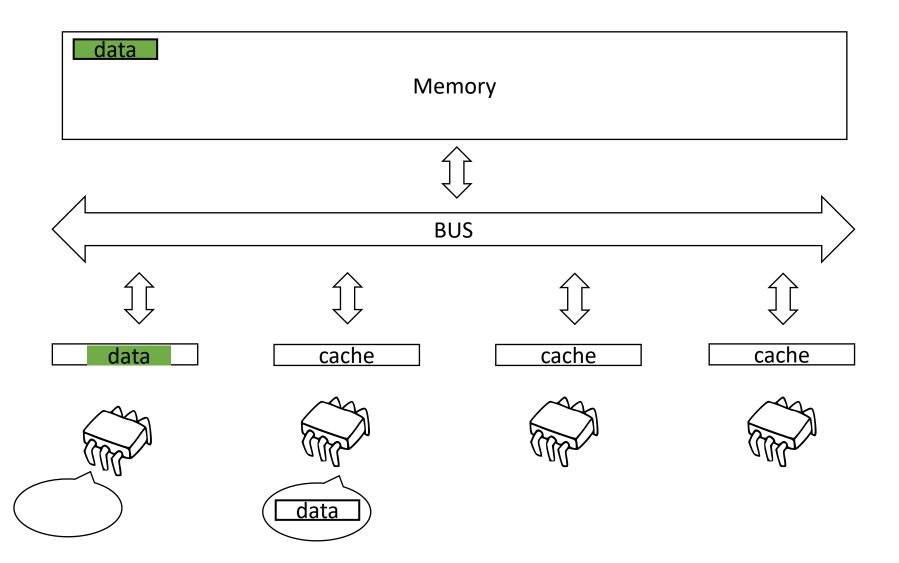
- Performance Metric:
 - Throughput = #Flips per second

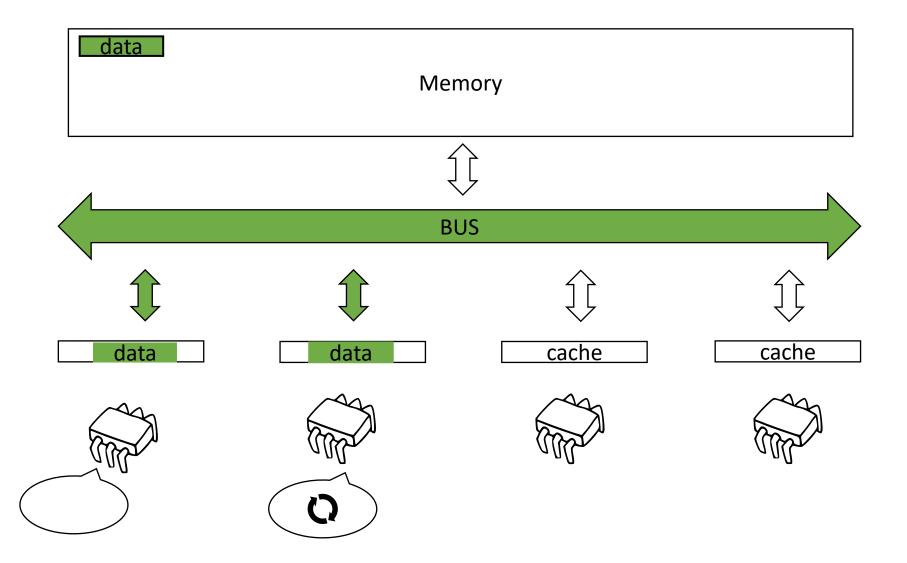
Results

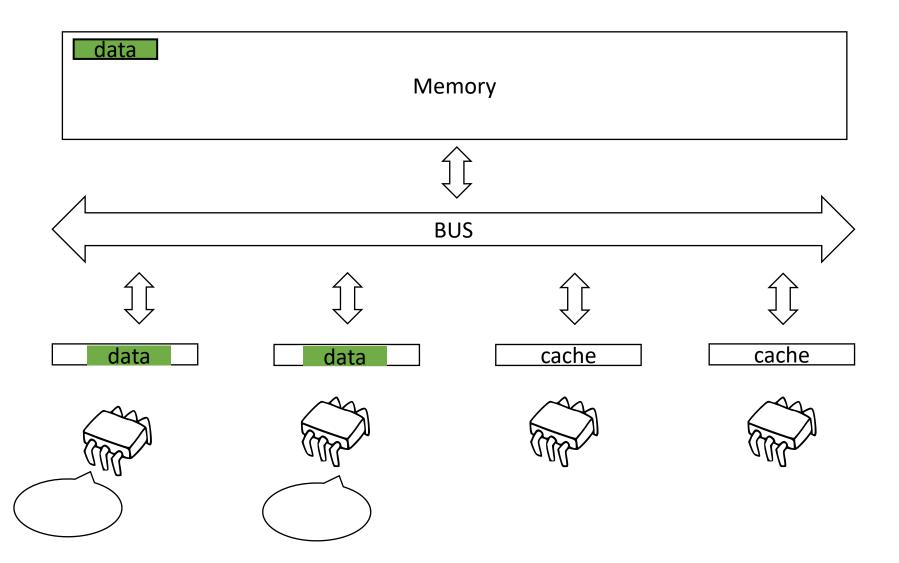


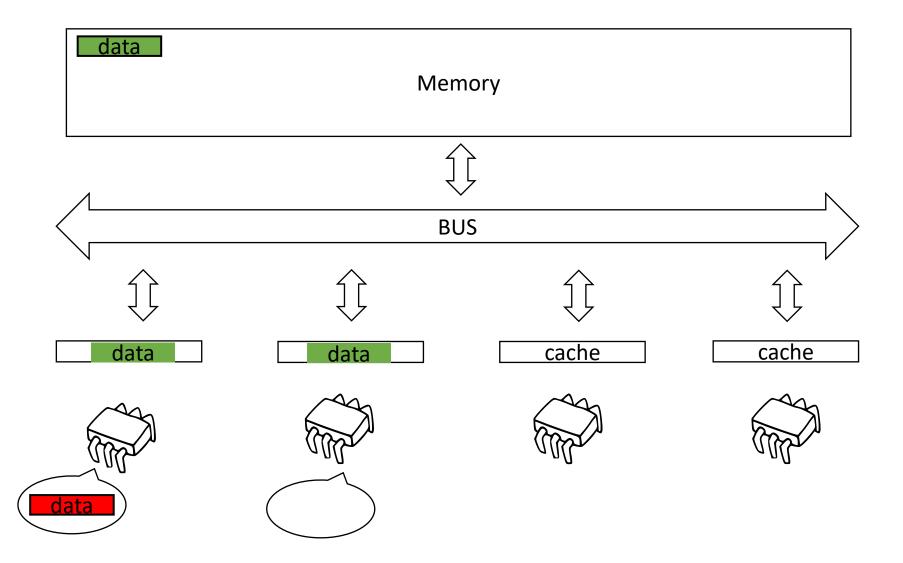


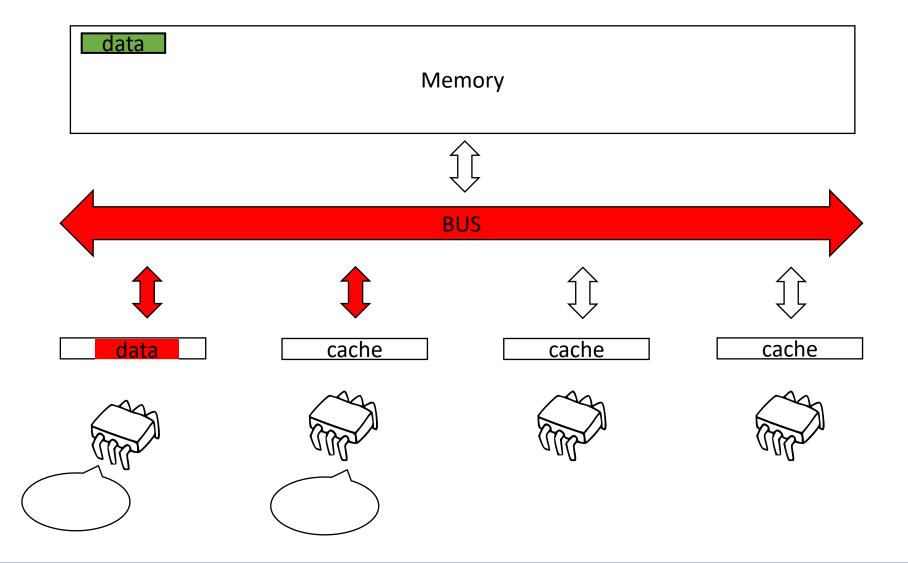


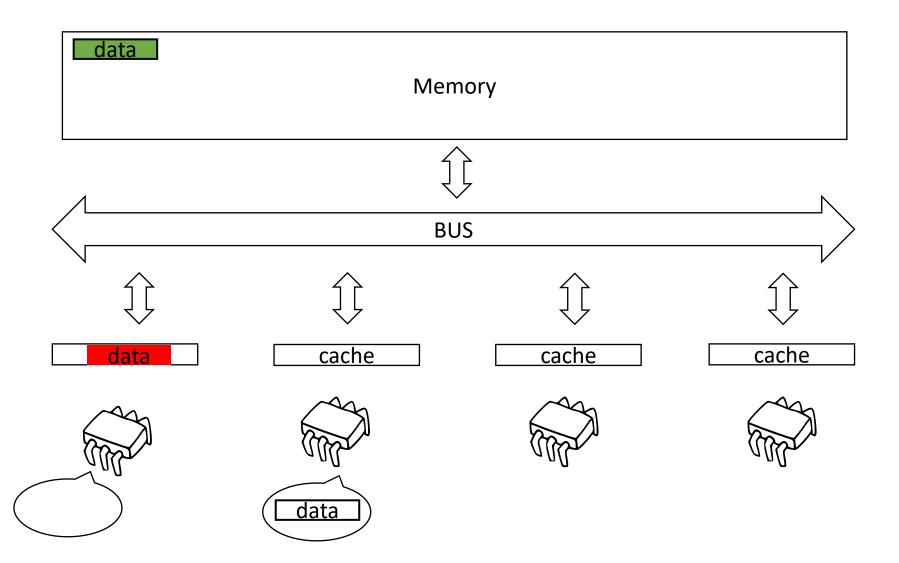


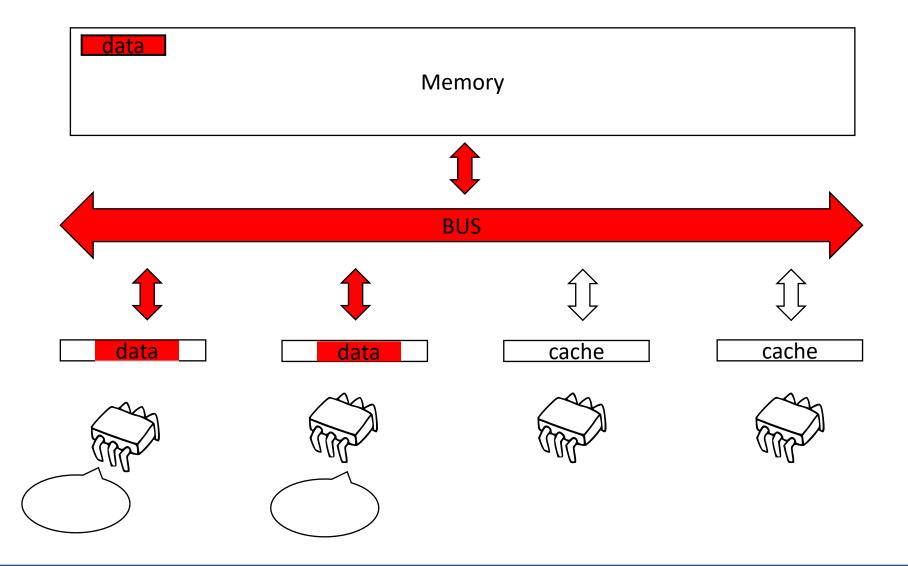


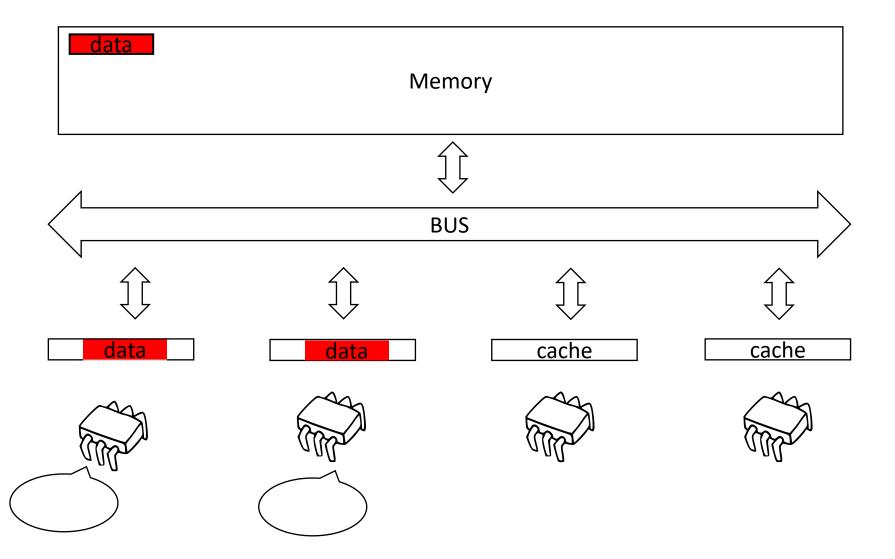










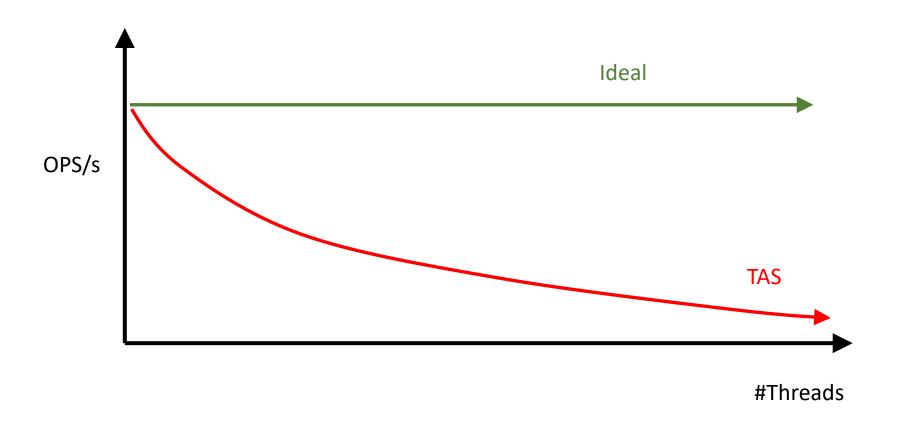


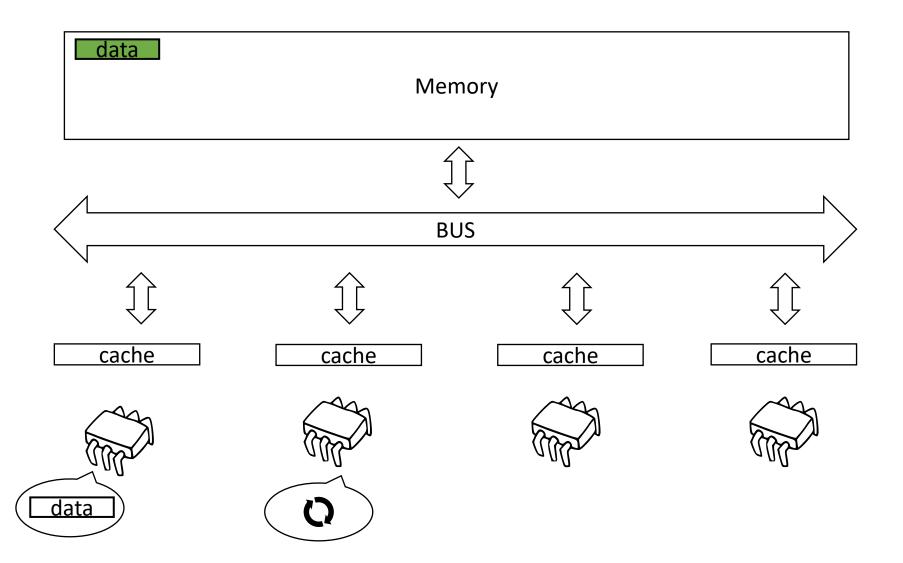
Lock implementations

Test-and-set spin lock

- Test-and-set lock is the simplest spin lock
- Acquiring threads always try to set a variable via RMW

Results





Test-and-set spin lock

- Test-and-set lock is the simplest spin lock
- Acquiring threads always try to set a variable via RMW

```
int lock = 0;
                             void release(int *lock){
void acquire(int *lock){
                               *lock = 0;
  while(XCHG(lock, 1));
                                 cache
    cache
                   cache
                                               cache
```

Test-and-set spin lock

- Test-and-set lock is the simplest spin lock
- Acquiring threads always try to set a variable via RMW

We can reduce the impact of memory traffic by introducing exponential back off!

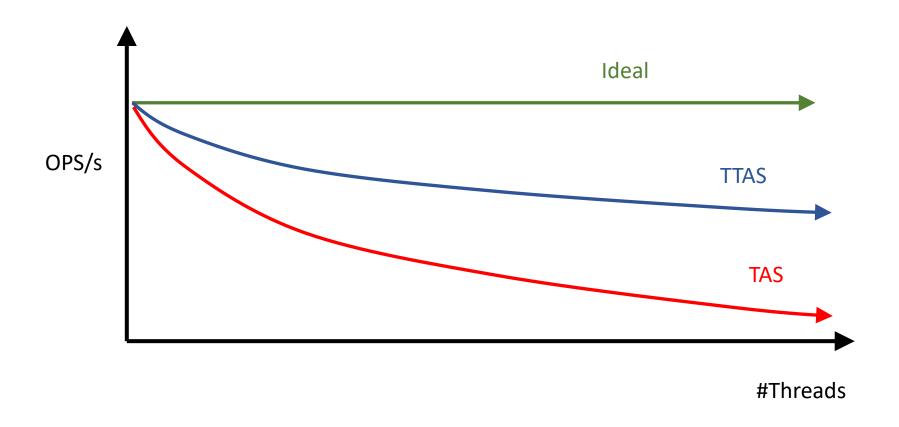
But how to set it properly?

Test-and-test-and-set spin lock

- Like test-and-set, but spins by reading the value of the lock
- Traffic is generated only upon lock handover

```
int lock = 0;
                            void release(int *lock){
void acquire(int *lock){
                              *lock = 0;
  while(XCHG(lock, 1))
     while(*lock);
    cache
                               cache
```

Results



Test-and-test-and-set spin lock

- Like test-and-set, but spins by reading the value of the lock
- Traffic is generated only upon lock handover

- Lock handover costs increase with the concurrency level
- Very lightweight for the uncontended case
- Is it feasible reducing handover costs?
- AND IMPROVING FAIRNESS?

FIFO locks

Ticket locks

- Similar to the bakery algorithm but it uses RMW instructions
- Two variables
 - The next available ticket
 - The served ticket

```
typedef struct _tck_lock{
  int ticket = 0;
  int current = 0;
} tck_lock;
```

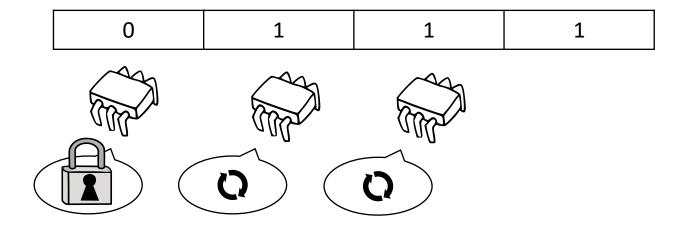
```
void acquire(tck_lock *lock){
   int cur_tck;
   int mytck = fetch&add(lock->ticket, 1);
   while(mytck != (cur_tck = lock->current) )
        delay((mytck-cur_tck)*BASE);
}
void release(tck_lock *lock){ lock->current += 1; }
```

Ticket locks

- Ensure fairness
- Similar structure w.r.t. TTAS spinlock
 - One variable updated once at each acquisition (better than TTAS)
 - Write-1-Read-N variable updated at each release (same as TTAS)
- How?

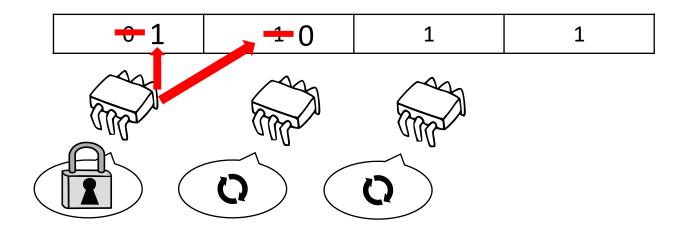
- Use similar to ticket lock
- Use the ticket to obtain an individual cache line

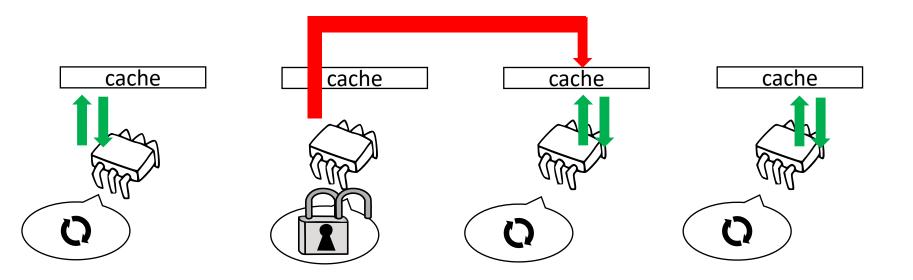
Ticket =
$$\frac{0.1}{2}$$
 3



- Use similar to ticket lock
- Use the ticket to obtain an individual cache line

Ticket =
$$\frac{0.1}{2}$$
 3





Pros:

- One variable updated once at each acquisition (like Ticket lock)
- Write-1-Read-1 variable updated once per release (better than (T)TAS and Ticket)

Cons:

- Increased memory footprint
- Each lock needs to know the maximum number of threads

Let:

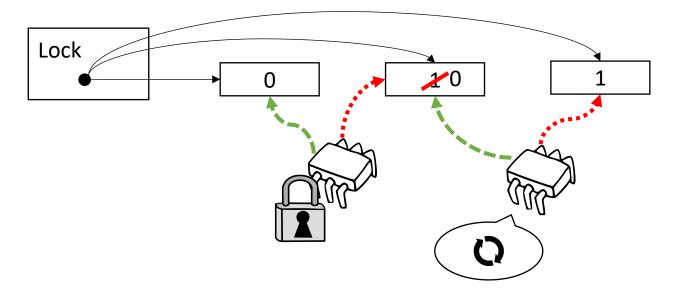
- T be the number of threads
- L be the number of locks

Space Usage

- Anderson = O(LT)
- TAS, TTAS, Ticket = O(L)

CLH lock

- An (implicit) linked list maintains the order between waiting threads
- An empty list represent an uncontended lock
- An arriving thread swaps the node with its private node
- Spin on the previous node
- Release on the new node



CLH queue lock

Pros:

- One variable updated once at each acquisition (like Ticket lock)
- Write-1-Read-1 variable updated once per release (better than (T)TAS and Ticket)

Cons:

Slightly increased memory footprint

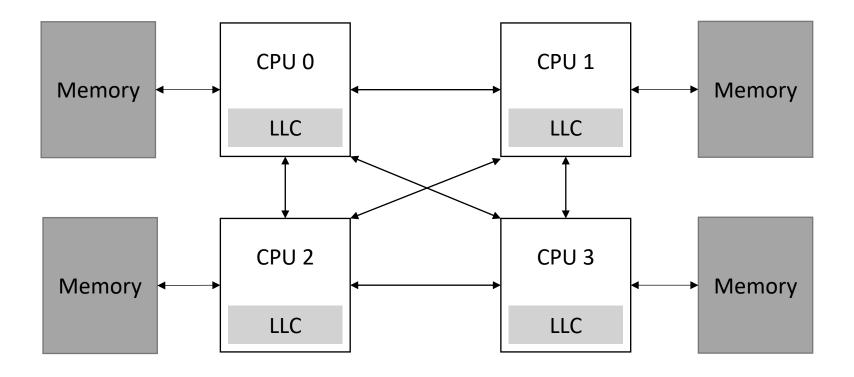
Let:

- T be the number of threads
- L be the number of locks

Space Usage

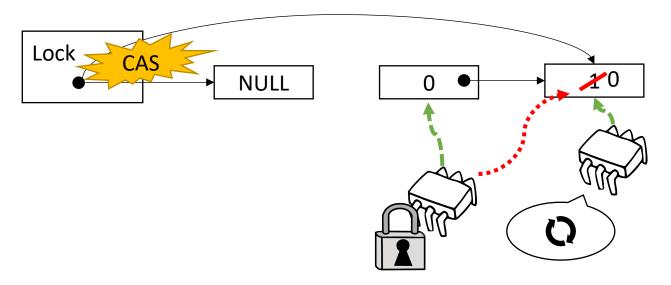
- CLH = O(L+T)
- Anderson = O(LT)
- TAS, TTAS, Ticket = O(L)

NUMA



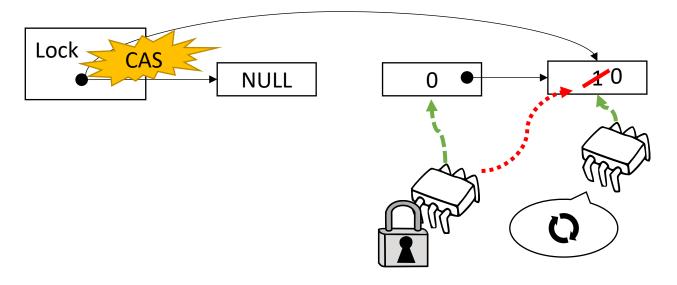
MCS lock

- An explicit linked list maintains the order between waiting threads
- An empty list represent an uncontended lock
- An arriving thread swaps the node with its private node
- Spin on the just inserted node
- Release on the new node



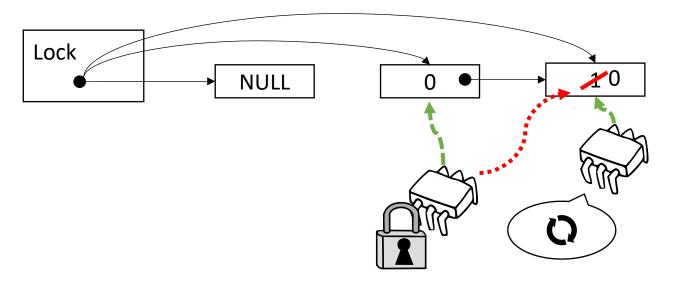
MCS lock

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MCS lock

- An explicit linked list maintains the order between waiting threads
- An empty list represent an uncontended lock
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- Spin on the just inserted node
- Release on the new node



MCS queue lock

Pros:

- One variable updated once at each acquisition (like Ticket lock)
- Write-1-Read-1 variable updated once per release (better than (T)TAS and Ticket)
- No-remote spinning

Cons:

Slightly increased memory footprint

Let:

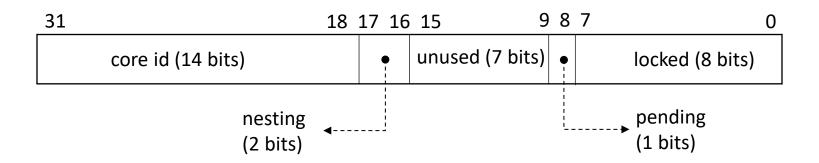
- T be the number of threads
- L be the number of locks

Space Usage

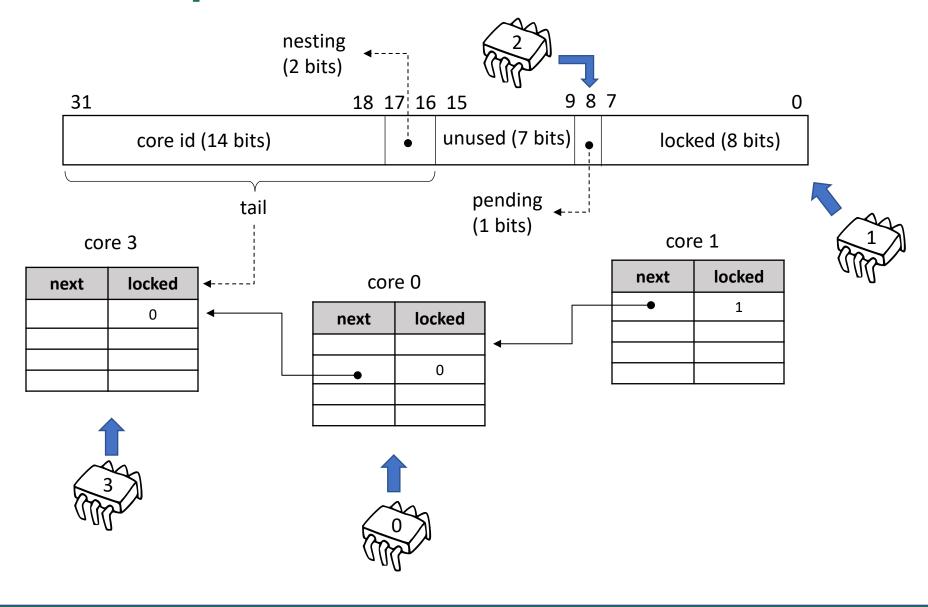
- MCS, CLH = O(L+T)
- Anderson = O(LT)
- TAS, TTAS, Ticket = O(L)

MCS in practice: the Linux kernel case

- The Linux kernel uses a particular implementation of a MCS lock: Qspinlock
- Additional challenge:
 - Maintain compatibility with classical 32-bit locks
 - MCS uses pointers (64-bit)
- Compact data:
 - 1. No recursion of same context in critical sections
 - 4 different contexts (task, softirq, hardirq, nmi)
 - 3. Finite number of cores
- Use an additional bit for fast lock handover



MCS in practice: the Linux kernel case



A small benchmark

- We have an array of integers
- Each thread reverse the array



This is done within a critical section

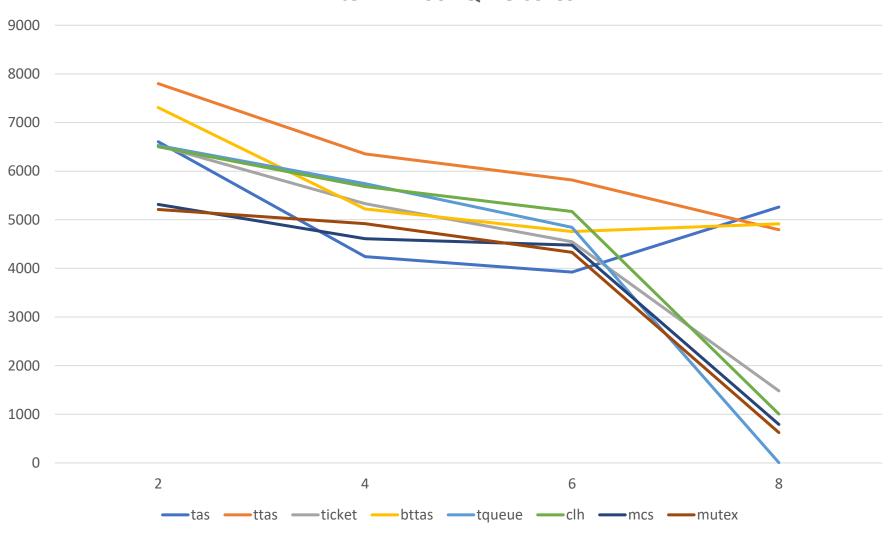
```
while(!stop){
   acquire(&lock);
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   release(&lock);
}
```

- Performance Metric:
 - Throughput = #Flips per second

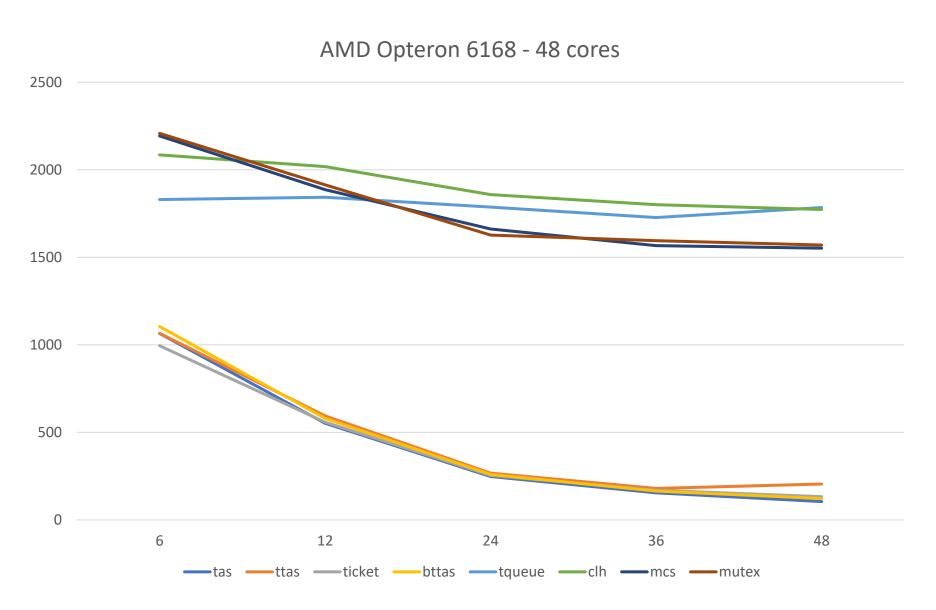
One lock to rule them all...

Performance



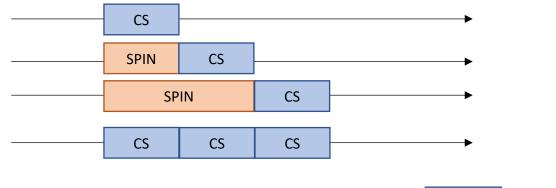


Performance



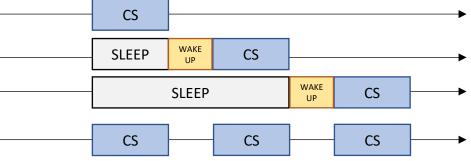
At the beginning was... Spin vs Sleep

	Waiting Policy	
Benefits	Spinning	Sleeping
Guaranteed low latency	~	X
Computing power savings	X	V



SPIN: ++Waste of CPU Cycles --Latency

Sleep:
--Waste of CPU Cycles
++Latency



How to avoid costs for sleeping?

A general approach exists:

- Reducing the frequency of sleep/wake-up pairs
- How?
- Trading Fairness in favor of Throughput
- Make some thread sleep longer than others
- If the lock is highly contented, some thread willing to access the critical section will arrive soon
- If the lock is scarcely contented, we pay lower latency as TTAS locks

An example - MutexEE

 MutexEE is a pthread_mutex optimized for throughput and energy efficiency

lock()

MUTEX	MUTEXEE	
For up to 100 attempts		
spin with pause		
if still busy, sleep		

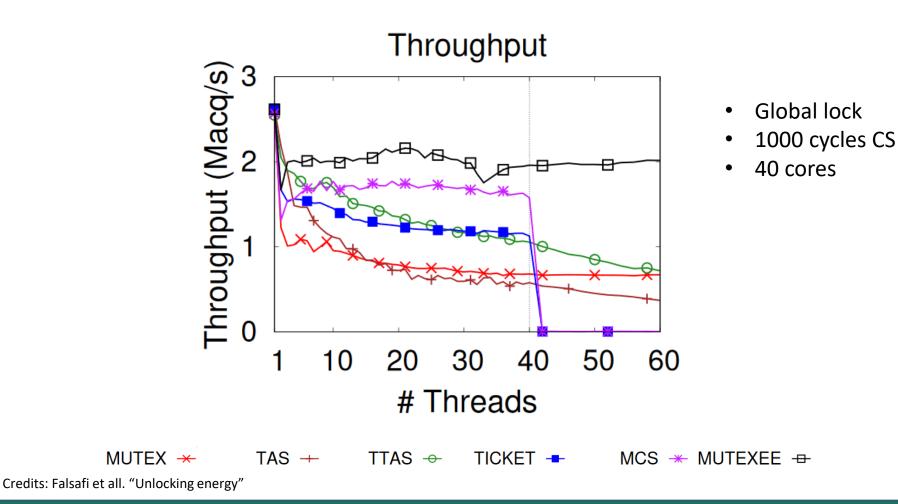
unlock()

MUTEX	MUTEXEE	
release in user space (lock->locked = 0)		
wake up a thread		

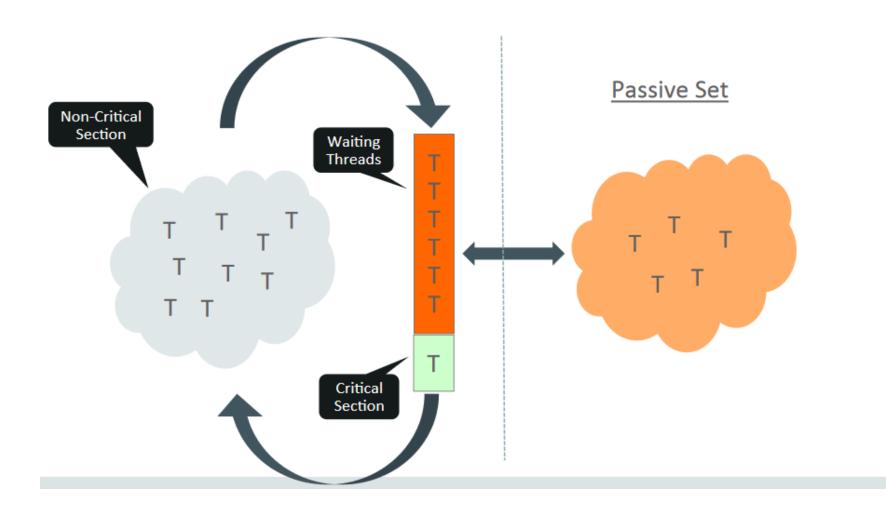
Credits: Falsafi et all. "Unlocking energy"

An example - MutexEE

 MutexEE is a pthread_mutex optimized for throughput and energy efficiency

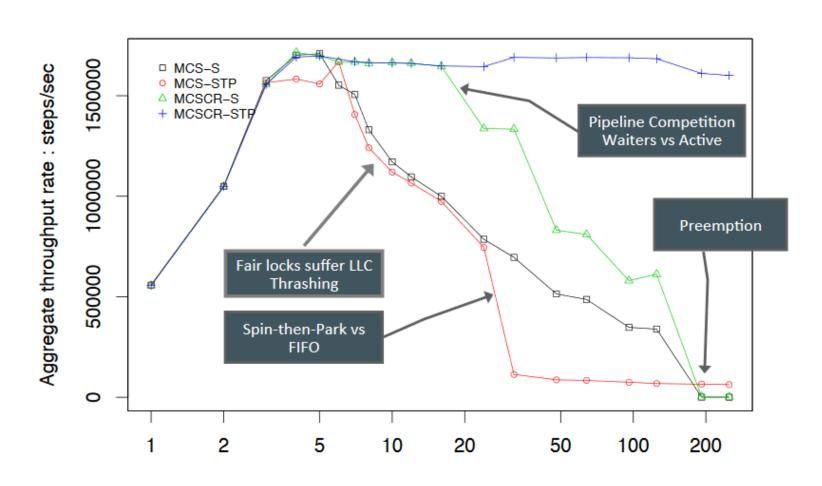


An example 2 – Malthusian locks



Credits: Dave Dice "Malthusian locks"

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Hierarchical locks

HPC wants maximum usage of CPU power

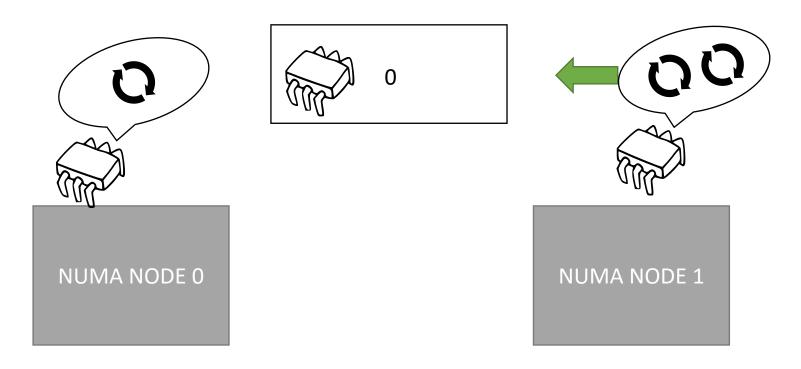
- Sleeping might be required for better management of I/O
- Large number of cores per machine
- ⇒NUMA (again)
- FIFO locks cannot avoid transfer to remote NUMA nodes

Again, we can trade fairness in favor of throughput

Optimizing Critical Section Execution

Hierarchical locks

- Transfer the lock to threads that reside on the same NUMA node
- Hierarchical TTAS
 - Shorter backoff for local threads, longer for remote ones



Hierarchical locks

- Transfer the lock to threads that reside on the same NUMA node
- Hierarchical TTAS
 - Shorter backoff for local threads, longer for remote ones
- Hierarchical QUEUE LOCKS (lock cohorting)
 - One global lock (the application one)
 - One lock per NUMA note ("under the hoods")

 NUMA NODE 0

 NUMA NODE 1

Optimizing the waiting phase

We have seen several approaches to optimize the lock acquisition phase:

- Back-off scheme
- Cache-awareness TTAS, FIFO locks
- Non-trivial combinations of both sleep and spin phases

What can we do to improve the execution of threads running the critical section?

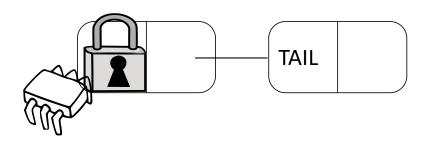
Improve locality and cache usage

How?

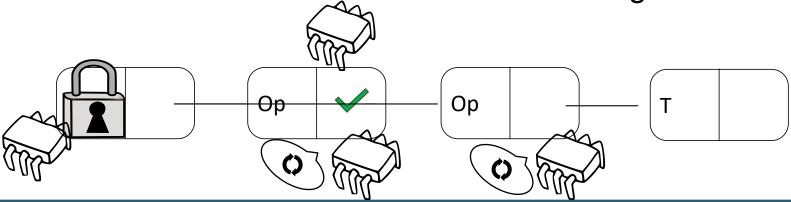
Observation:

- A lock (typically) protects data (instead of code)
 Idea!
- There is a good chance that threads willing to acquire a lock want to access "similar" sets of data
- ⇒Allow thread holding the lock to execute the critical section for waiting threads
- Reduces lock handover costs
- Increases locality

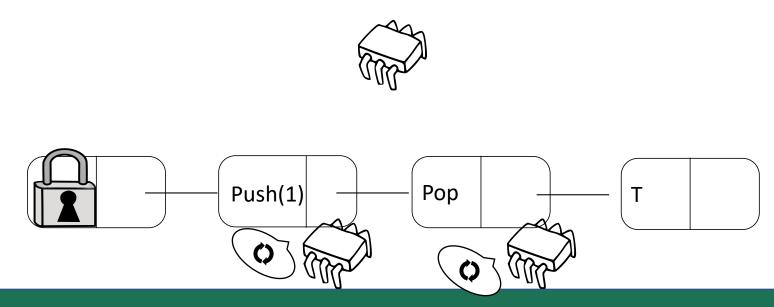
- Use a linked list for holding waiting threads
- Each node maintains:
 - The waiting thread ID
 - The critical section descriptor
- Thread check waiting queue before releasing the lock
 - If empty exit



- Use a linked list for holding waiting threads
- Each node maintains:
 - The waiting thread ID
 - The critical section descriptor
- Thread check waiting queue before releasing the lock
 - If empty exit
 - Otherwise take a node from the waiting queue and execute the critical section for the waiting thread

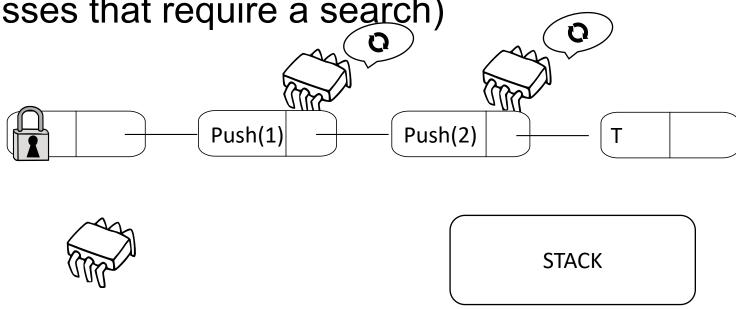


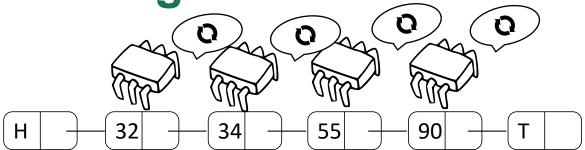
- It might allow further (asymptotic) optimizations (e.g., data structures)
- Operations can be combined to each other BEFORE interacting with protected data



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- Operations can be combined to each other BEFORE interacting with protected data

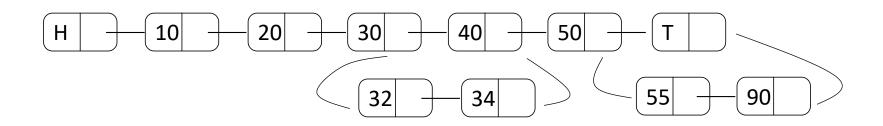
 Operations can be applied in batch (relevant for accesses that require a search)



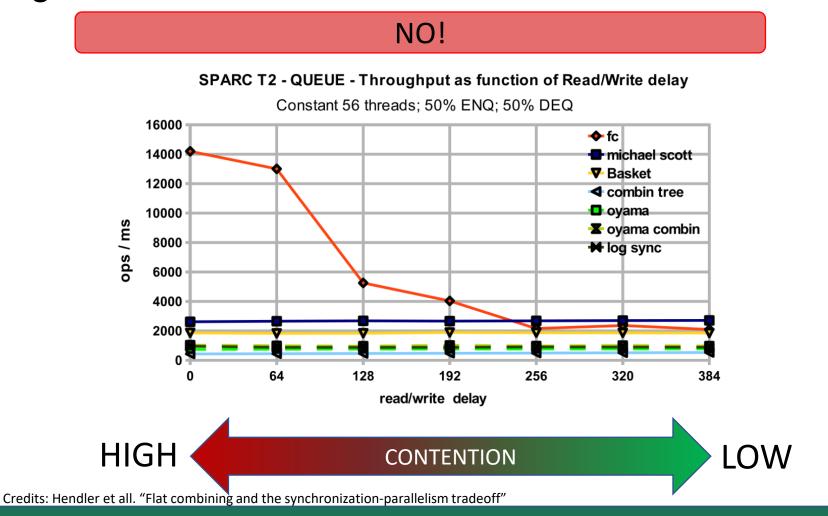




No need for restarting the search from scratch!



Is it a silver bullet? Can replace complex lock-free algorithms?



Is it a silver bullet? Can replace complex lock-free algorithms?

- No, performance depends on the actual contention!
- Combining requires hand-written code!

How to improve for NUMA?

Hierarchical Flat Combining

Approaches targeting peculiar workloads

- Read-Write locks
 - Threads that do not want to perform updates can acquire the lock with other "readers"
 - Threads willing to perform updates ("writers") take exclusive lock
- Easy to implement:

Lock < 0 : acquired by a writer

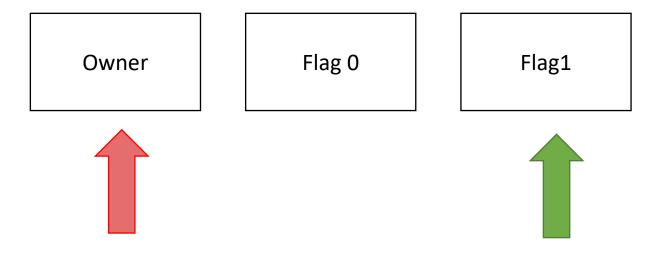
Lock = 0 : available

Lock = N > 0 : locked by N readers

- RW locks work well in read-mostly workloads, but:
 - It has a greater impact to readers (exclusive accesses to the lock variable)
 - Can be optimized by splitting the read counter

RW locks

Multiple RW locks (each one has its own cache line)



Writer acquire Owner and spin until all flags are 0

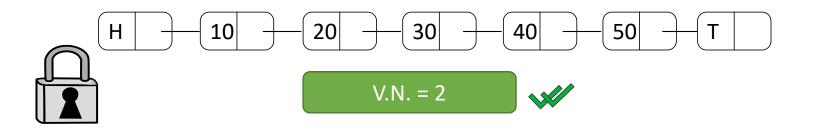
If Owner is free Readers acquire their assigned Flag (e.g. the one of their numa node) Then, check again Owner

Approaches targeting peculiar workloads (2)

- When read-only accesses are predominant, we can make reader DO NOT use any lock
- Version Numbers
- Writer:
 - Acquire a (writer) lock
 - Increase Version Number
 - Apply Update
 - Increase Version Number
 - Release Lock

Reader:

- Wait even Version Number
- Do job
- If Version Number is unchanged OK else retry



Approaches targeting peculiar workloads (3)

- When read-only accesses are predominant, we can make reader DO NOT use any lock
- Version Numbers
- Read-Copy-Update
 - Single shared-data entry point

These solutions NEEDS memory management as non-blocking algorithms!!!