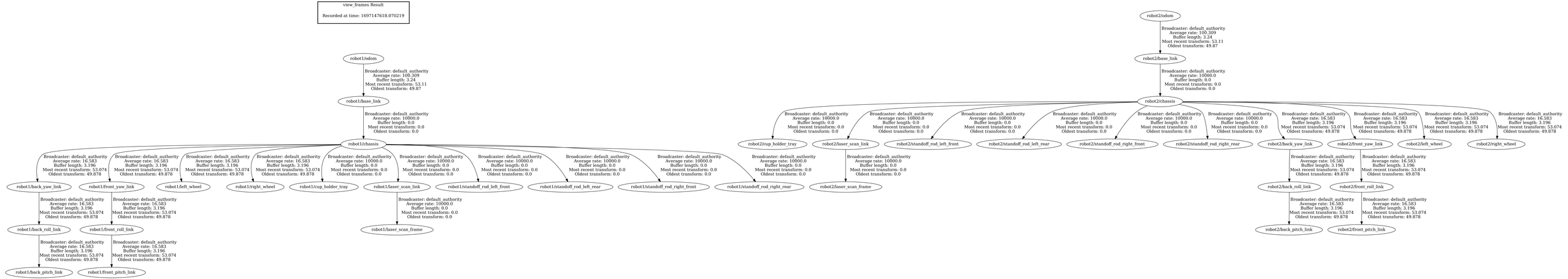
view_frames Result
Recorded at time: 1697147618.070219
robot1/odom
Broadcaster: default_authority
Average rate: 100.309
Buffer length: 3.24
Most recent transform: 53.11
Oldest transform: 49.87
robot1/base_link
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
robot1/chassis
Broadcaster: default_authority
Average rate: 16.583
Buffer length: 3.196
Most recent transform: 53.074
Oldest transform: 49.878
robot1/back_yaw_link
robot1/front_yaw_link
robot1/left_wheel
robot1/right_wheel
robot1/cup_holder_tray
robot1/laser_scan_link
robot1/standoff_rod_left_front
robot1/standoff_rod_left_rear
robot1/standoff_rod_right_front
robot1/standoff_rod_right_rear
robot1/back_roll_link
robot1/front_roll_link
robot1/laser_scan_frame
robot1/back_pitch_link
robot1/front_pitch_link
robot2/odom
Broadcaster: default_authority
Average rate: 100.309
Buffer length: 3.24
Most recent transform: 53.11
Oldest transform: 49.87
robot2/base_link
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
robot2/chassis
robot2/cup_holder_tray
robot2/laser_scan_link
robot2/standoff_rod_left_front
robot2/standoff_rod_left_rear
robot2/standoff_rod_right_front
robot2/standoff_rod_right_rear
robot2/back_yaw_link
robot2/front_yaw_link
robot2/left_wheel
robot2/right_wheel
robot2/laser_scan_frame
robot2/back_roll_link
robot2/front_roll_link
robot2/back_pitch_link
robot2/front_pitch_link