Rocket Problem

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BACKGROUND

In this problem, we solve several differential equations numerically using MATLAB. These equations describe the time-dependent mass, velocity, and position of a rocket ship during a launch. The associated MATLAB code and output plots are presented below.

```
% Input Values
                                                    function g = eqns(t,z)
Md = 730000; \% kg (dry mass)
Mp = 2100000; % kg (propellant mass)
                                                    % Input Values
                                                    T = 37000000; % N (thrust)
% Initial Conditions:
                                                    g = 9.8; % m/s/s (acceleration due to gravity)
Y0 = 0; % m (position)
                                                    P0 = 1.2; % kg/m<sup>3</sup> (density)
M0 = Md + Mp; \% kg (mass)
                                                    Cd = 0.0075; % (drag coefficient)
V0 = 0; % m/s (velocity)
                                                    As = pi*10*110; % Surface area (pi*D*H)
                                                    V_i = 3528; % m/s (velocity of jet)
% Time Window:
                                                    % Variables to solve for:
t0 = 0:
tmax = 350:
                                                    Y = z(1); % position
                                                    M = z(2); \% mass
% Solve for X0, v0, and M0:
                                                    V = z(3); % velocity
zo=[Y0 M0 V0];
                                                    % Forces:
% Call ODE:
                                                    Fd = .5*(P0)*Cd*As*(V^2)*exp(-Y/7300); \% N
[t,z]=ode45('eqns',[t0,tmax],zo);
                                                    (drag force)
                                                    Fg = g*M; % N (gravitational pull)
% Graph:
figure:
                                                    % ODEs:
plot(t,z(:,1),'b-');
                                                    dYdt = V;
title('Altitude');
xlabel('Time');
                                                    if M > 730000;
ylabel('Meters');
                                                    dMdt = (-1*T/Vi);
                                                    else
figure;
                                                    dMdt = 0;
plot(t,z(:,2),'r-');
                                                    end
title('Mass');
xlabel('Time');
                                                    if M > 730000:
ylabel('Kg');
                                                    dVdt = (T-Fd-(Fg)-((T/Vj)*V))/M;
                                                    dVdt = (-Fd-(Fg)-((T/Vj)*V))/M;
figure;
plot(t,z(:,3),'g-');
title('Velocity');
xlabel('Time');
                                                    g = [dYdt dMdt dVdt]';
ylabel('meters / sec');
```

Figure 1, MATLAB code.





