

# Exercise Sheet 1 - solutions

$$\textcircled{1} \quad |\alpha\rangle = 7i|1\rangle - |2\rangle + 3|3\rangle$$

$$|\beta\rangle = 4i|1\rangle + 2|2\rangle$$

$$a) \quad \langle\alpha| = (|\alpha\rangle)^\dagger = -7i\langle 1| - \langle 2| + 3\langle 3|$$

$$\langle\beta| = -4i\langle 1| + 2\langle 2|$$

$$b) \quad \langle\alpha|\beta\rangle = (-7i\langle 1| - \langle 2| + 3\langle 3|)(4i|1\rangle + 2|2\rangle)$$

$$= -7i \cdot 4i \langle 1|1\rangle - 2 \cdot 7i \langle 1|2\rangle - 2\langle 2|2\rangle$$

$$- 4i\langle 1|2\rangle + 3 \cdot 4i\langle 3|1\rangle + 3 \cdot 2\langle 3|2\rangle$$

$$= -28i^2 - 2 = 28 - 2 = 26$$

$$\langle\beta|\alpha\rangle = (-4i\langle 1| + 2\langle 2|)(7i|1\rangle - |2\rangle + 3|3\rangle)$$

$$= -28i^2 - 2 = 26$$

$$\|\alpha\|^2 = \langle \alpha | \alpha \rangle = (-7i\langle 1| - \langle 2| + 3\langle 3|)(7i|1\rangle - |2\rangle + 3|3\rangle)$$

$$= -49i^2 \langle 1|1\rangle + \langle 2|2\rangle + 3^2 \langle 3|3\rangle$$

$$= 49 + 1 + 9 = 59$$

normalized version of  $|\alpha\rangle$ :  $|\tilde{\alpha}\rangle = \frac{1}{\sqrt{59}} |\alpha\rangle$

$$c) |\alpha\rangle\langle\beta| = (7i|1\rangle - |2\rangle + 3|3\rangle)(-4i\langle 1| + 2\langle 2|)$$

$$= -28i^2 |1\rangle\langle 1| + 2 \cdot 7i |1\rangle\langle 2| - 4i |2\rangle\langle 1|$$

$$- 2|2\rangle\langle 2| - 4 \cdot 3i |3\rangle\langle 1| + 3 \cdot 2|3\rangle\langle 2|$$

$$= \begin{pmatrix} 28 & 14i & 0 \\ -4i & -2 & 0 \\ -12i & 6 & 0 \end{pmatrix}$$

$$(|\alpha\rangle\langle\beta|)^{\dagger} = \begin{pmatrix} 28 & -4i & -12i \\ 14i & -2 & 6 \\ 0 & 0 & 0 \end{pmatrix} \neq |\alpha\rangle\langle\beta|$$

→ not Hermitian

$$|\alpha\rangle\langle\alpha| = \begin{pmatrix} 49 & -7i & 21i \\ 7i & 1 & -3 \\ -21i & -3 & 9 \end{pmatrix}$$

$$(|\alpha\rangle\langle\alpha|)^{\dagger} = |\alpha\rangle\langle\alpha| \text{ is Hermitian.}$$

$$\textcircled{2} \quad |\psi\rangle = \alpha|0\rangle + \beta|1\rangle$$

$$\begin{aligned} \text{a) } \|\psi\|^2 &= \langle\psi|\psi\rangle = (\bar{\alpha}\langle 0| + \bar{\beta}\langle 1|)(\alpha|0\rangle + \beta|1\rangle) \\ &= \bar{\alpha}\alpha\langle 0|0\rangle + \bar{\beta}\beta\langle 1|1\rangle \end{aligned}$$

$$= |\alpha|^2 + |\beta|^2 = 1$$

$$b) \quad |\psi\rangle = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

$\alpha \in \mathbb{C} \rightarrow$  can be written as  $\alpha = \phi_0 e^{i\theta_0}$   $\begin{matrix} \swarrow \in \mathbb{R} \\ \searrow \in \mathbb{R} \end{matrix}$   
in terms of parameters  $\phi_0, \theta_0 \in \mathbb{R}$

$$\beta \in \mathbb{C} \rightarrow \beta = \phi_1 e^{i\theta_1}$$

$$|\psi\rangle = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} \phi_0 e^{i\theta_0} \\ \phi_1 e^{i\theta_1} \end{pmatrix} = \begin{pmatrix} \phi_0 e^{i\theta_0} \\ \sqrt{1-\phi_0^2} e^{i\theta_1} \end{pmatrix} = e^{i\theta_0} \begin{pmatrix} \phi_0 \\ \sqrt{1-\phi_0^2} e^{i(\theta_1-\theta_0)} \end{pmatrix}$$

$\uparrow$   
 $|\alpha|^2 + |\beta|^2 = \phi_0^2 + \phi_1^2$

global  
phase  $\rightarrow$

$$\begin{pmatrix} \phi_0 \\ \sqrt{1-\phi_0^2} e^{i(\theta_1-\theta_2)} \end{pmatrix} \begin{matrix} \uparrow \\ \uparrow \end{matrix} = \begin{pmatrix} \cos \frac{\Theta}{2} \\ \sin \frac{\Theta}{2} \cdot e^{i\omega} \end{pmatrix}$$

can reparametrize:  $\phi_0 = \cos \frac{\theta}{2}$   
 $\theta_1 - \theta_2 = \omega$

c) spherical coordinates:  $\vec{r}_{\theta, \omega} = \begin{pmatrix} \sin \theta \cos \omega \\ \sin \theta \sin \omega \\ \cos \theta \end{pmatrix}$

$$|0\rangle \stackrel{!}{=} \cos \frac{\theta}{2} |0\rangle + e^{i\omega} \sin \frac{\theta}{2} |1\rangle$$

$$\leadsto \cos \frac{\theta}{2} = 1 \leadsto \theta = 0$$

$$\sin \frac{\theta}{2} = 0$$

$\omega$  can be anything  
 $\omega = 0$

$$\vec{r}_{|0\rangle} = \vec{r}_{0,0} = \begin{pmatrix} 0 \\ 0 \\ \cos(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$|1\rangle \stackrel{!}{=} \cos \frac{\theta}{2} |0\rangle + e^{i\omega} \sin \frac{\theta}{2} |1\rangle$$

$$\leadsto e^{i\omega} \sin \frac{\theta}{2} = 1 \quad \{ \theta = \pi$$

$$\cos \frac{\theta}{2} = 1 \quad \omega = 0$$

$$\vec{r}_{115} = \vec{r}_{\pi, 0} = \begin{pmatrix} \sin(\pi) \cos(0) \\ \sin(\pi) \sin(0) \\ \cos(\pi) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$|+\rangle = \frac{1}{\sqrt{2}} |0\rangle + \frac{1}{\sqrt{2}} |1\rangle$$

$$\begin{aligned} \leadsto \cos \frac{\theta}{2} &= \frac{1}{\sqrt{2}} \\ \sin \frac{\theta}{2} e^{i\omega} &= \frac{1}{\sqrt{2}} \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \begin{array}{l} \theta = \pi/2 \\ \omega = 0 \end{array}$$

$$\vec{r}_{|+\rangle} = \vec{r}_{\pi/2, 0} = \begin{pmatrix} \sin \frac{\pi}{2} \cos 0 \\ \sin \frac{\pi}{2} \sin 0 \\ \cos \frac{\pi}{2} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$|-\rangle = \frac{1}{\sqrt{2}} |0\rangle - \frac{1}{\sqrt{2}} |1\rangle$$

$$\cos \frac{\theta}{2} = \frac{1}{\sqrt{2}} \quad \left. \begin{array}{l} \\ \end{array} \right\} \begin{array}{l} \theta = 3\pi/2 \\ \omega = 0 \end{array}$$

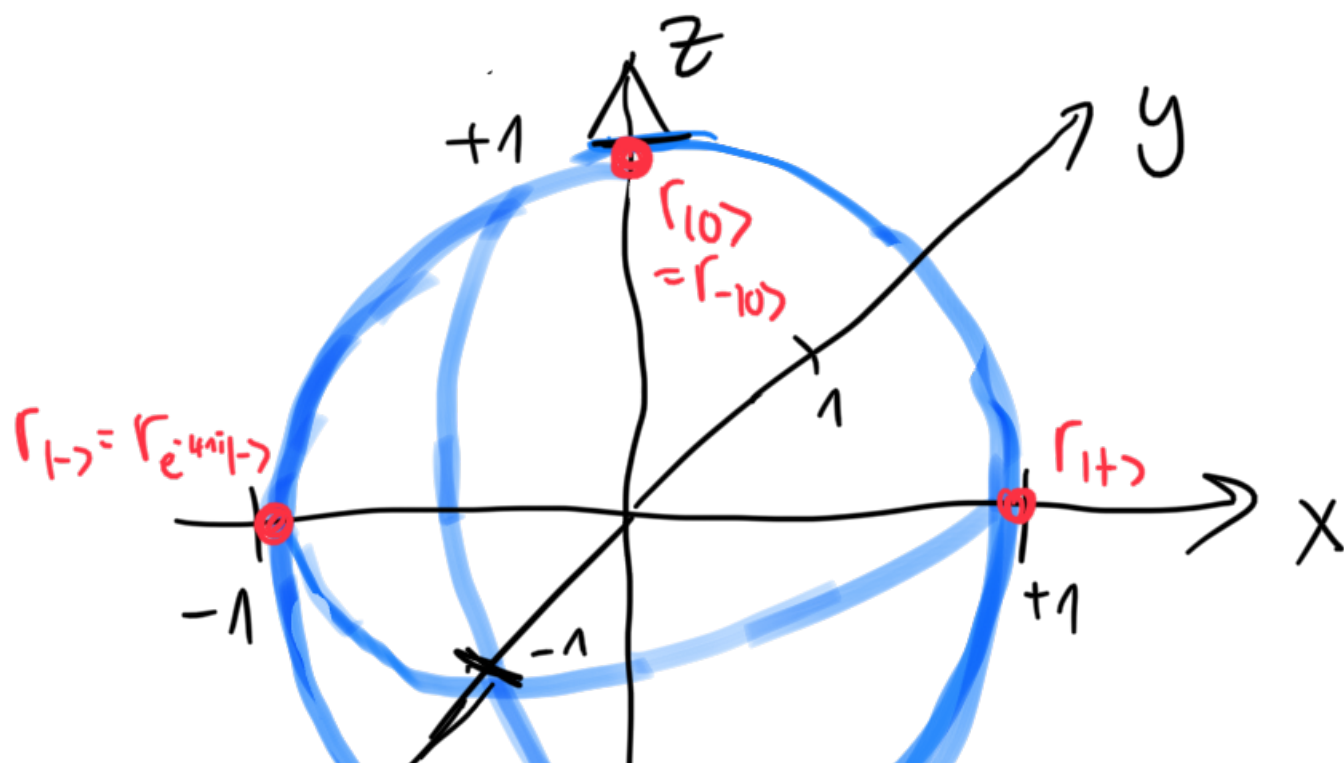
$$\sin \frac{\theta}{2} e^{i\omega} = -\frac{1}{\sqrt{2}} \quad \text{and}$$

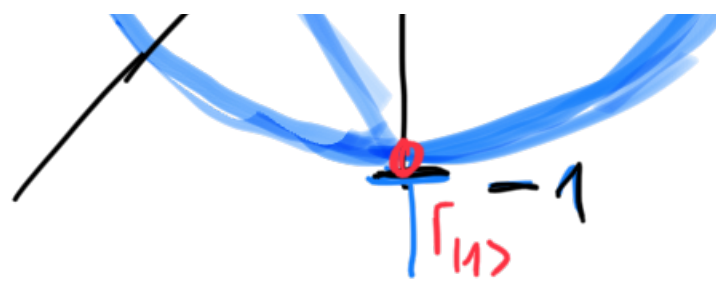
$$r_{1-\rangle} = \vec{r}_{3\pi/2,0} = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$$

$$-|0\rangle : \quad \cos \frac{\theta}{2} \stackrel{!}{=} -1 \quad \rightarrow \quad \theta = 2\pi \\ \omega = 0$$

$$r_{-|0\rangle} = \vec{r}_{2\pi,0} = r_{0,0}$$

$$e^{-4\pi i} |-\rangle = |-\rangle \quad \rightarrow \text{same vector} \quad \vec{r}_{e^{-4\pi i} |-\rangle} = \vec{r}_{|-\rangle}$$





relative angle:

$$|\psi_i\rangle = \cos \frac{\theta_i}{2} |0\rangle + e^{i\omega_i} \sin \frac{\theta_i}{2} |1\rangle \quad i=1,2$$

$$0 = \langle \psi_1 | \psi_2 \rangle = \left( \cos \frac{\theta_1}{2} \langle 0| + e^{-i\omega_1} \sin \frac{\theta_1}{2} \langle 1| \right) \cdot \left( \cos \frac{\theta_2}{2} |0\rangle + e^{+i\omega_2} \sin \frac{\theta_2}{2} |1\rangle \right)$$

$$= \cos \frac{\theta_1}{2} \cos \frac{\theta_2}{2} + e^{i(\omega_2 - \omega_1)} \sin \frac{\theta_1}{2} \sin \frac{\theta_2}{2}$$

$$\cos(x+y) = \cos x \cos y - \sin x \sin y$$

$$\cos(x-y) = \cos x \cos y + \sin x \sin y$$

$$\Rightarrow 2 \cos x \cos y = \cos(x+y) + \cos(x-y)$$

$$= \cos \frac{\theta_1}{2} \cos \frac{\theta_2}{2} + e^{i(\omega_2 - \omega_1)} \left( \cos \frac{\theta_1 + \theta_2}{2} - \cos \frac{\theta_1}{2} \cos \frac{\theta_2}{2} \right)$$

$$= e^{i(\omega_2 - \omega_1)} \cos \frac{\theta_1 + \theta_2}{2} + \underbrace{(1 - e^{i(\omega_2 - \omega_1)})}_{\text{...}} \cos \frac{\theta_1}{2} \cos \frac{\theta_2}{2}$$



$$= \left( \frac{1 - e^{i(\omega_2 - \omega_1)}}{2} + e^{i(\omega_2 - \omega_1)} \right) \cos \frac{\theta_1 + \theta_2}{2} + (1 - e^{i(\omega_2 - \omega_1)}) \cos \frac{\theta_1 - \theta_2}{2}$$

$$= \frac{1}{2} \left( (1 + e^{i(\omega_2 - \omega_1)}) \cos \frac{\theta_1 + \theta_2}{2} + (1 - e^{i(\omega_2 - \omega_1)}) \cos \frac{\theta_1 - \theta_2}{2} \right)$$

$$(1 + e^{i(\omega_2 - \omega_1)}) \cos \frac{\theta_1 + \theta_2}{2} = 0 = (1 - e^{i(\omega_2 - \omega_1)}) \cos \frac{\theta_1 - \theta_2}{2}$$

$$a) \quad \omega_2 - \omega_1 = \pi \rightarrow e^{i\pi} = -1 \rightarrow \omega_2 = \pi + \omega_1$$

$$\frac{\theta_1 + \theta_2}{2} = \frac{\pi}{2} \rightarrow \theta_2 = \pi - \theta_1$$

$$\begin{pmatrix} \sin \theta_2 & \cos \omega_2 \\ \sin \theta_2 & \sin \omega_2 \\ \cos \theta_2 \end{pmatrix} = \begin{pmatrix} \sin(\pi - \theta_1) & \cos(\omega_1 + \pi) \\ \sin(\pi - \theta_1) & \sin(\omega_1 + \pi) \\ \cos(\pi - \theta_1) \end{pmatrix}$$

$$= \begin{pmatrix} \sin(\theta_1) & (-\cos \omega_1) \\ \sin(\theta_1) & (-\sin \omega_1) \\ -\cos(\theta_1) \end{pmatrix} = - \begin{pmatrix} \sin \theta_1 \cos \omega_1 \\ \sin \theta_1 \sin \omega_1 \\ \cos \theta_1 \end{pmatrix}$$

$$b) \quad \omega_2 - \omega_1 = 0 \rightarrow e^{i\omega} = 1 \rightarrow \omega_1 = \omega_2$$

$$\frac{\theta_1 - \theta_2}{2} = \frac{\pi}{2} \leadsto \theta_2 = \pi + \theta_1$$

$$\begin{pmatrix} \sin \theta_2 & \cos \omega_2 \\ \sin \theta_2 & \sin \omega_2 \\ \cos \theta_2 \end{pmatrix} = \begin{pmatrix} \sin(\pi + \theta_1) & \cos(\omega_1) \\ \sin(\pi + \theta_1) & \sin(\omega_1) \\ \cos(\pi + \theta_1) \end{pmatrix} = - \begin{pmatrix} \sin \theta_1 & \cos \omega_1 \\ \sin \theta_1 & \sin \omega_1 \\ \cos \theta_1 \end{pmatrix}$$

$\Rightarrow$  Orthogonal states  
are at antipodes on the sphere.

③ a) how Pauli  $Z$  acts:

$$Z|0\rangle = |0\rangle$$

$$Z|1\rangle = -|1\rangle$$

Action of  $HXH$ :

$$HXH|0\rangle = HX|+\rangle = HX \cdot \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$$

$$= \frac{1}{\sqrt{2}} H(X|0\rangle + X|1\rangle)$$

$$= \frac{1}{\sqrt{2}} H(|1\rangle + |0\rangle)$$

$$= \frac{1}{\sqrt{2}} (|-\rangle + |+\rangle)$$

$$= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle + |0\rangle + |1\rangle)$$

$$= \frac{1}{2} \cdot 2|0\rangle = |0\rangle = Z|0\rangle$$

$$HXH|1\rangle = HX|-\rangle$$

$$= \frac{1}{\sqrt{2}} H (X|0\rangle - X|1\rangle)$$

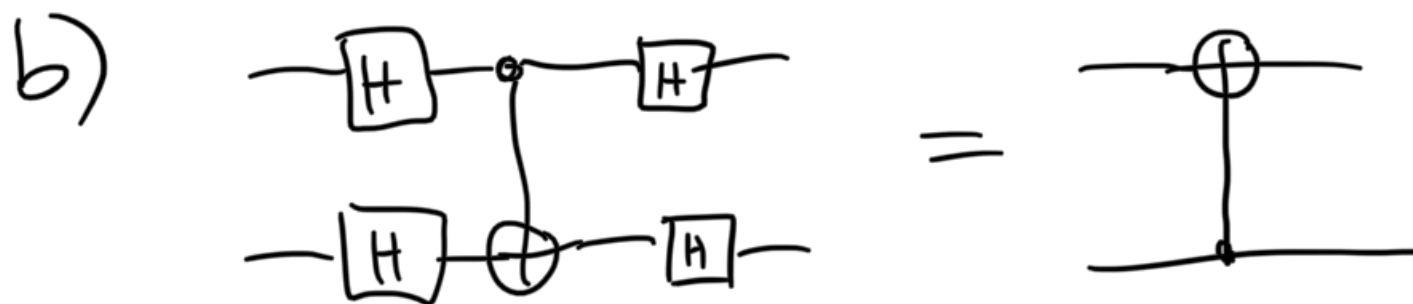
$$= \frac{1}{\sqrt{2}} H (|1\rangle - |0\rangle)$$

$$= \frac{1}{\sqrt{2}} (|-\rangle - |+\rangle)$$

$$= \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle - |0\rangle - |1\rangle)$$

$$= \frac{1}{2} \cdot (-2|1\rangle) = -|1\rangle = Z|1\rangle$$

$$\rightarrow HXH = Z$$



$$(H \otimes H) CNOT_1 (H \otimes H) = CNOT_2$$

Note:

$$(H \otimes H) |00\rangle = |++\rangle = \frac{1}{2} (|00\rangle + |01\rangle + |10\rangle + |11\rangle)$$

$$(H \otimes H) |01\rangle = |+-\rangle = \frac{1}{2} (|00\rangle - |01\rangle + |10\rangle - |11\rangle)$$

$$(H \otimes H) |10\rangle = |-+\rangle = \frac{1}{2} (|00\rangle + |01\rangle - |10\rangle - |11\rangle)$$

$$(H \otimes H) |11\rangle = |--\rangle = \frac{1}{2} (|00\rangle - |01\rangle - |10\rangle + |11\rangle)$$

$$\& H \otimes H |++\rangle = |00\rangle \text{ etc}$$

$|00\rangle$ :

$$H \otimes H |00\rangle = \frac{1}{2} (|00\rangle + |01\rangle + |10\rangle + |11\rangle)$$

$$CNOT_1 (H \otimes H) |00\rangle = \frac{1}{2} (|00\rangle + |01\rangle + |11\rangle + |10\rangle)$$

...

$$= |++\rangle$$

$$\begin{aligned} (H \otimes H) \text{CNOT}_1 (H \otimes H) |00\rangle &= (H \otimes H) |++\rangle \\ &= |00\rangle = \text{CNOT}_2 |00\rangle \end{aligned}$$

$|01\rangle$ :

$$\begin{aligned} \text{CNOT}_1 (H \otimes H) |01\rangle &= \frac{1}{2} \text{CNOT} (|00\rangle - |01\rangle + |10\rangle - |11\rangle) \\ &= \frac{1}{2} (|00\rangle - |01\rangle + |11\rangle - |10\rangle) \end{aligned}$$

$$(H \otimes H) \text{CNOT}_1 (H \otimes H) |01\rangle = |11\rangle = \text{CNOT}_2 |01\rangle$$

$|10\rangle$ :

$$\begin{aligned} \text{CNOT}_1 (H \otimes H) |10\rangle &= \frac{1}{2} \text{CNOT} (|00\rangle + |01\rangle - |10\rangle - |11\rangle) \\ &= \frac{1}{2} (|00\rangle + |01\rangle - |10\rangle - |11\rangle) \end{aligned}$$

$$(H \otimes H)(CNOT_1)(H \otimes H)|10\rangle = |10\rangle = CNOT_2|10\rangle$$

$|11\rangle$ :

$$\begin{aligned} CNOT_1(H \otimes H)|11\rangle &= CNOT_1 \cdot \frac{1}{2}(|00\rangle - |01\rangle - |10\rangle + |11\rangle) \\ &= \frac{1}{2}(|00\rangle - |01\rangle + |10\rangle - |11\rangle) \end{aligned}$$

$$(H \otimes H)(CNOT_1)(H \otimes H)|11\rangle = |01\rangle = CNOT_2|11\rangle$$

$$\Rightarrow (H \otimes H)(CNOT_1)(H \otimes H) = CNOT_2$$

a)  $|\psi_{in}\rangle = |00\rangle$

↓

$$|\phi_1\rangle = H \otimes I |00\rangle = |10\rangle = \frac{1}{\sqrt{2}}(|00\rangle + |10\rangle)$$

↓

$$|\phi_2\rangle = \text{CNOT}_1 |\phi_1\rangle = \frac{1}{\sqrt{2}} (|00\rangle + |11\rangle)$$

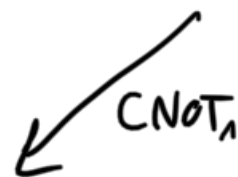


$$\begin{aligned} |\phi_3\rangle &= (Z \otimes H) |\phi_2\rangle = \frac{1}{\sqrt{2}} (|0+\rangle - |1-\rangle) \\ &= \frac{1}{\sqrt{2} \cdot \sqrt{2}} (|00\rangle + |01\rangle - |10\rangle + |11\rangle) \end{aligned}$$



$$\begin{aligned} |\phi_4\rangle &= \text{CNOT}_2 |\phi_3\rangle \\ &= \frac{1}{2} (|00\rangle + |11\rangle - |10\rangle + |01\rangle) \end{aligned}$$

$$b) \quad |01\rangle \xrightarrow{H \otimes I} |+\rangle = \frac{1}{\sqrt{2}} (|01\rangle + |11\rangle)$$



$$\frac{1}{\sqrt{2}} (|01\rangle + |10\rangle) \xrightarrow{Z \otimes H}$$



$$\rightarrow \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle)$$

$$\xrightarrow{CNOT_2} = \frac{1}{\sqrt{2}\sqrt{2}}(|00\rangle - |01\rangle - |10\rangle - |11\rangle)$$

$$\frac{1}{2}(|00\rangle - |11\rangle - |10\rangle - |01\rangle)$$

analogously:

$$|10\rangle \rightarrow \frac{1}{2}(|00\rangle - |01\rangle + |10\rangle + |11\rangle)$$

$$|11\rangle \rightarrow \frac{1}{2}(|00\rangle + |01\rangle + |10\rangle - |11\rangle)$$

$$\Rightarrow U = \frac{1}{2} \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & -1 & 1 \\ -1 & -1 & 1 & 1 \\ 1 & -1 & 1 & -1 \end{pmatrix}$$

in basis:  $(|00\rangle, |01\rangle, |10\rangle, |11\rangle)$

c) Since  $U$  is unitary,  $UU^\dagger = 1 \Rightarrow U^{-1} = U^\dagger$

$$U = \text{CNOT}_2 \cdot (Z \otimes H) \cdot \text{CNOT}_1 \cdot (H \otimes 1)$$

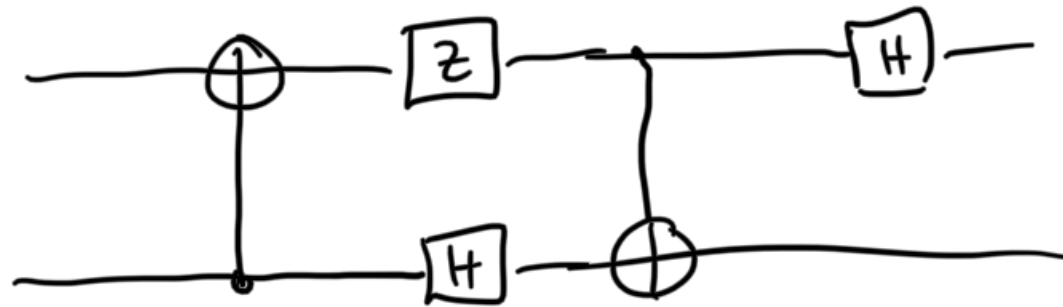
$$U^\dagger = (\text{CNOT}_2 \cdot (Z \otimes H) \cdot \text{CNOT}_1 \cdot (H \otimes 1))^\dagger$$

$$= (H \otimes 1)^\dagger \cdot \text{CNOT}_1^\dagger \cdot (Z \otimes H)^\dagger \cdot \text{CNOT}_2^\dagger$$

$H, Z,$   
 $\text{CNOT}$   
are unitary.

$$= (H \otimes 1) \cdot \text{CNOT}_1 \cdot (Z \otimes H) \cdot \text{CNOT}_2$$

$U^{-1}:$



(4) a)

$$\begin{pmatrix} 1 \\ 1+i \\ 2e^{i\pi/4} \end{pmatrix} \otimes \begin{pmatrix} 2-2i \\ (1-i)^{-1} \\ -5 \end{pmatrix} =$$

$$\begin{pmatrix} 2-2i \\ (1-i)^{-1} \\ -5 \\ (1+i)(2-2i) \\ (1+i)(1-i)^{-1} \\ -(1+i) \cdot 5 \\ 2e^{i\pi/4}(2-2i) \\ 2e^{i\pi/4}(1-i)^{-1} \\ -10e^{i\pi/4} \end{pmatrix} =$$

$$\begin{pmatrix} 2-2i \\ (1-i)^{-1} \\ -5 \\ 4 \\ i \\ -(5+5i) \\ 4\sqrt{2} \\ \sqrt{2}i \\ -5\sqrt{2}(1+i) \end{pmatrix}$$

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \otimes$$

$$\begin{pmatrix} i & 1 \\ -2 & 0 \end{pmatrix} =$$

$$\begin{pmatrix} i & 1 & \bar{i} & 1 \\ -2 & 0 & -2 & 0 \\ \bar{i} & 1 & -i & -1 \\ -2 & 0 & 2 & 0 \end{pmatrix}$$

$$b) \quad A \otimes B = \begin{pmatrix} A_{11}B & A_{12}B & \dots & A_{1d}B \\ A_{21}B & & & \\ \vdots & & & \\ A_{d1}B & & & \end{pmatrix}$$

$$V \otimes W = \begin{pmatrix} v_1 \cdot w \\ v_2 \cdot w \\ \vdots \\ v_d \cdot w \end{pmatrix}$$

$n \otimes m$

$$(A \otimes B)(V \otimes W) = \begin{pmatrix} A_{11}B & A_{12}B & \dots & A_{1d}B \\ A_{21}B & & & \\ \vdots & & & \\ A_{d1}B & & & \end{pmatrix} \begin{pmatrix} v_1 \cdot w \\ v_2 \cdot w \\ \vdots \\ v_d \cdot w \end{pmatrix}$$

$$= \begin{pmatrix} A_{11} \cdot B \cdot v_1 w + A_{12} \cdot B \cdot v_2 w + \dots + A_{1d} B \cdot v_d w \\ A_{21} B \cdot v_1 w + A_{22} \cdot B \cdot v_2 w + \dots \\ \vdots \\ \vdots \end{pmatrix}$$

$$\left( A_{d1} B v_1 w + \dots \right)$$

$$= \begin{pmatrix} (A_{11} v_1 + A_{12} v_2 + \dots + A_{1d} v_d) B w \\ (A_{21} v_1 + A_{22} v_2 + \dots + A_{2d} v_d) B w \\ \vdots \\ (A_{d1} v_1 + \dots + A_{dd} v_d) B w \end{pmatrix}$$

$$= \begin{pmatrix} (A \cdot v)_1 B w \\ (A \cdot v)_2 B w \\ \vdots \\ (A \cdot v)_d B w \end{pmatrix} = A v \otimes B w$$

c)  $A \otimes (B + C)$

$$\left( A_{11} (B + C) \quad A_{12} (B + C) \quad \dots \quad A_{1d} (B + C) \right)$$

$$= \begin{pmatrix} A_{21}(B+C) & \dots \\ \vdots \\ A_{n1}(B+C) \end{pmatrix}$$

$$= \begin{pmatrix} A_{11}B + A_{11}C & \dots \\ \vdots \end{pmatrix}$$

$\dots$

$$= \begin{pmatrix} A_{11}B & \dots \\ \vdots \end{pmatrix} + \begin{pmatrix} A_{11}C & \dots \\ \vdots \end{pmatrix}$$

$$= A \otimes B + A \otimes C$$

$$d) |\phi\rangle = \frac{1}{\sqrt{2}}(|0\rangle + i|1\rangle)$$

$$|\psi\rangle = \frac{1}{\sqrt{2}}(i|0\rangle - |1\rangle)$$

$$|\phi\rangle \otimes |\psi\rangle = \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} (|0\rangle + i|1\rangle) \otimes (i|0\rangle - |1\rangle)$$

$$= \frac{1}{2} (i|0\rangle \otimes |0\rangle - |0\rangle \otimes |1\rangle + \underbrace{i^2}_{-1} |1\rangle \otimes |0\rangle - i|1\rangle \otimes |1\rangle)$$

$$= \frac{1}{2} (i|00\rangle - |01\rangle - |10\rangle - i|11\rangle)$$