

# Tutorial 6

19 February 2022 11:04

Gradient Descent methods

Steepest Gradient method

- fixed step size
- exact line search
- Armijo's rule
- Newton's method
- Conjugate direction methods
  - conjugate gradient method (for quadratic problems)
  - " " " non-quadratic problems.

$$\|x_{k+1} - x^*\| \leq \underbrace{|\bar{\lambda}(\nabla^2 f(x_k))| L}_{< 1} \|x_k - x^*\|$$

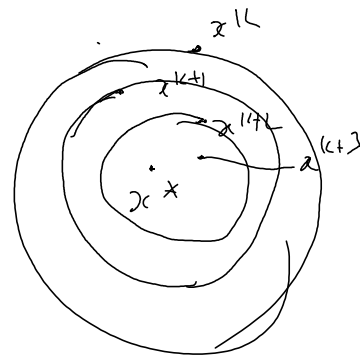
$$\|x_{k+1} - x^*\| \leq \underbrace{(|\bar{\lambda}(\nabla^2 f(x_k))| L \|x_k - x^*\|)}_{< 1} \underbrace{(\|x_k - x^*\|)}$$

Suppose  $|\bar{\lambda}(\nabla^2 f(x_k))| L < 1$   
 and  $\|x_k - x^*\| < 1$

$$\Rightarrow |\bar{\lambda}(\nabla^2 f(x_k))| \|x_k - x^*\| < 1$$

(Actually this is enough)

$$\Rightarrow \|x_{k+1} - x^*\| < \|x_k - x^*\| < 1$$



$$\underbrace{|\bar{\lambda}(\nabla^2 f(x_k))|}_{\leq 1} \|x_k - x^*\| < 1$$

$$\underbrace{\underbrace{1}_{\leq 1} \|x_k - x^*\|}_{\leq 1} < 1$$

$$\|x_k - x^*\| < \frac{1}{\underbrace{|\bar{\lambda}(\nabla^2 f(x_k))|}_{\leq 1}}$$

to begin with  $\|x_k - x^*\| \cdot \|\bar{L}(\nabla^2 f(x_k))\| < 1$  may not be satisfied  $\frac{\|x_k - x^*\|}{1} < 1$   
 - we modify Newton's method to address this:

0.000000.0000008  $\approx 0$   $\frac{1}{0}$  is undefined

$$x_{k+1} = x_k - \underbrace{\alpha_k (\nabla^2 f(x_k) + \delta_k I)^{-1} \nabla f(x_k)}_{d_k}$$

$x_{k+1} = x_k + \alpha_k d_k$   
 $d_k = -(\nabla^2 f(x_k) + \delta_k I)^{-1} \nabla f(x_k)$   
 $\alpha_k = \frac{d_k}{\|\nabla^2 f(x_k) + \delta_k I\|}$

$$x_{k+1} = x_k - (\nabla^2 f(x_k))^{-1} \nabla f(x_k)$$

- two ways to see it  
 (a)  $d_k = -\nabla f(x_k)$  (as in steepest descent)  
 $\alpha_k = \nabla^2 f(x_k)^{-1}$  (it is a matrix unlike gradient descent methods)

(b)  $d_k = -(\nabla^2 f(x_k))^{-1} \nabla f(x_k)$   
 $\alpha_k = 1$

$d_k = -(\nabla^2 f(x_k))^{-1} \nabla f(x_k)$   
 $\alpha_k = \frac{1}{\|\nabla^2 f(x_k) + \delta_k I\|}$

modified Newton's method  
 $f(x_{k+1}) \leq f(x_k)$

modified newton's method

$$\text{if } f(x_{k+1}) \leq f(x_k) \\ d_k = -(\nabla^2 f(x_k))^{-1} \nabla f(x_k) \\ \alpha_k = 1 //$$

else

$$d_k = -(\nabla^2 f(x_k) + \alpha_k I)^{-1} \nabla f(x_k) \\ \alpha_k \leftarrow \alpha_k + 1 \quad f(x_{k+1}) \leq f(x_k)$$

choose  $\alpha_k$  s.t. Armijo's rule

$$f(x^k + \alpha_k d_k) \leq f(x^k) - \sigma \alpha_k \|d_k\|^2 //$$

$$(d_k = -\nabla f(x_k) \text{ in gradient descent})$$

exact line search

$$\alpha_k = \underset{\alpha}{\operatorname{argmin}} f(x^k - \alpha (\nabla^2 f(x_k) + \alpha_k I)^{-1} \nabla f(x_k))$$

Q.2  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$f(x) = \frac{x^T A x}{2} - b^T x + c$$

(A is symmetric positive definite)

$$\nabla f(x) = Ax - b$$

steepest descent method

$$x_{k+1} = x_k - \alpha (Ax_k - b)$$

exact line search

$$\alpha_k = \underset{\alpha}{\operatorname{argmin}} f(x_k - \alpha (Ax_k - b))$$

$$= \underset{\alpha}{\operatorname{argmin}} f((I - \alpha A)x_k + \alpha b)$$

define

$$g(\alpha) = f((I - \alpha A)x_k + \alpha b)$$

$$g: \mathbb{R} \rightarrow \mathbb{R}$$

is  $g$  convex? (exercise)

Is  $g$  convex? (Exercise)

$$\begin{aligned}
 g'(\alpha) &= \nabla \left( (I - \alpha A) x_k + \alpha b \right)^T (b - Ax_k) \\
 &= \left( A(I - \alpha A) x_k + \alpha Ab - b \right)^T (b - Ax_k) \\
 &= \left( A(I - \alpha A) x_k - (I - \alpha A)b \right)^T (b - Ax_k) \\
 &= \frac{A(I - \alpha A)}{(I - \alpha A)A} \\
 &= \left( (I - \alpha A)(Ax_k - b) \right)^T (b - Ax_k) \\
 &= - \left( Ax_k - b \right)^T (I - \alpha A) (Ax_k - b)
 \end{aligned}$$

$$g''(\alpha)$$

$x_k$  is obtained via setting  $g'(\alpha) = 0$

$$\textcircled{b} \quad b - Ax_0 = \begin{bmatrix} 10 \\ 5 \end{bmatrix} - \underbrace{\begin{bmatrix} 2 & 4 \\ 4 & 10 \end{bmatrix}}_{=: A} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 10 \\ 5 \end{bmatrix} - \begin{bmatrix} 2 \\ 4 \end{bmatrix} = \begin{bmatrix} 8 \\ 1 \end{bmatrix}$$

Exact line search

$$\alpha_0 = \frac{\begin{bmatrix} 8 & 1 \end{bmatrix} \begin{bmatrix} 8 \\ 1 \end{bmatrix}}{\begin{bmatrix} 8 & 1 \end{bmatrix} \begin{bmatrix} 2 & 4 \\ 4 & 10 \end{bmatrix} \begin{bmatrix} 8 \\ 1 \end{bmatrix}}$$

$$\boxed{x_1 = x_0 + \alpha_0 d_0}$$

$$\underline{d_0 = b - Ax_0}$$

$$\times \quad (Ax_k - b)^T (I - \alpha A) (Ax_k - b) = 0$$

$$\Rightarrow (Ax_k - b)^T (Ax_k - b - \alpha A(Ax_k - b)) = 0$$

$$\Rightarrow (Ax_k - b)^T (Ax_k - b) = \alpha (Ax_k - b)^T A (Ax_k - b)$$

$$\Rightarrow \alpha_k = \frac{\|Ax_k - b\|^2}{(Ax_k - b)^T A (Ax_k - b)}$$

$$n=1$$

$$f(x) = \frac{1}{2} ax^2 - bx + c$$

$$f'(x) = ax - b$$

$$\alpha_k = \frac{(ax_k - b)^2}{(ax_k - b) a (ax_k - b)} = \frac{1}{a}$$

$$x_{k+1} = x_k - \alpha (ax_k - b)$$

$$d_k = \arg \min_{\alpha} \frac{1}{2} a (x_k - \alpha (ax_k - b))^2 - b (x_k - \alpha (ax_k - b)) + c$$

define

$$g(\alpha) = f(x_k - \alpha (ax_k - b))$$

$$g'(\alpha) = 0$$

$$- f'(x_k - \alpha (ax_k - b)) \cdot (ax_k - b) = 0$$

$$- \left( \underline{a(x_k - \alpha (ax_k - b)) - b} \right) \underbrace{(ax_k - b)}_{\neq 0} = 0$$

$$ax_k - b = \alpha a (ax_k - b)$$

$$\Rightarrow \underline{\underline{\alpha = 1/a}}$$