

MDP:-

State space: 
$$g(1, \dots, g)$$
; Terminal states:  $g(0, \log 1)$ .

Action space:

 $g(1, \dots, g)$ ; Terminal states:  $g(0, \log 1)$ .

Reward function:  $g(1, \dots, g)$ :

 $g(1, \dots, g)$ :

 $g(1, \dots, g)$ :

 $g(1, \dots, g)$ :

Reward function:  $g(1, \dots, g)$ :

 $g(1, \dots, g)$ 

Prob. of win ending up as head:

$$V_0 = 0$$
;

 $V_0 = 0$ ;

 $V_0 = 0$