

# Tutorial 8

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$$\min f(x)$$

$$\text{s.t. } h(x) = \underline{0}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$h(x) = \begin{bmatrix} h_1(x) \\ \vdots \\ h_m(x) \end{bmatrix}$$

$$h: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

Necessary conditions

Lagrangian function

$$L: \mathbb{R}^{n+m} \rightarrow \mathbb{R}$$

$$L(x, \lambda) = f(x) + \sum_{i=1}^m \lambda_i h_i(x)$$

If  $x^*$  is a local minimum that is regular, then  $\exists \lambda^*$  s.t.

$$\nabla_x L(x^*, \lambda^*) = \underline{0} \quad \text{--- (1)}$$

$$(\nabla f(x^*) + \sum_{i=1}^m \lambda_i^* \nabla h_i(x^*) = 0)$$

$\nabla h_1(x^*), \dots, \nabla h_m(x^*)$   
are linearly independent.

$$\nabla_\lambda L(x^*, \lambda^*) = \underline{0} \quad \text{--- (2)}$$

$$(h_i(x^*) = 0 \quad \forall i = 1, \dots, m)$$

$$y^T \nabla_{xx}^2 L(x^*, \lambda^*) y \geq 0 \quad \forall y: y^T \nabla h_i(x^*) = 0 \quad \forall i = 1, \dots, m \quad \text{--- (3)}$$

$$(y^T (\nabla^2 f(x^*) + \sum_{i=1}^m \lambda_i^* \nabla^2 h_i(x^*)) y \geq 0)$$

(1) & (2) are called first order necessary conditions  
( $m$  equations in  $n+m$  variables)

(3) is called second order necessary condition

Sufficient conditions

If  $\exists x^*$  and  $\lambda^*$  satisfying

$$\nabla_x L(x^*, \lambda^*) = 0$$

$$\nabla_\lambda L(x^*, \lambda^*) = 0$$

$$\text{and } y^T \nabla_{xx}^2 L(x^*, \lambda^*) y > 0$$

$$\forall y: y^T \nabla h_i(x^*) = 0 \quad \forall i = 1, \dots, m$$

$$y \neq 0$$

$\Rightarrow x^*$  is a strict local minimum

Sensitivity theorem

## Sensitivity Theorem

$$\min f(x) \\ \text{s.t. } h(x) = c$$

$$c \in \mathbb{R}^m$$

- $(x^*(c), \lambda^*(c))$  is a local minimum, Lagrange multiplier pair that satisfies sufficiency condition
- $x^*(c)$  is regular
- $p(c)$  is the optimal value.

$$\nabla p(c) = -\lambda^*(c)$$

$$\begin{bmatrix} \frac{\partial p(c)}{\partial c_1} \\ \vdots \\ \frac{\partial p(c)}{\partial c_m} \end{bmatrix} \in \mathbb{R}^m$$

Example  $\min \frac{1}{2}(x_1^2 - x_2^2) - x_2$   
s.t.  $x_2 = 0$

$$\nabla f(x^*) + \lambda^* \nabla h(x^*) = 0$$

$$\begin{bmatrix} x_1^* \\ -x_2^* - 1 \end{bmatrix} + \lambda^* \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0$$

$$\left. \begin{aligned} x_1^* &= 0 \\ -x_2^* - 1 + \lambda^* &= 0 \\ x_2^* &= 0 \end{aligned} \right\}$$

$$\Rightarrow x^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \lambda^* = 1$$

Also,  $x^*$  is regular

$$\nabla_{xx}^2 L(x^*, \lambda^*) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$y^T \nabla_{xx}^2 L(x^*, \lambda^*) y > 0$$

$$\left. \begin{aligned} &+ y: \begin{bmatrix} y_1 & y_2 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0 \\ &y \neq 0 \end{aligned} \right\} \Rightarrow \underline{\underline{y_2 = 0}}$$

$$\text{i.e., } y^T \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} y > 0$$

i.e.,  $y' \begin{bmatrix} 1 & -1 \end{bmatrix} y > 0$

i.e.,  $\begin{bmatrix} y_1 & y_2 \end{bmatrix} \begin{bmatrix} y_1 \\ -y_2 \end{bmatrix} > 0$

i.e.,  $y_1^2 - y_2^2 > 0$

- this condition is satisfied.

$\Rightarrow x^* = (0,0)$  is unique global minimum.

Now consider

$$\min \frac{1}{2} (x_1^2 - x_2^2) - x_2$$

s.t.  $x_2 = u$

$$p(u) = \min \frac{1}{2} (x_1^2 - u^2) - u$$

$$= \underline{\underline{-\frac{1}{2}u^2 - u}}$$

$$p'(u) = -u - 1$$

from sensitivity theorem we expect that

$$p'(0) = -\lambda^*$$

this is true as both equal -1.

Inequality constraints

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\min f(x)$$

s.t.  $h_i(x) = 0, i=1, \dots, m$

$g_j(x) \leq 0, j=1, \dots, r$

- let  $x^*$  be a local minimum.

- we want to come up with Necessary conditions.

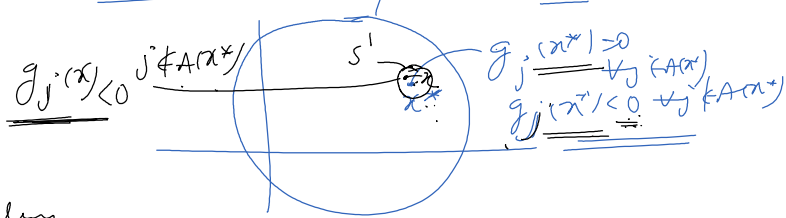
Suppose  $h_i(x^*) = 0 \quad i=1, \dots, m$

$g_j(x^*) = 0 \quad j \in A(x^*) \subseteq \{1, 2, \dots, r\}$

$$\underline{g_j(x^*) < 0 \quad \forall j \notin A(x^*)}$$

( $A(x^*)$  is the set of active constraints at  $x^*$ ).

$$S = \{y : h_i(x) = 0, g_j(x) \leq 0\}$$



$$\begin{aligned} \min f(x) \\ \text{s.t. } h_i(x) = 0 \quad \forall i=1, \dots, m \\ g_j(x) \leq 0 \quad \forall j \in A(x^*) \end{aligned}$$

$\Rightarrow x^*$  is a local min. of this problem.

consider the following problem

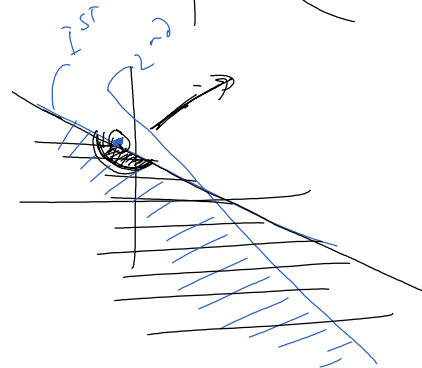
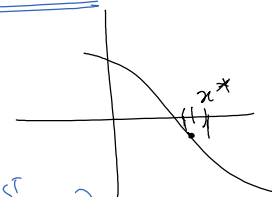
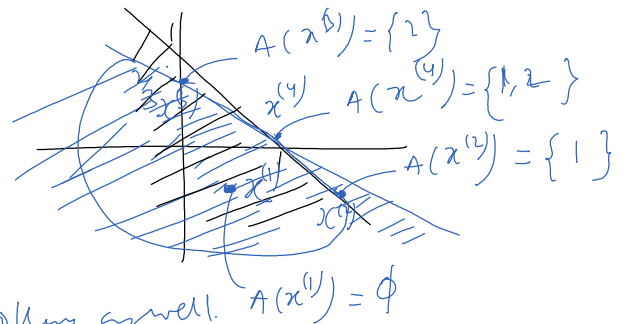
$$\begin{aligned} \min f(x) \\ \text{s.t. } h_i(x) = 0 \quad i=1, \dots, m \\ g_j(x) = 0 \quad \forall j \in A(x^*) \end{aligned}$$

if  $x^*$  is a local minimum of the original problem

$\Rightarrow x^*$  is a local minimum of this problem as well.

Example

$$\begin{aligned} g_1(x) &= x_1 + x_2 \leq 1 \\ g_2(x) &= 2x_1 + 3x_2 \leq 2 \end{aligned}$$



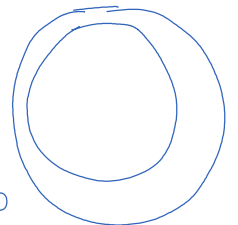
there exist

$$\lambda^* = \begin{bmatrix} \lambda_1^* \\ \vdots \\ \lambda_m^* \end{bmatrix} \text{ and } \mu^* = \begin{bmatrix} \mu_1^* \\ \vdots \\ \mu_r^* \end{bmatrix} \text{ s.t.}$$

$$f(x^*) + \sum_{i=1}^m \lambda_i^* h_i(x^*) + \sum_{j \in A(x^*)} \mu_j^* g_j(x^*) = 0$$

$$\min_{x \in \mathbb{R}^n} f(x) \\ \text{s.t. } h_i(x) = 0 \quad \forall i=1, \dots, m \\ g_j(x) \leq 0 \quad \forall j=1, \dots, r$$


$$\begin{aligned} h_i(x^*) &= 0 \\ g_j(x^*) &\leq 0 \end{aligned}$$



$$\begin{aligned} x \in \mathbb{R}^n \quad \text{s.t.} \quad & \underline{h_i(x)} \geq 0 \quad \forall i=1, \dots, m \\ & \underline{g_j(x)} \leq 0 \quad \forall j=1, \dots, r \end{aligned}$$

An equivalent problem, is

$$\begin{aligned} \min_{x \in \mathbb{R}^n, s \in \mathbb{R}^r} \quad & f(x) \\ \text{s.t.} \quad & \underline{h_i(x)} = 0 \quad \forall i=1, \dots, m \\ & \underline{g_j(x) + s_j} = 0 \quad \forall j=1, \dots, r. \end{aligned}$$

$$\begin{aligned} & \underline{h_i(x^*)} = 0 \\ & \underline{g_j(x^*)} \leq 0 \end{aligned}$$


$$\text{define } s_j^* = \sqrt{-g_j(x^*)} \quad \forall j=1, \dots, r$$

$(x^*, s^*)$  will satisfy these constraints

and a relaxed problem is

$$\begin{aligned} \min_{x, s} \quad & f(x) \\ \text{s.t.} \quad & \underline{h_i(x)} \geq 0 \quad \forall i=1, \dots, m \\ & \underline{g_j(x) + s_j} = c_j \quad \text{for some } j \\ & \underline{g_j(x) + s_j} = 0 \quad \text{for other } j \end{aligned}$$

$$(c_j > 0)$$

— suppose  $x^*(c)$  is a sol<sup>n</sup> to this.  
(let  $(\lambda^*, \mu^*)$  be the corresponding Lagrange multipliers)

$x^*$  is sol<sup>n</sup> to the original problem

$$\begin{aligned} g_j(x) & \leq c_j \\ g_j(x^*) & < 0 \end{aligned}$$

$$\begin{aligned} f(x^*(c)) & \leq f(x^*) \\ \Leftrightarrow f(x^*) + \frac{\partial f(x^*(c))}{\partial c_j} (c_j - 0) & \leq f(x^*) \end{aligned}$$

1st order approximation

$$\Leftrightarrow -\mu_j^* c_j \leq 0$$

$\mu_j^* \geq 0$   
(Lagrange multipliers corresponding to non-negativity constraints are non-negative)

\*  $\mu_j^* = 0 \quad \forall j \notin A(x^*)$   
So, the necessary condition.

$$f(x^*) + \sum_i \lambda_i^* h_i(x^*) + \sum_j \mu_j^* g_j(x^*) = 0$$

$$f(x^*) + \sum_{i=1}^m \lambda_i^* h_i(x^*) + \sum_{j \in A(x^*)} \mu_j^* g_j(x^*) = 0$$

is equivalent to

$$f(x) + \sum_{i=1}^m \lambda_i^* h_i(x) + \sum_{j=1}^r \mu_j^* g_j(x) = 0$$

(First order necessary conditions for inequality constrained problems)

$\lambda^*(c) \in \mathbb{R}^m$   
 $\lambda^*(c)$  is the corresponding L.M.

$$\begin{cases} \min f(x) \\ \text{s.t. } h_i(x) = c_i \quad i=1, \dots, m \end{cases}$$

$$\frac{\partial f(x^*(c))}{\partial c_i} = -\lambda_i^*(c) \quad i=1, \dots, m$$

