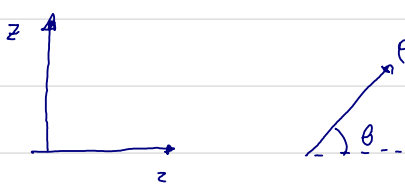


Analytische oplossing II

$$\begin{cases} \nabla (z \cdot \sigma \nabla C_v(z, z)) = f^1(u, v) z \\ \nabla (z \cdot \sigma \nabla C_u(z, z)) = f^2(u, v) z \end{cases}$$

$$\begin{cases} \frac{\partial}{\partial z} (z \cdot \sigma_z \cdot \frac{\partial C_u}{\partial z}) + \frac{\partial}{\partial \bar{z}} (z \cdot \sigma_{\bar{z}} \cdot \frac{\partial C_u}{\partial \bar{z}}) = f^1(u, v) z \\ \frac{\partial}{\partial z} (z \cdot \sigma_z \cdot \frac{\partial C_v}{\partial z}) + \frac{\partial}{\partial \bar{z}} (z \cdot \sigma_{\bar{z}} \cdot \frac{\partial C_v}{\partial \bar{z}}) = -f^2(u, v) z \end{cases}$$

$$\begin{cases} \sigma_z \frac{\partial C_u}{\partial z} + \sigma_{\bar{z}} \frac{\partial^2 C_u}{\partial z^2} \cdot z + z \cdot \sigma_{\bar{z}} \frac{\partial C_u}{\partial \bar{z}^2} = f^1(u, v) \\ \sigma_z \frac{\partial C_v}{\partial z} + \sigma_{\bar{z}} \frac{\partial^2 C_v}{\partial z^2} \cdot z + z \cdot \sigma_{\bar{z}} \frac{\partial C_v}{\partial \bar{z}^2} = -f^2(u, v) z \end{cases}$$

$$(z, \bar{z}) \rightarrow (e, \theta)$$


$$z = e \cos(\theta) \quad ; \quad \bar{z} = e \sin(\theta)$$

$$dz = d(e \cos(\theta)) - e \sin(\theta) d\theta \quad ; \quad d\bar{z} = d(e \sin(\theta)) + e \cos(\theta) d\theta$$

$$d(z^2) = d(e^2 \cos(\theta)) - \sin(\theta) d\theta d(e) - d(e d\theta \sin(\theta)) - e \cos(\theta) d(\theta^2)$$

$$d(z^2) = d(e^2 \cos(\theta)) - d\theta^2 e \cos(\theta) - 2 d\theta d(e \sin(\theta))$$

$$d(z^2) = d(e^2 \sin(\theta)) + d(e d\theta \cos(\theta)) + d\theta d\theta \cos(\theta) - e \sin(\theta) d\theta^2$$

$$d(\bar{z}^2) = d(e^2 \sin(\theta)) - e \sin(\theta) d\theta^2 + 2 d\theta d(e \cos(\theta))$$

$$C(z, \bar{z}) = C(e, \theta)$$

$$\frac{\partial C}{\partial \theta} = \frac{\partial C}{\partial z} \frac{\partial z}{\partial \theta} + \frac{\partial C}{\partial \bar{z}} \frac{\partial \bar{z}}{\partial \theta} = -e \frac{\partial C}{\partial z} \cdot \sin(\theta) + e \frac{\partial C}{\partial \bar{z}} \cdot \cos(\theta)$$

$$\frac{\partial C}{\partial e} = \frac{\partial C}{\partial z} \frac{\partial z}{\partial e} + \frac{\partial C}{\partial \bar{z}} \frac{\partial \bar{z}}{\partial e} = \frac{\partial C}{\partial z} \cos(\theta) + \frac{\partial C}{\partial \bar{z}} \sin(\theta)$$

$$\frac{\partial C}{\partial \theta} = e \left(\frac{\partial C}{\partial z} \cos(\theta) - \frac{\partial C}{\partial z} \sin(\theta) \right)$$

$$\frac{\partial C}{\partial \rho} = \frac{\partial C}{\partial z} \cos(\theta) + \frac{\partial C}{\partial z} \sin(\theta)$$

$$\frac{\partial^2 C}{\partial \theta^2} = e \left[\left(\frac{\partial^2 C}{\partial z \partial z} \frac{\partial z}{\partial \theta} + \frac{\partial^2 C}{\partial z \partial z} \frac{\partial z}{\partial \theta} \right) \cos(\theta) - \left(\frac{\partial^2 C}{\partial z \partial z} \frac{\partial z}{\partial \theta} + \frac{\partial^2 C}{\partial z \partial z} \frac{\partial z}{\partial \theta} \right) \sin(\theta) \right] - e \frac{\partial C}{\partial z} \sin(\theta) - \frac{\partial C}{\partial z} \cos(\theta)$$

$$\frac{\partial^2 C}{\partial \theta^2} = e \left[\left(\frac{\partial^2 C}{\partial z^2} e \cos(\theta) - \frac{\partial^2 C}{\partial z \partial z} e \sin(\theta) \right) \cos(\theta) - \left(-\frac{\partial^2 C}{\partial z^2} e \sin(\theta) + \frac{\partial^2 C}{\partial z \partial z} e \cos(\theta) \right) \sin(\theta) \right]$$

$$= \frac{\partial^2 C}{\partial z^2} e^2 \cos^2(\theta) - \frac{\partial^2 C}{\partial z \partial z} e^2 \sin(\theta) \cos(\theta) - \frac{\partial^2 C}{\partial z \partial z} e^2 \sin(\theta) \cos(\theta)$$

$$+ \frac{\partial^2 C}{\partial z^2} e^2 \sin^2(\theta) - e \frac{\partial C}{\partial z} \sin(\theta) - e \frac{\partial C}{\partial z} \cos(\theta)$$

$$\frac{\partial^2 C}{\partial \theta^2} = \frac{\partial^2 C}{\partial z^2} e^2 \cos^2(\theta) - 2 \frac{\partial^2 C}{\partial z \partial z} e^2 \sin(\theta) \cos(\theta) + \frac{\partial^2 C}{\partial z^2} e^2 \sin^2(\theta)$$

$$- e \frac{\partial C}{\partial z} \sin(\theta) - e \frac{\partial C}{\partial z} \cos(\theta)$$

$$\frac{\partial^2 C}{\partial \rho^2} = \left(\frac{\partial^2 C}{\partial z^2} \frac{\partial z}{\partial \rho} + \frac{\partial^2 C}{\partial z \partial z} \frac{\partial z}{\partial \rho} \right) \cos(\theta)$$

$$+ \left(\frac{\partial^2 C}{\partial z^2} \frac{\partial z}{\partial \rho} + \frac{\partial^2 C}{\partial z \partial z} \frac{\partial z}{\partial \rho} \right) \sin(\theta)$$

$$\frac{\partial^2 C}{\partial \rho^2} = \frac{\partial^2 C}{\partial z^2} \cos^2(\theta) + \frac{\partial^2 C}{\partial z^2} \sin^2(\theta) + 2 \sin(\theta) \cos(\theta) \frac{\partial^2 C}{\partial z \partial \rho}$$

$$\frac{\partial \mathcal{L}}{\partial \theta} = e \left(\frac{\partial \mathcal{L}}{\partial z} \cos(\theta) - \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right)$$

$$\frac{\partial \mathcal{L}}{\partial \rho} = \frac{\partial \mathcal{L}}{\partial z} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta)$$

$$\frac{\partial^2 \mathcal{L}}{\partial \theta^2} = \frac{\partial^2 \mathcal{L}}{\partial z^2} \cos^2(\theta) + \frac{\partial^2 \mathcal{L}}{\partial z^2} \sin^2(\theta) + 2 \sin(\theta) \cos(\theta) \frac{\partial^2 \mathcal{L}}{\partial z \partial \theta}$$

$$\frac{\partial^2 \mathcal{L}}{\partial \theta^2} = \frac{\partial^2 \mathcal{L}}{\partial z^2} e^2 \cos(\theta)^2 - 2 \frac{\partial^2 \mathcal{L}}{\partial z \partial \theta} e^2 \sin(\theta) \cos(\theta) + \frac{\partial^2 \mathcal{L}}{\partial z^2} e^2 \sin(\theta)^2$$

$$- e \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) - e \frac{\partial \mathcal{L}}{\partial z} \cos(\theta)$$

$$\sigma_1 \frac{\partial \mathcal{L}}{\partial z} + \sigma_1 \frac{\partial^2 \mathcal{L}}{\partial z^2} \cdot z + z \cdot \sigma_1 \frac{\partial^2 \mathcal{L}}{\partial z^2} = \int^1 (\omega, \omega) z$$

$$\sigma_2 \frac{\partial \mathcal{L}}{\partial z} + \sigma_2 \frac{\partial^2 \mathcal{L}}{\partial z^2} \cdot z + z \cdot \sigma_2 \frac{\partial^2 \mathcal{L}}{\partial z^2} = - \int^2 (\omega, \omega) z$$

$$z \sigma \cdot \left(\frac{\partial^2 \mathcal{L}}{\partial z^2} + \frac{\partial^2 \mathcal{L}}{\partial z^2} \right) = e \cos(\theta) \sigma \cdot \left(\frac{\partial^2 \mathcal{L}}{\partial \theta^2} + \frac{1}{e} \frac{\partial \mathcal{L}}{\partial \theta} + \frac{1}{e^2} \frac{\partial^2 \mathcal{L}}{\partial \theta^2} \right)$$

$$\left\{ \begin{aligned} & \frac{\partial^2 \mathcal{L}}{\partial z^2} \cos^2(\theta) + \frac{\partial^2 \mathcal{L}}{\partial z^2} \sin^2(\theta) + 2 \sin(\theta) \cos(\theta) \frac{\partial^2 \mathcal{L}}{\partial z \partial \theta} \\ & + \frac{1}{e} \left(\frac{\partial \mathcal{L}}{\partial z} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right) \\ & + \frac{1}{e^2} \left(\frac{\partial^2 \mathcal{L}}{\partial z^2} e^2 \cos(\theta)^2 - 2 \frac{\partial^2 \mathcal{L}}{\partial z \partial \theta} e^2 \sin(\theta) \cos(\theta) + \frac{\partial^2 \mathcal{L}}{\partial z^2} e^2 \sin(\theta)^2 \right. \\ & \quad \left. - e \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) - e \frac{\partial \mathcal{L}}{\partial z} \cos(\theta) \right) \end{aligned} \right\}$$

$$\frac{\partial \mathcal{L}}{\partial z} ?$$

$$\left(-\frac{\partial \mathcal{L}}{\partial z} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right) + \left(\frac{\partial \mathcal{L}}{\partial z} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right)$$

$$= \frac{\partial \mathcal{L}}{\partial z} (\sin(\theta) + \cos(\theta)) + \frac{\partial \mathcal{L}}{\partial z} (\sin(\theta) - \cos(\theta))$$

$$\left(-\frac{\partial \mathcal{L}}{\partial z} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right) \left(\frac{\partial \mathcal{L}}{\partial z} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right)$$

$$= -\frac{\partial \mathcal{L}}{\partial z} \frac{\partial \mathcal{L}}{\partial z} \cos(\theta)^2 + \frac{\partial \mathcal{L}}{\partial z} \frac{\partial \mathcal{L}}{\partial z} \sin(\theta)^2 - \frac{\partial \mathcal{L}}{\partial z} \frac{\partial \mathcal{L}}{\partial z} \cos(\theta) \sin(\theta) + \frac{\partial \mathcal{L}}{\partial z} \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \cos(\theta)$$

$$\frac{\partial \mathcal{L}}{\partial \theta} = \rho \left(\frac{\partial \mathcal{L}}{\partial z} \cos(\theta) - \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right)$$

$$\frac{\partial \mathcal{L}}{\partial \rho} = \frac{\partial \mathcal{L}}{\partial z} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta)$$

$$\left(\frac{\partial \mathcal{L}}{\partial \rho} - \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right) / \cos(\theta) = \frac{\partial \mathcal{L}}{\partial z}$$

$$\left(\frac{1}{\rho} \frac{\partial \mathcal{L}}{\partial \theta} + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta) \right) / \cos(\theta) = \frac{\partial \mathcal{L}}{\partial z}$$

$$-\left(\frac{1}{\rho} \frac{\partial \mathcal{L}}{\partial \theta} - \frac{\partial \mathcal{L}}{\partial z} \cos(\theta) \right) / \sin(\theta) = \frac{\partial \mathcal{L}}{\partial z}$$

$$\frac{\frac{\partial \mathcal{L}}{\partial \rho} - \frac{\partial \mathcal{L}}{\partial z} \sin(\theta)}{\cos(\theta)} = \frac{-1/\rho \frac{\partial \mathcal{L}}{\partial \theta} + \frac{\partial \mathcal{L}}{\partial z} \cos(\theta)}{\sin(\theta)}$$

$$\frac{\partial \mathcal{L}}{\partial \rho} \sin(\theta) - \frac{\partial \mathcal{L}}{\partial z} \sin^2(\theta) = -1/\rho \frac{\partial \mathcal{L}}{\partial \theta} \cos(\theta) + \frac{\partial \mathcal{L}}{\partial z} \cos^2(\theta)$$

$$\frac{\partial \mathcal{L}}{\partial \rho} \sin(\theta) + \frac{1}{\rho} \frac{\partial \mathcal{L}}{\partial \theta} \cos(\theta) = \frac{\partial \mathcal{L}}{\partial z}$$

$$\left(\frac{\partial \mathcal{L}}{\partial \rho} - \frac{\partial \mathcal{L}}{\partial z} \cos(\theta) \right) / \sin(\theta) = \frac{\partial \mathcal{L}}{\partial z}$$

$$\frac{\frac{\partial \mathcal{L}}{\partial \rho} - \frac{\partial \mathcal{L}}{\partial z} \cos(\theta)}{\sin(\theta)} = \frac{1/\rho \frac{\partial \mathcal{L}}{\partial \theta} + \frac{\partial \mathcal{L}}{\partial z} \sin(\theta)}{\cos(\theta)}$$

$$\frac{\partial \mathcal{L}}{\partial \rho} \cos(\theta) - \frac{\partial \mathcal{L}}{\partial z} \cos^2(\theta) = \frac{1}{\rho} \frac{\partial \mathcal{L}}{\partial \theta} \sin(\theta) + \frac{\partial \mathcal{L}}{\partial z} \sin^2(\theta)$$

$$\boxed{\frac{\partial \mathcal{L}}{\partial \rho} \cos(\theta) - \frac{1}{\rho} \frac{\partial \mathcal{L}}{\partial \theta} \sin(\theta) = \frac{\partial \mathcal{L}}{\partial z}}$$

$$\frac{\partial \mathcal{L}}{\partial z} = \frac{\partial \mathcal{L}}{\partial e} \cos(\theta) - \frac{1}{e} \frac{\partial \mathcal{L}}{\partial \theta} \sin(\theta)$$

$$z \sigma \cdot \left(\frac{\partial^2 \mathcal{L}}{\partial z^2} + \frac{\partial^2 \mathcal{L}}{\partial z^2} \right) = e \cos(\theta) \sigma \cdot \left(\frac{\partial^2 \mathcal{L}}{\partial e^2} + \frac{1}{e} \frac{\partial \mathcal{L}}{\partial e} + \frac{1}{e^2} \frac{\partial^2 \mathcal{L}}{\partial \theta^2} \right)$$

$$\sigma \cdot \frac{\partial \mathcal{L}}{\partial z} + \sigma \cdot z \left(\frac{\partial^2 \mathcal{L}}{\partial z^2} + \frac{\partial^2 \mathcal{L}}{\partial z^2} \right) = f'(L_u, u)$$

Assume $\frac{\partial \mathcal{L}}{\partial \theta} = 0$!

$$\sigma \cdot \frac{\partial \mathcal{L}_u}{\partial e} \cos(\theta) + \sigma \cdot e \cos(\theta) \left(\frac{\partial^2 \mathcal{L}_u}{\partial e^2} + \frac{1}{e} \frac{\partial \mathcal{L}_u}{\partial e} \right) = f'(L_u, u)$$

$$2 \cdot \sigma \cdot \frac{\partial \mathcal{L}_u}{\partial e} \cos(\theta) + \sigma \cdot e \cos(\theta) \frac{\partial^2 \mathcal{L}_u}{\partial e^2} = f'(L_u, u) z$$

$$2 \cdot \sigma \cdot \frac{\partial \mathcal{L}_u}{\partial e} \cos(\theta) + \sigma \cdot e \cos(\theta) \frac{\partial^2 \mathcal{L}_u}{\partial e^2} = -f^2(L_u, u) z$$

Best optioning:

$$2 \sigma \cdot \frac{\partial \mathcal{L}_u}{\partial e} \cdot \frac{1}{e} + \sigma \cdot \frac{\partial^2 \mathcal{L}_u}{\partial e^2} = f'(L_u, u)$$

A. $L_u = e^2 - 1 + L_u, \quad u = -e^2 + 1 + L_u \Rightarrow \text{CORRECT !}$
 $f'(L_u, u) = 6\sigma, \quad f^2(L_u, u) = 6\sigma$

B. $L_u = e^2 - u u \Leftrightarrow u = \frac{e^2}{1+u}$

$$L_u = e^2 + u u \Leftrightarrow u = \frac{e^2}{1-u}$$

$$\boxed{\begin{aligned} 2\sigma \cdot \frac{\partial C_u}{\partial e} \cdot \frac{1}{e} + \sigma \cdot \frac{\partial^2 C_u}{\partial e^2} &= f'(u, u) \\ 2\sigma \cdot \frac{\partial C_v}{\partial e} \cdot \frac{1}{e} + \sigma \cdot \frac{\partial^2 C_v}{\partial e^2} &= -f^2(u, u) \end{aligned}}$$

$$\begin{aligned} \text{B. } u &= e^2 - C_u C_v \Leftrightarrow u = \frac{e^2}{1+C_v} \\ C_v &= -e^2 + C_u C_v \Leftrightarrow u = \frac{-e^2}{1-C_u} \end{aligned}$$

$$f' = \frac{6\sigma}{1+C_v}$$

$$\frac{\partial f'}{\partial C_v} = \frac{-6\sigma}{(1+C_v)^2}$$

$$f^2 = \frac{6\sigma}{1-C_u}$$

$$\frac{\partial f^2}{\partial C_u} = \frac{6\sigma}{(1-C_u)^2}$$

$$\text{C. } u = e^4 - 1 + C_u \quad 4e^3 \quad 12e^2$$

$$\hookrightarrow 2\sigma 4e^2 + \sigma \cdot 12e^2 = f'(u, u)$$

$$20\sigma e^2 = 20\sigma (-C_v + 1 - C_u) = f'(u, u)$$

$$C_v = -e^2 + 1 + C_u$$

$$\hookrightarrow f^2(u, u) = 6\sigma$$