

# Ronald Wee

Final Year Student at NUS

Aspiring Robotics Software/AI Engineer

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Singapore



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## EDUCATION

### Mechanical Engineering (2nd major in Innovation and Design)

National University of Singapore

08/2019 - Present

GPA: 4.25/5

#### Relevant Courses

- Feedback Control Systems
- Automation
- Robot Mechanics and Control
- Introduction to Machine Learning

## WORK EXPERIENCE

### Robotics Software Engineering Intern

Solustar Pte Ltd

06/2022 - 08/2022

Robotics Company

Singapore

#### Achievements/Tasks

- Gazebo simulation of Disinfecting Robot using URDF
- Tested SLAM packages such as hector\_slam and gmapping
- Software development in Python
- Performed wheel calibration to improve AMCL
- Assisted in analysing odometry data in Octave

### Robotics Engineer Intern

Weston Robot Pte Ltd

12/2021 - 05/2022

Robotics Start-up company

Singapore

#### Achievements/Tasks

- Spearheaded conceptual design for cleaning robots using Fusion360
- Assisted with PCB casing design, soldering and testing
- Testing of Autonomous Ground Robots using ROS and Rviz

### Mechatronics Design Engineer

Flexlink Engineers Pte Ltd

05/2020 - 07/2020

Electrical and electronics engineering company

Singapore

#### Achievements/Tasks

- Produced 2D mechanical design and architecture site plan using AutoCAD
- Produced control wiring diagram, electrical schematics, PLC ladder diagram and flowcharts

### Engineering Intern

Flexlink Engineers Pte Ltd

03/2019 - 07/2019

Electrical and electronics engineering company

Singapore

#### Achievements/Tasks

- Spearheaded projects for panel building, from design phase to assembly phase, utilizing AutoCAD and electrical wiring knowledge
- Involved in a major engineering projects from companies such as SMRT, SAF, from procurement of sub-components to production and testing

## SKILLS

Computer-aided Design

C

C++

Python

Microcontroller Programming

Electrical Wiring

ROS

Machine Learning

Web Development

Git

PLC

PyTorch

## PERSONAL PROJECTS

Final Year Project (07/2022 - Present)

- Unseen Object Instance Segmentation in PyTorch

Design Project at NUS (01/2021 - 12/2021)

- Developing an automated rain screen for HDB estates
- Utilized SolidWorks to generate design concept
- Data collection using weather sensors and Raspberry Pi
- Trained machine learning models to predict rainwater penetration

TI RSLK Mechkit (06/2021 - 07/2021)

- Wired up sensors and actuators for a robot
- Programmed MSP432 microcontroller on a robot for teleoperation and obstacle avoidance

## CERTIFICATES

Deep Learning Specialisation

CS50x Introduction to Computer Science

ROS for Beginners: Basics, Motion, and OpenCV

The Mechatronics Revolution: Fundamentals and Core Concept

## LANGUAGES

English

Native or Bilingual Proficiency

Chinese

Native or Bilingual Proficiency