Quantum Mechanics

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1 Review of Preparatory Knowledge

1.1 Classical Mechanics

1. $\delta S \equiv 0$ Principle of Least Action

2.
$$\frac{\mathrm{d}}{\mathrm{d}t} \frac{\partial \mathcal{L}}{\partial \dot{q}_{\alpha}} = \frac{\partial \mathcal{L}}{\partial q_{\alpha}} \quad (\alpha = 1, 2, \cdots, D)$$
 Euler-Lagrange eqs.

3.
$$\begin{vmatrix} \dot{q}_{\alpha} = \frac{\partial H}{\partial p_{\alpha}} \\ \dot{p}_{\alpha} = -\frac{\partial H}{\partial q_{\alpha}} \end{vmatrix}$$
 $(\alpha = 1, 2, \dots, D)$ Hamilton's Canonical eqs.

4.
$$\boxed{\frac{\mathrm{d}f}{\mathrm{d}t} = \frac{\partial f}{\partial t} + [f,H]_{\mathrm{PB}}[f,H]_{\mathrm{PB}}}$$
 Poisson Bracket

5.
$$\boxed{\frac{\partial S}{\partial t} + H(q, \frac{\partial S}{\partial q}, t) = 0}$$
 Hamilton-Jacobi eq.

1.2 Newtonian Mechanics

Euclidean Space (Physical Space) \longrightarrow Cartesian (Descartes) Coordinates

$$\frac{\mathrm{d}\boldsymbol{p}}{\mathrm{d}t} = \boldsymbol{F}, \ \boldsymbol{p} = m\boldsymbol{v} \text{ (Momentum & Force)}$$

$$\frac{\mathrm{d} \boldsymbol{L}}{\mathrm{d} t} = \boldsymbol{M}, \ \boldsymbol{L} = \boldsymbol{x} \times \boldsymbol{p}, \ \boldsymbol{M} = \boldsymbol{x} \times \boldsymbol{F}$$
 (Angular Momentum & Torque)

Mass point \longrightarrow Mass point system \longrightarrow Rigid Body \longrightarrow Inertia $\begin{cases} \text{Mass: } m \\ \text{Inertia of Rotation: } mr^2 \end{cases}$

1.3 Lagrangian Mechanics - Analytical M.

1.3.1 Constraint

$$x_1, x_2, \dots, x_{3N}$$
 are dependent $\Longrightarrow q_1, q_2, \dots, q_D$ are independent $\left(\frac{\partial q_i}{\partial q_j} = 0, i \neq j\right)$ constraint $\begin{cases} \text{holonomic: } f(x;t) \equiv 0 \\ \text{non-holonomic: } f(x,\dot{x};t) \equiv 0 \end{cases}$

5

1.3.2 Coordinates and Space

Generalized Coordinates $q_{\alpha}(t)$, $\alpha = 1, 2, \dots, D \leq 3N$ Configuration Space (Abstract Space): *D*-dim

1.3.3 Functional

Example of functionals (function of function):

1. Lagrangian:

$$\mathcal{L}(q(t), \dot{q}(t); t)$$

generalized velocity: $\dot{q} = \frac{\mathrm{d}q}{\mathrm{d}t}$

2. Hamiltonian:

canonical position: q(t); canonical momentum: $p_{\alpha} = \frac{\partial \mathcal{L}}{\partial \dot{q}_{\alpha}}$ (in Phase Space)

3. Action:

$$S[q(t)] = \int_{t_1}^{t_2} \mathcal{L}(q(t), \dot{q}(t); t) dt$$

Dimensions of these functionals:

$$[\mathcal{L}] = [H] = [\text{Energy}], \ [S] = [\text{Energy}] \cdot [\text{Time}] = [\text{Length}] \cdot [\text{Momentum}] = [\hbar]$$

Reduced Planck's Constant: $\hbar = \frac{h}{2\pi}$

1.3.4 Difference & Differential & Variation

$$f(x_2) - f(x_1) = \underbrace{\Delta f}_{\text{difference}} \xrightarrow{\Delta x \to 0} \underbrace{\Delta f}_{\text{differential}}, \text{ variation: } \delta q(t) = q_2(t) - q_1(t)$$

$$f(q, \dot{q}; t) : \begin{cases} \Delta f = \frac{\partial f}{\partial q} \Delta q + \frac{\partial f}{\partial \dot{q}} \Delta \dot{q} \\ \mathrm{d}f = \frac{\partial f}{\partial q} \mathrm{d}q + \frac{\partial f}{\partial \dot{q}} \mathrm{d}\dot{q} \\ \delta f = \frac{\partial f}{\partial q} \delta q + \frac{\partial f}{\partial \dot{q}} \delta \dot{q} \ (\delta q(t_1) = \delta q_2 = 0; \delta t = 0) \end{cases}$$

1.3.5 Principle of Least Action (Hamilton's Principle)

$$\delta S \equiv 0 \implies$$
 dynamical equations

1.3.6 Euler-Lagrange Equations

$$\frac{\partial \mathcal{L}}{\partial q_{\alpha}} = \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}_{\alpha}} \right), \ \alpha = 1, 2, \cdots, D$$

D 2nd-order ODE

$$0 \equiv \delta S = \delta \int_{t_1}^{t_2} \mathcal{L}(q, \dot{q}; t) dt = \int_{t_1}^{t_2} \left(\frac{\partial \mathcal{L}}{\partial q} \delta q + \frac{\partial \mathcal{L}}{\partial \dot{q}} \delta \dot{q} \right) dt$$

$$= \int_{t_1}^{t_2} \left[\frac{\partial \mathcal{L}}{\partial q} \delta q + \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \delta q \right) - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) \delta q \right] dt$$

$$= \int_{t_1}^{t_2} \left[\frac{\partial \mathcal{L}}{\partial q} - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) \right] \delta q dt + \underbrace{\frac{\partial \mathcal{L}}{\partial \dot{q}} \delta q}_{t_1} \left| \frac{\partial \mathcal{L}}{\partial q} - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) \right| = 0$$

1.4 Hamiltonian Mechanics - Analytical M.

1.4.1 Legendre Transformations

$$\begin{cases} p_{\alpha} = \frac{\partial \mathcal{L}}{\partial \dot{q}_{\alpha}}, \ \alpha = 1, 2, \cdots, D \\ H(q, p; t) = \sum_{\alpha} p_{\alpha} \dot{q}_{\alpha} - \mathcal{L}(q, \dot{q}; t) \end{cases}$$

$$\Longrightarrow \frac{\partial H}{\partial \dot{q}_{\alpha}} = p_{\alpha} - \frac{\partial \mathcal{L}}{\partial \dot{q}_{\alpha}} \equiv 0 \Longrightarrow H \text{ is } \dot{q} \text{ - independent}, \mathcal{L} \text{ is } p \text{ - independent}$$

1.4.2 Hamilton's Canonical Equations of Motion

$$\begin{cases} \dot{q}_{\alpha} = \frac{\partial H}{\partial p_{\alpha}} \\ \dot{p}_{\alpha} = -\frac{\partial H}{\partial q_{\alpha}} \end{cases} \quad \alpha = 1, 2, \cdots, D$$

2D 1st-order ODE

$$0 \equiv \frac{\partial \mathcal{L}}{\partial p_{\alpha}} = \dot{q}_{\alpha} - \frac{\partial H}{\partial p_{\alpha}} \Longrightarrow \dot{q}_{\alpha} = \frac{\partial H}{\partial p_{\alpha}}; \ \dot{p}_{\alpha} = \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}_{\alpha}} \right) = \frac{\partial \mathcal{L}}{\partial q_{\alpha}}, \ \frac{\partial H}{\partial q_{\alpha}} = -\frac{\partial \mathcal{L}}{\partial q_{\alpha}} \Longrightarrow \dot{p}_{\alpha} = -\frac{\partial H}{\partial q_{\alpha}}$$
$$\mathrm{d}H = \frac{\partial H}{\partial t} \mathrm{d}t + \frac{\partial H}{\partial q} \mathrm{d}q + \frac{\partial H}{\partial p} \mathrm{d}p = \mathrm{d}\left(p\dot{q} - \mathcal{L}(q,q;t)\right)$$
$$= (\mathrm{d}p)\dot{q} + p\mathrm{d}\dot{q} - \frac{\partial \mathcal{L}}{\partial t} \mathrm{d}t - \frac{\partial \mathcal{L}}{\partial q} \mathrm{d}q - \frac{\partial \mathcal{L}}{\partial \dot{q}} \mathrm{d}\dot{q} = \dot{q}\mathrm{d}p - \dot{p}\mathrm{d}q - \frac{\partial \mathcal{L}}{\partial t} \mathrm{d}t$$
$$\Longrightarrow \dot{q} = \frac{\partial H}{\partial p}, \ \dot{p} = -\frac{\partial H}{\partial q}$$
$$0 \equiv \delta S = \delta \int (p\dot{q} - H(q,p;t)) \mathrm{d}t \Longrightarrow \dot{q} = \frac{\partial H}{\partial p}, \ \dot{p} = -\frac{\partial H}{\partial q}$$

1.4.3 Poisson Bracket (Classical Canonical Commutator)

$$AB_{\text{PB}} = \sum_{\alpha} \left(\frac{\partial A}{\partial q_{\alpha}} \frac{\partial B}{\partial p_{\alpha}} - \frac{\partial A}{\partial p_{\alpha}} \frac{\partial B}{\partial q_{\alpha}} \right)$$

 \Longrightarrow Quantum Canonical Commutator $\left[\hat{A},\hat{B}\right]=\hat{A}\hat{B}-\hat{B}\hat{A}$

$$\forall f(q, p; t), \frac{\mathrm{d}f}{\mathrm{d}t} = \frac{\partial f}{\partial t} + \sum_{\alpha} \left(\frac{\partial f}{\partial q_{\alpha}} \dot{q}_{\alpha} + \frac{\partial f}{\partial p_{\alpha}} \dot{p}_{\alpha} \right) = \frac{\partial f}{\partial t} + \sum_{\alpha} \left(\frac{\partial f}{\partial q_{\alpha}} \frac{\partial H}{\partial p_{\alpha}} - \frac{\partial f}{\partial p_{\alpha}} \frac{\partial H}{\partial q_{\alpha}} \right) = \frac{\partial f}{\partial t} + [f, H]_{\mathrm{PB}}$$

$$\text{if } f(q, p; t) = q_{\alpha} \Longrightarrow \frac{\mathrm{d}q_{\alpha}}{\mathrm{d}t} = \frac{\partial H}{\partial p_{\alpha}}, \text{ if } f(q, p; t) = p_{\alpha} \Longrightarrow \frac{\mathrm{d}p_{\alpha}}{\mathrm{d}t} = -\frac{\partial H}{\partial q_{\alpha}}$$

1.4.4 Fundamental Commutation Relations in CM

$$[q_{\alpha}, p_{\beta}]_{PB} = \delta_{\alpha\beta} \longleftrightarrow [\hat{q}_{\alpha}, \hat{p}_{\beta}] = i\hbar \delta_{\alpha\beta}$$

$$[q_{\alpha}, q_{\beta}]_{PB} = [p_{\alpha}, p_{\beta}]_{PB} \equiv 0 \longleftrightarrow [\hat{q}_{\alpha}, \hat{q}_{\beta}] = [\hat{p}_{\alpha}, \hat{p}_{\beta}] \equiv 0$$

$$[q_{\alpha}, p_{\beta}] = \sum_{\gamma} \left(\frac{\partial q_{\alpha}}{\partial q_{\gamma}} \frac{\partial p_{\beta}}{\partial p_{\gamma}} - \frac{\partial q_{\alpha}}{\partial p_{\gamma}} \frac{\partial p_{\beta}}{\partial q_{\gamma}} \right) = \delta_{\alpha\gamma} \delta_{\beta\gamma} - 0 = \delta_{\alpha\beta}$$

$$[q_{\alpha}, q_{\beta}] = \sum_{\gamma} \left(\frac{\partial q_{\alpha}}{\partial q_{\gamma}} \frac{\partial q_{\beta}}{\partial p_{\gamma}} - \frac{\partial q_{\alpha}}{\partial p_{\gamma}} \frac{\partial q_{\beta}}{\partial q_{\gamma}} \right) = \delta_{\alpha\gamma} \cdot 0 - 0 \cdot \delta_{\beta\gamma} = 0$$

1.4.5 Properties of Poisson Bracket

1.
$$[A, B]_{PB} = -[B, A]_{PB}$$

2.
$$[A+B,C]_{PB} = [A,C]_{PB} + [B,C]_{PB}, [A,B+C]_{PB} = [A,B]_{PB} + [A,C]_{PB}$$

3.
$$[A, BC]_{PB} = [A, B]_{PB}C + B[A, C]_{PB}, [AB, C]_{PB} = [A, C]_{PB}B + A[B, C]_{PB}$$

4.
$$[A, B^n]_{PB} = n[A, B]_{PB}B^{n-1}$$

5.
$$[A, f(B)]_{PB} = [A, B]_{PB} \frac{\partial f}{\partial B}$$

6.
$$[L_i, L_j]_{PB} = \epsilon_{ijk} L_k$$

7.
$$[L_i, \mathbf{L}^2]_{PB} = 0$$

8.
$$[L_i, x_j]_{PR} = \epsilon_{ijk} x_k$$

9.
$$[L_i, p_j]_{PB} = \epsilon_{ijk} p_k$$

$$[L_{i}, L_{j}]_{PB} = [\epsilon_{iab}x_{a}p_{b}, \epsilon_{jcd}x_{c}p_{d}]_{PB} = \epsilon_{iab}\epsilon_{jcd} \left(x_{a}\underbrace{[p_{b}, x_{c}]_{PB}}_{=-\delta_{bc}}p_{d} + x_{c}\underbrace{[x_{a}, p_{d}]_{PB}}_{=\delta_{ad}}p_{b}\right)$$

$$= \epsilon_{iab}\epsilon_{jca}x_{c}p_{b} - \epsilon_{iab}\epsilon_{jbd}x_{a}p_{d} = (\delta_{bj}\delta_{ic} - \delta_{bc}\delta_{ij})x_{c}p_{b} - (\delta_{ij}\delta_{ad} - \delta_{id}\delta_{aj})x_{a}p_{d}$$

$$= x_{i}p_{j} - \delta_{ij}(\mathbf{x} \cdot \mathbf{p}) + \delta_{ij}(\mathbf{x} \cdot \mathbf{p}) - x_{j}p_{i} = x_{i}p_{j} - x_{j}p_{i} = \epsilon_{ijk}L_{k}$$

1.4.6 Hamilton-Jacobi Equation

$$\frac{\partial S}{\partial t} + H(q, \frac{\partial H}{\partial q}; t) = 0$$

$$\delta S = \int_{t_0}^{t} \mathcal{L}(q, \dot{q}; t) dt = \int_{t_0}^{t} \left[\frac{\partial \mathcal{L}}{\partial q} \delta q + \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \delta q \right) - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) \delta q \right]$$

$$= \int_{t_0}^{t} \underbrace{\left(\frac{\partial \mathcal{L}}{\partial q} - \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}} \right)}_{=0 \text{ (physical path)}} \delta q dt + \underbrace{\frac{\partial \mathcal{L}}{\partial \dot{q}}}_{=0 \text{ (fixed)}} \delta q(t) - \underbrace{\frac{\partial \mathcal{L}}{\partial \dot{q}}}_{=0 \text{ (fixed)}} \delta q(t_0) = \underbrace{\frac{\partial \mathcal{L}}{\partial \dot{q}}}_{=0 \text{ (fixed)}} \delta q = p \delta q$$

$$\begin{cases} \delta S = p \delta q \\ \delta S[q(t), t] = \frac{\partial S}{\partial q} \delta q \end{cases} \implies p = \frac{\partial S}{\partial q}, \begin{cases} \frac{\mathrm{d}S}{\mathrm{d}t} = \frac{\partial S}{\partial t} + \frac{\partial S}{\partial q} \dot{q} \\ \frac{\mathrm{d}S}{\mathrm{d}t} = \mathcal{L} = p \dot{q} - H \end{cases} \implies \frac{\partial S}{\partial t} + H = 0$$

1.4.7 Phase Space (Dynamics)

phase point $(q, p) \longrightarrow \text{state}$

$$\int \rho(q, p; t) d^D q d^D p = 1$$

 ρ : probability

1.4.8 Regular Lagrangian

$$\left| \frac{\partial^2 \mathcal{L}}{\partial q_i \partial q_j} \right| \neq 0 \Longrightarrow \begin{cases} \mathcal{L} = T - V \\ H = T + V \end{cases}$$

2 Classical Electrodynamics

2.1 Vector Analysis

$$\boldsymbol{v} = v_1 \boldsymbol{e}_1 + v_2 \boldsymbol{e}_2 + v_3 \boldsymbol{e}_3 = \sum_i v_i \boldsymbol{e}_i = v_i \boldsymbol{e}_i$$
 (Einstein convention), $i = 1, 2, 3$

2.1.1 Generalized Stokes' Theorem

$$\int_{\Omega} d\omega = \int_{\partial \Omega} \omega$$

1. Newton-Leibniz formula

$$\int_{a}^{b} \mathrm{d}f = f(b) - f(a)$$

2. Green's theorem

$$\oint f \, dx + g \, dy = \iint \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \, dx \, dy$$

3. Stokes' theorem

$$\oint \mathbf{F} \cdot d\mathbf{l} = \iint (\nabla \times \mathbf{F}) \cdot d\mathbf{S}$$

$$\implies \oint \psi d\mathbf{l} = \iint d\mathbf{S} \times \nabla \psi$$

4. Gauss-Ostrogradsky's theorem

$$\oiint \mathbf{F} \cdot d\mathbf{S} = \iiint (\nabla \cdot \mathbf{F}) \, dV$$

$$\Longrightarrow \begin{cases}
\oiint \psi \, d\mathbf{S} = \iiint (\nabla \psi) \, dV$$

$$\oiint d\mathbf{S} \nabla \mathbf{A} = \iiint (\nabla \times \mathbf{A}) \, dV$$

2.1.2 Helmholtz's theorem

For all continuous differentiable F,

$$m{F} = m{F}_{\!\perp} + m{F}_{\!\parallel}$$

1. transverse component

$$\nabla \cdot \boldsymbol{F}_{\perp} = 0$$
 & $\boldsymbol{F}_{\perp} = \nabla \times \boldsymbol{A}$

2. longitudinal component

$$\nabla \times \boldsymbol{F}_{\parallel} = 0$$
 & $\boldsymbol{F}_{\parallel} = -\nabla \phi$

For magnetic field ${m B}$

$$\nabla \cdot \boldsymbol{B} \equiv 0$$

For electric field ${m E}$

$$\begin{cases} \nabla \times \boldsymbol{E} = 0 & \text{for static electric field} \\ \nabla \times \boldsymbol{E} \neq 0 & \text{for AC electric field} \end{cases}$$

2.2 Experimental Laws and Maxwell's Equations

2.2.1 Coulomb's Law

$$E(\boldsymbol{x}) = \int \frac{\rho(\boldsymbol{x}')(\boldsymbol{x} - \boldsymbol{x}')}{|\boldsymbol{x} - \boldsymbol{x}'|^3} dV' = -\nabla \phi, \quad \phi = \int \frac{\rho(\boldsymbol{x}')}{|\boldsymbol{x} - \boldsymbol{x}'|} dV'$$

$$\Longrightarrow \boxed{\nabla \cdot \boldsymbol{E} = 4\pi \rho(\boldsymbol{x})} \quad \text{Gauss' Law}$$

2.2.2 Biot-Savart's Law

$$\boldsymbol{B} = \int \frac{\boldsymbol{j}(\boldsymbol{x}') \times (\boldsymbol{x} - \boldsymbol{x}')}{\left| \boldsymbol{x} - \boldsymbol{x}' \right|^3} \, dV' = \nabla \times \boldsymbol{A}(\boldsymbol{x})$$

3 Fundamental Postulates (Axioms)

4 SOME IS

- 1. State
- 2. Observable (Operation)
- 3. Measurement
- 4. Evolution
- 5. Identical Particular and Symmetrization

4.1 State

system \longleftrightarrow state vector ket: $|\psi\rangle$

bra: $\langle \psi |$

$$(|\psi\rangle)^{\dagger} = \langle \psi |$$
$$[(|\psi\rangle)^{\dagger}]^{\dagger} = (\langle \psi |)^{\dagger} = |\psi\rangle$$

†: adjoint or Hermitian conjugate

4.2 Observable

physical quantity
$$\longleftrightarrow$$
 observable \longleftrightarrow operation $\hat{A} \begin{cases} \text{linear} \\ \text{Hermitian} \end{cases}$

4.3 Measurement

4.3.1 Measurement + Outcomes

$$\hat{A} |\psi\rangle = A_n |\psi_n\rangle$$
 (Eigenvalue equation)

 \hat{A} : operation (q-number); A_n : eigenvalue (c-number); ψ_n : eigenstate

4.3.2 Probability of Measurement Outcomes

$$|\psi\rangle = \sum_{n} c_{n} |\psi_{n}\rangle, \ c_{n} = \langle\psi_{n}|\psi\rangle$$

$$P(A_{n}) = |c_{n}|^{2} = |\langle\psi_{n}|\psi\rangle|^{2}$$

$$\langle\hat{A}\rangle = \langle\psi|\,\hat{A}\,|\psi\rangle = \sum_{n} P(A_{n})A_{n} = \sum_{n} |\langle\psi_{n}|\psi\rangle|^{2}A_{n}$$

4.3.3 State Collapse

$$|\psi\rangle \xrightarrow{\hat{A}\text{-measurement}} |\psi_n\rangle$$

4.4 Evolution (Dynamics)

4.4.1 Schrödinger Picture

state: change; observable: no change

where
$$\hat{H} = \hat{T} + \hat{V} = \frac{\hat{p}^2}{2m} + \hat{V}(\hat{x})$$

representation: coordinate system \hat{x} -representation (position):

$$\hat{x} | x \rangle = x | x \rangle, \ | \psi \rangle \longrightarrow \langle x | \psi \rangle = \psi(x) \rightarrow \text{wave-function}$$

$$\Longrightarrow \left[i\hbar \frac{\partial}{\partial t} \psi(\boldsymbol{x},t) = -\frac{\hbar^2}{2m} \nabla^2 \psi(\boldsymbol{x},t) + \hat{V}(\boldsymbol{x},t) \psi(\boldsymbol{x},t) \right]$$

 $\hat{\boldsymbol{p}}$ -representation (momentum): $\hat{\boldsymbol{p}} \left| \boldsymbol{p} \right\rangle = \boldsymbol{p} \left| \boldsymbol{p} \right\rangle$

4.4.2 Heisenberg Picture

state: no change; observable: change

$$\boxed{\frac{\mathrm{d}\hat{F}}{\mathrm{d}t} = \frac{\partial\hat{F}}{\partial t} + \frac{1}{\mathrm{i}\hbar} \left[\hat{F}, \hat{H}\right]}$$
 Heisenberg Equation

4.5 Identical Particles and Symmetrization

4.5.1 Identical Particles

 $\begin{cases} \text{boson: } s = 0, 1, 2, \cdots \text{ Bose-Einstein Statistics} \\ \text{fermion: } s = \frac{1}{2}, \frac{3}{2}, \cdots \text{ Fermi-Dirac Statistics} \end{cases} \xrightarrow{\text{classical} \\ \text{reduce}} \text{Maxwell-Boltzmann Statistics} \end{cases}$

4.5.2 Symmetrization

Boson: symmetric Femion: anti-symmetric

5 State Vector

5.1 Euclidean Space \mathbb{R}^3

$$\mathbf{v} = v_1 \mathbf{e}_1 + v_2 \mathbf{e}_2 + v_3 \mathbf{e}_3$$

$$\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \ \mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \ \mathbf{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}, \ \mathbf{v}^T = \begin{pmatrix} v_1 & v_2 & v_3 \end{pmatrix}$$

1. vector addition: $\mathbf{v}_1 + \mathbf{v}_2 = \mathbf{v}_2 + \mathbf{v}_1$

2. scalar multiplication:
$$\begin{cases} a(\mathbf{v}_1 + \mathbf{v}_2) = a\mathbf{v}_1 + a\mathbf{v}_2 \\ (a+b)\mathbf{v} = a\mathbf{v} + b\mathbf{v} \end{cases} \quad \forall a, b \in \mathbb{R}$$

3. inner product (dot product): $\boldsymbol{v}_1^T \boldsymbol{v}_2 = \boldsymbol{v}_1 \cdot \boldsymbol{v}_2 = \boldsymbol{v}_2 \cdot \boldsymbol{v}_1 = \boldsymbol{v}_2^T \boldsymbol{v}_1$

4. dyadic: $\mathbf{v}_1 \mathbf{v}_2 \neq \mathbf{v}_2 \mathbf{v}_1$

5. basis:
$$\mathbf{e}_i \cdot \mathbf{e}_j = \delta_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$
 \longrightarrow orthonormal $\mathbf{e}_i \mathbf{e}_i = \mathbf{I} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

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6.
$$\mathbf{v}_1 \cdot \mathbf{v}_2 = r \in \mathbb{R}$$

 $\mathbf{v} \cdot \mathbf{v} = r \in \mathbb{R}, r \ge 0 \text{ (equality iff } \mathbf{v} = \mathbf{0})$

5.2 State Vector Space H (Hilbert Space)

$$|\psi\rangle = \begin{pmatrix} \vdots \\ \vdots \\ \vdots \end{pmatrix}, \ \langle\psi| = \begin{pmatrix} \cdots & \cdots \end{pmatrix}$$

- 1. vector addition: $|\psi_1\rangle + |\psi_2\rangle = |\psi_2\rangle + |\psi_1\rangle$
- 2. scalar multiplication: $\begin{cases} c(|\psi_1\rangle + |\psi_2\rangle) = c |\psi_1\rangle + c |\psi_2\rangle \\ (c+c') |\psi\rangle = c |\psi\rangle + c' |\psi\rangle \end{cases} \quad \forall c \in \mathbb{C}$
- 3. inner product: $\langle \psi_1 | \psi_2 \rangle = (\langle \psi_2 | \psi_1 \rangle)^*$
- 4. outer product: $|\psi\rangle\langle\phi|\neq|\phi\rangle\langle\psi|$

$$(|\psi\rangle \langle \phi|)^{\dagger} = (\langle \phi|)^{\dagger} (|\psi\rangle)^{\dagger} = |\phi\rangle \langle \psi|$$

5. basis: for Hermitian operation $\begin{cases} \hat{A} | \psi_n \rangle = A_n | \psi_n \rangle \text{ discrete} \\ \hat{A} | a \rangle = a | a \rangle \text{ continuous} \end{cases}$

discrete:
$$\begin{cases} \langle \psi_n | \psi_m \rangle = \delta_{nm} = \begin{cases} 1, & n = m \\ 0, & n \neq m \end{cases} \\ \sum_n |\psi_n\rangle \langle \psi_n| = \hat{I} \end{cases}$$

continuous:
$$\begin{cases} \langle a|a'\rangle = \delta(a-a') = \begin{cases} \infty, \ a=a'\\ 0, \ a \neq a' \end{cases} \\ \int |a\rangle \langle a| \ \mathrm{d}a = \hat{I} \end{cases}$$

6.
$$\langle \psi_1 | \psi_2 \rangle = c \in \mathbb{C}$$

 $(\langle \psi_1 | \psi_2 \rangle)^* = \langle \psi_2 | \psi_1 \rangle$
 $\langle \psi | \psi \rangle = |||\psi \rangle||^2 = r \in \mathbb{R}, r \ge 0 \text{ (equality iff } |\psi \rangle = \mathbf{0})$

6 Operator

$$\hat{A} |\phi\rangle = |\psi\rangle, \ \hat{A}^{-1} |\psi\rangle = |\phi\rangle$$

6.1 Linear Operator

$$\forall |\psi_1\rangle, |\psi_2\rangle \in \mathbb{H}, a, b \in \mathbb{C}, \hat{A}(a|\psi_1\rangle + b|\psi_2\rangle) = a\hat{A}|\psi_1\rangle + b\hat{A}|\psi_2\rangle$$

then, \hat{A} is a linear operator

$$\hat{A}(a|\psi_1\rangle + b|\psi_2\rangle) = a^*\hat{A}|\psi_1\rangle + b^*\hat{A}|\psi_2\rangle$$

then, \hat{A} is an anti-linear operation

6.1.1 Two Kinds of Linear Operators

 $\begin{cases} \text{Hermitian operator: } \hat{A}^{\dagger} = \hat{A} \\ \text{Unitary operator: } \hat{U}^{\dagger} = \hat{U}^{-1} \end{cases}$

6.1.2 Rules

$$\forall |\psi\rangle$$
, if $\hat{A}|\psi\rangle = \hat{B}|\psi\rangle \iff \hat{A} = \hat{B}$

- 1. $\hat{A} + \hat{B} = \hat{B} + \hat{A}$ def: $\forall |\psi\rangle$, $\hat{A} |\psi\rangle + \hat{B} |\psi\rangle = (\hat{A} + \hat{B}) |\psi\rangle$
- 2. $(\hat{A} + \hat{B}) + \hat{C} = \hat{A} + (\hat{B} + \hat{C})$
- 3. $\hat{A}\hat{B} \neq \hat{B}\hat{A}$ def commutator: $\left[\hat{A}, \hat{B}\right] = \hat{A}\hat{B} - \hat{B}\hat{A} \longleftrightarrow \left[A, B\right]_{PB} \longleftrightarrow \frac{1}{i\hbar} \left[\hat{A}, \hat{B}\right]$
- 4. adjoint (Hermitian conjugate): $(\hat{A} | \phi \rangle)^{\dagger} = \langle \phi | \hat{A}^{\dagger} \iff \langle \phi | \hat{A}^{\dagger} | \psi \rangle = (\langle \psi | \hat{A} | \phi \rangle)^{*}$ \Longrightarrow Hermitian operation: $\hat{A}^{\dagger} = \hat{A}$ (Hermitian matrix) $\Longrightarrow A_{ij} = A_{ji}^{*}$

6.1.3 Properties

- 1. Identity: $\forall |\psi\rangle, \exists \hat{I}, \hat{I} |\psi\rangle = |\psi\rangle$
- 2. Inverse: $\hat{A} | \psi \rangle = | \phi \rangle \Longrightarrow | \psi \rangle = \hat{A}^{-1} | \phi \rangle$, $\hat{A} \hat{A}^{-1} = \hat{A}^{-1} \hat{A} = \hat{I}$ $(\hat{A}_1 \hat{A}_2 \cdots \hat{A}_n)^{-1} = \hat{A}_n^{-1} \cdots \hat{A}_2^{-1} \hat{A}_1^{-1}$
- 3. $(\hat{A}_1\hat{A}_2\cdots\hat{A}_n)^{\dagger}=\hat{A}_n^{\dagger}\cdots\hat{A}_2^{\dagger}\hat{A}_1^{\dagger}$

7 Overview of QM

ROSE P... M

8 Roles: State Vector, Operator

8.0.1 Operator

$$\begin{cases} \text{Observable} & \begin{cases} \text{Hermitian: } \hat{A}^{\dagger} = \hat{A} \\ \text{Unitary: } \hat{A}^{\dagger} = \hat{A}^{-1} \end{cases}$$

8.0.2 State

$$\begin{cases} \text{ket } |\psi\rangle \text{ (vector): } (|\psi\rangle)^{\dagger} = \langle\psi| \\ \text{bra } \langle\psi| \text{ (dual vector): } (\langle\psi|)^{\dagger} = |\psi\rangle \end{cases}$$

8.0.3 Eigenspectrum

8.1 Properties

Wave Particle Duality

8.2 Problems

8.2.1 Eigenvalue Problem

$$\hat{A} |\psi\rangle = \lambda |\psi\rangle \begin{cases} \hat{A} |u_n\rangle = A_n |u_n\rangle \begin{cases} \langle u_n | u_m\rangle = \delta_{nm} \\ \sum_n |u_n\rangle \langle u_n| = \hat{I} \end{cases} \\ \hat{A} |a\rangle = a |a\rangle \begin{cases} \langle a | a'\rangle = \delta(a - a') \\ \int da |a\rangle \langle a| = \hat{I} \end{cases} \end{cases}$$

8.2.2 Evolution Problem

$$\begin{cases} \mathrm{i}\hbar\frac{\mathrm{d}}{\mathrm{d}t} \left| \psi(t) \right\rangle = \hat{H} \left| \psi(t) \right\rangle & \mathrm{Schrödinger eq.} \\ \frac{\mathrm{d}\hat{F}}{\mathrm{d}t} = \frac{\partial\hat{F}}{\partial t} + \frac{1}{\mathrm{i}\hbar} \Big[\hat{F}, \hat{H}\Big] & \mathrm{Heisenberg eq.} \end{cases}$$

8.3 Picture

8.3.1 Schrödinger Picture

$$\frac{\mathrm{d}\hat{F}}{\mathrm{d}t} = \frac{\partial\hat{F}}{\partial t} \equiv 0$$

8.3.2 Heisenberg Picture

$$\frac{\mathrm{d}}{\mathrm{d}t} |\psi(t)\rangle \equiv 0$$

8.4 Particles

 $\begin{cases} \text{Boson: s=integer} \longrightarrow \text{Bose-Einstein Statistics} \\ \text{Femion: s=half-integer} \longrightarrow \text{Fermi-Dirac Statistics} \end{cases} \xrightarrow{\hbar \to 0} \text{Maxwell-Boltzmann Statistics}$

8.5 Perturbation Theories

 $\begin{cases} \text{Non-degenerate} \\ \text{Degenerate} \end{cases}$

8.6 Angular Momentum and Magnetic Moment

 $\begin{cases} \text{Orbital Angular Momentum} \\ \text{Spin Angular Momentum} \end{cases} \iff \begin{cases} \text{Orbital Magnetic Moment} \\ \text{Intrinsic Magnetic Moment} \end{cases}$

8.7 Mechanics

 $\begin{cases} \text{Wave Mechanics: wavefunction} \longleftrightarrow \text{state vector} \\ \text{Matrix Mechanics: matrix forms of} \end{cases} \begin{cases} \text{state vector} \\ \text{operator: } n \times n \text{ matrix} \end{cases}$

8.8 Theorem of Hermitian Operator

$$\hat{A}^{\dagger}=\hat{A},\quad \hat{A}\left|\psi_{n}\right\rangle =A_{n}\left|\psi_{n}\right\rangle \text{ (non-degenerate, discrete)}$$

- 1. eigenvalue $A_n \in \mathbb{R}$
- 2. eigenstate \longrightarrow orthonarmal and complete basis

$$\langle \psi_{n} | \hat{A}^{\dagger} | \psi_{n} \rangle = (\langle \psi_{n} | \hat{A} | \psi_{n} \rangle)^{*} = A_{n}^{*} \langle \psi_{n} | \psi_{n} \rangle = \langle \psi_{n} | \hat{A} | \psi_{n} \rangle = A_{n} \langle \psi_{n} | \psi_{n} \rangle$$

$$\Longrightarrow A_{n}^{*} = A_{n} \Longrightarrow A_{n} \in \mathbb{R}$$

$$\begin{cases} \hat{A} | \psi_{n} \rangle = A_{n} | \psi_{n} \rangle \\ \hat{A} | \psi_{m} \rangle = A_{m} | \psi_{m} \rangle \end{cases} \Longrightarrow \langle \psi_{n} | \hat{A}^{\dagger} | \psi_{m} \rangle = (\langle \psi_{m} | \hat{A} | \psi_{n} \rangle)^{*} = A_{n}^{*} (\langle \psi_{m} | \psi_{n} \rangle)^{*} = A_{n}^{*} \langle \psi_{n} | \psi_{m} \rangle$$

$$\langle \psi_{n} | \hat{A} | \psi_{m} \rangle = A_{m} \langle \psi_{n} | \psi_{m} \rangle \Longrightarrow (A_{n} - A_{m}) \langle \psi_{n} | \psi_{m} \rangle = 0$$

$$n \neq m \Longrightarrow A_{n} \neq A_{m} \Longrightarrow \langle \psi_{n} | \psi_{m} \rangle = 0 \Longrightarrow |\psi_{n} \rangle \perp |\psi_{m} \rangle$$

Remark: Degenerate,

$$\hat{A} \left| \psi_n^i \right\rangle = A_n \left| \psi_n^i \right\rangle \quad (i = 1, 2, \cdots, g_n) \Longrightarrow \left| \psi_n^i \right\rangle \neq c \left| \psi_n^j \right\rangle \text{ (linear independent)}$$

$$\left| \psi_n^i \right\rangle \xrightarrow{\text{Gram-Schmidt Orthogonalization}} \left| \phi_n^i \right\rangle \begin{cases} \left\langle \phi_n^i \middle| \phi_m^j \right\rangle = \delta_{nm} \delta_{ij} \\ \sum_{n,i} \left| \phi_n^i \right\rangle \left\langle \phi_n^i \middle| = \hat{1} \end{cases}$$

9 Wave Mechanics & Matrix Mechanics

9.1 Wave Mechanics: wavefunction

wavefunction
$$\begin{cases} \text{matter wave (Schrödinger)} \\ \text{probabilistic wave (Born): } \left| \Psi(\boldsymbol{x},t) \right|^2 \sim \text{probability density} \end{cases}$$

wavefunction is the projection of state vector in representation

$$|\psi\rangle = \hat{1} |\psi\rangle = \begin{cases} \left(\sum_{n} |u_{n}\rangle \langle u_{n}|\right) |\psi\rangle = \sum_{n} c_{n} |u_{n}\rangle, & c_{n} = \langle u_{n}|\psi\rangle & \text{discrete} \\ \left(\int da |a\rangle \langle a|\right) |\psi\rangle = \int da \, \psi(a) |a\rangle, & \psi(a) = \langle a|\psi\rangle & \text{continuous} \end{cases}$$

 c_n is the wavefunction in $\{|u_n\rangle\}$ -representation, $\psi(a)$ is the wavefunction in $\{|a\rangle\}$ -representation.

$$|\psi\rangle = \sum_{n} c_n |\psi_n\rangle, \quad c_n = \langle \psi_n |\psi\rangle, \hat{A} |\psi\rangle = A_n |\psi_n\rangle$$

$$\begin{cases} \boldsymbol{x}\text{-representation: } \hat{\boldsymbol{x}} \, | \boldsymbol{x} \rangle = \boldsymbol{x} \, | \boldsymbol{x} \rangle \begin{cases} \langle \boldsymbol{x} | \boldsymbol{x}' \rangle = \delta(\boldsymbol{x} - \boldsymbol{x}') \\ \int \mathrm{d}^3 x \, | \boldsymbol{x} \rangle \, \langle \boldsymbol{x} | = \hat{1} \end{cases} \\ \boldsymbol{p}\text{-representation: } \hat{\boldsymbol{p}} \, | \boldsymbol{p} \rangle = \boldsymbol{p} \, | \boldsymbol{p} \rangle \begin{cases} \langle \boldsymbol{p} | \boldsymbol{p}' \rangle = \delta(\boldsymbol{p} - \boldsymbol{p}') \\ \int \mathrm{d}^3 x \, | \boldsymbol{p} \rangle \, \langle \boldsymbol{p} | = \hat{1} \end{cases}$$

Energy-representation, Fork-state representation (occupation number representation)

$$|\psi\rangle = \left(\int d^3x \, |\boldsymbol{x}\rangle \, \langle \boldsymbol{x}| \right) |\psi\rangle = \int d^3x \, \psi(\boldsymbol{x}) \, |\boldsymbol{x}\rangle$$
$$= \left(\int d^3p \, |\boldsymbol{p}\rangle \, \langle \boldsymbol{p}| \right) |\psi\rangle = \int d^3p \, \tilde{\psi}(\boldsymbol{p}) \, |\boldsymbol{p}\rangle$$

$$\psi(\boldsymbol{x}) = \langle \boldsymbol{x} | \psi \rangle \quad \tilde{\psi}(\boldsymbol{p}) = \langle \boldsymbol{p} | \psi \rangle$$

$$\tilde{\psi}(\boldsymbol{p}) = \langle \boldsymbol{p} | \psi \rangle = \langle \boldsymbol{p} | \hat{1} | \psi \rangle = \langle \boldsymbol{p} | \left(\int d^3 x | \boldsymbol{x} \rangle \langle \boldsymbol{x} | \right) | \psi \rangle = \int d^3 x \langle \boldsymbol{p} | \boldsymbol{x} \rangle \psi(\boldsymbol{x})$$

$$= \int d^3 x \psi(\boldsymbol{x}) \psi_{\boldsymbol{p}}^*(\boldsymbol{x}) \quad \text{where } \psi_{\boldsymbol{p}}(\boldsymbol{x}) = \langle \boldsymbol{x} | \boldsymbol{p} \rangle = \frac{1}{(2\pi\hbar)^{\frac{3}{2}}} e^{-i\boldsymbol{p}\cdot\boldsymbol{x}/\hbar}$$

$$\implies \text{in } \boldsymbol{x}\text{-representation, } \hat{\boldsymbol{x}} = \boldsymbol{x}, \ \hat{\boldsymbol{p}} = -i\hbar \frac{\partial}{\partial \boldsymbol{x}}$$

$$\implies \begin{cases} i\hbar \frac{\mathrm{d}}{\mathrm{d}t} |\psi(t)\rangle = \hat{H} |\psi(t)\rangle \\ \hat{H} = \frac{\hat{\boldsymbol{p}}^{2}}{2m} + V(\hat{\boldsymbol{x}}) \end{cases} \xrightarrow{\int \mathrm{d}^{3}x \, |\boldsymbol{x}\rangle\langle\boldsymbol{x}| = \hat{I}} i\hbar \frac{\partial}{\partial t} \Psi(\boldsymbol{x}, t) = -\frac{\hbar^{2}}{2m} \nabla^{2} \Psi(\boldsymbol{x}, t) + V(\boldsymbol{x}) \Psi(\boldsymbol{x}, t)$$

$$\text{where } \begin{cases} \Psi(\boldsymbol{x}, t) = \langle \boldsymbol{x} | \psi(t) \rangle \\ \hat{\boldsymbol{x}} = \boldsymbol{x}, \quad \hat{\boldsymbol{p}} = -i\hbar \nabla \end{cases}$$

$$\text{in } \boldsymbol{p}\text{-representation, } \hat{\boldsymbol{x}} = +\mathrm{i}\hbar\frac{\partial}{\partial\boldsymbol{p}}, \ \hat{\boldsymbol{p}} = \boldsymbol{p}$$
 Schrödinger eq.
$$\frac{\int \mathrm{d}^{3}\boldsymbol{p}\,|\boldsymbol{p}\rangle\langle\boldsymbol{p}| = \hat{\boldsymbol{I}}}{\partial} \,\mathrm{i}\hbar\frac{\partial}{\partial t}\tilde{\psi}(\boldsymbol{p},t) = \frac{\boldsymbol{p}^{2}}{2m}\tilde{\psi}(\boldsymbol{p},t) + V\left(\mathrm{i}\hbar\frac{\partial}{\partial\boldsymbol{p}}\right)\tilde{\psi}(\boldsymbol{p},t)$$
 where
$$\begin{cases} \tilde{\psi}(\boldsymbol{p}) = \langle\boldsymbol{p}|\psi(t)\rangle \\ \hat{\boldsymbol{p}} = \boldsymbol{p}, \quad \hat{\boldsymbol{x}} = +\mathrm{i}\hbar\frac{\partial}{\partial\boldsymbol{p}} \end{cases}$$

9.2 Matrix Mechanics: State Vector

$$|\psi\rangle = \hat{1} |\psi\rangle = \sum_{n} c_{n} |u_{n}\rangle = \begin{pmatrix} c_{1} \\ c_{2} \\ \vdots \\ c_{n} \\ \vdots \end{pmatrix} = \begin{pmatrix} c_{1} & c_{2} & \cdots & c_{n} & \cdots \end{pmatrix}^{T}$$

$$\hat{A} = \mathbf{I}\hat{A}\mathbf{I} = \left(\sum_{n} |u_{n}\rangle \langle u_{n}|\right) \hat{A} \left(\sum_{m} |u_{m}\rangle \langle u_{m}|\right) = \sum_{n,m} \underbrace{\langle u_{n}|\hat{A}|u_{m}\rangle}_{=A_{nm}} (|u_{n}\rangle \langle u_{m}|) = \begin{pmatrix} A_{nm} \\ \end{pmatrix}$$

9.3 Matrix Mechanics: Hermitian Conjugate

if the operator \hat{A} can be written as a matrix,

$$\langle \psi | \hat{A}^{\dagger} | \phi \rangle = \left(\langle \phi | \hat{A} | \psi \rangle \right)^* \Longrightarrow \hat{A}^{\dagger} = \left(\hat{A}^{\mathrm{T}} \right)^*$$

$$\mathbf{Pf.} \text{ Let } \begin{cases} |\psi\rangle = \sum_{n} c_{n} |u_{n}\rangle \\ |\phi\rangle = \sum_{n} d_{n} |u_{n}\rangle \end{cases},$$

$$\langle \psi | \hat{A}^{\dagger} | \phi \rangle = \left(\sum_{n} c_{n}^{*} \langle u_{n} | \right) \hat{A}^{\dagger} \left(\sum_{m} d_{m} |u_{m}\rangle\right) = \sum_{n,m} c_{n}^{*} d_{m} \langle u_{n} | \hat{A}^{\dagger} |u_{m}\rangle = \sum_{n,m} c_{n}^{*} d_{m} \left(\hat{A}^{\dagger}\right)_{nm}$$

$$\left(\langle \phi | \hat{A} | \psi \rangle\right)^{*} = \left[\left(\sum_{n} d_{n}^{*} \langle u_{n} | \right) \hat{A} \left(\sum_{m} c_{m} |u_{m}\rangle\right)\right]^{*} = \left(\sum_{n,m} d_{n}^{*} c_{m} \langle u_{n} | \hat{A} |u_{m}\rangle\right)^{*}$$

$$= \sum_{n} d_{n} c_{m}^{*} A_{nm}^{*} = \sum_{n} d_{m} c_{n}^{*} A_{mn}^{*} = \sum_{n} c_{n}^{*} d_{n} A_{mn}^{*} \Longrightarrow \left(\hat{A}^{\dagger}\right)_{nm} = \left(\hat{A}\right)_{nm}^{*} = \left(\hat{A}^{T}\right)_{nm}^{*}$$

10 Commutation

10.0.1 Definition

$$\left[\hat{A},\hat{B}\right] = \hat{A}\hat{B} - \hat{B}\hat{A} \tag{1}$$

10.0.2 Compare

$$\begin{cases}
q\text{-number}: \hat{A}\hat{B} \neq \hat{B}\hat{A} & (QM) \\
\text{c-number}: AB = BA & (CM)
\end{cases}$$

$$[A, B]_{PB} = \sum_{\alpha} \left(\frac{\partial A}{\partial q_{\alpha}} \frac{\partial B}{\partial p_{\alpha}} - \frac{\partial A}{\partial p_{\alpha}} \frac{\partial B}{\partial q_{\alpha}} \right)$$
Classical Canonical Commutator
$$(2)$$

10.0.3 Relation

$$[A, B]_{PB} \longleftrightarrow \frac{1}{i\hbar} \left[\hat{A}, \hat{B} \right]$$
 (3)

11 Properties of Commutations

 $[\hat{A}, \hat{B}] \neq 0 \Longrightarrow \text{Uncertainty Relation}$

$$\Delta \hat{A} \cdot \Delta \hat{B} \ge \frac{\left| \langle \left[\hat{A}, \hat{B} \right] \rangle \right|}{2} \tag{4}$$

$$\left[\hat{A}, \hat{B}\right] = 0 \Longrightarrow \underset{\text{Simultaneous}}{\text{Common}} \text{ Eigenstates}$$

1. Linearity

$$\left[a\hat{A}, b\hat{B} + c\hat{C}\right] = ab\left[\hat{A}, \hat{B}\right] + ac\left[\hat{A}, \hat{C}\right]$$
(5)

2. Leibniz rule

$$\begin{cases}
 \left[\hat{A}, \hat{B}\hat{C}\right] = \left[\hat{A}, \hat{B}\right]\hat{C} + \hat{B}\left[\hat{A}, \hat{C}\right] \\
 \left[\hat{A}\hat{B}, \hat{C}\right] = \left[\hat{A}, \hat{C}\right]\hat{B} + \hat{A}\left[\hat{B}, \hat{C}\right]
\end{cases} (6)$$

3. Power related

$$\left[\hat{A}, \hat{B}^n\right] = n\left[\hat{A}, \hat{B}\right] \hat{B}^{n-1} \tag{7}$$

provided that $\left[\hat{B}, \left[\hat{A}, \hat{B}\right]\right] = 0$

Pf.
$$\left[\hat{A}, \hat{B}\right] = 1 \left[\hat{A}, \hat{B}\right] \hat{B}^{1-1} \ (n=1)$$
. Suppose $\left[\hat{A}, \hat{B}^k\right] = k \left[\hat{A}, \hat{B}\right] \hat{B}^{k-1}$, then when $n = k+1$, one has $\left[\hat{A}, \hat{B}^{k+1}\right] = \left[\hat{A}, \hat{B}^k\right] \hat{B} + \hat{B}^k \left[\hat{A}, \hat{B}\right] = (k+1) \left[\hat{A}, \hat{B}\right] \hat{B}^k$ $\Longrightarrow \left[\hat{A}, \hat{B}^n\right] = n \left[\hat{A}, \hat{B}\right] \hat{B}^{n-1}$

4.

$$\left[\hat{A}, f(\hat{B})\right] = \left[\hat{A}, \hat{B}\right] \frac{\partial f}{\partial \hat{B}} \tag{8}$$

provided that $\left[\hat{B}, \left[\hat{A}, \hat{B}\right]\right] = 0$

Pf.
$$[\hat{A}, f(\hat{B})] = [\hat{A}, \sum_{n} \frac{f^{(n)}(0)}{n!} \hat{B}^{n}] = \sum_{n} \frac{f^{(n)}(0)}{n!} [\hat{A}, \hat{B}^{n}] = \sum_{n} \frac{f^{(n)}(0)}{(n-1)!} \hat{B}^{n-1} [\hat{A}, \hat{B}]$$

$$= \sum_{n} \frac{f^{(n)}(0)}{n!} [\hat{A}, \hat{B}] \hat{B}^{n} = [\hat{A}, \hat{B}] \frac{\partial f}{\partial \hat{B}}$$

5. **Jacobi identity** \longrightarrow Lie Algebra

$$[A, [B, C]_{PB}]_{PB} + [B, [C, A]_{PB}]_{PB} + [C, [A, B]_{PB}]_{PB}$$
 (CM) (9)

$$\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) + \mathbf{B} \times (\mathbf{C} \times \mathbf{A}) + \mathbf{C} \times (\mathbf{A} \times \mathbf{B}) = 0$$
 (VA) (10)

$$\mathbf{F}_{\mu\nu,\lambda} + \mathbf{F}_{\nu\lambda,\mu} + \mathbf{F}_{\lambda\mu,\nu} = 0 \quad \text{(CED)}$$

$$\left[\hat{A}, \left[\hat{B}, \hat{C}\right]\right] + \left[\hat{B}, \left[\hat{C}, \hat{A}\right]\right] + \left[\hat{C}, \left[\hat{A}, \hat{B}\right]\right] = 0 \quad (QM) \tag{12}$$

12 Fundamental Commutation Relations

$$\operatorname{CM} \left\{ \begin{bmatrix} x_i, p_j \end{bmatrix}_{\operatorname{PB}} = \delta_{ij} \\ \left[x_i, x_j \right]_{\operatorname{PB}} = \left[p_i, p_j \right]_{\operatorname{PB}} = 0 \right\} \longleftrightarrow \left[\operatorname{QM} \left\{ \begin{bmatrix} \hat{x}_i, \hat{p}_j \end{bmatrix} = i\hbar \delta_{ij} \\ \left[\hat{x}_i, \hat{x}_j \right] = \left[\hat{p}_i, \hat{p}_j \right] = 0 \right] \right\}$$

$$(13)$$

Pf. in
$$\boldsymbol{x}$$
-representation, $\hat{\boldsymbol{x}} = \boldsymbol{x}$, $\hat{\boldsymbol{p}} = -\mathrm{i}\hbar\nabla \Longrightarrow \hat{\boldsymbol{x}} = \boldsymbol{x}$, $\hat{p}_x = -\mathrm{i}\hbar\frac{\partial}{\partial x}$. $\forall \psi(x)$,

$$[\hat{x}, \hat{p}_x]\psi(x) = (\hat{x}\hat{p}_x - \hat{p}_x\hat{x})\,\psi(x) = -\mathrm{i}\hbar\left(x\frac{\partial}{\partial x} - \frac{\partial}{\partial x}x\right)\psi(x) = -\mathrm{i}\hbar\left[x\frac{\partial\psi}{\partial x} - \frac{\partial}{\partial x}(x\psi)\right]$$
$$= \mathrm{i}\hbar\psi(x) \Longrightarrow [\hat{x}, \hat{p}_x] = \mathrm{i}\hbar.$$

Similarly, $[\hat{y}, \hat{p}_y] = [\hat{z}, \hat{p}_z] = i\hbar$. $[\hat{x}_i, \hat{p}_j] = 0, (i \neq j)$.

13 Commutation Relations of Orbital Angular Momentum

$$\hat{\boldsymbol{L}} = \hat{\boldsymbol{x}} \times \hat{\boldsymbol{p}} \iff \hat{L}_i = \varepsilon_{ijk} \hat{x}_j \hat{p}_k \tag{14}$$

$$\Longrightarrow \left[\hat{L}_i, \hat{L}_j \right] = i\hbar \varepsilon_{ijk} \hat{L}_k \iff \hat{L} \times \hat{L} = i\hbar \hat{L}$$
(15)

$$\Longrightarrow \left[\hat{L}_i, \hat{\boldsymbol{L}}^2\right] = 0 \Longrightarrow \left[\hat{L}_z, \hat{\boldsymbol{L}}^2\right] = 0, \ z: \text{ quantum axis}$$
 (16)

$$\begin{cases}
\left[\hat{L}_{i},\hat{x}_{j}\right] = i\hbar\varepsilon_{ijk}\hat{x}_{k} \iff \hat{\boldsymbol{L}} \times \hat{\boldsymbol{x}} + \hat{\boldsymbol{x}} \times \hat{\boldsymbol{L}} = 2i\hbar\hat{\boldsymbol{x}} \\
\left[\hat{L}_{i},\hat{p}_{j}\right] = i\hbar\varepsilon_{ijk}\hat{p}_{k} \iff \hat{\boldsymbol{L}} \times \hat{\boldsymbol{p}} + \hat{\boldsymbol{p}} \times \hat{\boldsymbol{L}} = 2i\hbar\hat{\boldsymbol{p}}
\end{cases} \tag{17}$$

$$\forall \text{ vector } \hat{\boldsymbol{v}}, \ \left[\hat{L}_i, \hat{v}_j\right] = i\hbar \varepsilon_{ijk} \hat{v}_k \iff \hat{\boldsymbol{L}} \times \hat{\boldsymbol{v}} + \hat{\boldsymbol{v}} \times \hat{\boldsymbol{L}} = 2i\hbar \hat{\boldsymbol{v}}$$
(18)

for
$$V(\boldsymbol{x}) = V(r), \ \left[\hat{L}_i, V(r)\right] = 0$$
 (19)

for
$$\hat{T} = \frac{\hat{\boldsymbol{p}}^2}{2m}$$
, $\left[\hat{L}_i, \hat{T}\right] = 0$ (20)

for
$$\hat{H} = \hat{T} + V(r)$$
, $\left[\hat{L}_i, \hat{H}\right] = \left[\hat{\boldsymbol{L}}^2, \hat{H}\right] = 0$ (21)

$$\mathbf{Pf.} \ (\hat{\boldsymbol{L}} \times \hat{\boldsymbol{L}})_{i} = \varepsilon_{ijk} \hat{L}_{j} \hat{L}_{k} = \frac{1}{2} \varepsilon_{ijk} \hat{L}_{j} \hat{L}_{k} - \frac{1}{2} \varepsilon_{ijk} \hat{L}_{k} \hat{L}_{j} = \frac{1}{2} \varepsilon_{ijk} \left[\hat{L}_{j}, \hat{L}_{k} \right]$$

$$= \frac{1}{2} \varepsilon_{ijk} (i\hbar) \varepsilon_{jkl} \hat{L}_{l} = i\hbar \delta_{il} \hat{L}_{l} = i\hbar \hat{L}_{i} \Longrightarrow \hat{\boldsymbol{L}} \times \hat{\boldsymbol{L}} = i\hbar \hat{\boldsymbol{L}}$$

$$\left[\hat{L}_{i}, \hat{L}_{j} \right] = i\hbar \varepsilon_{ijk} \hat{L}_{k} \Longrightarrow \left[\hat{L}_{i}, \hat{\boldsymbol{L}}^{2} \right] = \left[\hat{L}_{i}, \hat{L}_{j} \hat{L}_{j} \right] = \left[\hat{L}_{i}, \hat{L}_{j} \right] \hat{L}_{j} + \hat{L}_{j} \left[\hat{L}_{i}, \hat{L}_{j} \right]$$

$$= i\hbar \varepsilon_{ijk} (\hat{L}_{k} \hat{L}_{j} + \hat{L}_{j} \hat{L}_{k}) = 0$$

$$\left[\hat{L}_i, \hat{x}_j\right] = \left[\varepsilon_{iab}\hat{x}_a\hat{p}_b, \hat{x}_j\right]$$

$$\begin{bmatrix} \hat{L}_i, V(r) \end{bmatrix} = \begin{bmatrix} \hat{L}_i, \hat{x}_j \end{bmatrix} \frac{\partial V}{\partial x_j} = i\hbar \varepsilon_{ijk} \hat{x}_k \frac{dV}{dr} \frac{\hat{x}_j}{r} = \left(\frac{i\hbar}{r} \frac{dV}{dr} \right) \varepsilon_{ijk} \hat{x}_k \hat{x}_j = 0$$

$$\begin{bmatrix} \hat{L}_i, \hat{\boldsymbol{p}}^2 \end{bmatrix} = \begin{bmatrix} \hat{L}_i, \hat{p}_j \hat{p}_j \end{bmatrix} = \begin{bmatrix} \hat{L}_i, \hat{p}_j \end{bmatrix} \hat{p}_j + \hat{p}_j \begin{bmatrix} \hat{L}_i, \hat{p}_j \end{bmatrix} = i\hbar \varepsilon_{ijk} (\hat{p}_k \hat{p}_j + \hat{p}_j \hat{p}_k) = 0$$

14 Eigenvalue Problem

15 Observables

1. Position (canonical)

$$\hat{\boldsymbol{x}} = \begin{cases} \boldsymbol{x} & \boldsymbol{x}\text{-representation} \\ +i\hbar \frac{\partial}{\partial \boldsymbol{p}} & \boldsymbol{p}\text{-representation} \end{cases}$$
 (22)

2. Momentum (canonical)

$$\hat{\boldsymbol{p}} = \begin{cases} -i\hbar \frac{\partial}{\partial \boldsymbol{x}} & \boldsymbol{x}\text{-representation} \\ \boldsymbol{p} & \boldsymbol{p}\text{-representation} \end{cases}$$
(23)

Fundamental Commutation Relation $\begin{cases} [\hat{x}_i, \hat{p}_j] = i\hbar \delta_{ij} \\ [\hat{x}_i, \hat{x}_j] = [\hat{p}_i, \hat{p}_j] = 0 \end{cases}$

3. Orbital Angular Momentum

$$\hat{\boldsymbol{L}} = \hat{\boldsymbol{x}} \times \hat{\boldsymbol{p}} \text{ or } \hat{L}_i = \varepsilon_{ijk} \hat{x}_j \hat{p}_k$$

Commutation Relations $\left[\hat{L}_i, \hat{L}_j\right] = i\hbar \varepsilon_{ijk} \hat{L}_k \Longrightarrow \left[\hat{L}_i, \hat{L}^2\right]$

Remark $\hat{\boldsymbol{L}} \times \hat{\boldsymbol{L}} \neq 0$, but $\hat{\boldsymbol{x}} \times \hat{\boldsymbol{p}} = -\hat{\boldsymbol{p}} \times \hat{\boldsymbol{x}}$

4. Intrinsic Angular Momentum (No classical correspondence) - SPIN

$$\begin{bmatrix} \hat{S}_i, \hat{S}_j \end{bmatrix} = i\hbar \varepsilon_{ijk} \hat{S}_k \iff \hat{S} \times \hat{S} = i\hbar \hat{S}$$
$$\begin{bmatrix} \hat{L}_i, \hat{S}_j \end{bmatrix} = 0$$

5. Hamiltonian

$$\hat{H} = \hat{T} + \hat{V} = \frac{\hat{p}^2}{2m} + \hat{V}(x)$$

$$\begin{cases} \hat{T} : & \hat{p}\text{-dependent only} \\ \hat{V} : & \hat{x}\text{-dependent only} \end{cases}$$

6. Energy

$$\begin{cases} \hat{E} = i\hbar \frac{\partial}{\partial t} & \text{wavefuncitons} \\ \hat{E} = i\hbar \frac{d}{dt} & \text{state vector} \end{cases}$$

Remark In non-relativistic QM, time t is NOT observable.

16 Eigenvalue & Eigenstates

1. Position

$$\hat{m{x}} | m{x'}
angle = m{x'} | m{x'}
angle$$
 eigenvalue eq. $\left\{ \langle m{x'} | m{x''}
angle = \delta(m{x'} - m{x''}) \quad (ON) \right\}$ $\left\{ \int \mathrm{d}^3 x | m{x}
angle \langle m{x} | = \hat{1} \quad (RI) \right\}$ $\left\langle m{x} | \hat{m{x}} | m{x'}
angle = m{x'} \delta(m{x} - m{x'}) \right\}$

In \hat{x} -representation, wavefunction of $|x\rangle$ is $\langle x'|x\rangle = \delta(x-x')$, and eigenvalue eq. is

$$\hat{\boldsymbol{x}} \delta(\boldsymbol{x} - \boldsymbol{x}') = \boldsymbol{x}' \delta(\boldsymbol{x} - \boldsymbol{x}')$$

2. Momentum

$$\hat{p} | p'
angle = p' | p'
angle$$

$$\begin{cases} \langle p' | p''
angle = \delta(p' - p'') & (ON) \\ \int | p
angle \langle p | dp = I & (RI) \end{cases}$$

In \hat{p} -representation, wavefunction of $|p\rangle$ is $\langle p'|p\rangle = \delta(p-p')$, and eigenvalue eq. is

$$\hat{\boldsymbol{p}}\,\delta(\boldsymbol{p}-\boldsymbol{p}')=\boldsymbol{p}'\delta(\boldsymbol{p}-\boldsymbol{p}')$$

Remark eigenspectrum: set of eigenvalues of observable

3. Relation

$$\psi(\boldsymbol{x}) = \psi_{\boldsymbol{p}}(\boldsymbol{x})\tilde{\psi}(\boldsymbol{p}), \quad \psi_{\boldsymbol{p}}(\boldsymbol{x}) = \langle \boldsymbol{x}|\boldsymbol{p}\rangle$$

$$|\psi\rangle = \hat{I} |\psi\rangle = \begin{cases} \int d\mathbf{x} |\mathbf{x}\rangle \langle \mathbf{x}|\psi\rangle = \int d\mathbf{x} |\mathbf{x}\rangle \psi(\mathbf{x}) \\ \int d\mathbf{p} |\mathbf{p}\rangle \langle \mathbf{p}|\psi\rangle = \int d\mathbf{p} |\mathbf{p}\rangle \tilde{\psi}(\mathbf{p}) \end{cases} = \begin{cases} \psi(\mathbf{x}) & \hat{\mathbf{x}}\text{-representation} \\ \tilde{\psi}(\mathbf{p}) & \hat{\mathbf{p}}\text{-representation} \end{cases}$$
$$|\psi\rangle = \int d\mathbf{p} |\mathbf{p}\rangle \tilde{\psi}(\mathbf{p}) = \int d\mathbf{x} |\mathbf{x}\rangle \left(\langle \mathbf{x}|\mathbf{p}\rangle \tilde{\psi}(\mathbf{p})\right) = \int d\mathbf{x} |\mathbf{x}\rangle \psi(\mathbf{x})$$
$$\implies \psi(\mathbf{x}) = \langle \mathbf{x}|\mathbf{p}\rangle \tilde{\psi}(\mathbf{p}) = \psi_{\mathbf{p}}(\mathbf{x})\tilde{\psi}(\mathbf{p})$$

$$\hat{\boldsymbol{p}} | \boldsymbol{p} \rangle = \boldsymbol{p} | \boldsymbol{p} \rangle \Longrightarrow \int d\boldsymbol{x} | \boldsymbol{x} \rangle \langle \boldsymbol{x} | \hat{\boldsymbol{p}} | \boldsymbol{p} \rangle = \boldsymbol{p} \int d\boldsymbol{x} | \boldsymbol{x} \rangle \langle \boldsymbol{x} | \boldsymbol{p} \rangle \quad (\hat{\boldsymbol{p}} = -i\hbar \frac{\partial}{\partial \boldsymbol{x}})$$

$$\Longrightarrow -i\hbar \frac{\partial}{\partial \boldsymbol{x}} \psi_{\boldsymbol{p}}(\boldsymbol{x}) = \boldsymbol{p} \psi_{\boldsymbol{p}}(\boldsymbol{x})$$

$$-i\hbar \frac{d}{dx} \psi_{\boldsymbol{p}}(\boldsymbol{x}) = p \psi_{\boldsymbol{p}}(\boldsymbol{x}) \Longrightarrow \psi_{\boldsymbol{p}}(\boldsymbol{x}) = N \exp\left(\frac{i}{\hbar} \boldsymbol{p} \boldsymbol{x}\right) \Longrightarrow \psi_{\boldsymbol{p}}(\boldsymbol{x}) = N \exp\left(\frac{i}{\hbar} \boldsymbol{p} \cdot \boldsymbol{x}\right)$$

17 Spin and Pauli Matrices

17.1 Stern-Gerlach Experiment

17.1.1 Meanings

- 1. Quantization of Spatial Orientation of Angular Momentum
- 2. Intrinsic Angular Momentum (Spin)
- 3. S-G experiment \longrightarrow Rabi oscillation \longrightarrow Ramsey (atom clock, Hydrogen maser) \longrightarrow Quantum measurement

17.1.2 Analysis

- 1. (Silver) neutral atom beam \Longrightarrow no Lorentz force
- 2. Magnetic field is inhomogeneous

$$\mathbf{F} = -\nabla W_{\rm m} = \boldsymbol{\mu} \cdot \nabla \mathbf{B} \tag{24}$$

$$W_{\rm m} = -\boldsymbol{\mu} \cdot \boldsymbol{B} \tag{25}$$

 μ : magnetic dipole moment

- 3. Deflection: two values $\begin{cases} up & 50\% \\ dowm & 50\% \end{cases}$
- 4. furnace: low-temperature $\longrightarrow v$ is small $\longrightarrow p$ is small $\longrightarrow L$ is small $\xrightarrow{\mu_L \propto L} \mu_L$ is small \Longrightarrow Intrinsic freedom?

17.1.3 History

1921-1922 Stern, Gerlach - S-G experiment

1924 Pauli - Two-valuedness not described classically \longrightarrow Pauli exclusion principle

1925 Kronig - Self-rotation of electron (unpublished)

1925 Uhlenbeck, Gordsmit - Self-rotation

1927 Pauli - Pauli matrices, Pauli equation (wavefunction is a spinor with 2-component)

1928 Dirac - Relativistic QM, Dirac equation (4-component spinor)

17.1.4 Cascaded S-G Experiment

$$\operatorname{Ag} \xrightarrow{\uparrow B} \mu_z \to \begin{cases} +\mu_{\mathrm{B}} \text{ up } 50\% \\ -\mu_{\mathrm{B}} \text{ down } 50\% \end{cases} \quad \mu_{\mathrm{B}} = \frac{e\hbar}{2mc} \quad \text{(Bohr magneton)}$$

$$\operatorname{Ag} \longrightarrow \mu_x \to \begin{cases} |\mu_{x,+}\rangle \to \mu_z \to \begin{cases} +\mu_{\mathrm{B}} 50\% \\ -\mu_{\mathrm{B}} 50\% \end{cases}$$

$$|\mu_{x,-}\rangle \to |$$

18 Spin Angular Momentum

18.0.1 Significance

- 1. Spin is an Intrinsic Angular Momentum
- 2. Spin is a signiture to distinguish two families

(a)
$$\begin{cases} s = 0, 1, 2, \cdots \text{ (integer)} & \text{Bosons} \\ s = \frac{1}{2}, \frac{3}{2}, \cdots \text{ (half-integer)} & \text{Fermion} \end{cases}$$

(b) Boson
$$\begin{cases} \text{Statistics: Bose-Einstein statistics} \\ \text{Permutation: } \psi_{S}(\cdots, x_{i}, \cdots, x_{j}, \cdots) = \psi_{S}(\cdots, x_{j}, \cdots, x_{i}, \cdots) \\ \text{unchanged} \end{cases}$$

(c) Fermion
$$\begin{cases} \text{Statistics: Fermi-Dirac statistics} \\ \text{Permutation: } \psi_{\mathbf{A}}(\cdots, x_{i}, \cdots, x_{j}, \cdots) = -\psi_{\mathbf{A}}(\cdots, x_{j}, \cdots, x_{i}, \cdots) \\ \text{opposite sign} \end{cases}$$

(d) Quantum Statistics
$$\begin{cases} \text{Bose-Einstein} \\ \text{Fermi-Dirac} \end{cases} \xrightarrow{\hbar \to 0} \text{Maxwell-Boltzmann statistics}$$

$$\left[\hat{S}_{i}, \hat{S}_{j}\right] = i\hbar \varepsilon_{ijk} \hat{S}_{k} \iff \hat{\boldsymbol{S}} \times \hat{\boldsymbol{S}} = i\hbar \hat{\boldsymbol{S}}$$
(26)

$$\Longrightarrow \left[\hat{\boldsymbol{S}}^{2}, \hat{S}_{i}\right] = 0 \Longrightarrow \begin{cases} \hat{\boldsymbol{S}}^{2} \left|s, m_{s}\right\rangle = \hbar^{2} s(s+1) \left|s, m_{s}\right\rangle \\ \hat{S}_{z} \left|s, m_{s}\right\rangle = \hbar m_{s} \left|s, m_{s}\right\rangle \end{cases} \quad \text{common eigenstates: } \left|s, m_{s}\right\rangle$$

Dirac eq.
$$\longleftrightarrow s = \frac{1}{2}$$
 (electron & positron, proton, neutron, \cdots) (27)

$$\left| s = \frac{1}{2}, m_s = +\frac{1}{2} \right\rangle = \left| + \right\rangle = \left| \uparrow \right\rangle = \left| 0 \right\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 (28)

$$\left| s = \frac{1}{2}, m_s = -\frac{1}{2} \right\rangle = \left| - \right\rangle = \left| \downarrow \right\rangle = \left| 1 \right\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \tag{29}$$

$$\begin{cases} |0\rangle \langle 0| + |1\rangle \langle 1| = \mathbf{I} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ \langle 0|0\rangle = \langle 1|1\rangle = 1; \ \langle 1|0\rangle = \langle 0|1\rangle = 0 \end{cases}$$

$$\implies \text{In } \hat{S}_z\text{-representation } \begin{cases} \hat{S}_z |0\rangle = +\frac{\hbar}{2} |0\rangle \\ \hat{S}_z |1\rangle = -\frac{\hbar}{2} |0\rangle \end{cases} \implies \hat{\mathbf{S}} = \frac{\hbar}{2} \hat{\boldsymbol{\sigma}} \implies \begin{cases} \hat{\boldsymbol{\sigma}}_z |0\rangle = |0\rangle \\ \hat{\boldsymbol{\sigma}}_z |1\rangle = -|1\rangle \end{cases}$$

$$\implies \hat{m{\sigma}}_z = \ket{0}\bra{0} - \ket{1}\bra{1} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\hat{\boldsymbol{S}}^2 = \frac{3}{4}\hbar^2 \boldsymbol{I} \Longrightarrow \hat{\boldsymbol{\sigma}}^2 = 3\boldsymbol{I} \Longrightarrow [\hat{\boldsymbol{\sigma}}_i, \hat{\boldsymbol{\sigma}}_j] = 2\mathrm{i}\varepsilon_{ijk}\hat{\boldsymbol{\sigma}}_k$$

19 Algebraic Method to Eigenvalue Problem of Angular Momentum

20 Review

Fundamental Commutations

$$[\hat{x}_i, \hat{p}_j] = i\hbar \delta_{ij} \quad [\hat{x}_i, \hat{x}_j] = [\hat{p}_i, \hat{p}_j] = 0$$
 (30)

20.1 Orbital Angular Momentum

20.1.1 Definition of Orbital AM

$$\hat{\boldsymbol{L}} = \hat{\boldsymbol{x}} \times \hat{\boldsymbol{p}} \quad \text{or} \quad \hat{L}_i = \varepsilon_{ijk} \hat{x}_i \hat{p}_k$$
 (31)

20.1.2 Commutation Relations of Orbital AM

$$\left[\hat{L}_{i},\hat{L}_{j}\right] = i\hbar\varepsilon_{ijk}\hat{L}_{k} \iff \hat{\boldsymbol{L}} \times \hat{\boldsymbol{L}} = i\hbar\hat{\boldsymbol{L}}$$
(32)

$$\left[\hat{L}^2, \hat{L}_i\right] = 0 \Longrightarrow \text{Common Eigenstates}$$
 (33)

20.1.3 Eigenvalue Equation

$$\begin{cases} \hat{\mathbf{L}}^2 | l, m_l \rangle = \hbar^2 l(l+1) | l, m_l \rangle \\ \hat{L}_z | l, m_l \rangle = \hbar m_l | l, m_l \rangle \end{cases} \qquad m_l = \underbrace{-l, -l+1, \cdots, l-1, l}_{2l+1}$$
 (34)

20.2 Intrinsic Angular Momentum (Spin)

Generalize to Intrinsic AM (Spin):

$$\left[\hat{S}_{i}, \hat{S}_{j}\right] = i\hbar \varepsilon_{ijk} \hat{S}_{k} \iff \hat{\boldsymbol{S}} \times \hat{\boldsymbol{S}} = i\hbar \hat{\boldsymbol{S}}$$
(35)

$$\left[\hat{S}^2, \hat{S}_i\right] = 0 \Longrightarrow \text{Common Eigenstates}$$
 (36)

20.2.1 Eigenvalue Equation

$$\begin{cases} \hat{\mathbf{S}}^2 | s, m_s \rangle = \hbar^2 s(s+1) | s, m_s \rangle \\ \hat{S}_z | s, m_s \rangle = \hbar m_s | s, m_s \rangle \end{cases} \qquad m_s = \underbrace{-s, -s+1, \cdots, s-1, s}_{2s+1}$$

$$(37)$$

$$s = \frac{1}{2} \Longrightarrow |s, m_s\rangle = \begin{cases} |+\rangle = |0\rangle = \begin{pmatrix} 1 & 0 \end{pmatrix}^{\mathrm{T}} \\ |-\rangle = |1\rangle = \begin{pmatrix} 0 & 1 \end{pmatrix}^{\mathrm{T}} \end{cases}$$
(38)

20.3 Pauli Matrix

$$\hat{\mathbf{S}} = \frac{\hbar}{2}\hat{\boldsymbol{\sigma}} \tag{39}$$

$$\begin{cases} \hat{\mathbf{S}}^2 = \frac{3}{4}\hbar\hat{1}_2 \Longrightarrow \hat{\boldsymbol{\sigma}}^2 = 3\hat{1}_2 \\ \hat{S}_z^2 = \frac{1}{4}\hbar\hat{1}_2 \Longrightarrow \hat{\sigma}_z^2 = \hat{1}_2 \end{cases}$$

$$(40)$$

Cascaded SGE
$$\Longrightarrow$$

$$\begin{cases} |\mu_x, +\rangle = c_1 |0\rangle + c_2 |1\rangle \\ |c_1|^2 = |c_2|^2 = \frac{1}{2} \end{cases} \Longrightarrow \hat{\sigma_x}^2 = \hat{\sigma_y}^2 = \hat{1}_2$$

$$\hat{\sigma}_i = \hat{1}_2 \tag{41}$$

$$\{\hat{\sigma}_1, \hat{\sigma}_i\} = 2\delta_{ij}\hat{1}_2 \tag{42}$$

$$[\hat{\sigma}_i, \hat{\sigma}_j] = 2i\varepsilon_{ijk}\hat{\sigma}_k \tag{43}$$

$$\hat{\sigma}_i \hat{\sigma}_j = \delta_{ij} \hat{1}_2 + i \varepsilon_{ijk} \hat{\sigma}_k \tag{44}$$

$$\operatorname{tr}(\hat{\sigma}_i) = 0 \quad \operatorname{tr}(\hat{\sigma}_i \hat{\sigma}_j) = 2\delta_{ij} \tag{45}$$

$$\hat{S}_{\pm} = \hat{S}_x \pm i\hat{S}_y = \frac{\hbar}{2} \left(\hat{\sigma}_x \pm i\hat{\sigma}_y \right) = \hbar \hat{\sigma}_{\pm}$$
 (46)

$$\begin{cases} \hat{\sigma}_x = \hat{\sigma}_+ + \hat{\sigma}_- \\ \hat{\sigma}_y = -\mathrm{i}(\hat{\sigma}_+ - \hat{\sigma}_-) \end{cases}$$

$$(47)$$

20.3.1 Ladder / Raising & Lowering / Transition Operator

$$\hat{\sigma}_{+} = |0\rangle \langle 1| \quad \& \quad \hat{\sigma}_{-} = |1\rangle \langle 0|$$
 (48)

20.3.2 Pauli Matrices ($S_z(\sigma_z)$ -representation)

$$\hat{\sigma}_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \hat{\sigma}_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \hat{\sigma}_x = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \tag{49}$$

21 Arbitrary Angular Momentum

$$\hat{\boldsymbol{J}} = \hat{\boldsymbol{L}} + \hat{\boldsymbol{S}} \tag{50}$$

$$\left[\hat{J}_i, \hat{J}_j\right] = i\hbar \varepsilon_{ijk} \hat{J}_k \tag{51}$$

OAM & Spin are in DIFFERENT State Vector Spaces:

$$\left[\hat{L}_i, \hat{S}_j\right] \equiv 0 \tag{52}$$

$$\left[\hat{J}_{i},\hat{J}_{j}\right] = \left[\hat{L}_{i} + \hat{S}_{i},\hat{L}_{j} + \hat{S}_{j}\right] = \left[\hat{L}_{i},\hat{L}_{j}\right] + \left[\hat{S}_{i},\hat{S}_{j}\right] = i\hbar\varepsilon_{ijk}(\hat{L}_{k} + \hat{S}_{k}) = i\hbar\varepsilon_{ijk}\hat{J}_{k}$$

21.1 Ladder Operator

21.1.1 Definition of Ladder Operators

$$\hat{J}_{\pm} = \hat{J}_x \pm i\hat{J}_y \tag{53}$$

$$\begin{bmatrix} \hat{J}_i, \hat{\boldsymbol{J}}^2 \end{bmatrix} = 0 \Longrightarrow \begin{cases} \hat{\boldsymbol{J}}^2 |j, m_j\rangle = \hbar j(j+1) |j, m_j\rangle \\ \hat{J}_z |j, m_j\rangle = \hbar m_j |j, m_j\rangle \end{cases} \qquad j \ge 0, \quad m_j = \underbrace{-j, -j+1, \cdots, j-1, j}_{(2j+1)\text{-fold (degeneracy)}} \tag{54}$$

 $\begin{cases} j: \text{ azimuthal quantum number} \\ m_j: \text{ magnetic quantum number} \end{cases}$

21.1.2 Effect of Ladder Operators on Common Eigenstates

$$\hat{J}_{\pm} |j, m_j\rangle = \hbar \sqrt{j(j+1) - m_j(m_j \pm 1)} |j, m_j \pm 1\rangle$$
 (55)

21.1.3 Restriction

$$\hat{J}_{+}|j,j\rangle = \hat{J}_{-}|j,-j\rangle = 0$$
 (56)

21.1.4 Commutations

1.
$$\left[\hat{J}_i, \hat{J}_j\right] = i\hbar \varepsilon_{ijk} \hat{J}_k$$

$$2. \left[\hat{\boldsymbol{J}}^2, \hat{J}_i \right] = 0$$

$$3. \left[\hat{\boldsymbol{J}}^2, \hat{J}_{\pm} \right] = 0$$

4.
$$\left[\hat{J}_z, \hat{J}_{\pm}\right] = \pm \hbar \hat{J}_{\pm}$$

$$\left[\hat{J}_z, \hat{J}_{\pm}\right] = \left[\hat{J}_z, \hat{J}_x \pm i\hat{J}_y\right] = \left[\hat{J}_z, \hat{J}_x\right] \pm i\left[\hat{J}_z, \hat{J}_y\right] = i\hbar\hat{J}_y \pm i(-i\hbar)\hat{J}_x = \pm\hbar\hat{J}_{\pm}$$

5.
$$\hat{J}_{+}\hat{J}_{-} = \hat{J}^{2} - \hat{J}_{z}^{2} + \hbar \hat{J}_{z}$$

$$\hat{J}_{+}\hat{J}_{-} = (\hat{J}_{x} + i\hat{J}_{y})(\hat{J}_{x} - i\hat{J}_{y}) = \hat{J}_{x}^{2} + \hat{J}_{y}^{2} - i\left[\hat{J}_{x}, \hat{J}_{y}\right] = \hat{\boldsymbol{J}}^{2} - \hat{J}_{z}^{2} + \hbar\hat{J}_{z}$$

6.
$$(\hat{J}_{\pm})^{\dagger} = \hat{J}_{\mp}$$

 \hat{J}_{\pm} are NOT Hermitian Operators, but \hat{J}_{+} & \hat{J}_{-} are mutually Hermitian Conjugates.

21.2 Eigenvalue Equation of Angular Momentum Operator

$$\begin{cases} \hat{J}^2 | \lambda, m \rangle = \hbar^2 \lambda | \lambda, m \rangle \\ \hat{J}_z | \lambda, m \rangle = \hbar m | \lambda, m \rangle \end{cases}$$
 (57)

$$\left[\hat{\boldsymbol{J}}^{2}, \hat{J}_{\pm}\right] = 0 \Longrightarrow \hat{J}_{\pm}\hat{\boldsymbol{J}}^{2} |\lambda, m\rangle = \hat{\boldsymbol{J}}^{2} \hat{J}_{\pm} |\lambda, m\rangle \Longrightarrow \lambda \hbar^{2} (\hat{J}_{\pm} |\lambda, m\rangle) = \hat{\boldsymbol{J}}^{2} (\hat{J}_{\pm} |\lambda, m\rangle) \quad (58)$$

$$\left[\hat{J}_{\pm}, \hat{J}_{z}\right] = \pm \hbar \hat{J}_{\pm} \Longrightarrow \hat{J}_{z} \hat{J}_{\pm} = \hat{J}_{\pm} \hat{J}_{z} \pm \hbar \hat{J}_{\pm}$$

$$\implies \hat{J}_z \left(\hat{J}_{\pm} | \lambda, m \rangle \right) = (\hat{J}_{\pm} \hat{J}_z \pm \hbar \hat{J}_{\pm}) | \lambda, m \rangle = m \hbar \hat{J}_{\pm} | \lambda, m \rangle \pm \hbar \hat{J}_{\pm} | \lambda, m \rangle$$

$$= (m \pm 1) \hbar \left(\hat{J}_{\pm} | \lambda, m \rangle \right)$$
(59)

 $\implies \hat{J}_{\pm} | \lambda, m \rangle$ is an eigenstate of \hat{J}_z , with eigenvalue of $(m \pm 1)\hbar$.

$$\Longrightarrow \hat{J}_{\pm} |\lambda, m\rangle = C_{\pm} |\lambda, m \pm 1\rangle \tag{60}$$

$$\Longrightarrow \hat{J}_{+}^{n} |\lambda, m\rangle = D_{\pm} |\lambda, m \pm n\rangle \tag{61}$$

$$\begin{cases} \langle \hat{J}^2 \rangle = \langle \lambda, m | \hat{J}^2 | \lambda, m \rangle = \lambda \hbar^2 \\ \langle \hat{J}_z^2 \rangle = \langle \lambda, m | \hat{J}_z^2 | \lambda, m \rangle = m^2 \hbar^2 \end{cases}$$
(62)

$$\langle \hat{J}^2 \rangle \ge \langle \hat{J}_z \rangle \Longrightarrow \lambda \ge m^2 \ge 0$$
 (63)

 $\exists m_0 \text{ (minimal)}, \exists N \text{ (integer)}, m_0 + N \text{ is the maximal}$

$$\hat{J}_{-}|\lambda, m_0\rangle = 0 \quad \hat{J}_{+}|\lambda, m_0 + N\rangle = 0 \tag{64}$$

$$0 = \hat{J}_{+}\hat{J}_{-}|\lambda, m_{0}\rangle = (\hat{J}^{2} - \hat{J}_{z}^{2} + \hbar\hat{J}_{z})|\lambda, m_{0}\rangle = \hbar^{2}(\lambda - m_{0}^{2} + m_{0})$$
(65)

$$0 = \hat{J}_{-}\hat{J}_{+} |\lambda, m_{0} + N\rangle = (\hat{\mathbf{J}}^{2} - \hat{J}_{z}^{2} - \hbar \hat{J}_{z}) |\lambda, m_{0} + N\rangle = \hbar^{2} [\lambda - (m_{0} + N)^{2} - (m_{0} + N)]$$
(66)

$$\begin{cases} \lambda - m_0^2 + m_0 = 0 \\ \lambda - (m_0 + N)^2 - (m_0 + N) = 0 \end{cases} \implies \begin{cases} m_0 = -\frac{N}{2} \\ m_0 + N = \frac{N}{2} \\ \lambda = -\frac{N}{2} \left(\frac{N}{2} + 1\right) \end{cases}$$
 (67)

let
$$j = \frac{N}{2}$$
, $\lambda = j(j+1)$, $m_j = \underbrace{-j, -j+1, \cdots, j-1, j}_{2j+1}$

$$\Longrightarrow \begin{cases} \hat{\mathbf{J}}^2 |j, m_j\rangle = j(j+1)\hbar^2 |j, m_j\rangle \\ \hat{J}_z |j, m_j\rangle = m_j\hbar |j, m_j\rangle \end{cases}$$
(68)

$$\hat{J}_{\pm} |j, m_j\rangle = C_{\pm} |j, m_j \pm 1\rangle \tag{69}$$

$$\langle j, m_j | j', m_{j'} \rangle = \delta_{jj'} \delta_{m_j m_{j'}} \quad (\hat{J}_{\pm})^{\dagger} = \hat{J}_{\mp}$$
 (70)

$$\Longrightarrow 1 = \langle j, m_j \pm 1 | j, m_j \pm 1 \rangle = \langle j, m_j | \hat{J}_{\mp} \hat{J}_{\pm} | j, m_j \rangle = |C_{\pm}|^2 \langle j, m_j | j, m_j \rangle \tag{71}$$

$$\hat{J}_{\pm}\hat{J}_{\pm} = (\hat{J}_x \mp i\hat{J}_y)(\hat{J}_x \pm i\hat{J}_y) = \hat{J}_x^2 + \hat{J}_y^2 \pm i\left[\hat{J}_x, \hat{J}_y\right] = \hat{J}^2 - \hat{J}_z^2 \mp \hbar\hat{J}_z$$
 (72)

$$\Longrightarrow \langle j, m_j | \hat{J}_{\pm} \hat{J}_{\pm} | j, m_j \rangle = \langle j, m_j | (\hat{J}^2 - \hat{J}_z^2 \mp \hbar \hat{J}_z) | j, m_j \rangle$$

$$= \hbar^2 [j(j+1) - m_j^2 \mp m_j] \langle j, m_j | j, m_j \rangle = |C_{\pm}|^2 \langle j, m_j | j, m_j \rangle$$

$$\Longrightarrow |C_{\pm}|^2 = [j(j+1) - m_j(m_j \pm 1)] \hbar^2$$
(73)

for simplicity, let $C_{\pm} \in \mathbb{R}$

$$\Longrightarrow C_{\pm} = \hbar \sqrt{j(j+1) - m_j(m_j \pm 1)} \tag{74}$$

$$\Longrightarrow \left| \hat{J}_{\pm} \left| j, m_j \right\rangle = \hbar \sqrt{j(j+1) - m_j(m_j \pm 1)} \left| j, m_j \pm 1 \right\rangle \right| \tag{75}$$

22 Commutation Relations between Angular Momentum Operators and Hamiltonian

$$\hat{H} = \frac{\hat{\boldsymbol{p}}^2}{2m} + V(r) + \xi(r)\hat{\boldsymbol{L}} \cdot \hat{\boldsymbol{S}}$$
(76)

V(r): central potential, $\xi(r)\hat{\boldsymbol{L}}\cdot\hat{\boldsymbol{S}}$: $\hat{\boldsymbol{L}}$ - $\hat{\boldsymbol{S}}$ coupling \longleftrightarrow fine structure

$$\left[\hat{L}_{i},\hat{p}_{j}\right] = i\hbar\varepsilon_{ijk}\hat{p}_{k} \Longrightarrow \left[\hat{L}_{i},\hat{\boldsymbol{p}}^{2}\right] = \left[\hat{L}_{i},\hat{p}_{j}\right]\hat{p}_{j} + \hat{p}_{j}\left[\hat{L}_{i},\hat{p}_{j}\right] = i\hbar\varepsilon_{ijk}(\hat{p}_{k}\hat{p}_{j} + \hat{p}_{j}\hat{p}_{k}) = 0 \quad (77)$$

$$\left[\hat{S}_i, \hat{\boldsymbol{p}}^2\right] = 0 \Longrightarrow \left[\hat{J}_i, \hat{\boldsymbol{p}}^2\right] = 0 \tag{78}$$

$$\left[\hat{L}_i, V(r)\right] = 0 \quad \& \quad \left[\hat{S}_i, V(r)\right] = 0 \Longrightarrow \quad \left[\hat{J}_i, V(r)\right] = 0 \tag{79}$$

$$\left[\hat{L}_i, \hat{\boldsymbol{L}} \cdot \hat{\boldsymbol{S}}\right] = \left[\hat{L}_i, \hat{L}_j \hat{S}_j\right] = i\hbar \varepsilon_{ijk} \hat{L}_k \hat{S}_j \neq 0$$
(80)

$$\left[\hat{\boldsymbol{L}}^{2},\hat{\boldsymbol{L}}\cdot\hat{\boldsymbol{S}}\right] = \left[\hat{L}_{i}\hat{L}_{i},\hat{L}_{j}\hat{S}_{j}\right] = \left[\hat{L}_{i},\hat{L}_{j}\right]\hat{L}_{i}\hat{S}_{j} + \hat{L}_{i}\left[\hat{L}_{i},\hat{L}_{j}\right]\hat{S}_{j} = i\hbar\varepsilon_{ijk}(\hat{L}_{k}\hat{L}_{i} + \hat{L}_{i}\hat{L}_{k}) = 0 \quad (81)$$

similarly,
$$\left[\hat{S}_i, \hat{\boldsymbol{L}} \cdot \hat{\boldsymbol{S}}\right] \neq 0$$
, but $\left[\hat{\boldsymbol{S}}^2, \hat{\boldsymbol{L}} \cdot \hat{\boldsymbol{S}}\right] = 0$. futher, $\left[\hat{J}_i, \hat{\boldsymbol{L}} \cdot \hat{\boldsymbol{S}}\right] = 0$, $\left[\hat{\boldsymbol{J}}^2, \hat{\boldsymbol{L}} \cdot \hat{\boldsymbol{S}}\right] = 0$.

$$\hat{\boldsymbol{L}}^2, \hat{\boldsymbol{S}}^2, \hat{\boldsymbol{J}}^2, \hat{J}_i$$
 commutes with $\hat{H} = \frac{\hat{\boldsymbol{p}}^2}{2m} + V(r) + \xi(r)\hat{\boldsymbol{L}} \cdot \hat{\boldsymbol{S}}$

23 Addition of Angular Momenta

assume $\hat{\boldsymbol{J}}_1,\,\hat{\boldsymbol{J}}_2,\,\hat{\boldsymbol{J}}=\hat{\boldsymbol{J}}_1+\hat{\boldsymbol{J}}_2,$ and Commutation Relations:

$$\left[\hat{J}_{\alpha i}, \hat{J}_{\beta j}\right] = i\hbar \delta_{\alpha \beta} \varepsilon_{ijk} \hat{J}_{\alpha k} \quad (\alpha, \beta = 1, 2)$$
(82)

$$\left[\hat{\boldsymbol{J}}_{\alpha}^{2}, \hat{J}_{\alpha i}\right] \quad (\alpha = 1, 2) \tag{83}$$

Eigenvalue Equations:

$$\begin{cases} \hat{J}_{1}^{2} | j_{1}, m_{1} \rangle = j_{1}(j_{1} + 1)\hbar^{2} | j_{1}, m_{1} \rangle \\ \hat{J}_{1z} | j_{1}, m_{1} \rangle = m_{1}\hbar | j_{1}, m_{1} \rangle \end{cases}$$
(84)

$$\begin{cases} \hat{J}_{2}^{2} | j_{2}, m_{2} \rangle = j_{2}(j_{2} + 1)\hbar^{2} | j_{2}, m_{2} \rangle \\ \hat{J}_{2z} | j_{2}, m_{2} \rangle = m_{2}\hbar | j_{2}, m_{2} \rangle \end{cases}$$
(85)

$$\left[\hat{J}_i, \hat{J}_j\right] = i\hbar \varepsilon_{ijk} \hat{J}_k \tag{86}$$

Uncertainty Principle 24

24.1Heisenberg Uncertainty Principle

 $\forall |\psi\rangle$,

$$\Delta \hat{x}^2 \cdot \Delta \hat{p}^2 \ge \frac{\hbar^2}{4}$$
 or $\Delta \hat{x} \cdot \Delta \hat{p} \ge \frac{\hbar}{2}$ (87)

Generalized Uncertainty Principle 24.2

 $\forall |\psi\rangle$, if $[\hat{A}, \hat{B}] \neq 0$, then

$$\Delta \hat{A}^2 \cdot \Delta \hat{B}^2 \ge \frac{\left| \langle \left[\hat{A}, \hat{B} \right] \rangle \right|^2}{4} \quad \text{or} \quad \Delta \hat{A} \cdot \Delta \hat{B} \ge \frac{\left| \langle \left[\hat{A}, \hat{B} \right] \rangle \right|}{2}$$
 (88)

Variance:

$$\Delta \hat{A}^2 = \langle (\hat{A} - \langle \hat{A} \rangle)^2 \rangle = \langle \hat{A}^2 \rangle - \langle \hat{A} \rangle^2 \tag{89}$$

root-mean-square:

$$\Delta \hat{A} = \sqrt{\Delta \hat{A}^2} = \sqrt{\langle \hat{A}^2 \rangle - \langle \hat{A} \rangle^2} \tag{90}$$

Essential Mathematical Tools

- 1. If $\hat{F}^{\dagger} = \hat{F}$ (Hermitian), then eigenvalue of \hat{F} is REAL
- 2. If $\hat{F}^{\dagger} = -\hat{F}$ (skew-Hermitian), then \hat{F} is IMAGINARY
- 3. Cauchy-Schwarz Inequality

(a)
$$\left(\sum_{n} a_n^2\right) \left(\sum_{n} b_n^2\right) \ge \left(\sum_{n} a_n b_n\right)^2$$
, equality iff $a_n = k b_n$

(b)
$$|\boldsymbol{u}|^2 |\boldsymbol{v}|^2 \ge |\boldsymbol{u} \cdot \boldsymbol{v}|^2$$
, equality iff $\boldsymbol{u} = k\boldsymbol{v}$

(b)
$$|\boldsymbol{u}|^2 |\boldsymbol{v}|^2 \ge |\boldsymbol{u} \cdot \boldsymbol{v}|^2$$
, equality iff $\boldsymbol{u} = k\boldsymbol{v}$
(c) $|\langle \psi | \psi \rangle \langle \phi | \phi \rangle \ge |\langle \psi | \phi \rangle|^2$, equality iff $|\psi \rangle = \lambda |\phi \rangle$

24.2.2 Define Deviation Operator

$$\hat{\sigma}_A = \hat{A} - \langle \hat{A} \rangle \quad \& \quad \hat{\sigma}_B = \hat{B} - \langle \hat{B} \rangle$$
 (91)

$$\Longrightarrow \begin{cases} \Delta \hat{A}^2 = \langle \hat{\sigma}_A^2 \rangle \\ \Delta \hat{B}^2 = \langle \hat{\sigma}_B^2 \rangle \end{cases} \tag{92}$$

24.2.3 Properties of $\hat{\sigma}_A, \hat{\sigma}_B$

1.
$$\hat{\sigma}_A^{\dagger} = \hat{\sigma}_A, \, \hat{\sigma}_B^{\dagger} = \hat{\sigma}_B \, (\text{Hermitian})$$

2.
$$\hat{\sigma}_A^{\dagger}\hat{\sigma}_A = \hat{\sigma}_A^2$$
, $\hat{\sigma}_B^{\dagger}\hat{\sigma}_B = \hat{\sigma}_B^2$

3.
$$\left[\hat{\sigma}_A, \hat{\sigma}_B\right] = \left[\hat{A}, \hat{B}\right]$$

4.
$$\hat{\sigma}_A \hat{\sigma}_B = \frac{1}{2} [\hat{\sigma}_A, \hat{\sigma}_B] + \frac{1}{2} {\{\hat{\sigma}_A, \hat{\sigma}_B\}}$$

5.
$$\left[\hat{\sigma}_A, \hat{\sigma}_B\right]^{\dagger} = -\left[\hat{\sigma}_A, \hat{\sigma}_B\right]$$
 (skew-Hermitian)

6.
$$\{\hat{\sigma}_A, \hat{\sigma}_B\}^{\dagger} = \{\hat{\sigma}_A, \hat{\sigma}_B\}$$
 (Hermitian)

7.
$$\Delta \hat{A}^2 = \langle \hat{\sigma}_A^2 \rangle, \ \Delta \hat{B}^2 = \langle \hat{\sigma}_B^2 \rangle$$

24.2.4 Proof of GUP

$$\det: \hat{\sigma}_{A} | \psi \rangle = | \psi_{A} \rangle \quad \& \quad \hat{\sigma}_{B} | \psi \rangle = | \psi_{B} \rangle$$

$$\langle \hat{\sigma}_{A}^{2} \rangle = \langle \psi | \hat{\sigma}_{A} \hat{\sigma}_{A} | \psi \rangle = \langle \psi | \hat{\sigma}_{A}^{\dagger} \hat{\sigma}_{A} | \psi \rangle = \langle \psi_{A} | \psi_{A} \rangle \quad \& \quad \langle \hat{\sigma}_{B}^{2} \rangle = \langle \psi_{B} | \psi_{B} \rangle$$

$$\Longrightarrow \langle \hat{\sigma}_{A}^{2} \rangle \langle \hat{\sigma}_{B}^{2} \rangle = \langle \psi_{A} | \psi_{A} \rangle \langle \psi_{B} | \psi_{B} \rangle \geq |\langle \psi_{A} | \psi_{B} \rangle|^{2} = |\langle \psi | \hat{\sigma}_{A} \hat{\sigma}_{B} | \psi \rangle|^{2} = |\langle \hat{\sigma}_{A} \hat{\sigma}_{B} \rangle|^{2}$$

$$\langle \hat{\sigma}_{A} \hat{\sigma}_{B} \rangle = \frac{1}{2} \langle [\hat{\sigma}_{A}, \hat{\sigma}_{B}] \rangle + \frac{1}{2} \langle \{\hat{\sigma}_{A}, \hat{\sigma}_{B}\} \rangle$$

$$\Longrightarrow |\langle \hat{\sigma}_{A} \hat{\sigma}_{B} \rangle|^{2} \geq \frac{1}{4} |\langle [\hat{\sigma}_{A}, \hat{\sigma}_{B}] \rangle|^{2} = \frac{1}{4} |\langle [\hat{A}, \hat{B}] \rangle|^{2} \quad \Longrightarrow \text{GUP}$$

24.3 Energy-Time Uncertainty Relation

$$\Delta E \cdot \Delta T \ge \frac{\hbar}{2} \tag{93}$$

24.3.1 Ehrenfest Theorem

$$\left[\hat{A}, \hat{H}\right] \neq 0, \frac{\partial \hat{A}}{\partial t} = 0,$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \langle \hat{A} \rangle = \frac{1}{\mathrm{i}\hbar} \langle \left[\hat{A}, \hat{H}\right] \rangle \tag{94}$$

24.3.2 Proof

$$\Longrightarrow \Delta \hat{A} \cdot \Delta \hat{H} \ge \frac{1}{2} \Big| \langle \Big[\hat{A}, \hat{H} \Big] \rangle \Big| = \frac{\hbar}{2} \Big| \frac{\mathrm{d}}{\mathrm{d}t} \langle \hat{A} \rangle \Big| \quad \Longrightarrow \Delta \hat{H} \frac{\Delta \hat{A}}{\Big| \frac{\mathrm{d}}{\mathrm{d}t} \langle \hat{A} \rangle \Big|} = \frac{\hbar}{2}$$

define
$$\Delta \hat{H} = \Delta E$$
, $\Delta T = \frac{\Delta \hat{A}}{\left|\frac{\mathrm{d}}{\mathrm{d}t}\langle \hat{A}\rangle\right|}$

$$\implies \Delta E \cdot \Delta T \ge \frac{\hbar}{2}$$

24.4 Minimum Uncertainty State

 $\frac{\hbar}{2}$: quantum limit (Heisenberg limit) \Longrightarrow Minimum Uncertainty State

$$\exists \, |\psi\rangle_{\min} \,, \,\, \Delta \hat{A} \cdot \Delta \hat{B} = \frac{1}{2} \Big| \langle \left[\hat{A}, \hat{B} \right] \rangle \Big|$$

 $|\psi\rangle_{\rm min}$: Minimum Uncertainty State

24.4.1 MUS of $\hat{x} \& \hat{p}$

$$\begin{cases} \hat{\sigma}_x = \hat{x} - \langle \hat{x} \rangle \\ \hat{\sigma}_p = \hat{p} - \langle \hat{p} \rangle \end{cases}, \text{ let } |\phi\rangle = (\hat{\sigma}_x - i\lambda\hat{\sigma}_p) |\psi\rangle \text{ (testing state)}$$

$$\langle \phi | \phi \rangle = \langle \psi | (\hat{\sigma}_{x} + i\lambda \hat{\sigma}_{p})(\hat{\sigma}_{x} - i\lambda \hat{\sigma}_{p}) | \psi \rangle = \langle \psi | (\hat{\sigma}_{x}^{2} - i\lambda \hat{\sigma}_{x} \hat{\sigma}_{p} + i\lambda \hat{\sigma}_{p} \hat{\sigma}_{x} + \lambda^{2} \hat{\sigma}_{p}^{2}) | \psi \rangle$$

$$= \langle \psi | \hat{\sigma}_{x}^{2} | \psi \rangle - i\lambda \langle \psi | [\hat{\sigma}_{x}, \hat{\sigma}_{p}] | \psi \rangle + \lambda^{2} \langle \psi | \hat{\sigma}_{p}^{2} | \psi \rangle = \langle \hat{\sigma}_{x}^{2} \rangle + \lambda \hbar + \lambda^{2} \langle \hat{\sigma}_{p}^{2} \rangle$$

$$| \psi \rangle = 0 \Longrightarrow \langle \phi | \phi \rangle = 0 \Longrightarrow \langle \hat{\sigma}_{p}^{2} \rangle \lambda^{2} + \hbar \lambda + \langle \hat{\sigma}_{x}^{2} \rangle = 0$$

$$\Delta = \hbar^{2} - 4 \langle \hat{\sigma}_{x}^{2} \rangle \langle \hat{\sigma}_{p}^{2} \rangle \lambda^{2} \leq 0 \Longrightarrow \langle \hat{\sigma}_{x}^{2} \rangle \langle \hat{\sigma}_{p}^{2} \rangle \lambda^{2} \geq \frac{\hbar^{2}}{4}$$

$$\Longrightarrow \Delta \hat{x}^{2} \cdot \Delta \hat{p}^{2} \geq \frac{\hbar^{2}}{4} \quad \text{or} \quad \Delta \hat{x} \cdot \Delta \hat{p} \geq \frac{\hbar}{2}$$

$$(95)$$

$$\Delta = 0 \Longrightarrow \begin{cases} \lambda = -\frac{2}{\hbar} \Delta \hat{x}^2 \\ |\phi\rangle = \left(\hat{\sigma}_x + \frac{2i}{\hbar} \Delta \hat{x}^2 \hat{\sigma}_p\right) |\psi\rangle = 0 \end{cases}$$
(96)

$$\langle x | (\hat{x} - \langle \hat{x} \rangle) - i\lambda \left(-i\hbar \frac{\mathrm{d}}{\mathrm{d}x} - \langle \hat{p} \rangle \right) | \psi \rangle = (x - \langle \hat{x} \rangle)\psi(x) - \lambda\hbar \frac{\mathrm{d}}{\mathrm{d}x}\psi(x) + i\lambda \langle \hat{p} \rangle \psi(x)$$

25 Quantum Dynamics

25.1 Schrödinger Equation

$$i\hbar \frac{\mathrm{d}}{\mathrm{d}t} |\psi(t)\rangle = \hat{H} |\psi(t)\rangle$$
 (97)

where $\hat{H} = \frac{\hat{p}^2}{2m} + V(\hat{x})$

25.1.1 Remark

- 1. Pure State
- 2. Closed System $\Longrightarrow \langle \psi(t)|\psi(t)\rangle = 1$
- 3. Non-Relativistic QM
- 4. Initial Value Problem (IVP): $|\psi(t=t_0)\rangle = |\psi(t_0)\rangle$
- 5. Schrödinger Picture: $\frac{\mathrm{d}\hat{A}}{\mathrm{d}t} \equiv 0$

25.1.2 Representation of Position

In \boldsymbol{x} -representation: $\hat{\boldsymbol{p}} = -\mathrm{i}\hbar\nabla$, $\langle \boldsymbol{x}|\psi(t)\rangle = \psi(\boldsymbol{x})$

$$i\hbar \frac{\mathrm{d}}{\mathrm{d}t} |\psi(t)\rangle = \hat{H} |\psi(t)\rangle \Longrightarrow i\hbar \frac{\partial}{\partial t} \psi(\boldsymbol{x}, t) = \left(-\frac{\hat{p}}{2m} + V(\hat{x})\right) \psi(\boldsymbol{x}, t)$$
 (98)

- 1. In general, $\frac{\partial \hat{A}}{\partial t} \equiv 0 \& \frac{\partial \hat{H}}{\partial t} \equiv 0$. Unless there is external influence.
- 2. $\langle \psi(t)|\psi(t)\rangle = 1 \longleftrightarrow \int d^3x |\psi(\boldsymbol{x},t)|^2 = 1$
- 3. $\psi(\mathbf{x}, t = t_0) = \psi(\mathbf{x}, t_0)$

25.2 Time Evolution Operator

$$|\psi(t)\rangle = \hat{U}(t, t_0) |\psi(t_0)\rangle \tag{99}$$

Schrödinger eq.
$$\Longrightarrow i\hbar \frac{\mathrm{d}}{\mathrm{d}t} \left[\hat{U}(t, t_0) | \psi(t_0) \rangle \right] = \hat{H} \left[\hat{U}(t, t_0) | \psi(t_0) \rangle \right]$$
 (100)

$$\Longrightarrow i\hbar \frac{\mathrm{d}}{\mathrm{d}t} \hat{U}(t, t_0) = \hat{H} \hat{U}(t, t_0) \tag{101}$$

25.2.1 TEO for Conservative System

If the system is conservative, that is $\frac{\partial \hat{H}}{\partial t} \equiv 0$.

$$\Longrightarrow \frac{\mathrm{d}\hat{U}}{\hat{U}} = -\frac{\mathrm{i}}{\hbar}\hat{H}\,\mathrm{d}t \Longrightarrow \left[\hat{U}(t,t_0) = \mathrm{e}^{-\mathrm{i}\hat{H}(t-t_0)/\hbar}\right]$$

If $\frac{\partial \hat{H}}{\partial t} \neq 0$, then

$$\hat{U}(t, t_0) = \hat{1} - \frac{i}{\hbar} \int dt' \, \hat{U}(t', t_0)$$

$$= \hat{1} - \frac{i}{\hbar} \text{(Dyson Series)}$$
(102)

25.2.2 Properties of $\hat{U}(t, t_0)$

1.
$$\hat{U}^{\dagger}(t, t_0) = \hat{U}^{-1}(t, t_0 = \hat{U}(t_0, t))$$
 or $\hat{U}^{\dagger}(t, t_0)\hat{U}(t, t_0) = \hat{1}$

2.
$$\hat{U}(t,t_1)\hat{U}(t_1,t_0) = \hat{U}(t,t_0) \xrightarrow{\text{expand}} \hat{U}(t,t_n)\hat{U}(t_n,t_{n-1})\cdots\hat{U}(t_2,t_1)\hat{U}(t_1,t_0) = \hat{U}(t,t_0)$$

3.
$$\hat{U}(t,t_0) = \hat{U}(t-t_0) = \hat{U}(\tau) \ (\tau \stackrel{\text{def}}{===} t - t_0)$$

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