

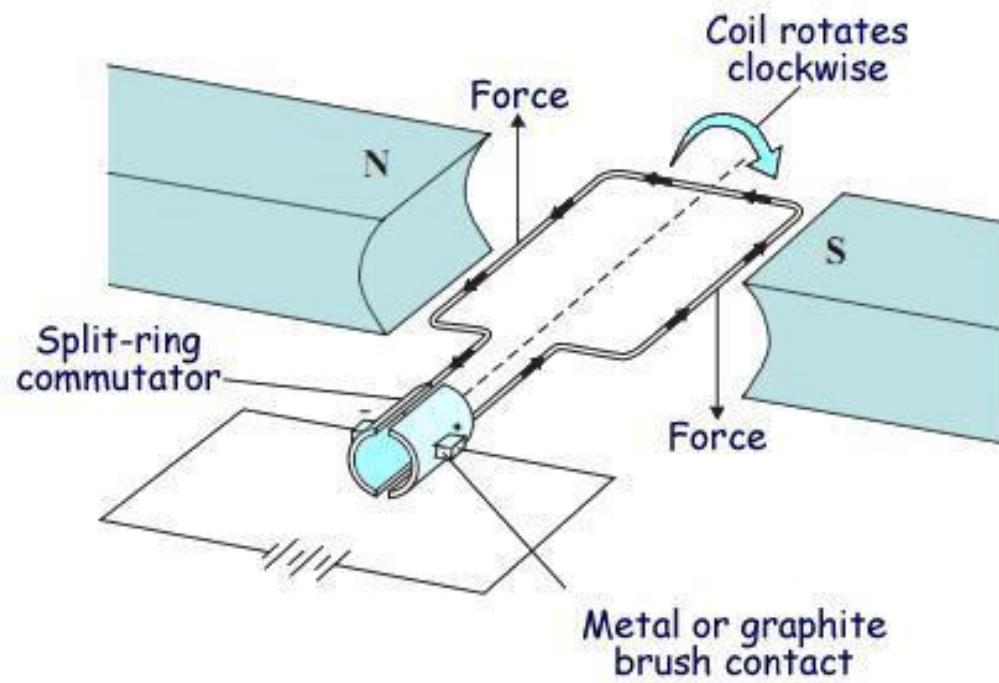
## Lecture-29

On

# INTRODUCTION TO ELECTRICAL ENGINEERING (ESO203)

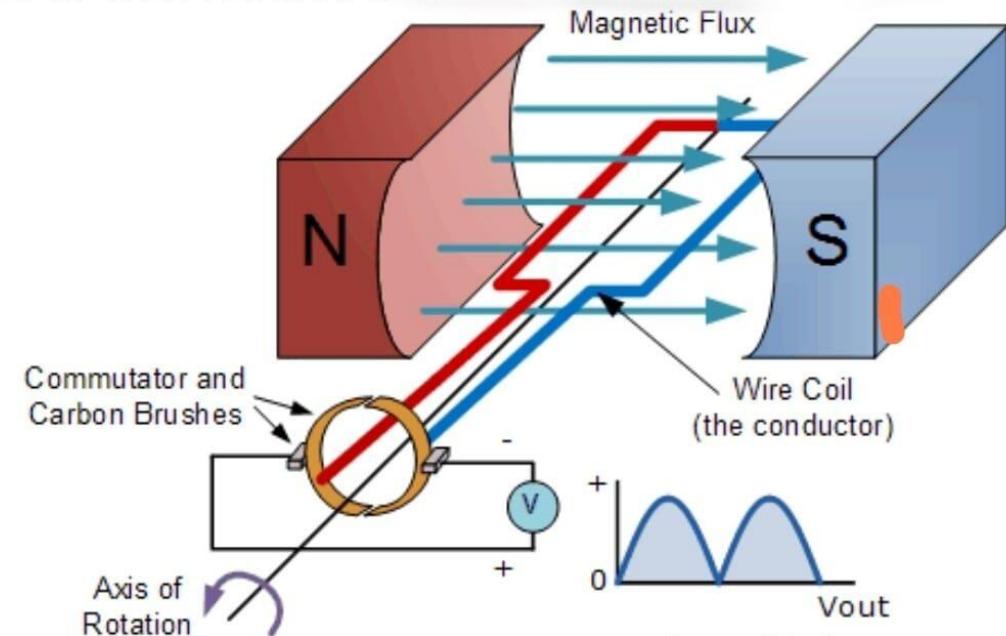
- DC generator.

# Introduction to Machines (Cont...)



Operation of DC motor

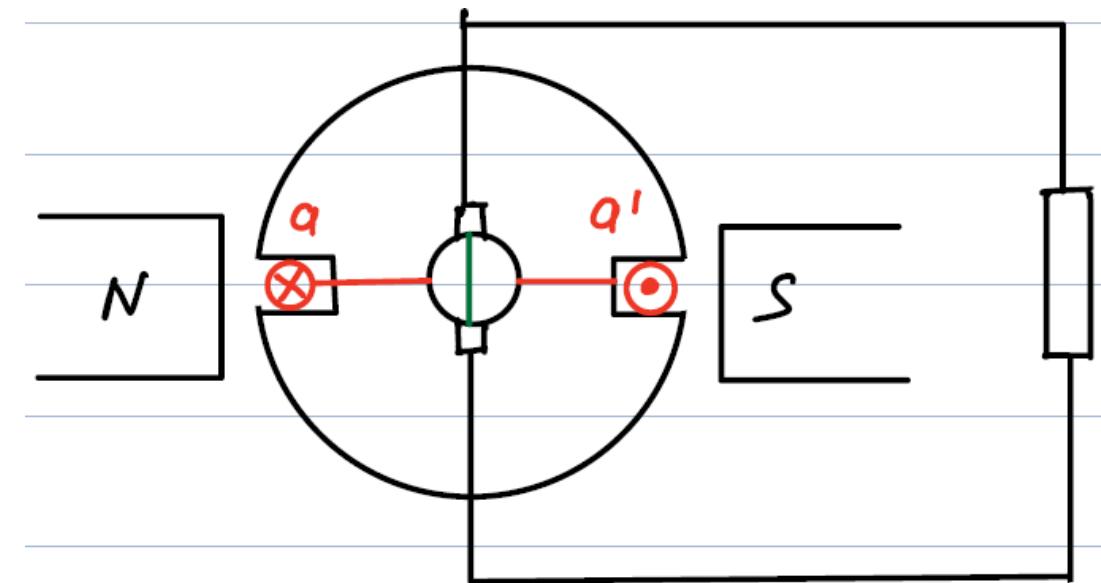
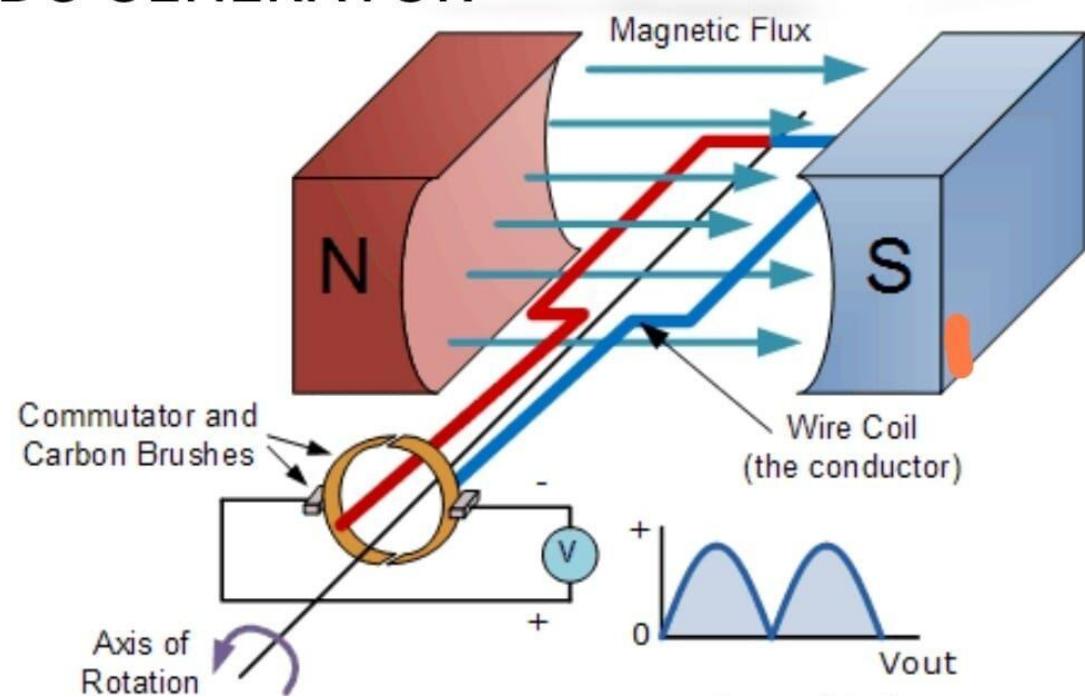
## DC GENERATOR



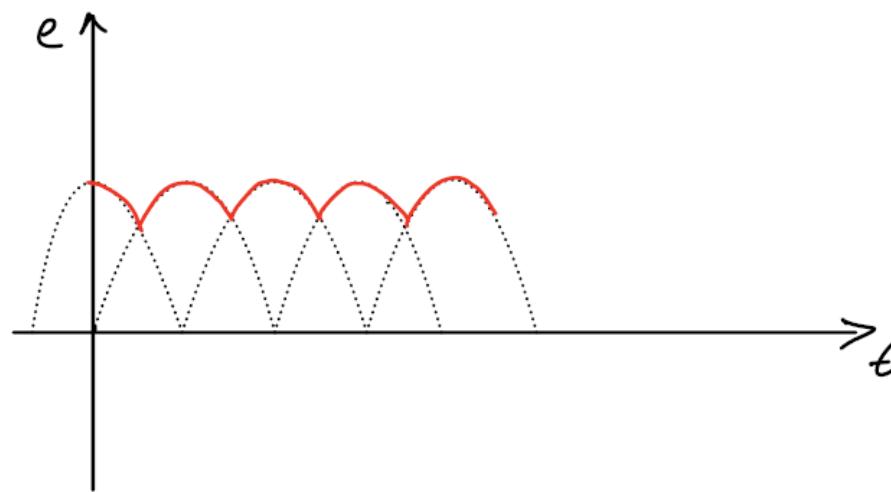
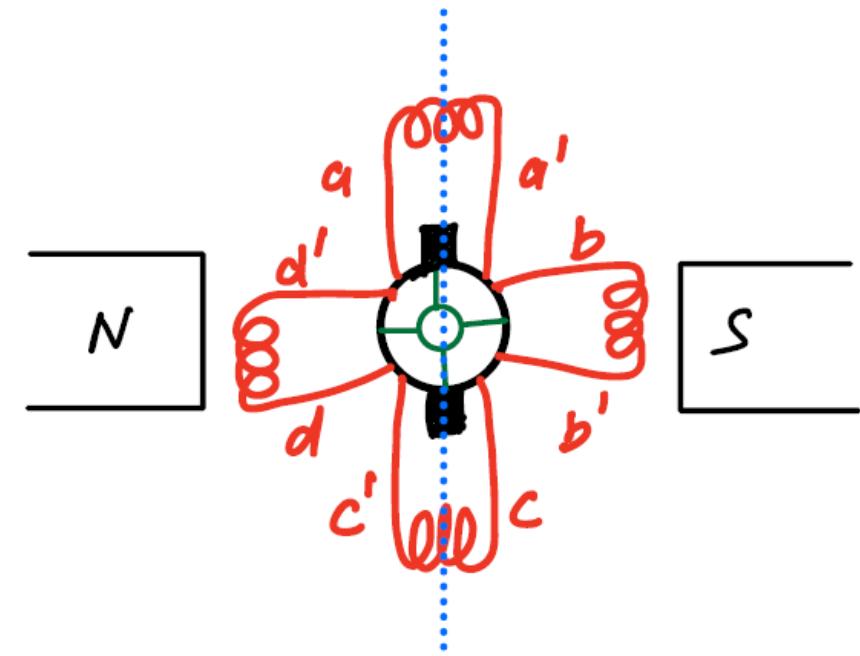
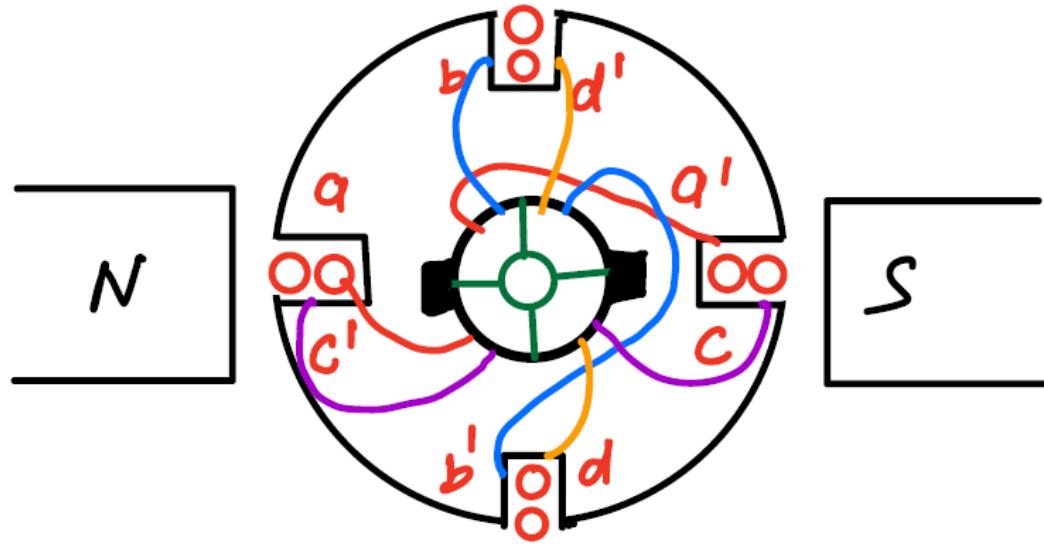
Operation of DC generator

# DC Generator

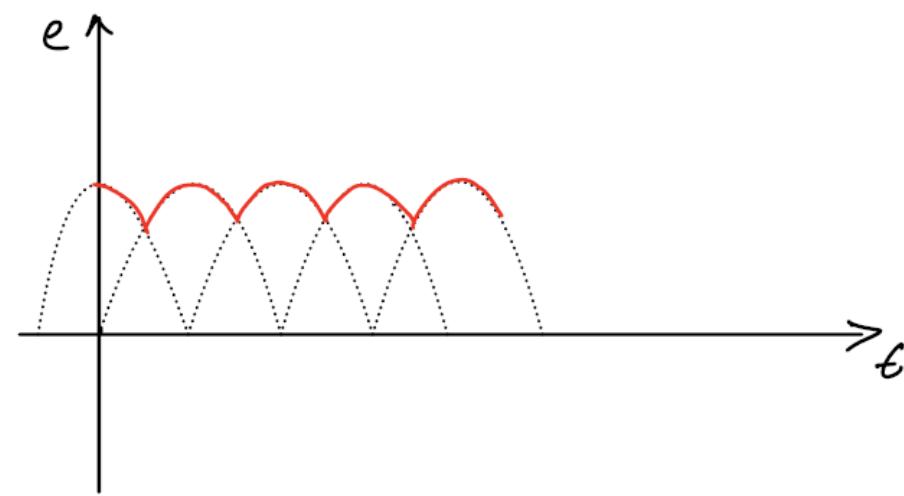
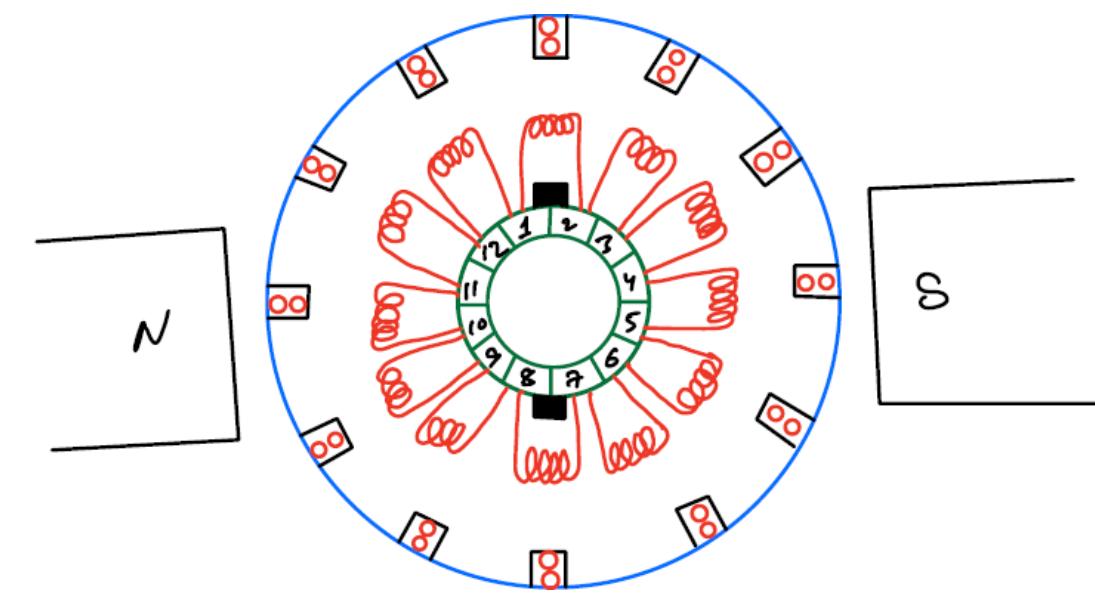
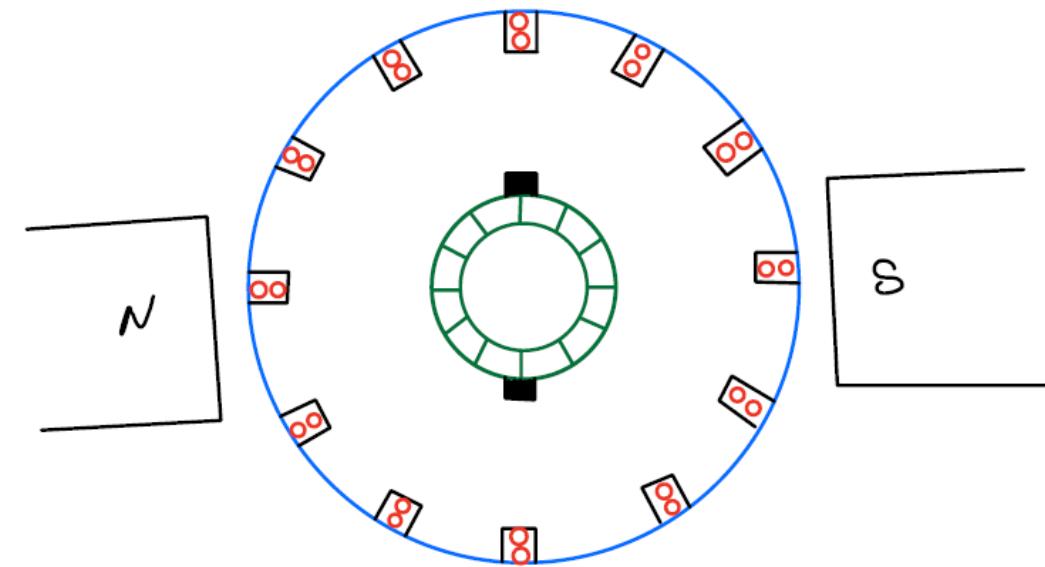
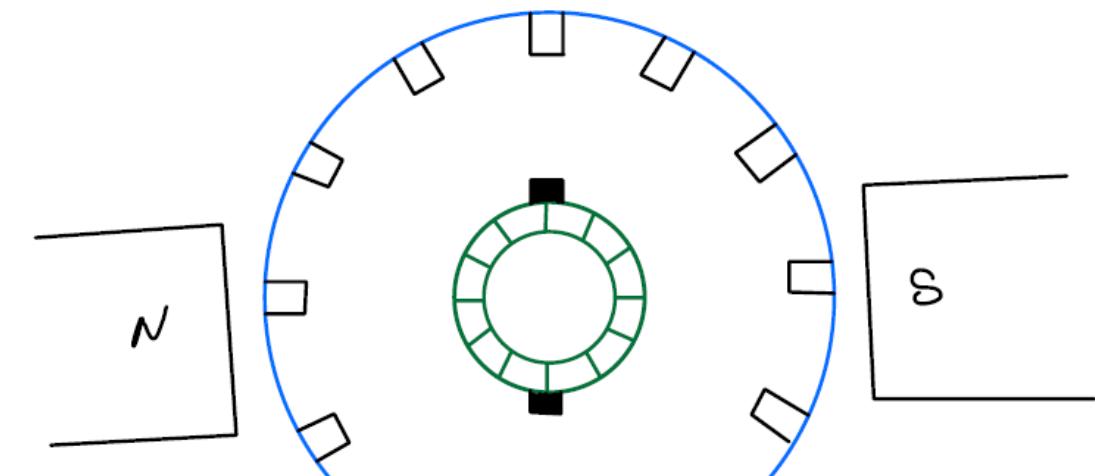
## DC GENERATOR



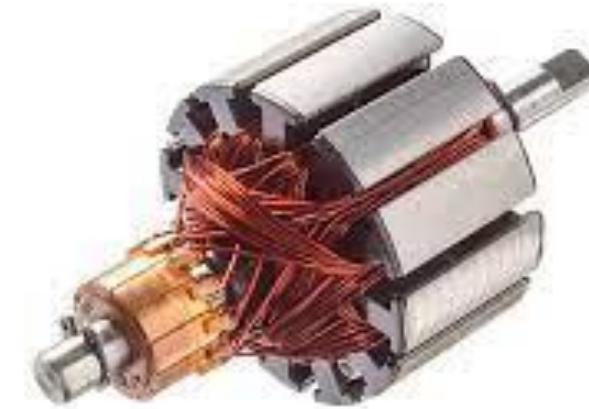
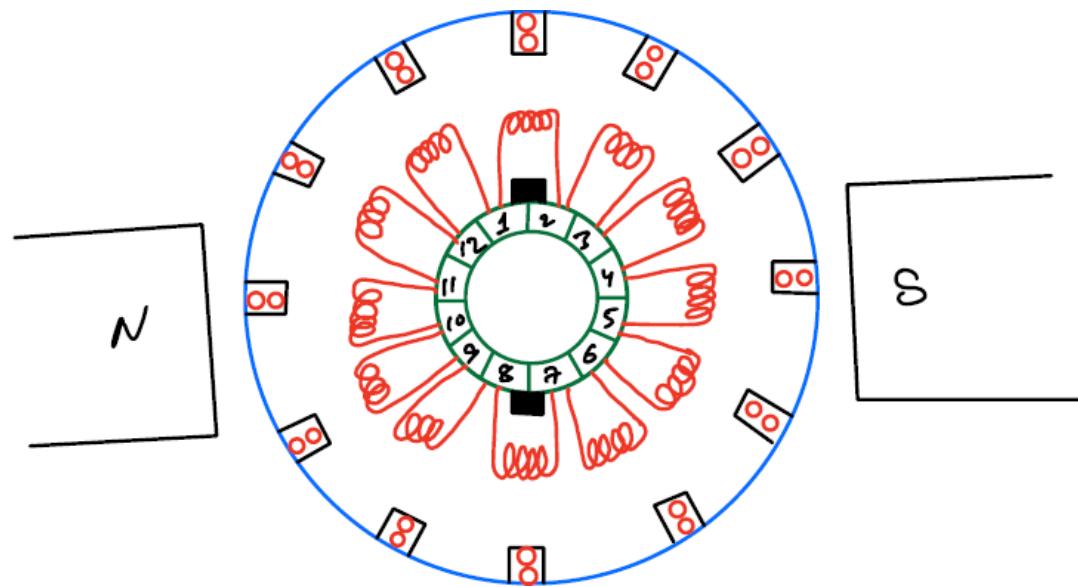
## DC Generator (cont...)



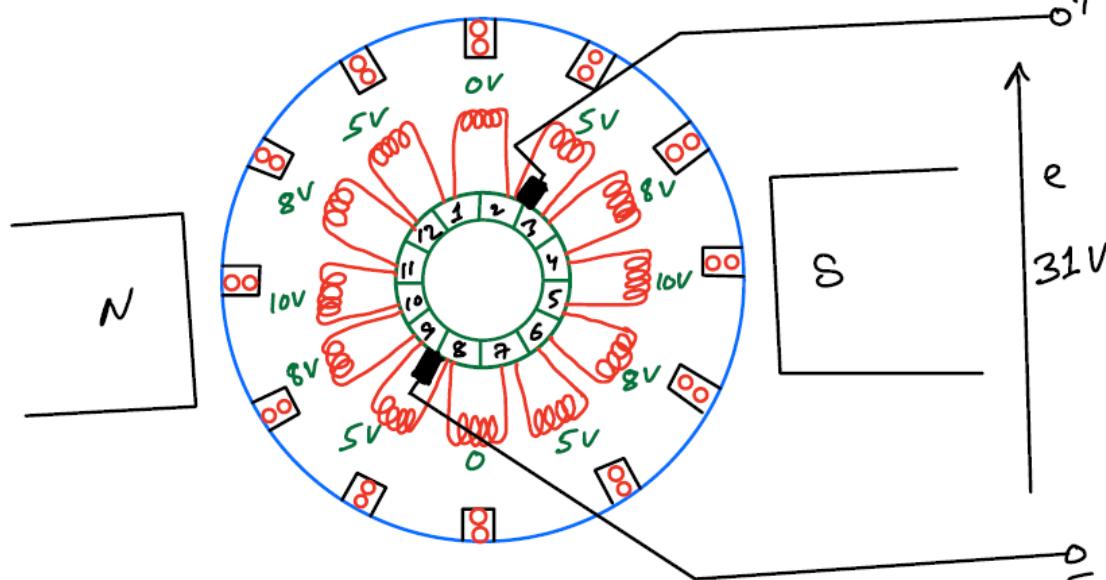
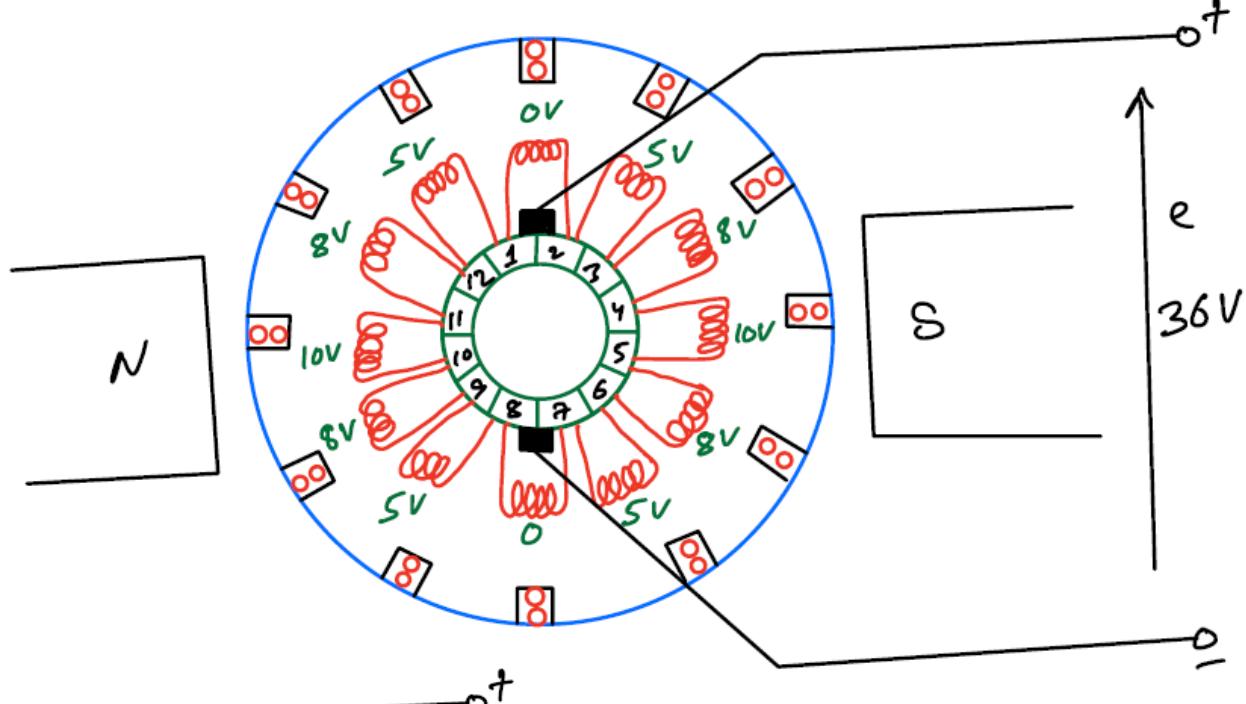
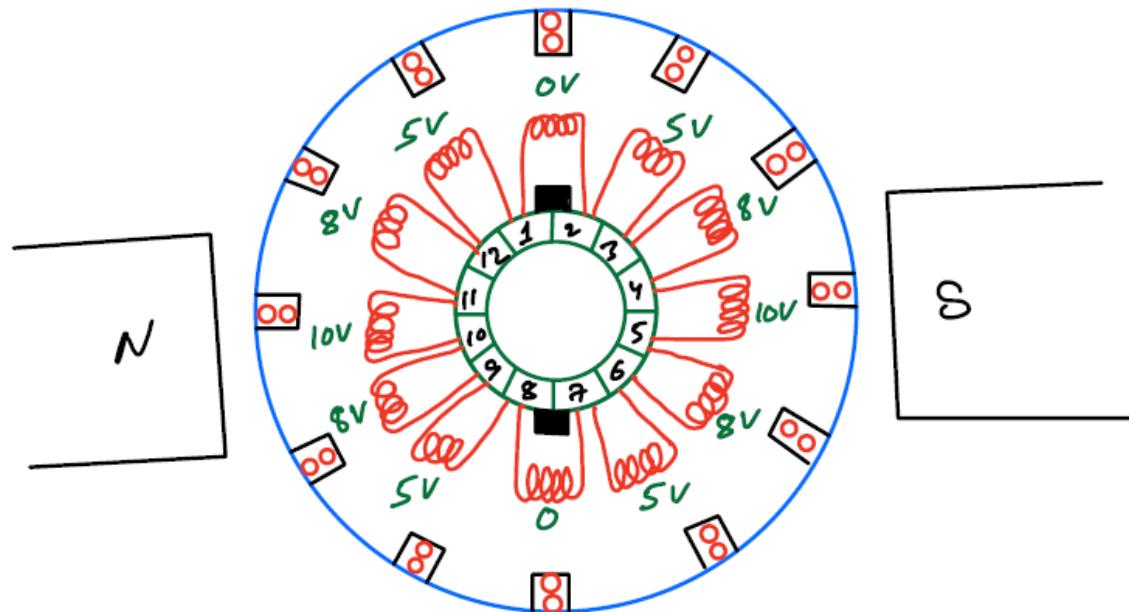
## DC Generator (cont...)



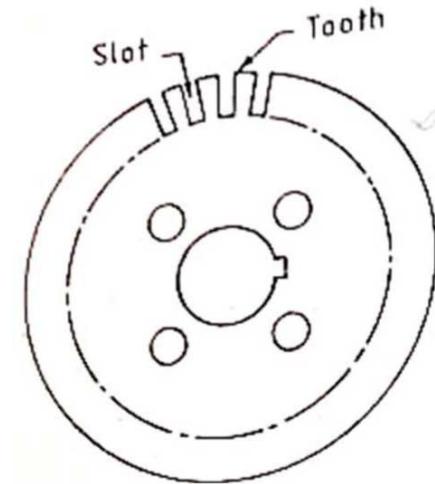
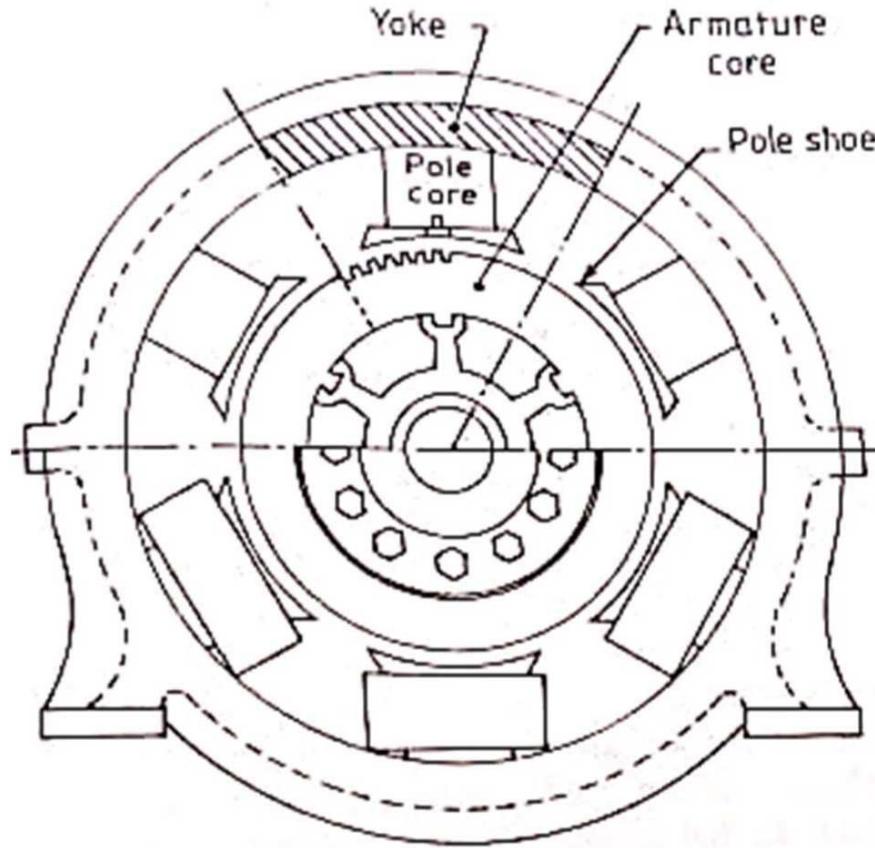
## DC Generator (cont...)



## DC Generator (cont...)



# DC Machine Construction



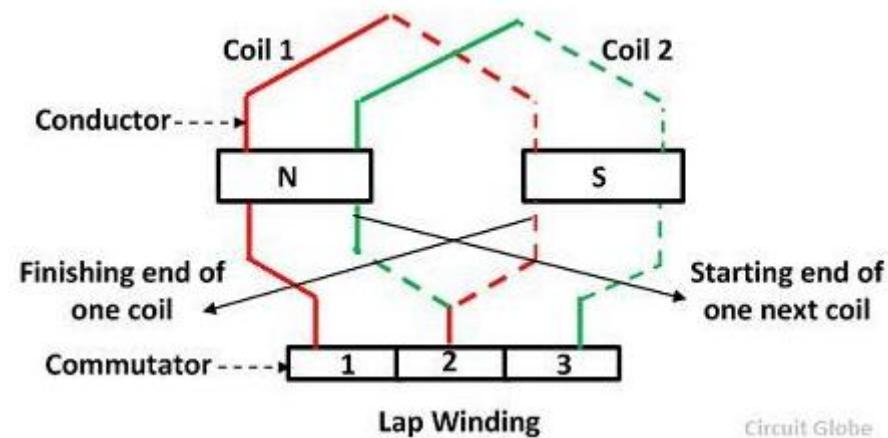
- Flux density in pole core is higher than pole shoes.
- Pole shoes are laminated to avoid heating and eddy current loss.
- Yoke is part of the frame and carries flux from pole to pole.
- Armature teeth are skewed to avoid vibration of teeth.

## DC Machine Construction (cont...)

### □ Lap & Wave Winding:

#### □ Lap Winding:

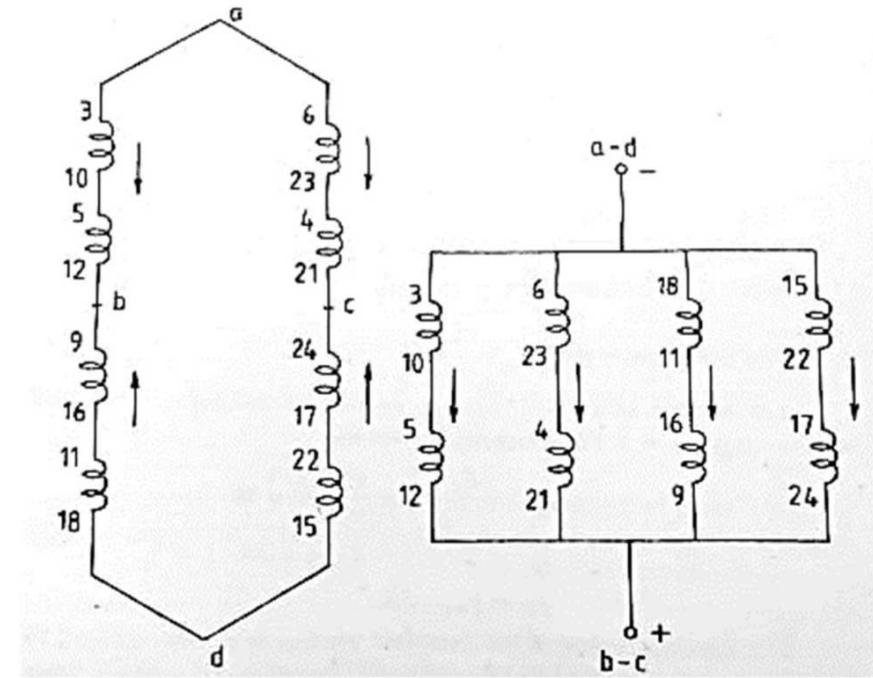
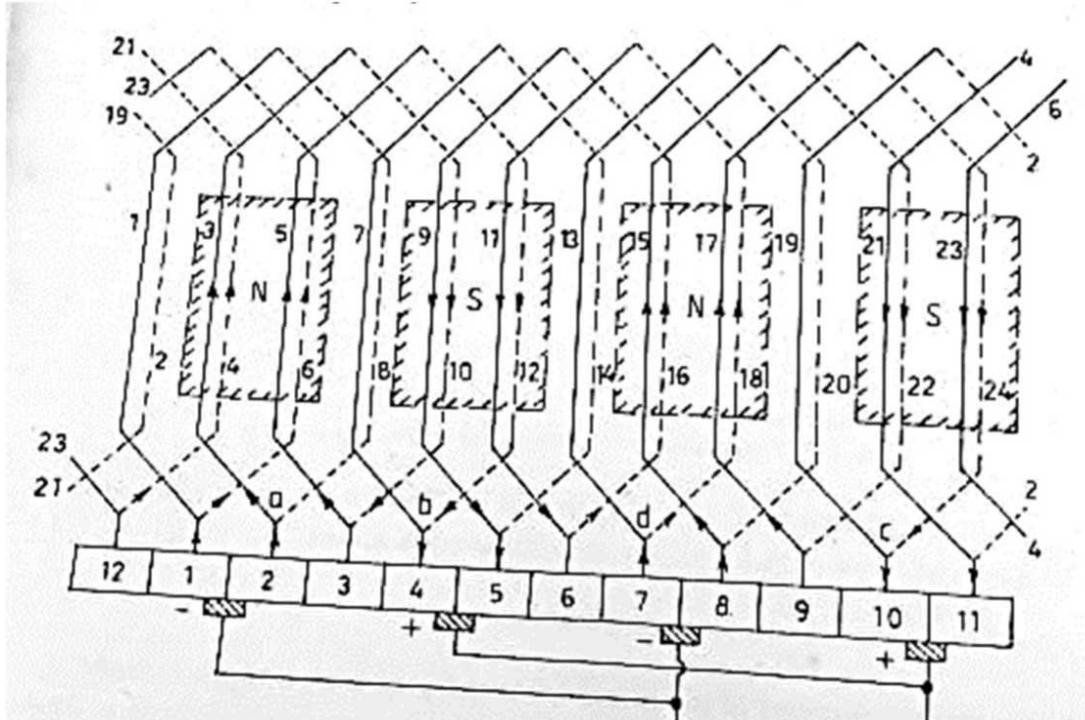
- In lap winding, the conductors are joined in such a way that their parallel paths (a) and poles (p) are equal in number.
- The end of each armature coil is connected to the adjacent segment on the commutator.
- The number of brushes in the lap winding is equal to the number of parallel paths, and these brushes are equally divided into negative and positive polarity.



Circuit Globe

## DC Machine Construction (cont...)

### □ Lap Winding:



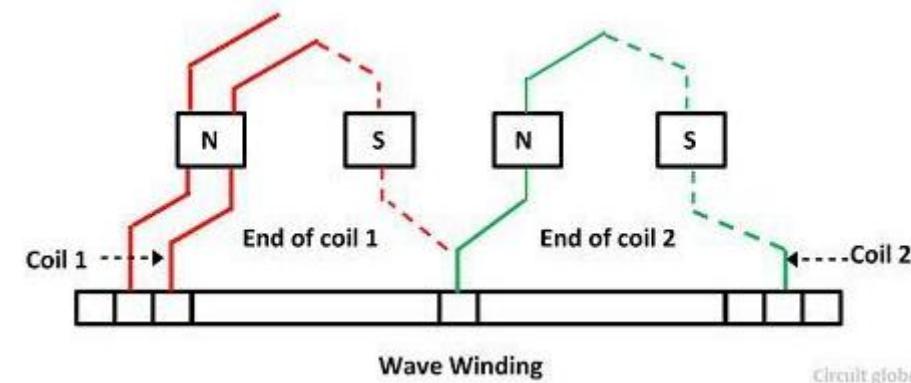
### Winding Pitches –

The distance between two coil sides of the coil, measured in terms of coil sides between them.

## DC Machine Construction (cont...)

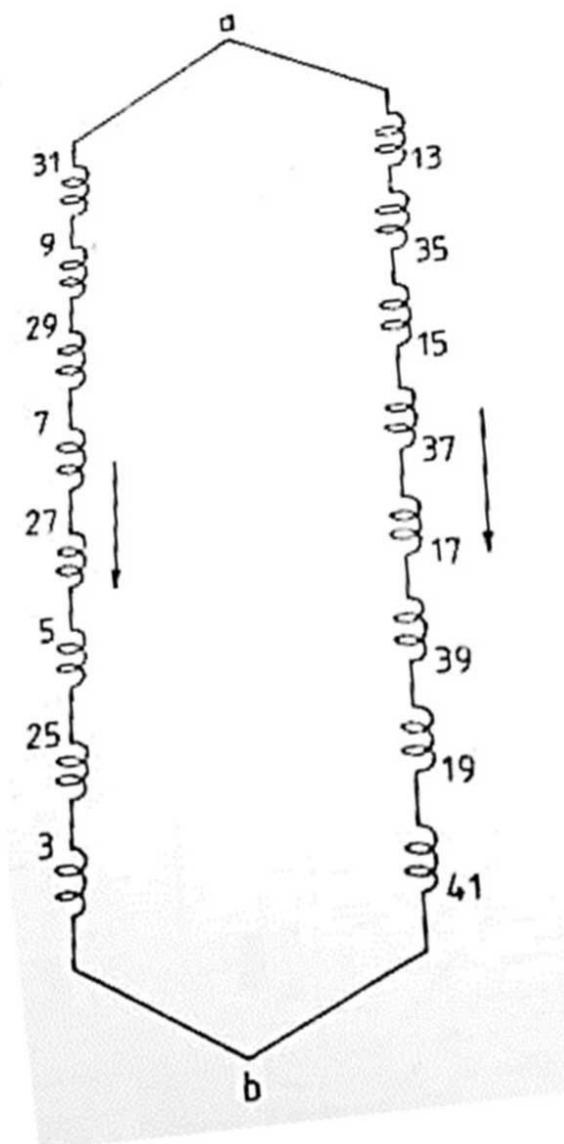
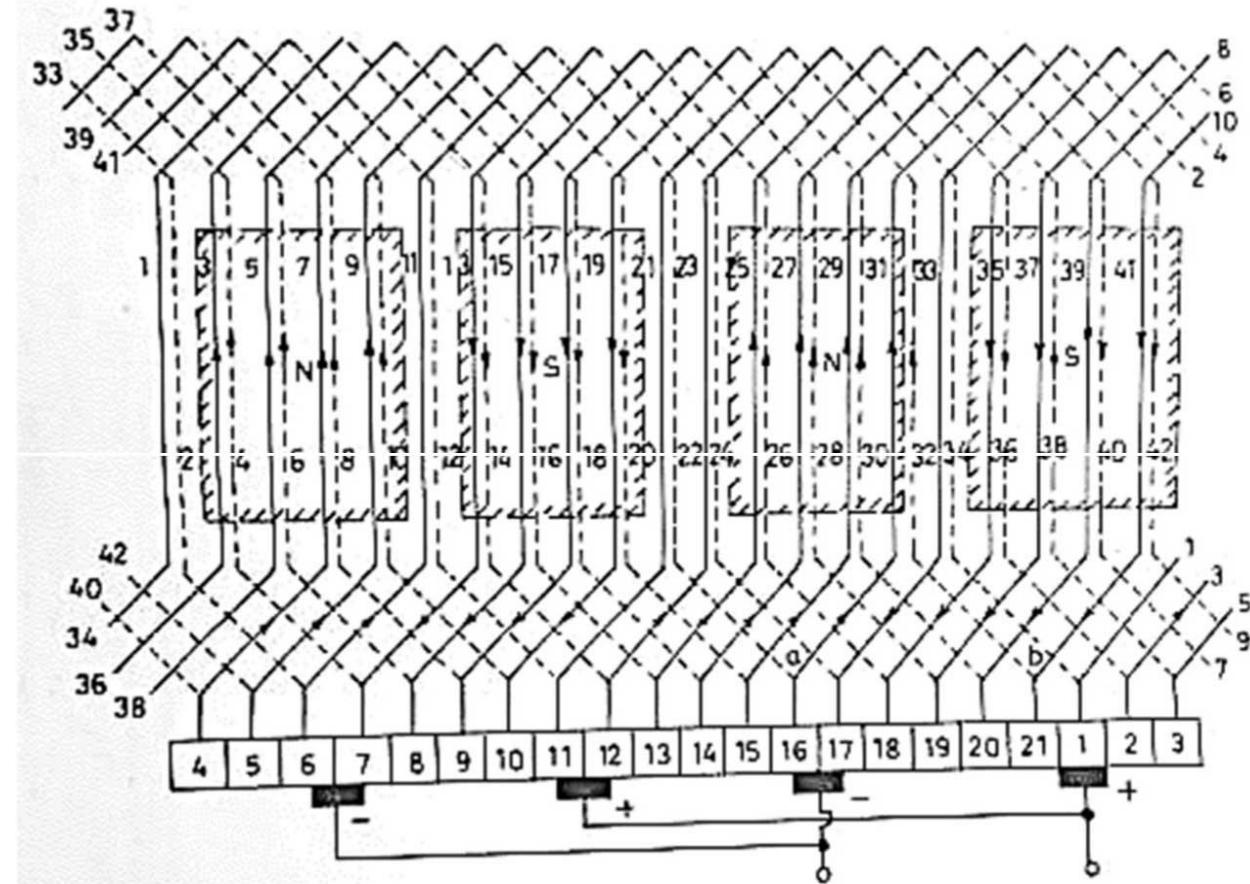
### □ Wave Winding:

- In wave winding, only two parallel paths are provided between the positive and negative brushes.
- The finishing end of the one armature coil is connected to the starting end of the other armature coil commutator segment at some distance apart.
- In this winding, the conductors are connected to **two parallel paths** irrespective of the number of poles of the machine.
- The number of brushes is equal to the number of parallel paths. The wave winding is mainly used in **high voltage, low current** machines.



## DC Machine Construction (cont...)

### □ Wave Winding:

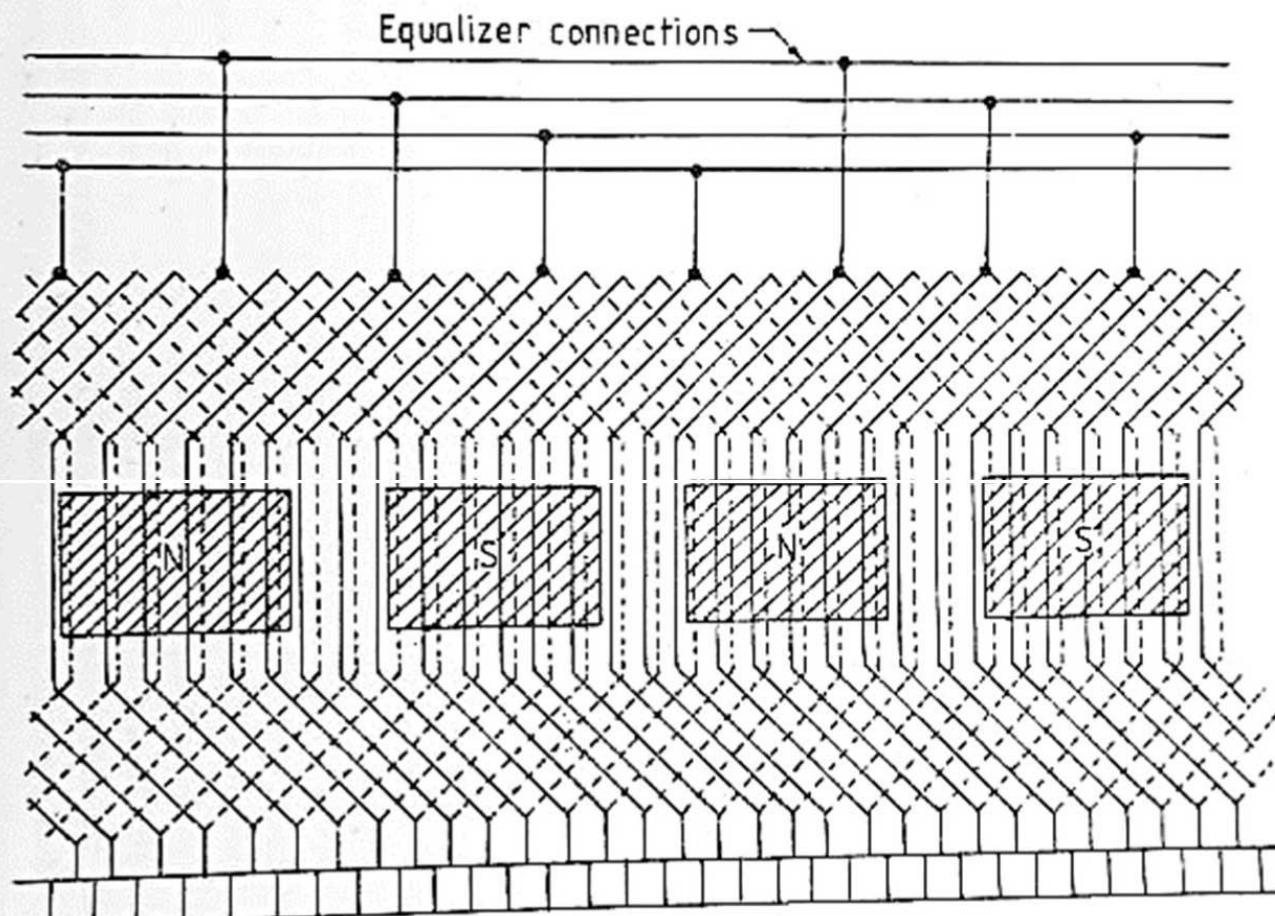


## DC Machine Construction (cont...)

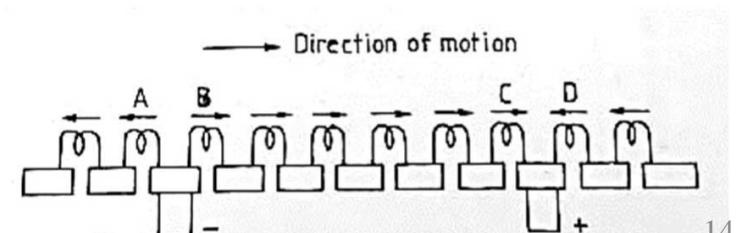


## DC Machine Construction (cont...)

### □ Equalizer Rings and Commutator

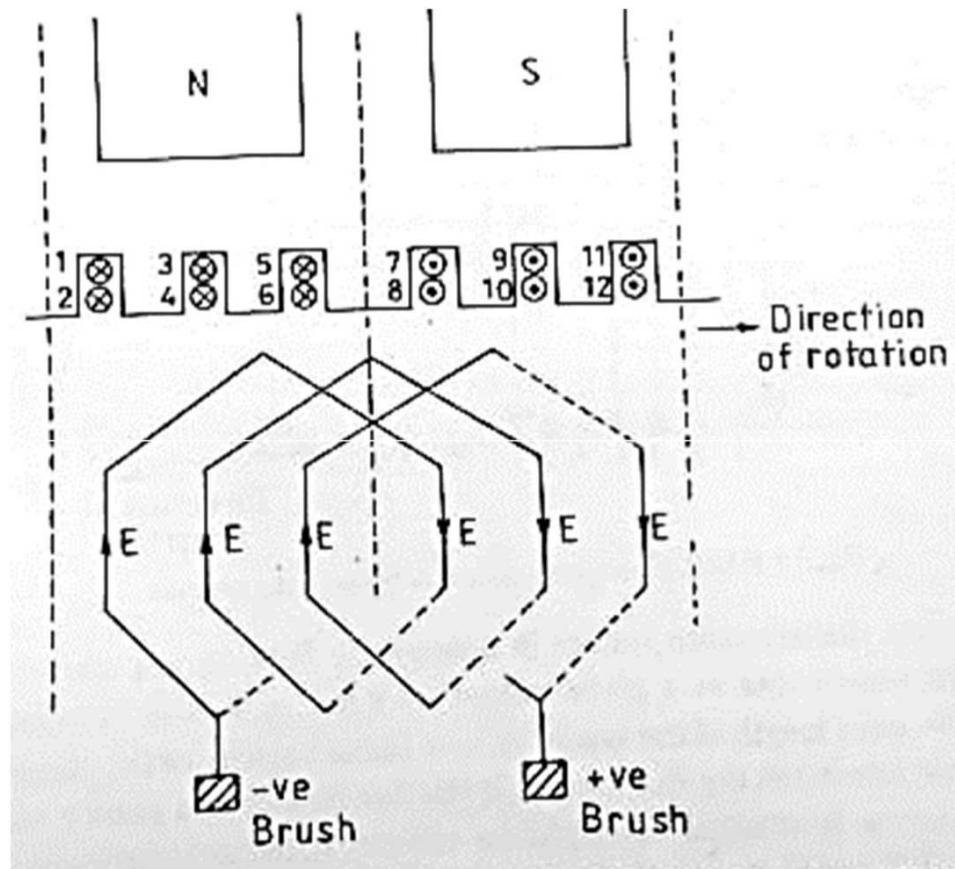


- Armature has multiple parallel paths.
- Different e.m.f. generated in different paths cause circulating current.
- Circulating current is prevented by adding equalizer ring in the armature.
- Commutator is a set of copper bars, insulated from each other, where armature windings are connected.
- The brushes are fixed while commutator moves with the armature.



## DC Machine Construction (cont...)

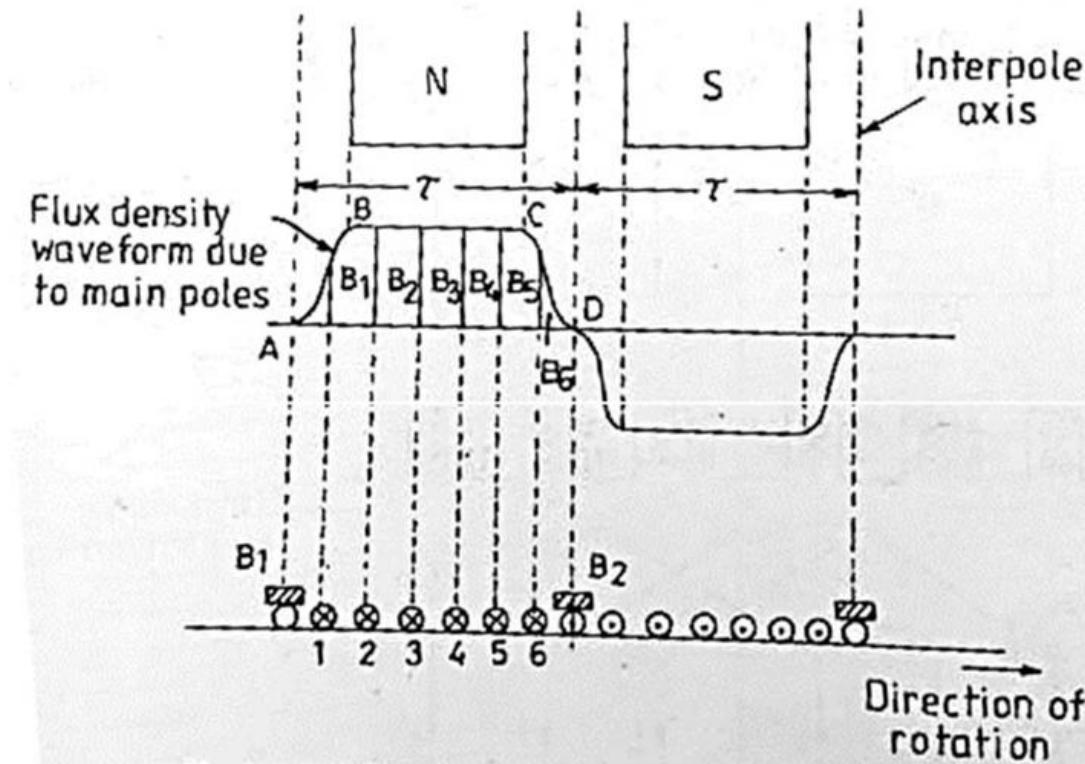
### □ E.M.F in the Coil



- The direction of induced e.m.f. in the armature conductor can be determined with the help of Fleming's right hand rule.
- Two coil sides are always under the influence of opposite poles. Hence induced e.m.f. in both sides of coil is additive.

## DC Machine Construction (cont...)

### □ e.m.f. induced between brushes



- Brushes are connected to armature conductors in the interpolar axes
- When armature rotates, at any instant, e.m.f. induced in every armature conductor is –

$$e_x = B_x l v$$

- If there are total **Z** conductors in armature winding and **a** parallel paths, total induced e.m.f. is –

$$E = e_1 + e_2 + e_3 + \dots + e_{\frac{Z}{a}}$$

$$E = \left( B_1 + B_2 + \dots + B_{\frac{Z}{a}} \right) l v$$

$$E = l v \sum_{x=1}^{\frac{Z}{a}} B_x$$

## DC Machine Construction (cont...)

- With large number of coil sides between the brushes :-

$$\sum_{x=1}^{z/a} B_x = \frac{Z}{a} B_{av}$$

$$E = lv \sum_{x=1}^{z/a} B_x = lv \frac{Z}{a} B_{av}$$

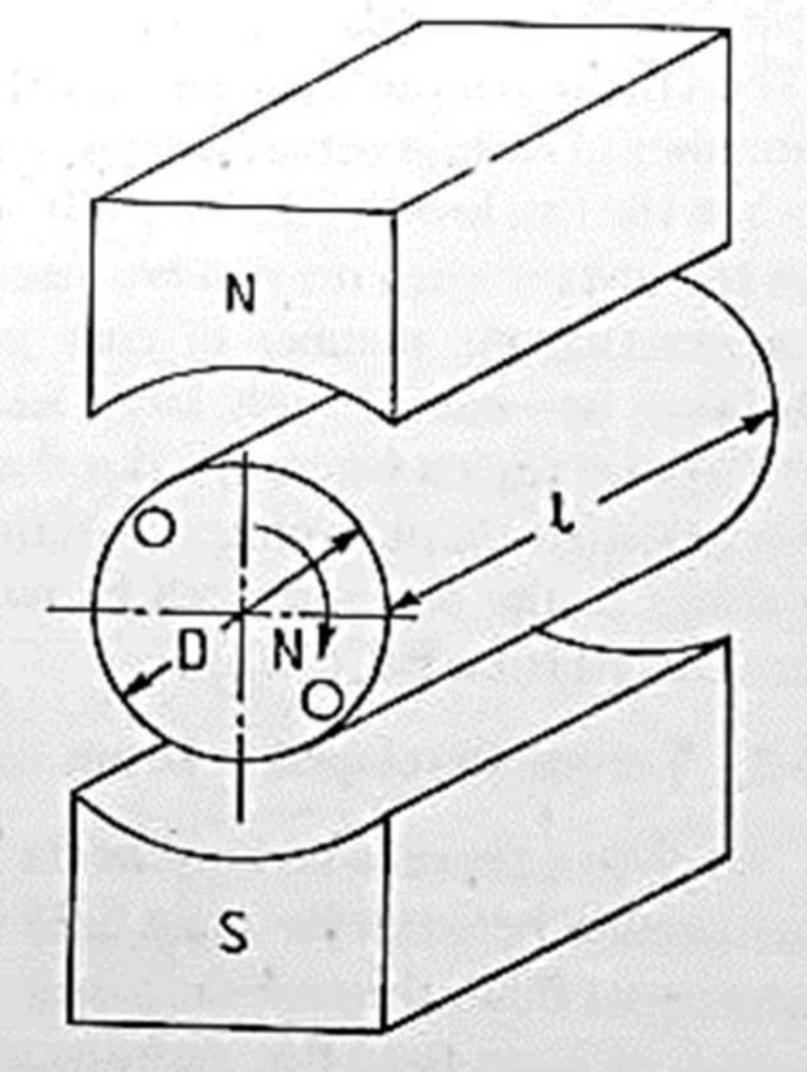
Area over one pole pitch =  $\frac{\pi Dl}{p}$

So,  $B_{av} = \phi / (\frac{\pi Dl}{p})$  and  $v = \frac{\omega D}{2} = \frac{\pi Dn}{60}$

So,  $E = l (\frac{\pi Dn}{60}) \phi / (\frac{\pi Dl}{p}) (\frac{z}{a})$

$$E = \frac{\phi Z np}{60a}$$

where 'n' is speed of armature in rpm, 'p' is number of poles of the machine.



## DC Machine Construction (cont...)

$$E = \frac{\phi Z np}{60a}$$

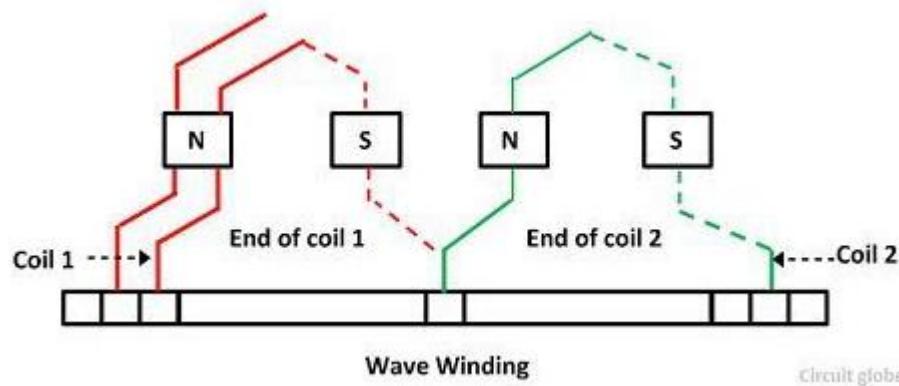
$$E = K\phi N$$

where 'K' is

$$K = \frac{Z \times p}{60 \times a}$$

## DC Machine Construction (cont...)

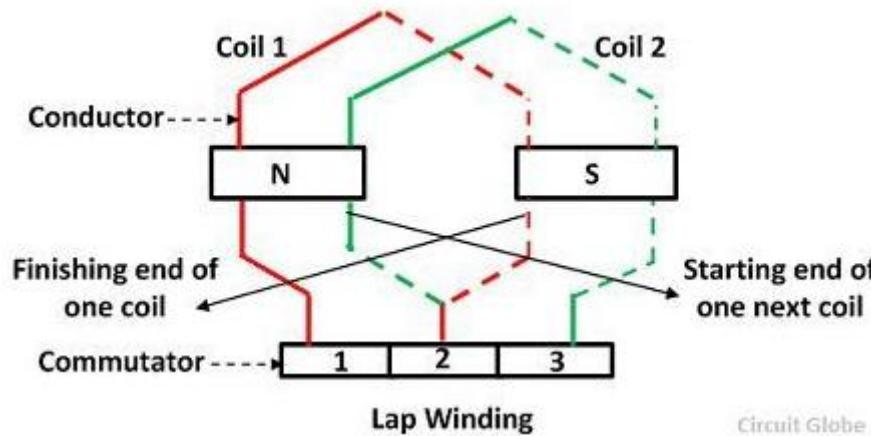
### □ Wave Winding:



$$E = \frac{\phi Znp}{60a}$$

∴ For wave winding  $a=2$

### □ Lap Winding:



$$E = \frac{\phi Znp}{60a}$$

∴ For lap winding  $p=a$

$$E = \frac{\phi Zn}{60}$$

## DC Machine Construction (cont...)

### □ Example

A lap winding connected DC-generator has 6-poles in armature, 600 rpm, 0.04 wb flux per pole, 90-slots and 4 turns per coil. Find the induced voltage by generator?

### □ Solution:

$$Z = 90 \text{ coils} \times 4 \frac{\text{turns}}{\text{coil}} \times 2 \frac{\text{conductors}}{\text{turns}} = 720$$

∴ For lap winding  $p=a$

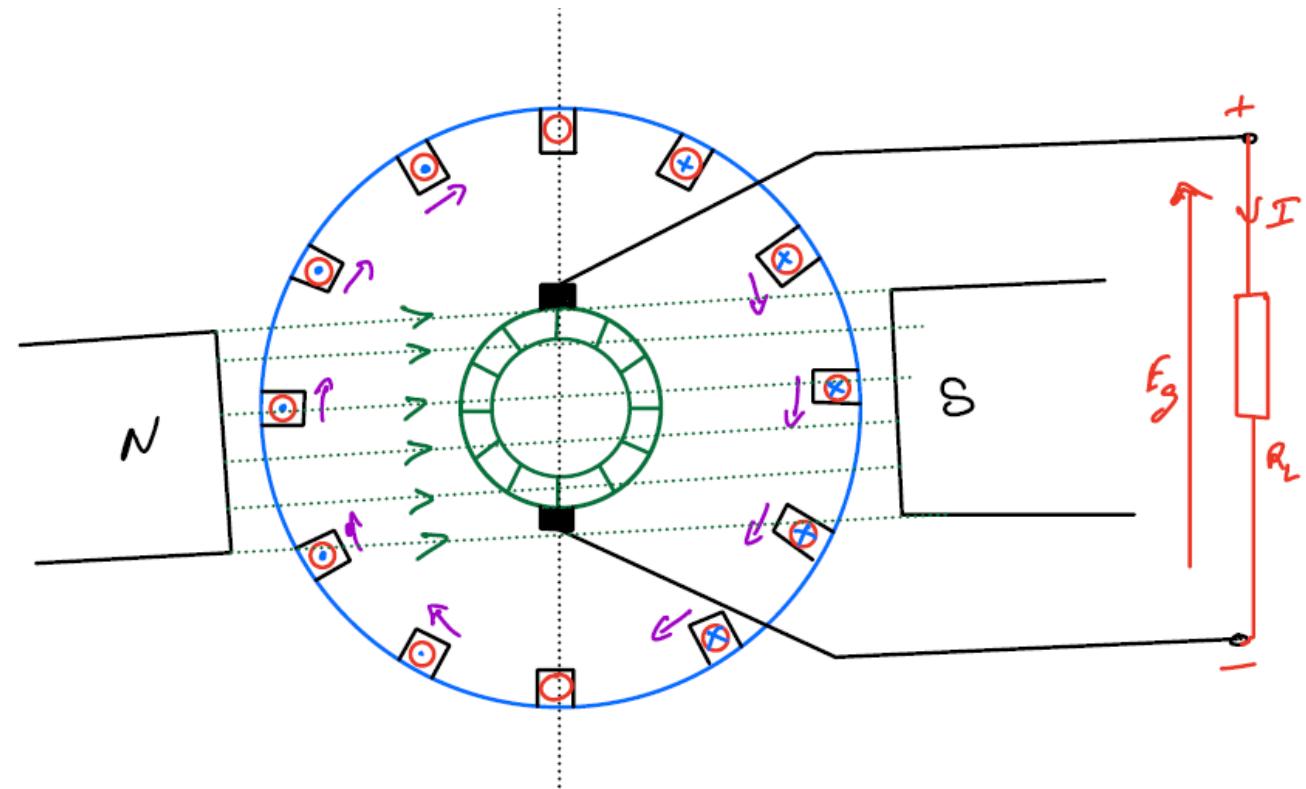
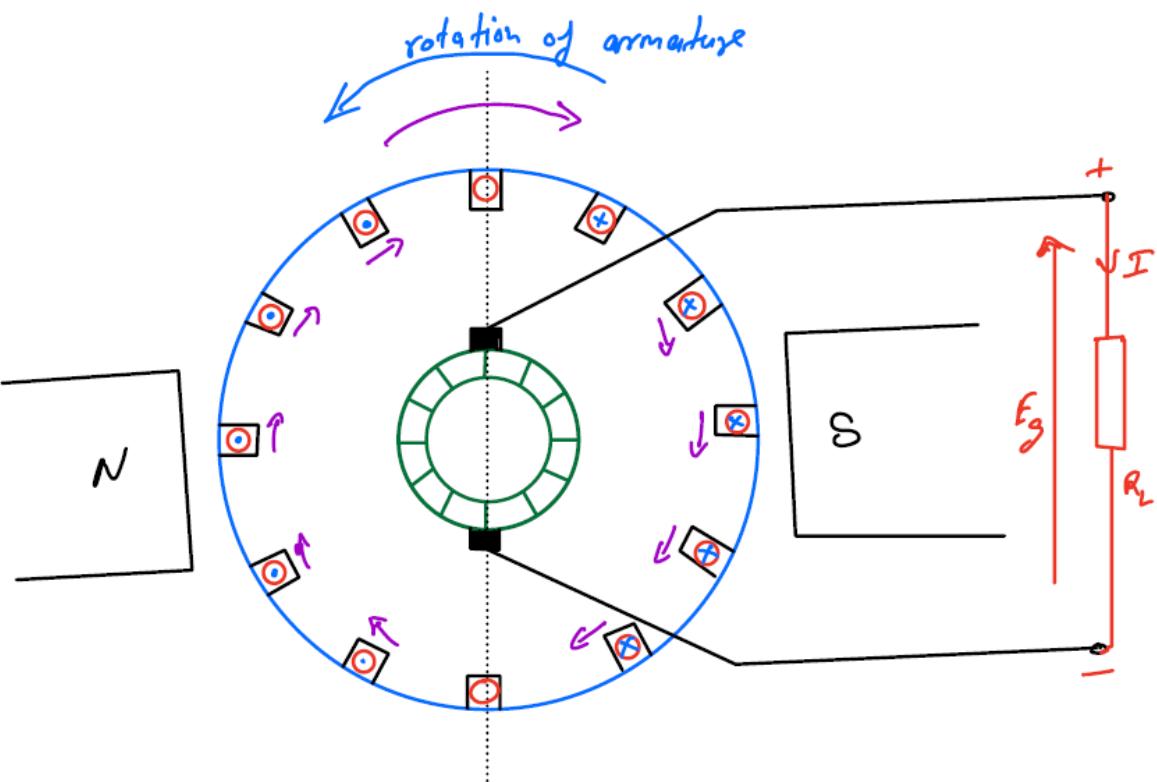
$$E = \frac{\phi Z N}{60} = \frac{0.04 \times 720 \times 600}{60} = 288V$$

∴ For wave winding  $a=2$

$$E = \frac{\phi Z N P}{60 \times a} = \frac{0.04 \times 720 \times 600 \times 6}{60 \times 2} = 864V$$

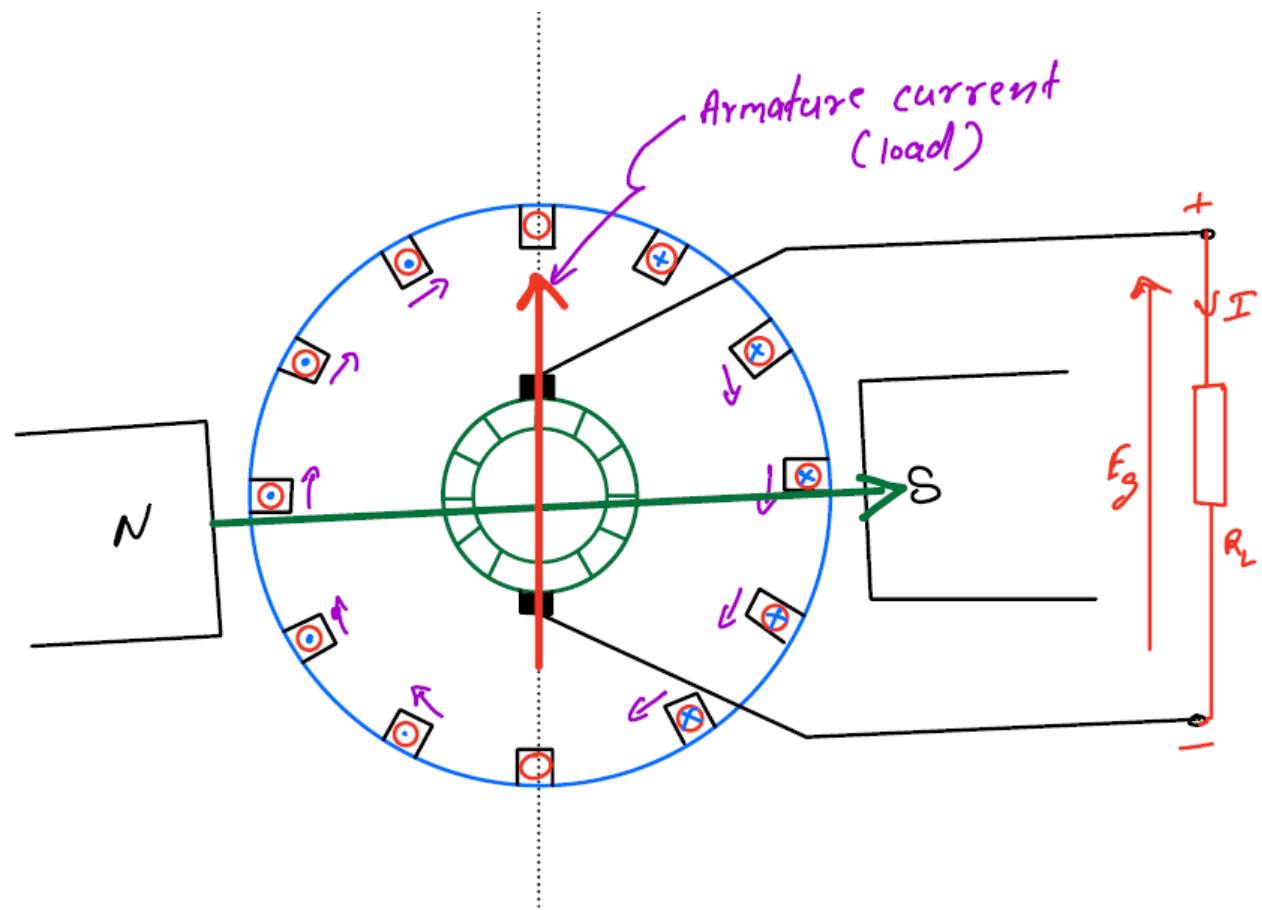
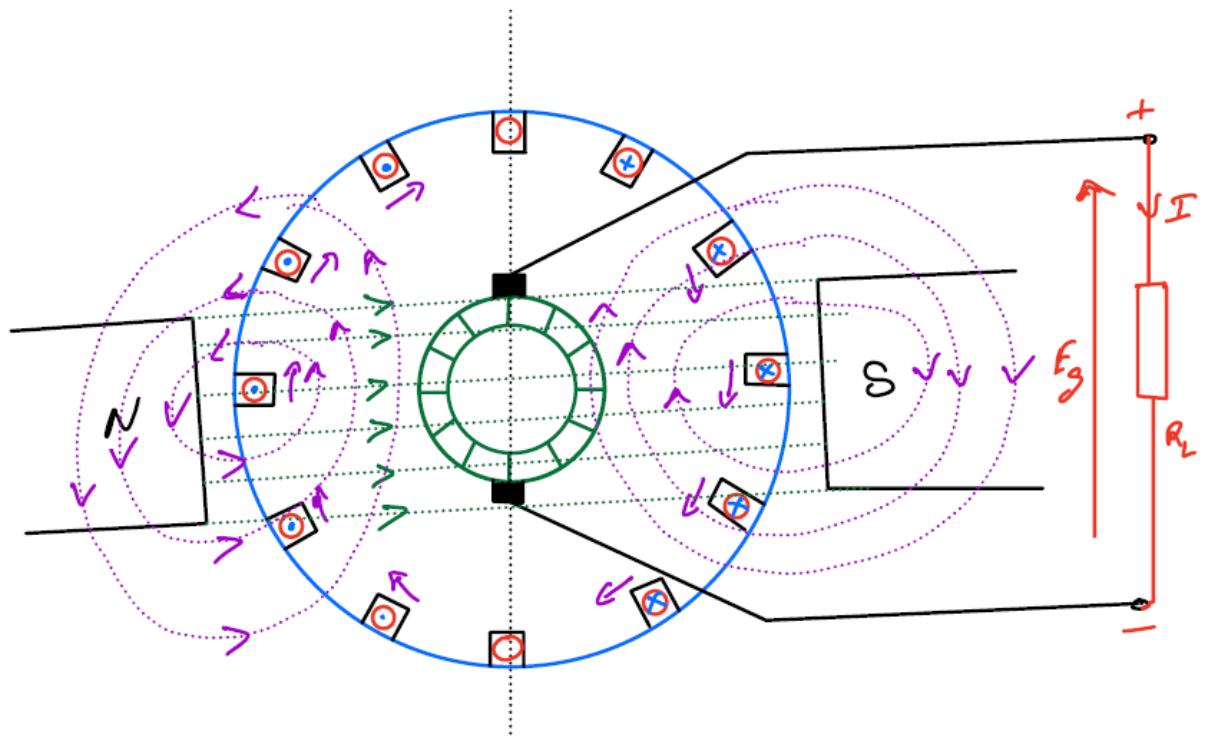
## DC Generator (cont...)

□ Loading on DC generator:



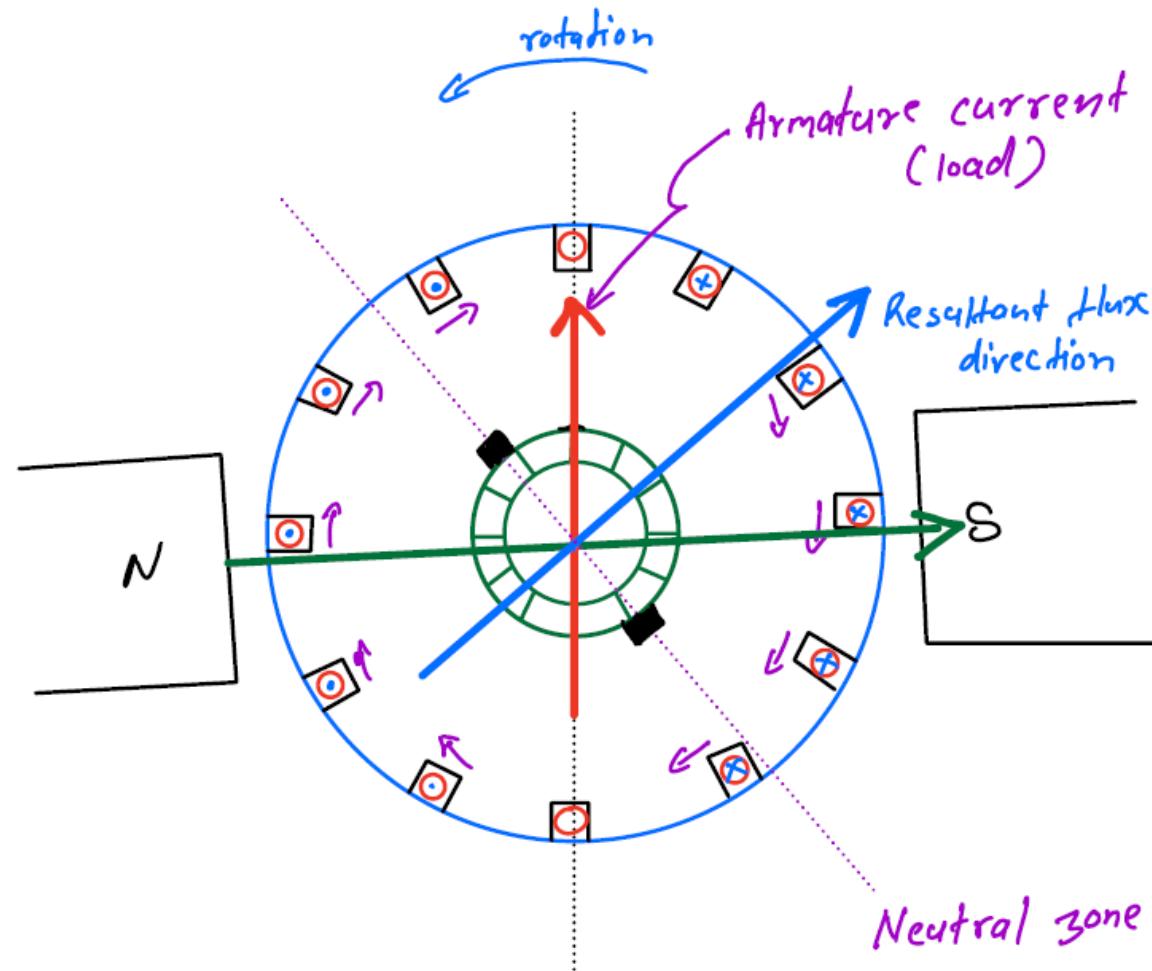
## DC Generator (cont...)

□ Loading on DC generator:



## DC Generator (cont...)

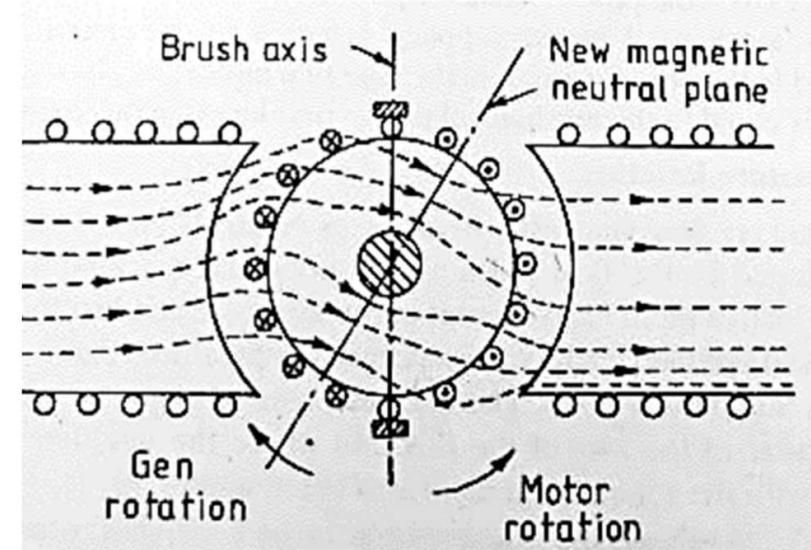
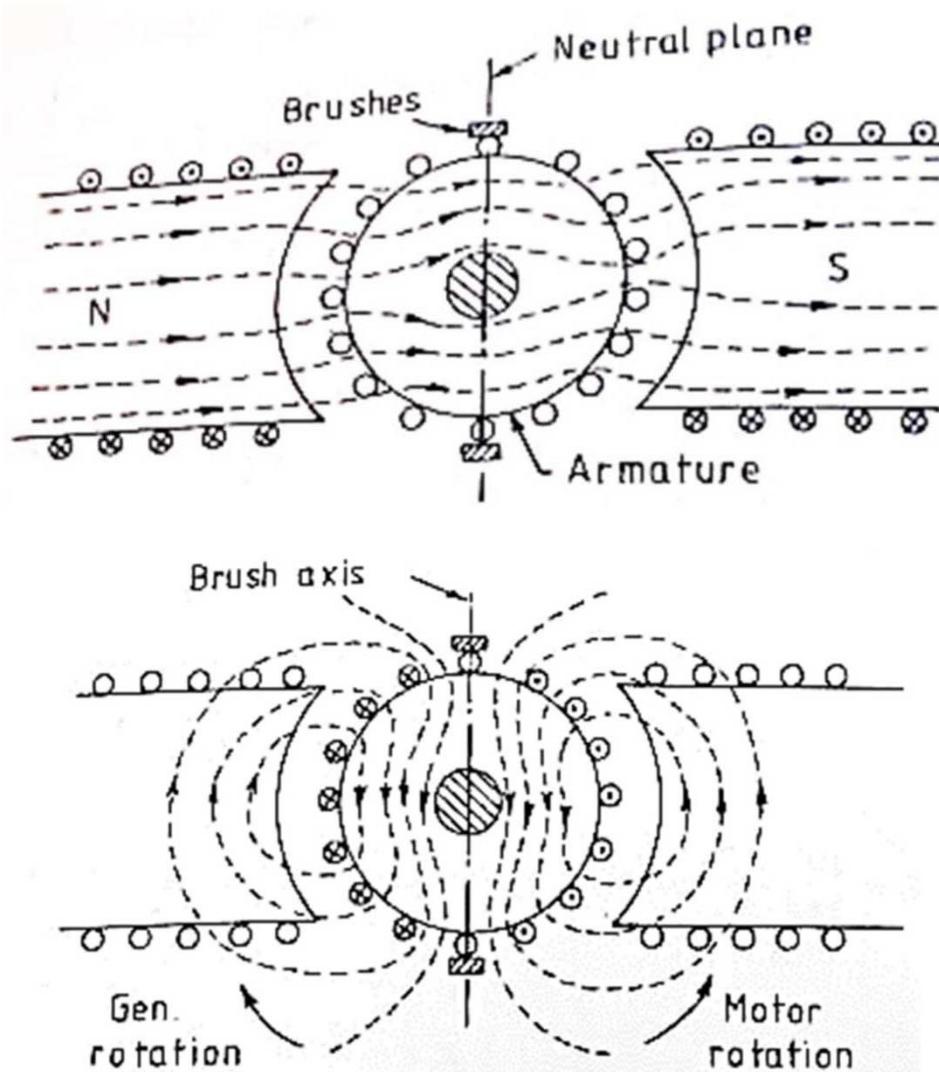
□ Loading on DC generator:



□ Armature Reaction:

## DC Generator (cont...)

### □ Armature Reaction:



- Armature reaction causes mainly the cross magnetism.
- The armature current displaces the resultant field flux in the direction of generator and against the direction of rotation in motor.
- Here, the flux is displaced by the armature current, not the mechanical motion.

## DC Generator (cont...)

□ Armature Reaction:

