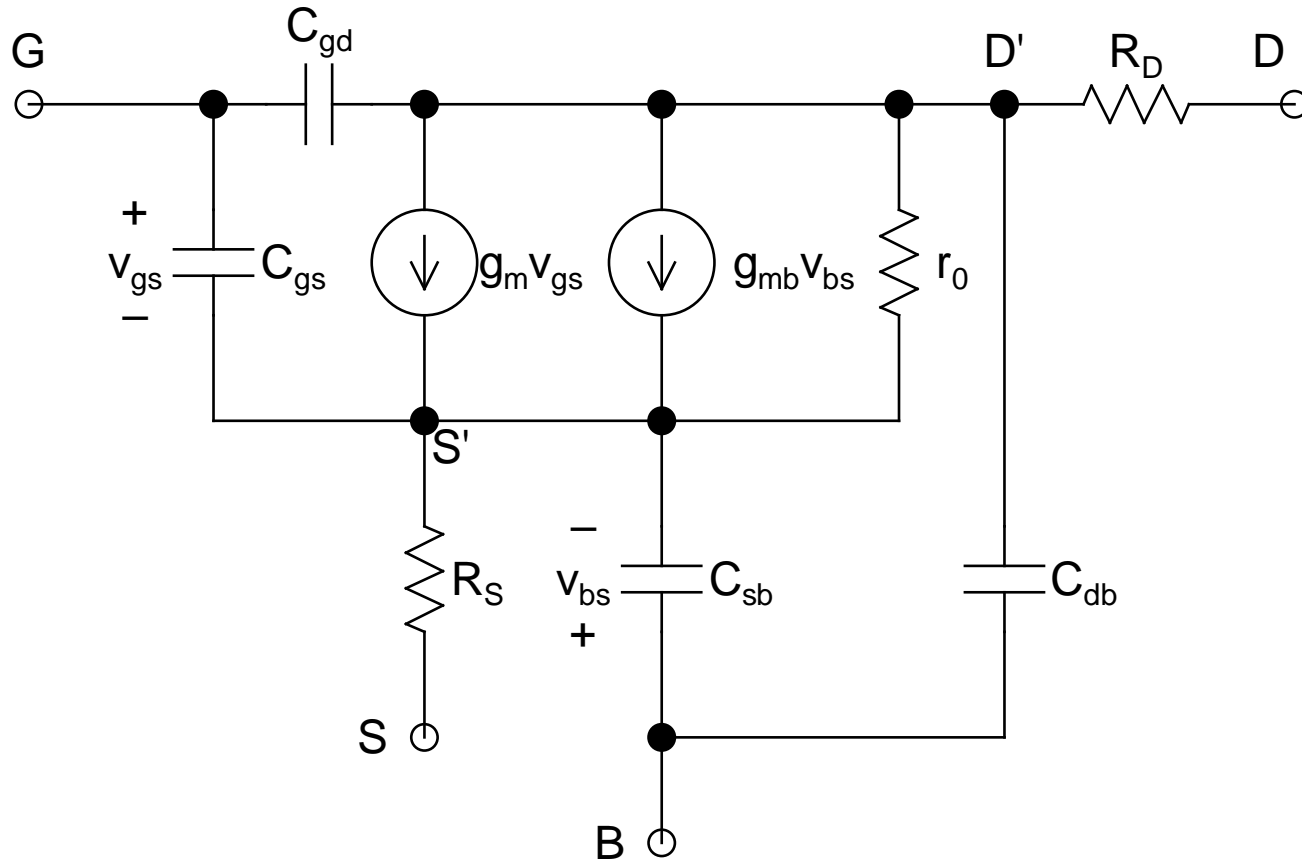
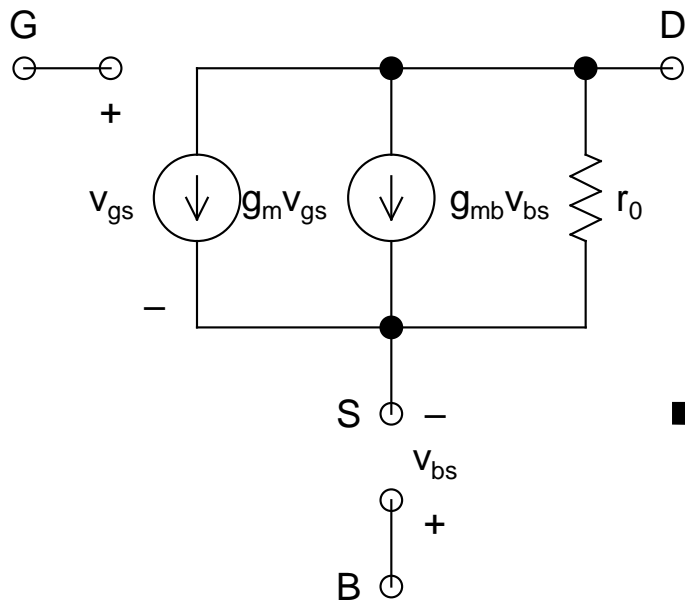


The Hybrid- π Model

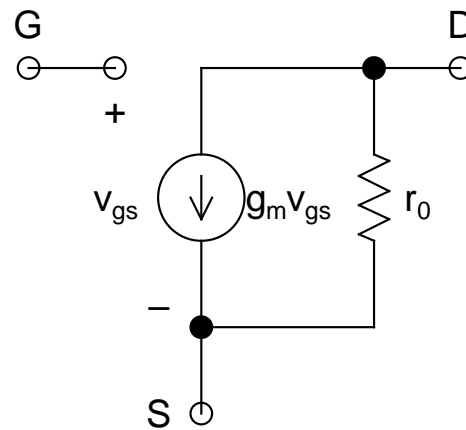


- *Simplifications:*

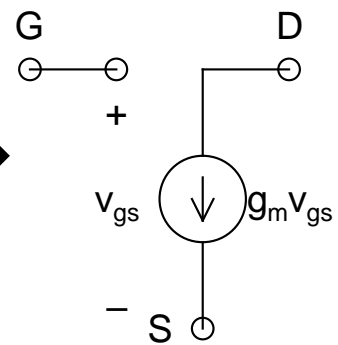
- R_S and R_D can be safely neglected
- For *low to moderate frequencies*, the *capacitive reactances* of all the capacitances will be *extremely large* \Rightarrow *can be neglected*
- *If both B and S are connected to fixed DC potentials*, *current source $g_{mb}v_{bs}$ disappears*
- Leads to the *Low-Frequency T-Model*, having only *two components*: $g_m v_{gs}$ and r_o
- *Simplest possible equivalent results if r_o is also neglected (ideal current source!)*



Low-Frequency



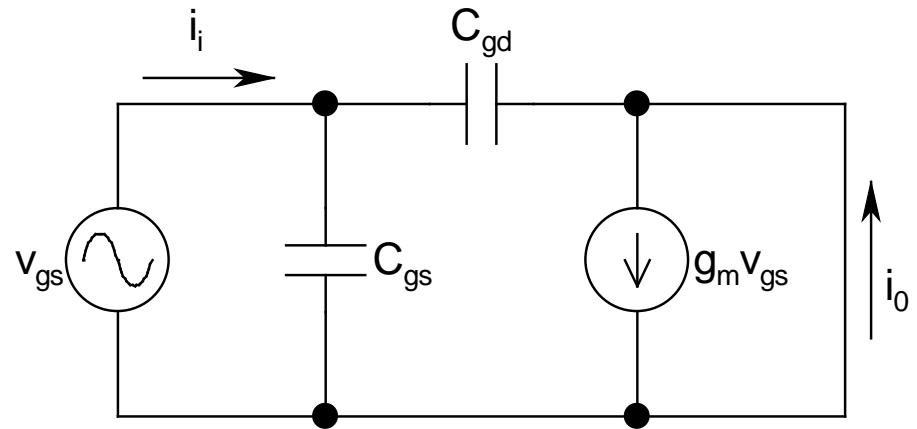
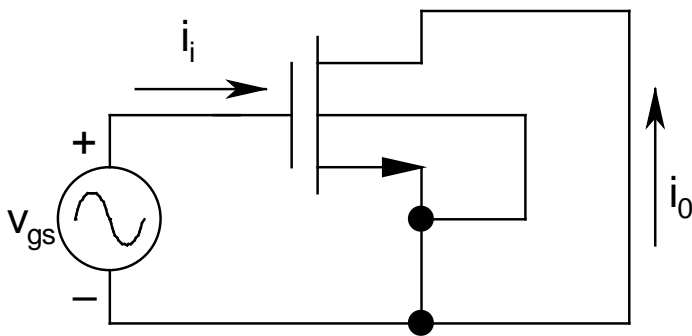
Without Body Effect



Without CLM

Frequency Specification of MOSFETs

- Only *Unity-Gain Frequency* (f_T)



- $i_o \approx g_m v_{gs}$ (neglecting *reverse transmission* through C_{gd})
- $i_i = j\omega(C_{gs} + C_{gd})$

$$\Rightarrow \frac{i_o(j\omega)}{i_i(j\omega)} = \frac{g_m}{j\omega(C_{gs} + C_{gd})}$$

$$\text{At } f = f_T, |i_o/i_i| = 1$$

$$\Rightarrow f_T = \frac{g_m}{2\pi(C_{gs} + C_{gd})}$$

- *Remarkable similarity with that for BJT*

- **Maximum Operable Frequency** (f_{\max}):

- *Maximum possible f_T*

- Noting that $C_{gs} \gg C_{gd}$, *neglecting C_{gst}* , and *substituting the expressions for C_{gsi} and g_m* :

$$f_{\max} = f_T \Big|_{\max} = \frac{3\mu_n V_{GT}}{4\pi L^2}$$

- $f_{\max} \propto 1/L^2$

- *Thrust towards making L as small as possible*

- $f_{\max} \propto V_{GT}$

- *Making V_{GT} large may be detrimental!*

BIASING

- To find the *DC operating point* (*bias point*, *Q-point*)
- Has to *precede ac analysis*, since *small-signal parameters depend on the bias point*
- For *diodes*: (I_D , V_D)
- For *BJTs*: (I_C , V_{CE})
- For *MOSFETs*: (I_D , V_{DS})
- Also, $P_D = V_D \times I_D$ (*Diodes*), $V_{CE} \times I_C$ (*BJTs*), and $V_{DS} \times I_D$ (*MOSFETs*)

- *DC power dissipated in a circuit* = (*Supply Voltage*) \times (*Supply Current*)
- Circuits may be *biased* by *single supply* (*positive/negative and ground*) or *dual supply* (*positive and negative*)
- Devices should be *properly biased* and *ideally* should be under the *best biasing* (BB)
- Also, need *voltage references* to provide *fixed DC voltages* at some *circuit nodes*

- *Two types:*

- *Discrete Stage Biasing:*

- Uses *power supplies* and *resistors* along with the *active devices*
- Used for *discrete circuits* assembled in *breadboards*
- Also known as *passive biasing*

- *IC (Integrated Circuit) Stage Biasing:*

- *Avoids resistors* as much as possible and *uses transistors* as *biasing elements*
- Used for *IC stages*
- Also known as *active biasing*

Discrete Stage Biasing: BJT

- Will be using *quick estimate* ($V_{BE} = 0.7 \text{ V}$)
- **FA mode of operation** with $V_{CE} \geq 0.2 \text{ V}$
- *Error of $\pm 5\text{-}10\%$ quite acceptable*
- *Common Schemes:*
 - *Fixed Resistor Bias*
 - *Emitter Feedback Bias*
 - *Collector Feedback Bias*
 - *Voltage Divider (or 4-Resistor) Bias*

- ***Fixed Resistor Bias:***

- $I_B = (V_{CC} - V_{BE})/R_B$

- $I_C = \beta I_B$

- $I_E = (\beta + 1)I_B \approx I_C$

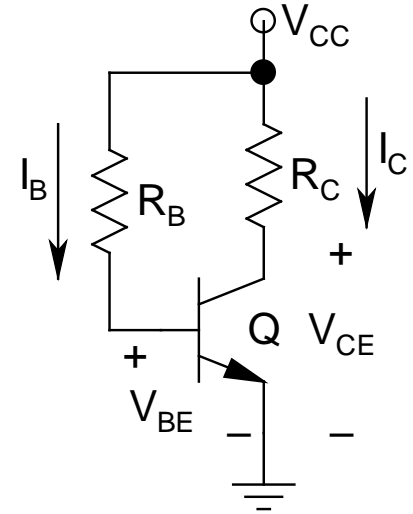
- $V_{CE} = V_{CC} - I_C R_C$

- For BB, $V_{CE} = V_{CC}/2$

- $P_D (\text{circuit}) = V_{CC} \times I_E$

- ***Note:*** *Need β to find the operating point*

- The ***simplest biasing circuit***, but has ***severe β dependence***



- ***Emitter Feedback Bias:***

- *While writing KVL, never take CE or BC loops, since V_{CE} and V_{BC} are not known*

- *Consider only BE loops with $V_{BE} = 0.7\text{ V}$*

- $V_{CC} = I_B R_B + V_{BE} + I_E R_E$

$$\Rightarrow I_B = \frac{V_{CC} - V_{BE}}{R_B + (\beta + 1)R_E}$$

