

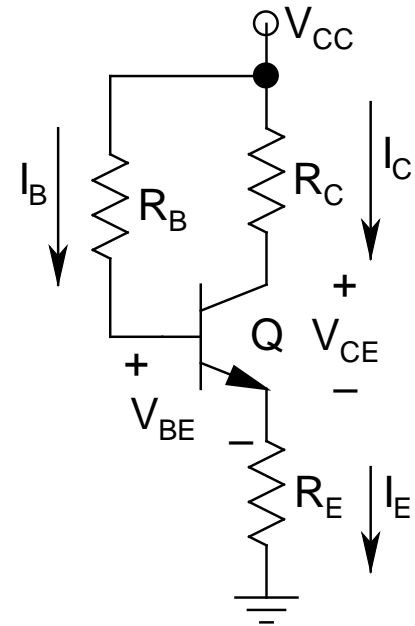
- ***Emitter Feedback Bias:***

- *While writing KVL, never take CE or BC loops, since V_{CE} and V_{BC} are not known*

- *Consider only BE loops with $V_{BE} = 0.7\text{ V}$*

- $V_{CC} = I_B R_B + V_{BE} + I_E R_E$

$$\Rightarrow I_B = \frac{V_{CC} - V_{BE}}{R_B + (\beta + 1) R_E}$$



- $I_C = \beta I_B$
- $V_{CE} = V_{CC} - I_C R_C - I_E R_E \approx V_{CC} - I_C (R_C + R_E)$
- $P_D (\text{circuit}) = V_{CC} \times I_E$
- This is a **3-element output branch**, with $V_{CE} = V_{CC}/3$ for BB
- **Rest $2V_{CC}/3$ drops across R_C and R_E , with the ratio typically chosen to be 2:1** (reason later!)
- Circuit is **very robust** since R_E provides **negative feedback**
- Also, has **better β insensitivity**

- ***Collector Feedback Bias:***

- $V_{CC} = I_E(R_C + R_E) + I_B R_B + V_{BE}$

$$\Rightarrow I_B = \frac{V_{CC} - V_{BE}}{R_B + (\beta + 1)(R_C + R_E)}$$

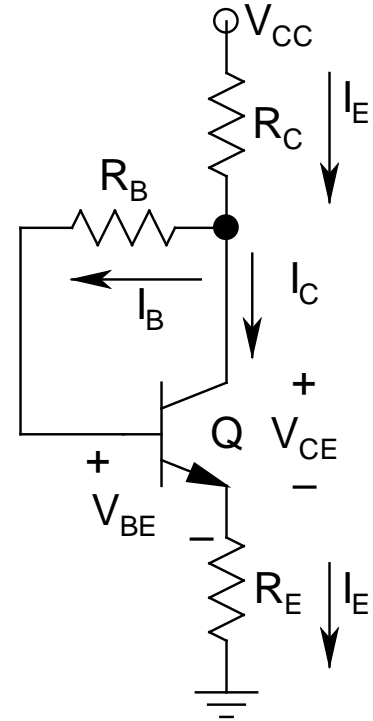
- $I_C = \beta I_B$

- $V_{CE} = V_{CC} - I_E(R_C + R_E)$

- $P_D (\text{circuit}) = V_{CC} \times I_E$

- This circuit also provides

better β insensitivity



- ***Voltage Divider (or 4-Resistor) Bias:***

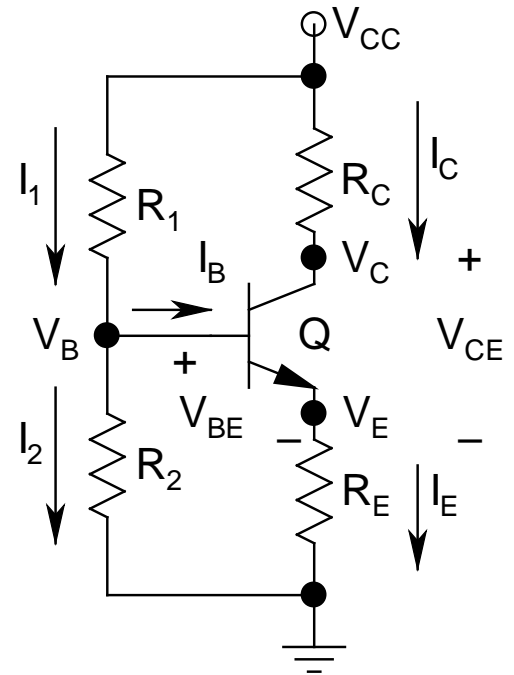
- *The best: Extremely robust and versatile*

- If properly designed, *almost β independent*

- If $I_1 \geq 10I_B$, $I_1 \approx I_2$

$$\Rightarrow V_B \approx \frac{R_2}{R_1 + R_2} V_{CC}$$

$$\Rightarrow V_E = V_B - V_{BE} \text{ and } I_C \approx I_E = V_E / R_E$$



- **Example:** Let $V_{CC} = 5 \text{ V}$, $R_1 = 40 \text{ k}\Omega$, $R_2 = 10 \text{ k}\Omega$, $R_C = 2 \text{ k}\Omega$, and $R_E = 300 \Omega$
 - **Quick estimate:** Assume $\beta \geq 100$
 - $\Rightarrow V_B = 1 \text{ V}$, $V_E = 0.3 \text{ V}$, $I_C \approx I_E = 1 \text{ mA}$, $V_{CE} = 2.7 \text{ V}$, and $P_D = 5.5 \text{ mW}$
 - \Rightarrow Done! Piece of cake, isn't it?
 - $I_1 = 100 \mu\text{A}$ and $I_B \leq 10 \mu\text{A}$ (for $\beta \geq 100$):
Assumption of $I_1 \geq 10I_B$ validated
 - Actually, as I_1 and β go down, this **analysis becomes more and more inaccurate!**

- **Exact Analysis:**

- *Sufficiently more complicated*

- *Open the base lead and*

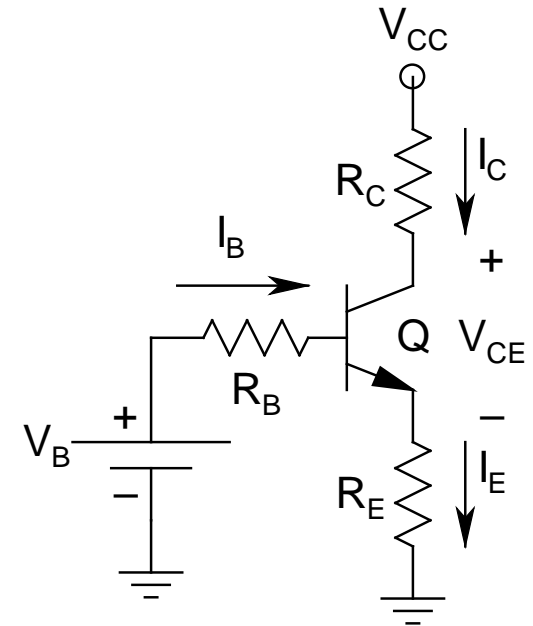
Thevenize the left branch

$$\Rightarrow V_B = \frac{R_2}{R_1 + R_2} V_{CC} = 1 \text{ V}$$

$$R_B = R_1 \parallel R_2 = 8 \text{ k}\Omega$$

- Also, $V_B = I_B R_B + V_{BE} + I_E R_E$

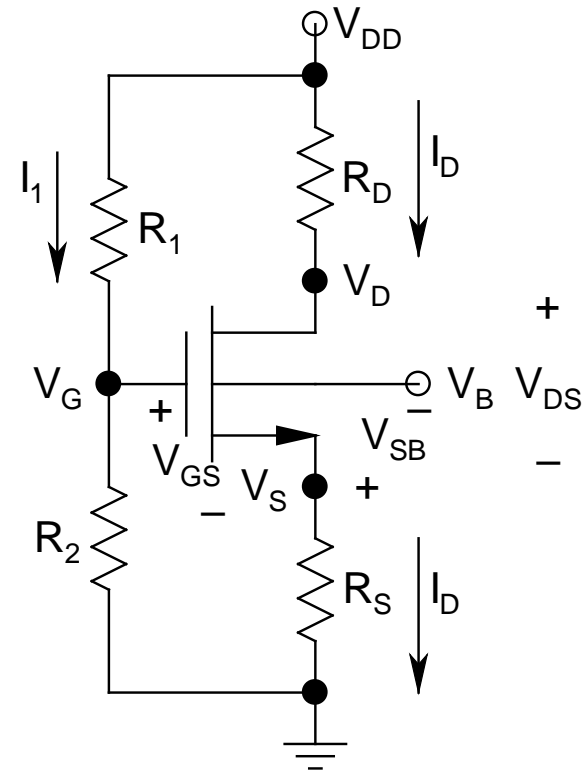
$$\Rightarrow I_B = \frac{V_B - V_{BE}}{R_B + (\beta + 1) R_E}$$



- Gives:
 - $I_B = 7.83 \mu\text{A}$, $I_C = 0.78 \text{ mA}$, and $V_{CE} = 3.2 \text{ V}$ for $\beta = 100$ (*quite off from quick estimate!*)
 - $I_B = 3.6 \mu\text{A}$, $I_C = 0.9 \text{ mA}$, and $V_{CE} = 2.93 \text{ V}$ for $\beta = 250$ (*within $\pm 10\%$ error band*)
- Thus, *as $\beta \uparrow$, accuracy of quick estimate \uparrow*
- Also, *as $R_B \downarrow$, accuracy \uparrow*
- *R_B should not be too small, since $P_D \uparrow\uparrow$*
- Thus, there are *various design constraints*

Discrete Stage Biasing: MOSFET

- *Almost universally biased using 4-Resistor Bias*
- *Significantly more complicated than BJT biasing, since there is no quick estimate*
- *Also, body effect and CLM complicate matters*



- **No I_G** \Rightarrow *R_1 - R_2 combination provides a perfect voltage division*

$$\Rightarrow V_G \simeq \frac{R_2}{R_1 + R_2} V_{DD}$$

- $V_S = I_D R_S$ and $V_D = V_{DD} - I_D R_D$

$$\Rightarrow I_D = \frac{k_N}{2} (V_G - I_D R_S - V_{TN})^2 \times \\ \left(1 + \lambda [V_{DD} - I_D (R_S + R_D)] \right)$$

- Also:

$$V_{\text{TN}} = V_{\text{TN0}} + \gamma \left(\sqrt{2\phi_F + I_D R_S - V_B} - \sqrt{2\phi_F} \right)$$

- *Extremely intimidating!*
- *I_D equation becomes cubic!*
- *Thus, bias calculation including all higher order effects is pretty tedious, and almost impossible for hand analysis*
- *Need to make approximations!*

- Assume $\lambda V_{DS} < 0.1$:

$$\Rightarrow I_D = \frac{k_N}{2} (V_G - I_D R_S - V_{TN})^2$$

- *Even then it's quite complicated, since V_{TN} has a square root dependence on I_D*
- *Tie B and S together* $\Rightarrow V_{SB} = 0$ and $V_{TN} = V_{TN0}$

➤ *Note that it can't be done always!*

$$\Rightarrow I_D = \frac{k_N}{2} (V_G - I_D R_S - V_{TN0})^2$$

- *Even now, it's a quadratic equation in I_D*
- *However, much easier to solve than earlier cases*
- *No further simplification possible!*
- *Solving, we will get 2 values of I_D : one will be the correct one, while the other one will be unphysical*
- *2 values of I_D will give 2 different values of V_{GS} : one $> V_{TN0}$ and the other $< V_{TN0}$*

- *Obviously, I_D for $V_{GS} < V_{TN0}$ is completely meaningless, since the device is off under that condition*
- Compute $V_{DS} [= V_{DD} - I_D(R_S + R_D)]$
 - *Should be $> V_{GT}$ (saturation mode)*
 - *For BB, $V_{DS} = V_{DD}/3$*
- $P_D = V_{DD} \times (I_D + I_1) \quad [I_1 = V_{DD}/(R_1 + R_2)]$
- *Here, no constraints on R_1 and R_2 , and they can be made as large as physically possible to reduce I_1 , and thus P_D*