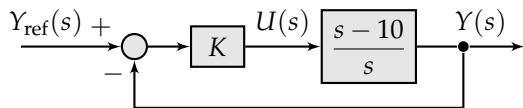


Midsem. # 2, EE 250 (Control System Analysis), 2011*

DEPARTMENT OF ELECTRICAL ENGINEERING, IIT KANPUR

1. Determine, using Nyquist stability theory, the values of $K \geq 0$ for which the following control system is stable. Each problem is of 1 point.



- 1.1. Sketch the BP.

- 1.2. Sketch the polar plot (PP) section of the NP. Show this section by a thick solid line. Mark the critical point.

- 1.3. If necessary, work out a few points on the s -plane contour and the $G(s)$ -plane contour that will help complete the NP.

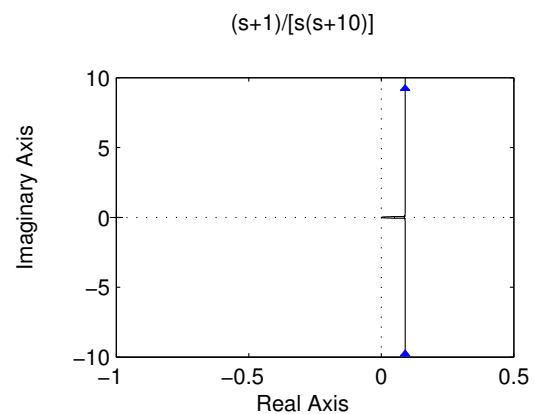
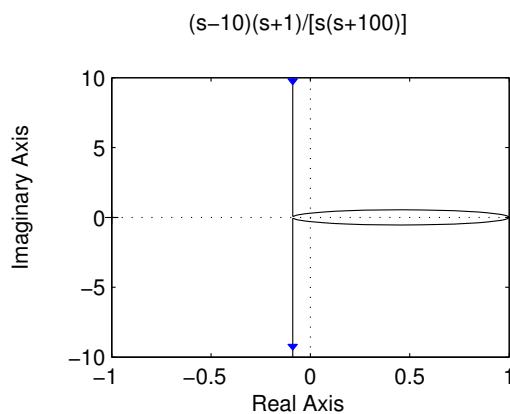
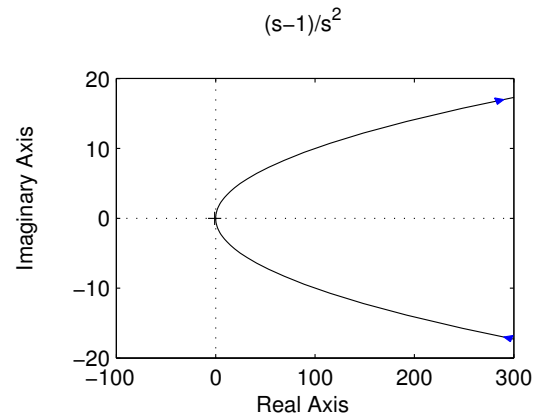
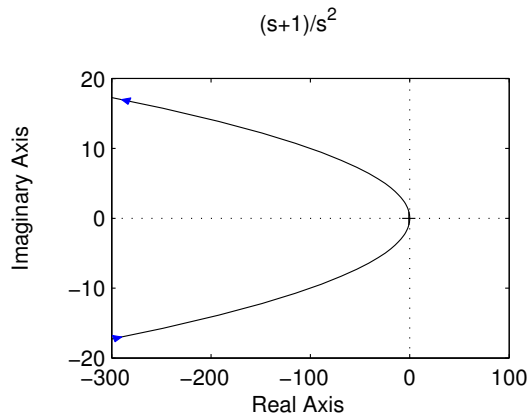
- 1.4. Sketch the NP. Label the sections of the s -plane contour $C1, C2, \dots$ and the corresponding sections of the NP $C1', C2', \dots$.

- 1.5. Use NST to determine the values of K for which the CL system is stable.

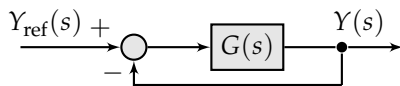
- 1.6. Is this system conditionally stable? Explain.

*Instructor: Ramprasad Potluri, Office: WL217A, Lab: WL217B, Phones: (0512) 259-8837, 259-7735, E-mail: potluri@iitk.ac.in

2. [4 points] The following are the plots generated by MATLAB's nyquist function. In whatever space you can squeeze out near each plot, complete each of these plots to obtain the Nyquist plot.



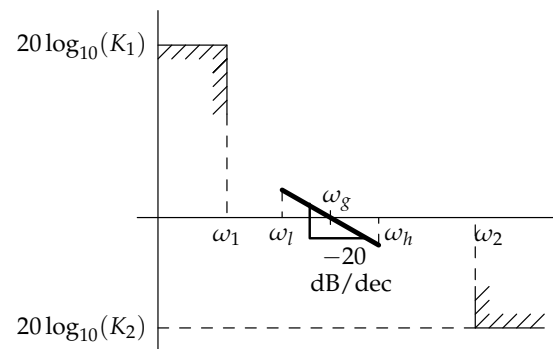
3. We wish to design $G(s)$ for the control system



to satisfy the following specifications: We wish to design a compensator $D(s)$ that satisfies the following design specifications:

- Peak overshoot in the unit step response of approximately 20%.
- Sinusoidal inputs of up to 1 rad/sec to be reproduced with $\leq 5\%$ error.
- Sinusoidal inputs with a frequency of greater than 100 rad/sec to be attenuated at the output to $\leq 10\%$ of their input value.
- Steady-state error to a unit step to be less than 1%.

With respect to the following figure



- 3.1. [2 points] Determine K_1 and K_2 .

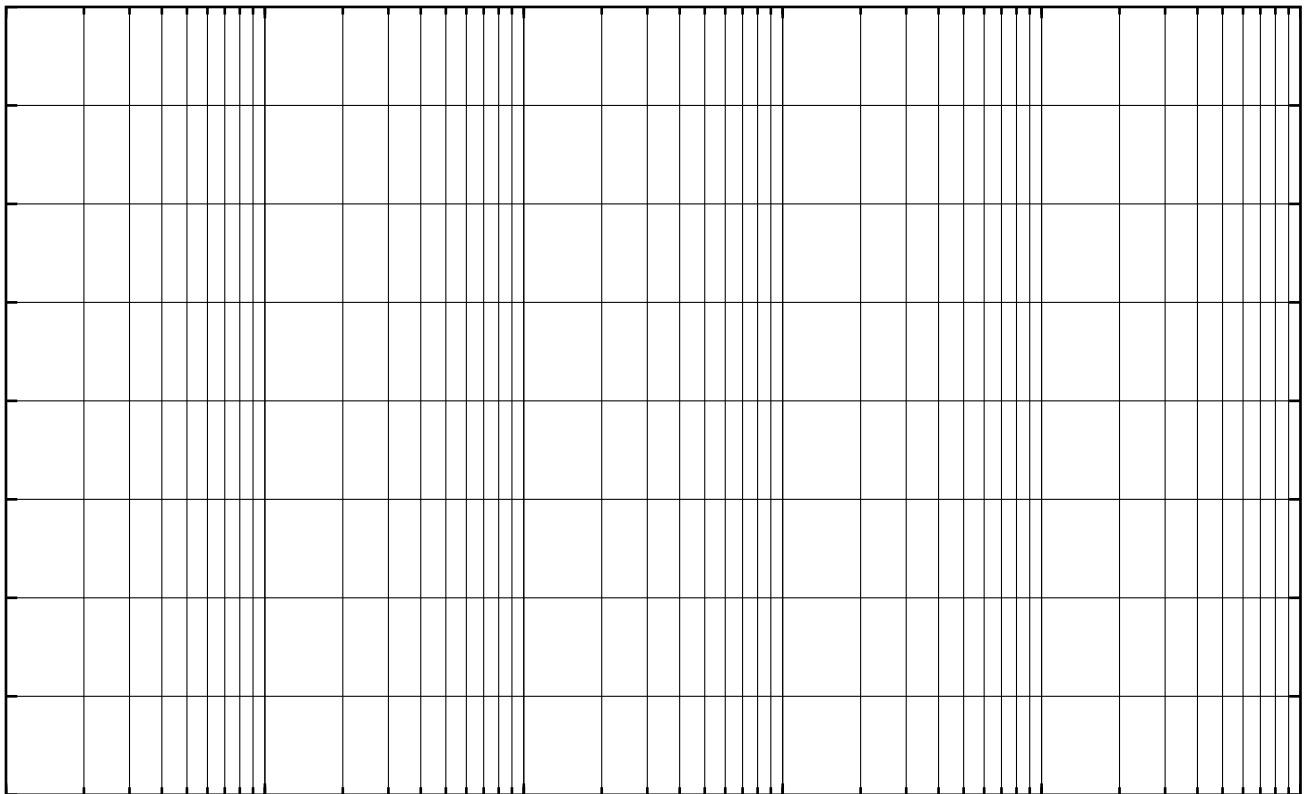
- 3.2. [1 points] $\omega_1 = ?$ and $\omega_2 = ?$

3.3. [1 points] What is the decade distance needed between the corner frequencies ω_l and ω_h for the desired Bode plot?

3.4. [1 points] Is this DD the distance on the BMP or on the ABMP or both?

3.5. [3 points] On the semilog grid provided, draw the ABMP of the desired $G(s)$. Your figure must contain all the necessary labels.

3.6. [1 points] For the resulting CL system, given that $\omega_B \in [\omega_{\min}, \omega_{\max}]$, where ω_B is the bandwidth, what are the values of ω_{\min} and ω_{\max} ?



Useful information:

25°	40°	60°	70°	90° (−90°)	60° (−60°)	45° (−45°)	30° (−30°)
45%	25%	10%	5%	∞	1.1439	0.76555	0.47712
					≈ 1.144	≈ 0.766	≈ 0.477