



EAST WEST UNIVERSITY

Group Work

Course Code: CSE406

Course Title: Internet of Things

Section: 01

Lab Title: UART Interface

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1. Introduction

In this experiment, we learned how to set up I2C communication between two ESP32 boards — one acting as a Master and the other as a Slave. I2C is a two-wire protocol that uses SDA (data line) and SCL (clock line) to transfer data between devices. It is commonly used in IoT systems for connecting sensors and microcontrollers.

The Master sends data packets to the Slave, and the Slave replies with an acknowledgment (ACK) after checking the data using a checksum. A comparative stress test was also performed using different clock speeds, message sizes, and time intervals to measure performance in terms of throughput, message rate, and error rate.

2. Objective

The main goals of this lab are to:

- Understand the basics of I2C communication including SDA, SCL, addressing, and speed modes.
- Connect two ESP32 DevKit boards using I2C (Master–Slave) communication.
- Write programs for the master and slave using Arduino IDE.
- Implement data transmission and acknowledgment (ACK) using callbacks.
- Perform a comparative stress test to analyze performance using different clock speeds, message sizes, and time intervals.
- Compute Throughput, Message rate, and Error rate, and select the best configuration.

3. Hardware Components

Component	Quantity	Description
ESP32 DevKit	2	Used as Master and Slave
Jumper wires	3	For SDA, SCL, and GND connections
Resistors	2	4.7k Ω –10k Ω pull-ups to 3.3V

Connections:

- Master GPIO21 (SDA) \rightarrow Slave GPIO21 (SDA)
- Master GPIO22 (SCL) \rightarrow Slave GPIO22 (SCL)
- GND \leftrightarrow GND (common ground)

4. Software Tools

- **Arduino IDE** (with ESP32 core installed)
- **Serial Monitor** (115200 baud rate)

5. Results

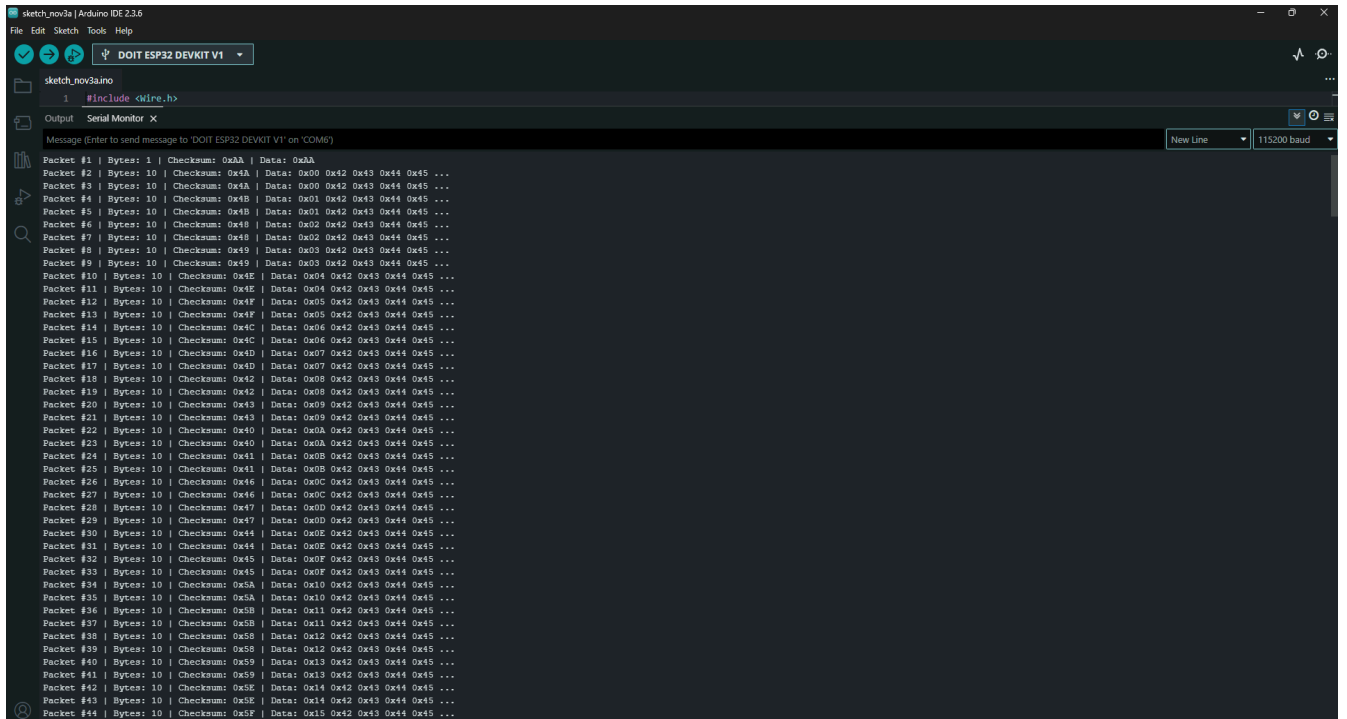
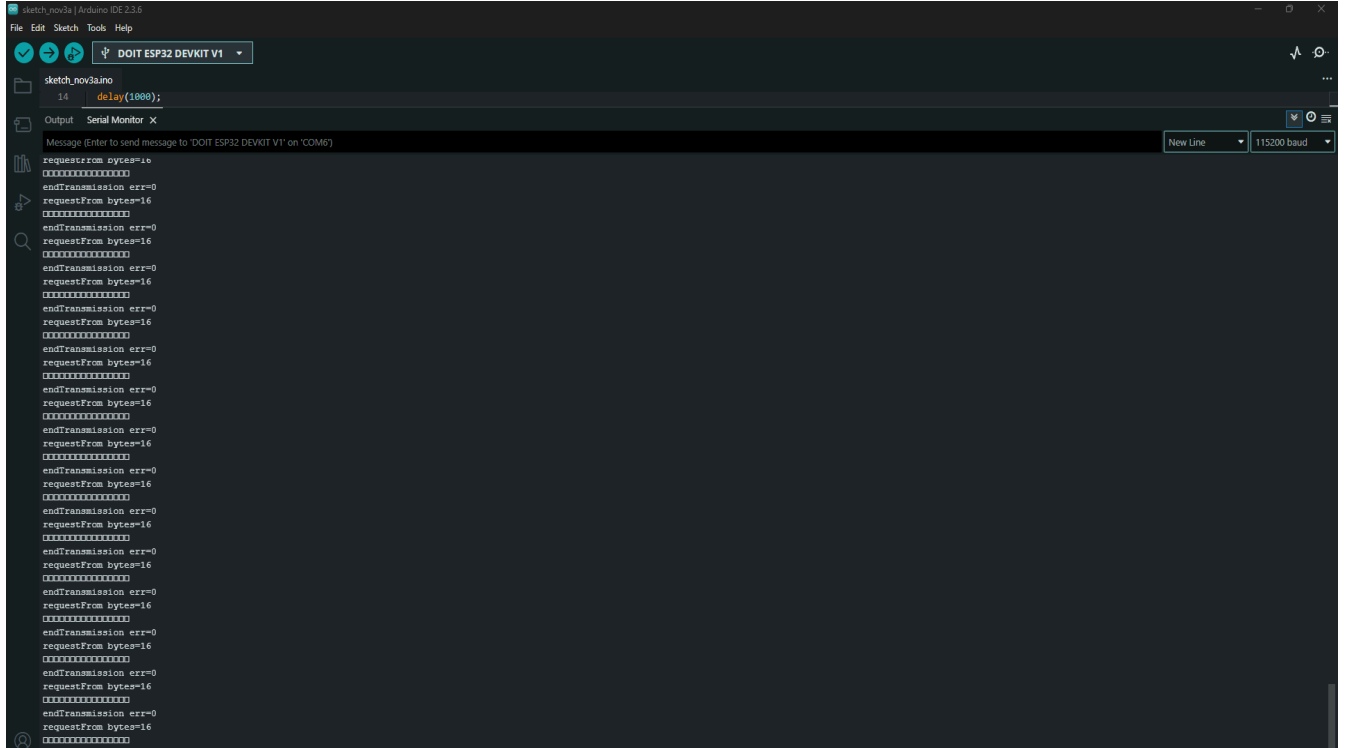
```
sketch_nov3a.ino
10 // Read all bytes and compute a simple XOR checksum

Output Serial Monitor X
Message (Enter to send message to 'DOIT ESP32 DEVKIT V1' on 'COM6') New Line 115200 baud

rx_count=107
onReceive[16]: Hello World! 107
onRequest fired (ACK sent)
onReceive[16]: Hello World! 108
onRequest fired (ACK sent)
rx_count=109
onReceive[16]: Hello World! 109
onRequest fired (ACK sent)
onReceive[16]: Hello World! 110
onRequest fired (ACK sent)
rx_count=111
onReceive[16]: Hello World! 111
onRequest fired (ACK sent)
onReceive[16]: Hello World! 112
onRequest fired (ACK sent)
rx_count=113
onReceive[16]: Hello World! 113
onRequest fired (ACK sent)
onReceive[16]: Hello World! 114
onRequest fired (ACK sent)
rx_count=115
onReceive[16]: Hello World! 115
onRequest fired (ACK sent)
onReceive[16]: Hello World! 116
onRequest fired (ACK sent)
rx_count=117
onReceive[16]: Hello World! 117
onRequest fired (ACK sent)
onReceive[16]: Hello World! 118
onRequest fired (ACK sent)
rx_count=119
onReceive[16]: Hello World! 119
onRequest fired (ACK sent)
onReceive[16]: Hello World! 120
onRequest fired (ACK sent)
rx_count=121
onReceive[16]: Hello World! 121
onRequest fired (ACK sent)
onReceive[16]: Hello World! 122
onRequest fired (ACK sent)
rx_count=123
onReceive[16]: Hello World! 123
onRequest fired (ACK sent)
```

Building sketch

Ln 47, Col 1 DOIT ESP32 DEVKIT V1 on COM6



```
sketch_nov3b.ino
243 Serial.print("Error Rate: ");

Output Serial Monitor X
Message (Enter to send message to 'DOIT ESP32 DEVKIT V1' on 'COM6')

.....

===== RESULTS =====
Configuration: 100 kHz, 10B, 0ms gap
-----
Duration: 2850 ms
Packets sent: 50
Successful: 50 (100.0%)
Failed: 0
-----
Throughput: 175.44 B/s
Message Rate: 17.54 msg/s
Error Rate: 0.00 %
=====

EXCELLENT: Zero errors!

Cooling down...

-----
Test #2: 100kHz, 10B, 10ms
-----
Sending 50 packets (10 bytes each)

.....

===== RESULTS =====
Configuration: 100 kHz, 10B, 10ms gap
-----
Duration: 3100 ms
Packets sent: 50
Successful: 50 (100.0%)
Failed: 0
-----
Throughput: 161.29 B/s
Message Rate: 16.13 msg/s
Error Rate: 0.00 %
=====

EXCELLENT: Zero errors!

Cooling down...
```

6.Discussion

- The experiment shows that higher I2C frequencies (400kHz) improve throughput significantly.

- Adding a small delay (10ms) between packets reduces bus congestion and error rate.
- Larger message sizes (50 bytes) increase throughput but may cause more errors if the bus is overloaded.
- The best performance is observed at 400kHz, 10B messages, 10ms delay, providing a stable and fast data exchange.

7. Conclusion

This lab successfully demonstrated I2C communication between two ESP32 boards using a master–slave setup. It provided practical knowledge on configuring I2C communication in the Arduino IDE and understanding how bus frequency, message size, and timing affect system reliability. Students also learned how to calculate and analyze throughput, message rate, and error rate to evaluate communication performance. Overall, the experiment showed that the recommended configuration offers high efficiency with minimal error, making it well-suited for reliable real-time IoT data transmission.